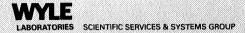
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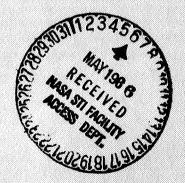
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ENGINEERING EVALUATION OF SSME DYNAMIC DATA FROM ENGINE TESTS AND SSV FLIGHTS

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WYLE LABORATORIES - RESEARCH STAFF TECHNICAL REPORT 64058-03

ENGINEERING EVALUATION OF SSME DYNAMIC DATA FROM ENGINE TESTS AND SSV FLIGHTS

by

Research Staff

A final report of work performed under contract NAS8-33508

for

NATIONAL AERONAUTICS AND SPACE ADMINISTRATION GEORGE C. MARSHALL SPACE FLIGHT CENTER MARSHALL SPACE FLIGHT CENTER, ALABAMA 35812

February 1986

FOREWORD

This report was prepared by Wyle Laboratories, Scientific Services & Systems Group, for the George C. Marshall Space Flight Center, National Aeronautics and Space Administration. The work was performed under contract NAS8-33508, entitled "Dynamic Analysis of SSME Vibration and Pressure Data."

Mr. T. Coffin and Mr. W. L. Swanson, of the Wyle/Huntsville Research Department, served as Program Manager and Project Engineer, respectively, on this study. Messrs. T. Gardner, R. Dandridge, and Dr. J. Jong provided valuable contributions to SSME data analysis and component modeling tasks. Mr. W. C. Smith, MSFC/ED24 served as Contracting Officer's Technical Representative for the study. In this capacity he provided valuable assistance in the coordination of test evaluation activities and served as a focal point for defining task requirements and priorities.

ABSTRACT

This report summarizes an engineering evaluation of dynamic data from SSME hot firing tests and SSV flights. The basic objective of the study was to provide analyses of vibration, strain and dynamic pressure measurements in support of MSFC performance and reliability improvement programs. A brief description of the SSME test program is given and a typical test evaluation cycle reviewed. Data banks generated to characterize SSME component dynamic characteristics are described and statistical analyses performed on these data base measurements are discussed. Analytical models applied to define the dynamic behavior of SSME components (such as turbopump bearing elements and the flight accelerometer safety cut-off system) are also summarized. Appendices are included to illustrate some typical tasks performed under this study.

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SECTION I

EXECUTIVE SUMMARY

The Space Shuttle Main Engine (SSME) system and components have been and are presently undergoing extensive development and certification tests, at which time some 250 measurements are acquired, including vibration, strain, and dynamic pressure at critical engine locations. Limited engine data is also recorded during operational flights. Under the severe temperature, pressure, and dynamic environments sustained during operation, engine systems and components have been subject to malfunction and failure. Over the past 13 years of SSME development, 28 major component failures have occurred, causing extensive damage to engine hardware and test facilities, at considerable expense in cost and schedules. In addition, numerous off normal operations of a less severe nature have been observed.

Detailed analysis and evaluation of the dynamic measurements obtained is mandatory to permit quick assessment of engine component condition and the initiation of corrective measures when necessary. A wealth of dynamic data is available to support this effort. Efficient performance of this task is especially critical when considering the high test and launch rate in progress and the significant impact of dynamic evaluation results on test and launch turn-around time. Dynamic analysis, modeling and evaluation of SSME measurements and components have been performed by Wyle, under NASA contract NAS8-33508, in support of these efforts. This report documents the results of this investigation.

The basic objective of the effort was to provide detailed analyses and evaluation of vibration, dynamic pressure, and strain data available and being acquired during SSME tests. Additionally, analyses were performed on data obtained from Space Shuttle Vehicle flights. Statistical analyses were performed to characterize nominal and abnormal SSME component dynamic behavior under available operating conditions. Data banks representing component characteristics were generated and updated, and analyses performed to assess system response under actual and hypothesized operating conditions. This included update of the MSFC Diagnostic Data Base and application of the SSME Isospectral Automated Data Base System. A data base was also generated and updated in a format compatible with the Flight Accelerometer Safety Cut-Off System (FASCOS) filter characteristics to provide a basis for comparison of static test and flight results. FASCOS operational characteristics

have recently been defined statistically through system analysis and simulation, to permit assessment of the system logic.

The work was performed under three broad tasks, which are summarized as follows.

TASK I: Analysis, Evaluation, and Documentation of SSME Dynamic Test Results

Under this task Wyle performed analysis, evaluation and documentation of SSME This task represented the mainstream of the contract effort dynamic test results. and included data verification, analysis, evaluation, and documentation for each SSME ground test and additionally for SSV flight measurements. Results included definition of temporal and spectral characteristics observed. Subsynchronous. synchronous, and higher order spectral characteristics were summarized for engine components under all available operating conditions to characterize SSME component behavior. Full utilization of the SSME Isospectral Automated Data Base System was employed to provide informative data summaries. Strain measurements were analyzed as above, and improved strain data reduction procedures evaluated for subsequent Oral presentation and written summaries were strength and fatigue analysis. provided to document the results of each test and flight.

TASK III: Development and Documentation of Statistical Models of SSME Component Dynamic Behavior

Under this task Wyle developed, maintained, and updated the data base and statistical models of SSME component dynamic response measurements to provide characterizing profiles of observed parameter ranges, distributions, etc., under normal and abnormal operating conditions at available power levels. These models included wide-band root-mean-square values, narrow-band spectra, and band-pass results in the flight data format. Analytical models and computer schemes were applied to define the dynamic and statistical behavior of SSME components, such as bearing elements and the Flight Accelerometer Safety Cut-off Systems.

The above tasks are seen to be intimately related, since promising statistical/analytical models may be immediately integrated into the SSME evaluation process. Also, data base statistics were immediately updated as test and flight measurements became available. It should be noted that the above evaluations were performed under extremely limited time constraints consistent with test and flight schedules. The extent of a given investigation varied widely depending on the specific measure-

ments acquired, whether or not observed engine operation was nominal, and the severity of any observed component malfunction of failure.

The following section presents an overview of the study. The SSME test/measurement program is briefly described. Dynamic evaluation considerations are discussed. SSME data base development and application tasks performed under this contract are summarized along with analytical/statistical modeling efforts. A list of engineering investigations recently performed in support of SSME dynamic evaluations is presented. This table indicates the wide diversity of engineering effort required in accomplishing contract objectives.

As with most test/evaluation programs, quick turnaround of investigative results was imperative to successful task accomplishment. These results were therefore provided directly to the MSFC COTR and cognizant Program personnel through informal data packages and presentations. A detailed discussion of each evaluation performed is given in the technical progress and interim reports provided under this contract. Several of these reports, addressing specific task evaluations, are included as Appendices for reference.

SECTION II

PROGRAM REVIEW AND SURVEY OF TASKS

2.1 Background

The Space Shuttle Main Engines (SSME) are required to operate under extreme temperatures with high fluid pressures and rotational pump speeds. Developmental work is presently in progress to uprate SSME performance, including engine certification at FPL (109%). The SSME and components have been subjected to extensive hot firing tests. Acceleration, dynamic pressure and strain data have been acquired during these tests and additionally from Space Shuttle Vehicle (SSV) flights. Analysis and evaluation of results obtained from SSME operation, to aid in the identification and resolution of sources of malfunction, were performed by Wyle Laboratories under NASA Contract NAS8-33508. Dynamic and statistical modeling to assess system behavior and component condition has also been accomplished.

This section presents an overview of the Space Shuttle Vehicle (SSV) system and SSME in particular. The SSME test program is briefly described, and a typical SSME test evaluation cycle is outlined. Some methods applied by Wyle to the assessment of acceleration, strain and dynamic pressure measurements are discussed. A recent investigation of the FASCOS system is also described.

2.1.1 The Space Shuttle Vehicle System

The SSV is composed of the Orbiter, an External Tank (ET), which contains the ascent propellant to be used by the Orbiter's three main engines, and two Solid Rocket Boosters (SRB). The Orbiter and SRBs are reusable; the ET is expended on each launch.

A Space Shuttle mission begins with installation of the mission payload into the Orbiter cargo bay. The SRBs and the SSMEs fire together at liftoff. The two SRBs are jettisoned after burnout -- about 45 kilometers (28 miles) high -- and recovered for reuse by means of a parachute recovery system. The SSMEs continue to burn until the Orbiter is just short of orbital velocity, at which time the engines are shut down and the ET jettisoned. During its return through the atmosphere, the tank will tumble, break up and be destroyed.

The orbital maneuvering system is used to attain the desired orbit and to make any subsequent maneuvers that may be needed during a mission. After orbital operations are completed, normally about seven days, deorbiting maneuvers are initiated. The Orbiter reenters the Earth's atmosphere at a high angle of attack. It then levels into horizontal flight at low altitude for an unpowered aircraft-type approach, landing at a speed of about 335 kilometers per hour (208 miles per hour).

2.1.2 The Space Shuttle Main Engines

The Orbiter vehicle main propulsion system consists of three SSMEs. The SSMEs are reusable, high-performance, liquid-propellant rocket engines with variable thrust. They are ignited on the ground at launch and operate in parallel, with approximately 500 seconds total firing duration. Each of the rocket engines operates at a mixture ratio (liquid oxygen/liquid hydrogen) of 6:1 and a chamber pressure of approximately 3000 psia to produce a sea-level thrust of 375,000 pounds and a vacuum thrust of 470,000 pounds. The engines are presently throttleable over a thrust range of 60 to 109 percent of the design thrust level. This provides a higher thrust level during liftoff and the initial ascent phase, and allows Orbiter acceleration to be limited to 3 g's during the final ascent phase. The engines are gimbaled (±10.5 degrees for pitch and ±8.5 degrees yaw) to provide pitch, yaw, and roll control during the Orbiter boost phase.

Significant to meeting performance requirements is the use of a staged combustion power cycle coupled with high combustion chamber pressures. In the SSME-staged combustion cycle, the propellants are partially burned at high pressure and relatively low temperature in the preburners, then completely combusted at high temperature and pressure in the main chamber before expanding through the high-area-ratio nozzle. Hydrogen fuel is used to cool all combustion devices in contact with high-temperature combustion products. An electronic engine controller automatically performs checkout, start, mainstage, and engine shutdown functions. Major components of the SSME are illustrated in Figure 1. A more detailed view of the SSME power head is shown in Figure 2. This figure provides an indication of the complexity of the SSME turbomachinery.

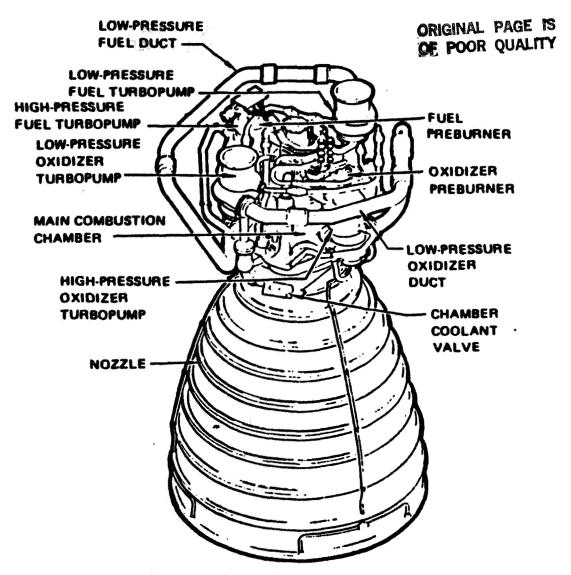


FIGURE 1. Space Shuttle Main Engine

2.1.3 SSME Development and Acceptance Testing

To validate system performance and ensure equipment reliability, the SSME and components have been and are presently undergoing extensive development and qualification tests. Testing of the engine and components is conducted at several NASA and contractor locations. Full scale engine test firings for development and flight acceptance are performed on two single-engine test stands at the National Space Technology Laboratories (NSTL), Bay St. Louis, Mississippi, and at one stand operated by Rockwell International near Santa Susana, California, with plans to include a development test stand at MSFC. In addition, main propulsion testing (MPT) is performed at NSTL on a stand designed to accommodate the Shuttle main propulsion system elements—the three-engine cluster, the ET, and the Orbiter systems.

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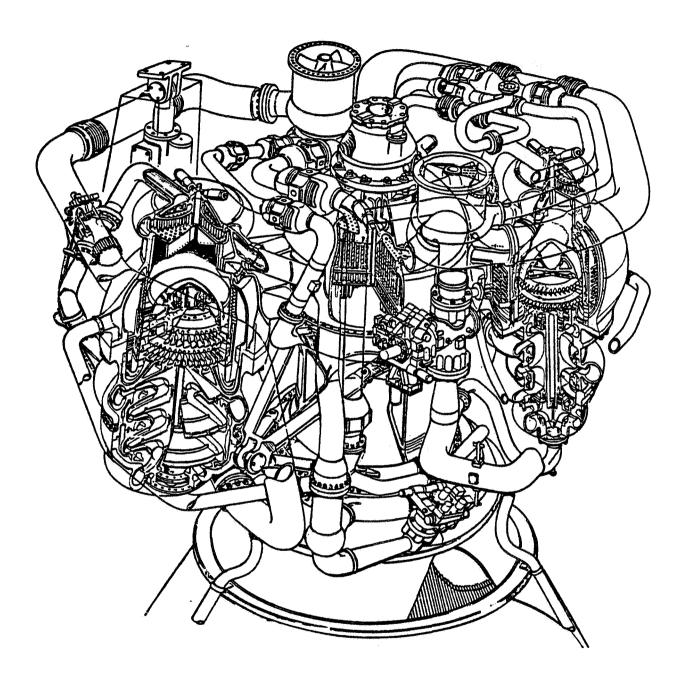
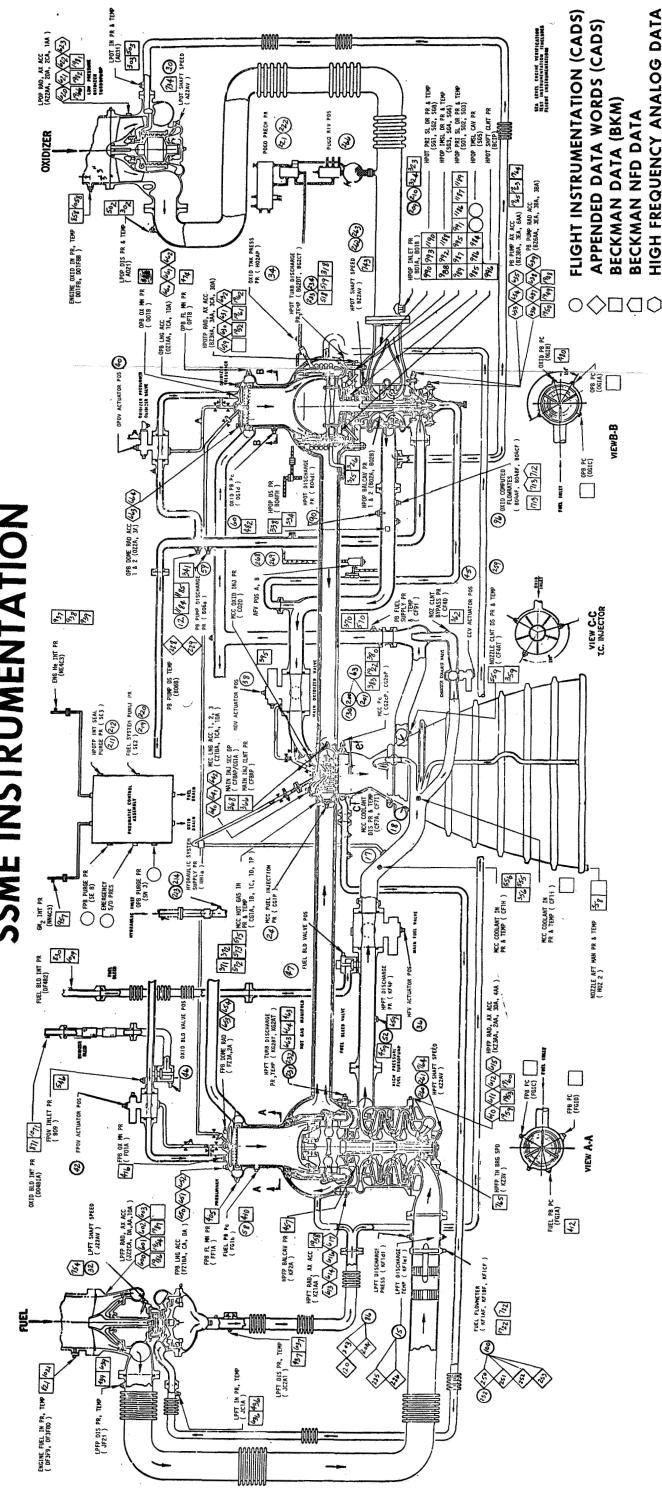


Figure 2. Space Shuttle Main Engine Power Head



Typical SSME Measurement Layout <u>ښ</u> Figure

HIGH FREQUENCY ANALOG DATA

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Testing is being performed on a continuing basis. The length of a given test is dependent on specific test objectives and may run from several seconds to over 800 seconds. Tests are generally designed to satisfy multiple specific objectives, which fall into two broad categories; acceptance/certification firing of flight hardware and development testing directed towards design verification, performance and reliability improvement. Test operations are controlled by a computer called the Command and Data Simulator (CADS) which communicates with the engine, displays vital measurements for on-line observation/control and initiates pre- and post-test procedures.

Approximately 250 measurements are recorded on a given test including wide band vibration, dynamic pressure and strain at critical engine locations. Some of these measurements are utilized on-line as emergency cut-off indicators and all are recorded on magnetic tape for subsequent analysis and evaluation. Limited SSME vibration measurements are recorded on magnetic tape during SSV flights for evaluation with orbiter return. Typical dynamic measurements obtained during SSME operation are illustrated in Figure 3.

2.2 Engineering Evaluation of SSME Dynamic Data

2.2.1 Dynamic Analysis and Evaluation Considerations

Acceleration measurements are obtained at fuel and oxidizer turbopump locations during all test firings, providing an extensive vibration data base representing various turbopump builds under widely differing operating conditions. Additional measurements are obtained on a test-specific basis, depending on performance, structural integrity, or rotor dynamic characteristics under evaluation. For example, test series have been performed with some 80 strain measurements to support engine nozzle and injector dynamic stress evaluations. Recent firings have also been conducted with internally instrumented turbopumps to define component dynamic load and signature characteristics. Thus it is seen that the extent of the evaluation process varies widely from test to test, even though engine performance is nominal. In the event of anomalous performance or component malfunction, the extent of this process is increased significantly. Limited turbopump measurements are also obtained from the three SSMEs on each SSV flight. Data bandwidths available from SSV flight instrumentation differ from the wide-band capability used during ground testing, thus the need for generating a data base of filtered ground test measure-

ments to permit direct comparison with flight results. Typical engineering activities supported by Wyle in an SSME test evaluation cycle are summarized as follows.

Data evaluation and documentation:

- Data verification and validation
- Events analysis
- Temporal and spectral correlation with operating profile and machine dynamic characteristics
- Test/flight data summary

Analytical/statistical modeling and classification:

- Develop statistical models characterizing normal and abnormal behavior
- Update SSME diagnostic data base
- Establish and update engine cut-off redlines
- Develop and apply computer programs to define SSME component dynamic behavior

Failure investigation:

- Time/event correlations with other test parameters/observations
- Temporal and spectral comparison with structural dynamic and statistical models and associated failure modes
- Evaluation and recommendations of probable failure/effect scenarios, and means of resolution.

It should be noted that the above evaluation must be performed under extremely limited time constraints consistent with test and flight schedules. Also, the extent of a given evaluation depended on the specific measurements acquired and whether or not observed engine operation was nominal.

2.2.2 SSME Data Base Development and Application

Wyle personnel have been instrumental in the development, modification and application of the MSFC Diagnostic and Isospectral data base programs. These routines are used extensively in routine test evaluation and also in diagnostic investigations. The SSME diagnostic data base and software implemented in the last year has greatly facilitated the generation of quick-look performance summaries and comparisons for input to the SSME data reviews conducted immediately after each test, as well as the maintenance of historic statistical profiles. Figure 4, from Wyle TM 64058-01, illustrates a statistical summary of measurements obtained from the oxidizer

preburner pump during 141 test firings and the fuel turbopump flight data as of August 1985. These data represent measurements obtained under nominal engine operating conditions. Separate statistical definition is given for wide-band (composite) levels and the spectral levels at pump shaft speed (synchronous) and selected harmonics. Figure 5 illustrates cumulative and probability distributions characterizing the measurements. The cumulative distribution provides a useful tool for the quick-look assessment of test results with the historical distribution of measurements observed over a number of test firings, and also indicates the statistical risks implied by vibration level redlines.

A plot of the classical gamma distribution is included in these figures for reference, with parameters defined by

$$\Gamma^*(G) = (\lambda^{\alpha} / \Gamma(\alpha))$$

$$\int_0^G x^{\alpha-1} e^{-\lambda x} dx$$

where

$$\lambda = \overline{m}/\overline{\sigma}^2$$

$$\alpha = \overline{m}^2/\overline{\sigma}^2$$

and

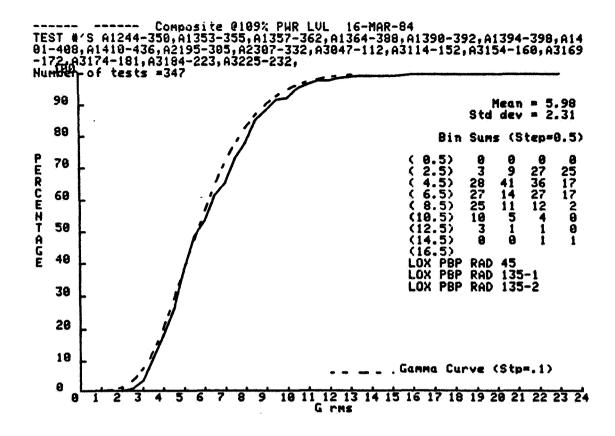
 $\ddot{\sigma}^2$ = sample mean

The application of classical statistical models is desirable for data characterization since this permits continuous statistical definition and manipulation from discrete measurement observations. Automated optimal function definition has also been developed for implementation in the diagnostic data base program. Software has been written to assess a wide class of competing functions including the Weibull, Gumbel and generalized lambda distributions.

	STAT	ISTICAL SUM	MARY OF SSH	VIBRATION	DATA 16-MAR-84				
· LO	X PBP RAI		site @109% LOX PBP RA	Power Leve 0 135-1 Max	LOX PBP RAD 135-2 Max				
Test Stand Te	# G sts res	G Sig rms		Sig rms	# G G Tests rms Sig rms				
	41 6.4	2.8 15.5	47 5.2	2.1 10.5	30 6.3 2.2 13.3				
	44 5.3	2.3 11.9	52 5.3	1.6 10.0	24 5.5 1.9 9.0				
	41 7.2	2.4 15.8	42 7.5	2.0 12.0	26 5.0 1.8 10.0				
Combined 1	26 6.3	2.6 15.5	141 5.9	2.2 12.0	80 5.6 2.0 13.3	1			
1.6	OX PBP RA		hronous @10 LOX PBP RA	9% Power Le	evel LOX PBP RAD 135-2				
Test	* G.	Max	# G	Hax	# G G				
Stand Te	ests rms	Sig rms	Tests rms		Tests rms Sig rms				
A1	48 2.9	1.8 7.6	44 3.2	2.0 8.6	31 3.5 1.9 8.5				
A2	39 2.5	1.6 6.4	45 3.9	1.4 6.8	24 3.3 1.9 6.8				
A3	37 2.5	1.6 7.6	40 2.8	1.5 8.9	24 2.5 1.8 9.1				
TEST #'S	A1244-356	36.A2195-38	。 61357~362 。	1.7 8.9 11364-388,A 183047-112,	79 3.1 1.9 9.1 1390-392,A1394-398, A3114-152,A3154-160,A3				
	UEL PUMP		Selie 8184% FUEL PUMP F		FUEL PUMP RAD 174				
Test	. 5	Mex G	=	Max	# G G				
Stand	ests rms	Sig ras	Tests rms		Tests rms Sig rms				
STS	24 3.0	1.8 5.8		1.9 3.8	18 3.4 1.5 7.3				
	STA	TISTICAL SU	MARY OF SSM	VIBRATION	DATA 23-AUG-85				
ş	FUEL PUMP	RAD 186	FUEL TURB	RAD 98	FUEL TURB AXIAL				
Test Stand	# G	Mex G Sig rms	a G	Mex G Sig rms	# G G Tests rms Sig rms				

STS	27 3.0	1.8 5.2	8 0.9	8.9 8.8					
	EUE: BU	Sy	nchronous 8	184% Power L P RAD 98	evel FUEL PUMP RAD 174				
Test		B Me	× _	XeM	TOEL FOR RAD 174 Tox G G				
Stend	Tests			_	Tests rms Sig rms				
STS	24 2	.7 1.8 4.	7 3 1.	3 1.0 2.3	18 2.6 0.8 3.8				
STATISTICAL SUMMARY OF SSME VIBRATION DATA 23-AUG-85									
Synchronous @184% Power Level FUEL PUMP RAD 186 FUEL TURB RAD 98 FUEL TURB AXIAL									
Test		C C	×	Max	FUEL TURB AXIAL Nox S G G				
Stend			_		Tests cas Sig res				
STS	27 2	2.5 1.6 5.	8 9 9.	9 8.8 9.9	0 0.9 0.0 0.0				
	Figu	ıre 4. Stati	stical Summa	rv of High	Pressure Fuel and				

Figure 4. Statistical Summary of High Pressure Fuel and Oxidizer Pump Measurements for Ground and Flight Tests



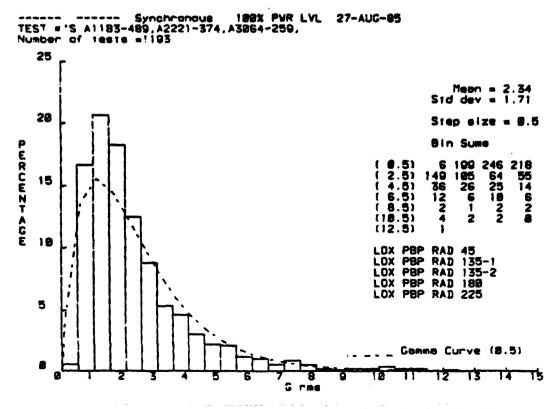
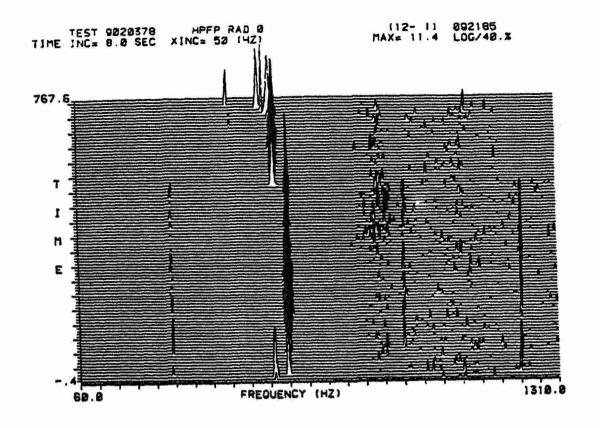


Figure 5. Cumulative and Probability Distribution Plots for a Selected Vibration Data Sample

In addition to the SSME diagnostic data base, the SSME Isospectral Data Base System was applied extensively. Historically, analog tapes were flown to MSFC, dubbed, reduced, and evaluated. Under the new system, spectra are extracted from the tapes every 0.4 second for each measurement throughout each test and stored at NSTL/Slidell. On command, the spectral data is telemetered to MSFC via satellite. Based on MSFC-developed software, these preprocessed data are then manipulated and printed to display isoplots, bandpass trends, engine speed, etc., on user command. As the diagnostic data base system has made test-to-test comparisons more efficient, the SSME isospectral analysis system has been a significant aid in the evaluation of time/amplitude/frequency trends within a test. In addition to the above preprocessed data, analog tapes are also obtained by MSFC for special-purpose time and frequency domain analysis. Modification of the Isospectral data base is under evaluation to include transmission of the Fourier coefficients (amplitude and phase) as well as PSD samples. This will permit immediate access to the vibration time history for detailed analysis, by straightforward inverse transformation.

Figure 6 is an example of an isoplot representing a high pressure fuel turbine measurement throughout test 902-378. A frequency band of 60 Hz to 1310 Hz and 1310 to 2560 Hz was selected and a spectrum plotted every 8 seconds. The displayed amplitude range is selectable, permitting clear representation of major spectral peaks or identification of low level spectral components. Interpretation obviously requires correlation with engine speed and other parameters. Figure 7 illustrates the root-mean-square acceleration time history composite, synchronous and selected harmonics for the same measurement. This time history is synthesized from the stored isospectral data by integrating over the PSDs obtained each 0.4 second during the test.

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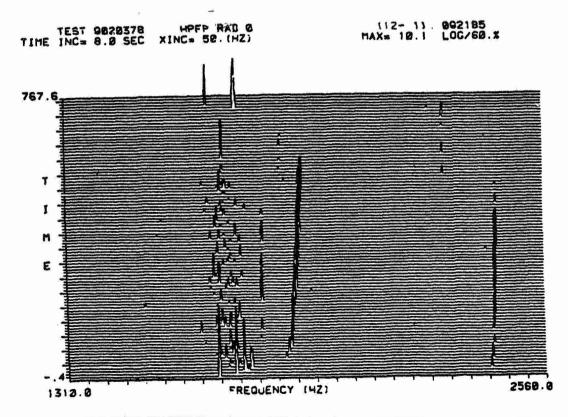


Figure 6. Isoplot of a High Pressure Fuel Turbopump Measurement

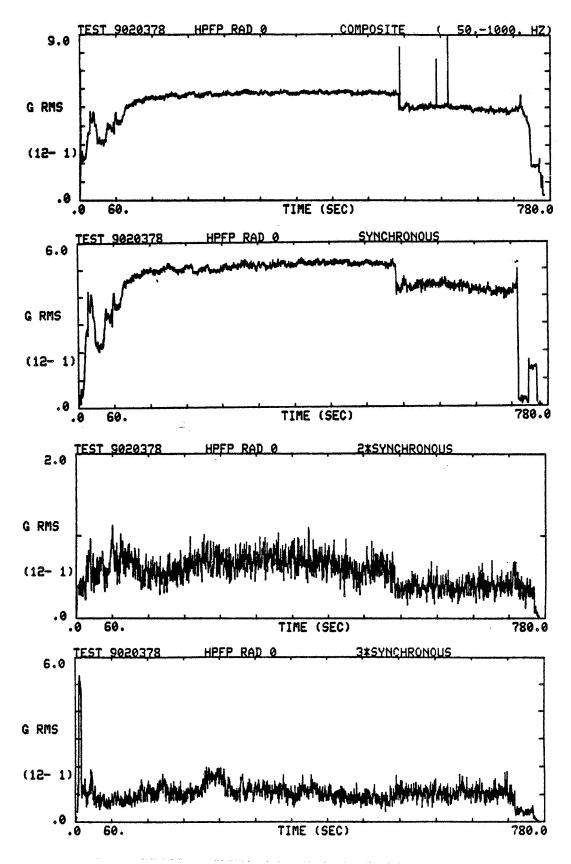


Figure 7. Acceleration Time History of a High Pressure Fuel Pump Measurement and Selected Harmonic Contributions

A sample PSD for the same measurement is illustrated in Figure 8. An "Anomalous Frequency" routine was developed to track spectral components within a selected frequency band and relate these to the synchronous behavior. Figures 9 and 10 illustrate the output of the procedure in the selectable frequency bands of 200-400 Hz and 1700-2000 Hz. Another feature of the Isospectral Data Base Program is the cumulative speed analysis routine. Certain components on the SSME respond more strongly when exposed to a narrow speed range. Software was developed to track and evaluate the total time a particular serial number pump has accumulated in each speed range for a given test or series of tests. An example plot and tabulated values for two recent tests (A1-377 and A1-378) are shown in Figure 11.

2.2.3 Special Considerations in Dynamic Strain Assessment

Wide band strain measurements have generally been characterized in terms of power spectra and rms time histories. In special cases (such as a LOX injector post fatigue evaluation supported under this contract) peak strain distributions were estimated. More refined cycle counting techniques appeared desirable to characterize dynamic strain measurements. A cursory review of the experimental literature on high cycle fatigue was therefore performed.

Miles' classical relation for fatigue under random vibration is based on an assumed distribution of stress or strain peaks. In a complex time history, consideration of adjacent peaks (and valleys) only can mask wide variations (the range) of the dynamic stress or strain incurred. A number of empirical cycle counting techniques have therefore been developed by researchers to better account for the ranges of stresses in a complex wave. When considering that damage has been shown to be roughly proportional to the sixth power of the strain range, importance of cycle counting and range definition techniques is underlined.

The objective of all cycle counting methods is to relate the effect of a complex load, stress or strain time history to material fatigue properties obtained under simple cyclic loading conditions. "Overall range" counting methods have been shown to correlate more highly with observed fatigue life than simple peak value distributions.

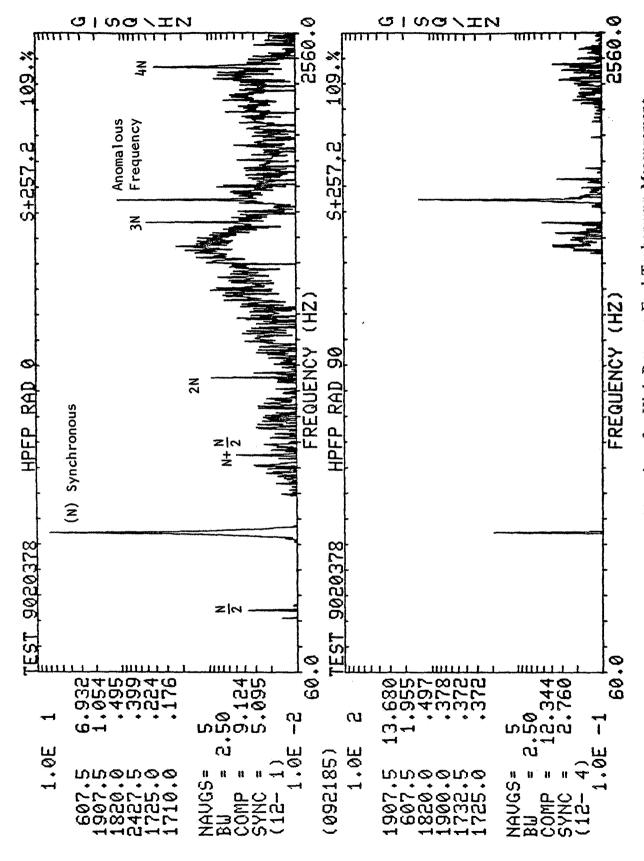


Figure 8. Power Spectral Density of a High Pressure Fuel Turbopump Measurement

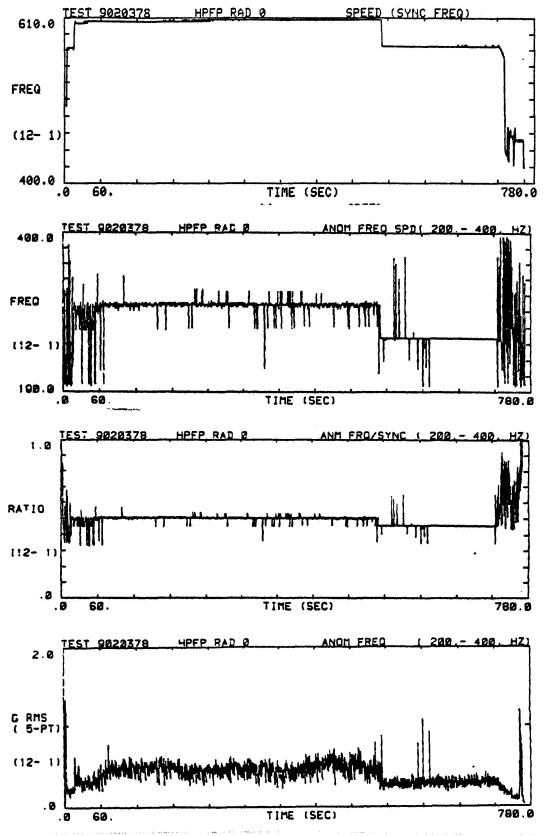


Figure 9. Sample of Anomalous Frequency Routine Output (200-400 Hz)

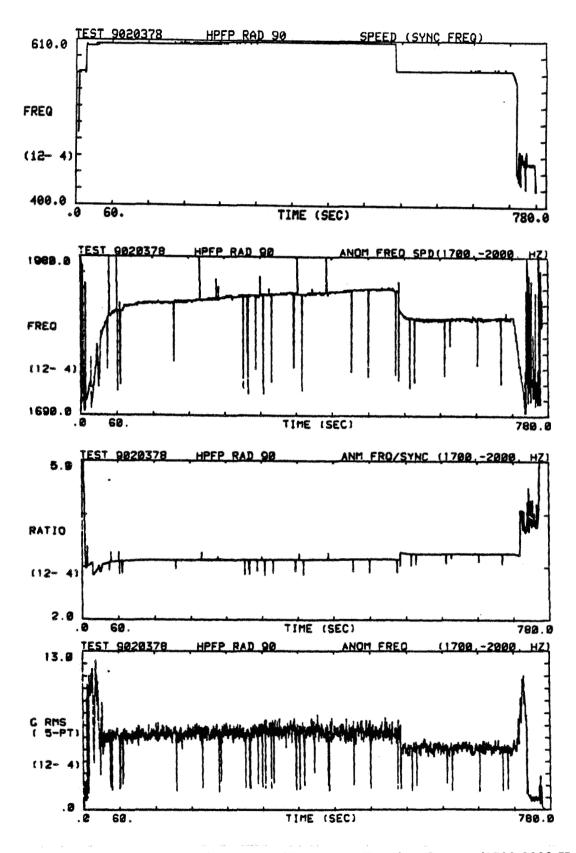
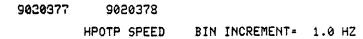


Figure 10. Sample of Anomalous Frequency Routine Output (1700-2000 Hz)



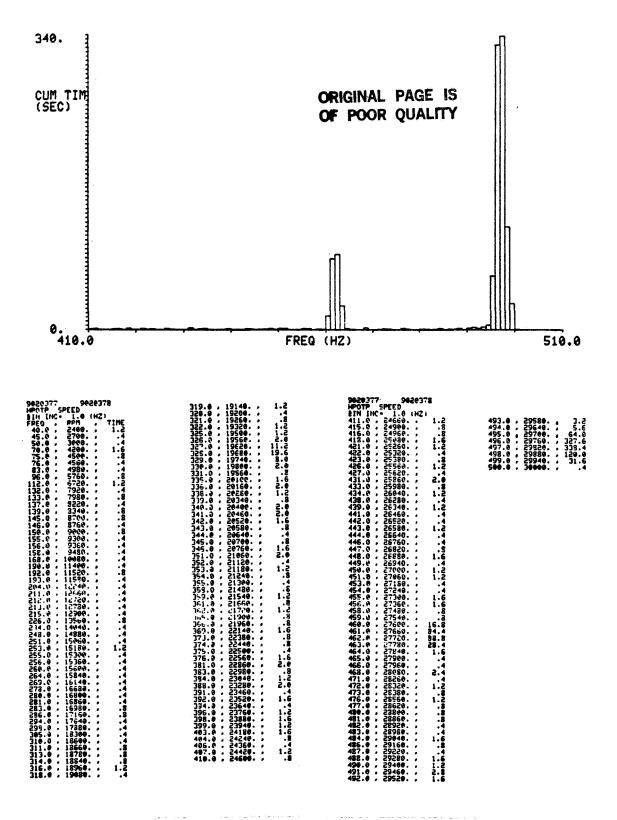


Figure 11. Sample of Cumulative Speed Analysis

Three cycle counting techniques and associated computational algorithms appear most prominent in the literature for fatigue evaluation of complex strain (stress) time histories. These are known as the range-pair, Rainflow (or hysteresis loop closure) and ordered overall range (or racetrack) methods. These three procedures yield Computational schemes for implementation of these virtually identical results. methods were also obtained from the references. These techniques permit significant data compression, in that only major strain excursions need be retained to characterize fatigue growth. The strain ranges generated as above are generally used concurrently with a fatigue analysis. However, the techniques may also be used directly in the data reduction procedure to generate strain range spectra depicting the number of occurrences as a function of strain range (a probability density Statistical definition of strain range spectra per event (such as engine startup) or per unit time (during constant power operation, for example) should constitute a valuable component fatigue life estimation tool.

2.3 Analytical/Statistical Modeling

The above discussion illustrates some capabilities of the SSME data base systems and software. Wyle personnel have made extensive use of this capability to define component test heritage and response characteristics. Numerous dynamic modeling investigations have also been conducted ranging from quick-look failure evaluations to extensive computer simulations of system behavior. As an example of these efforts, we summarize a recent evaluation of the SSME Flight Accelerometer Safety Cut-Off System (FASCOS) logic. Some additional investigations are described in the Appendix.

Certification of the SSME at full power level (109%) is in progress. Implementation of the FASCOS system is an essential element of the certification program. The FASCOS is a vibration based engine condition monitor. The system continuously monitors accelerations measured on the SSME turbopumps during engine operation. Based on these measurements and assigned vibration "redlines," the FASCOS and engine control computer determine the "operational health" of each engine through a series of nonlinear operations on the vibration signals and a voting protocol. The outcome of the decision process (run/cut-off) is highly dependent on the redline values assigned to the FASCOS comparator and the (statistical) behavior of the monitored signals. For this reason an intensive analysis/simulation effort was

recently initiated by MSFC to define the FASCOS decision process as a guide to the assessment of redlines with respect to mission success and safety. Wyle performed analytical modeling and computer simulations in support of this challenging and significant task.

A functional schematic of the FASCOS logic is illustrated in Figure 12. Three accelerometer signals are processed simultaneously to perform the required turbopump operational condition assessment. Major elements of the system are

- A filter/detection stage
- A comparator with time delay
- A voting protocol based on the simultaneous state of the three comparator outputs.

The filter/detection stage is shown in more detail in Figure 13. This circuit consists of:

- Band-pass filter (approximately 50 Hz-1 KHz)
- Square-law detector
- Exponential low-pass filter
- Square-root detector
- Second low-pass filter.

It is seen that this nonlinear sequence of operations transforms the (possibly) wide-band vibration input into a slowly varying "weighted RMS" signal output which is fed to the comparator.

The comparator is essentially a voltage gate with an adjustable threshold level and time delay required to activate the "switch." The threshold level defines the vibration redline which must be exceeded to initiate an output. The time delay precludes a threshold exceedance indication due to spurious noise sources. Transfer characteristics of the FASCOS comparator are illustrated in Figure 14. The output is seen typical of a random telegraph signal. The length of each pulse represents the (random) persistence time (minus delay) of the input signal above the redline threshold level.

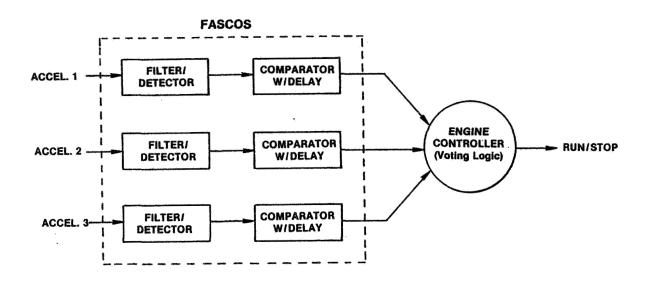


Figure 12. Functional Schematic of the FASCOS

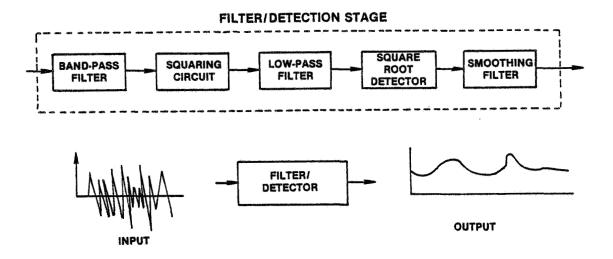


Figure 13. FASCOS Detection Stage and Transfer Characteristic

The controller periodically samples the state of the three comparator outputs and determines whether engine shut-down should be initiated based on a counting procedure. The voting protocol is quite simple. On a given sampling cycle a cut-off vote is registered only if all three controller inputs simultaneously indicate a redline exceedance. Shut-down is initiated only after three such consecutive cycles have been observed; otherwise the voting process is reinitialized. An effort to demonstrate this voting process is illustrated in Figure 15, which indicates a sequence of events leading to a cut-off decision.

The above qualitative description of the FASCOS system indicates a number of key issues to be addressed in system modeling, simulation and performance assessment, including

- Statistical characterization of the class of (random) functions representative of operational vibration signals.
- Modeling of the nonlinear detector output to representative stochastic inputs.
- Derivation of threshold exceedance persistence time probabilities representative of the comparator operation.
- Estimation of joint statistical properties required to model the probability of combined level exceedance as utilized in the controller voting process.

The above list is not exhaustive, but it does underline some significant technical considerations. At the outset, the (band-passed) vibration signals were considered representative of a random sine wave plus independent Gaussian noise process. This model admits a wide range of spectrum shapes and signal-to-noise level, and is yet mathematically tractable. Under this assumption a mathematical description of the filter/detection stage output (power spectrum and covariance function) was derived as a function of input, filter, and averaging characteristics. Limited computer results have demonstrated excellent agreement with empirical simulations performed by MSFC. The definition of threshold exceedance time persistance probabilities, to model the comparator output, represents a formidable theoretical problem. Several approximate formulations, however, have been implemented for evaluation. These are called the Rice method, the method of non-correlated pulses and the quadratic approximation method. (See "Non-Linear Transformations of Stochastic Processes."

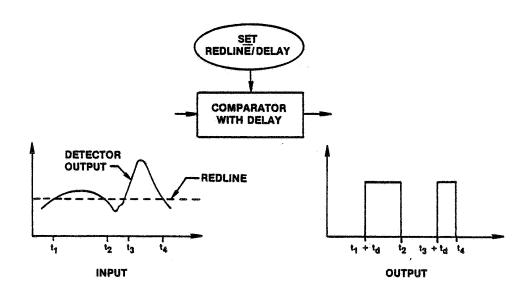


Figure 14. FASCOS Comparator Transfer Characteristics

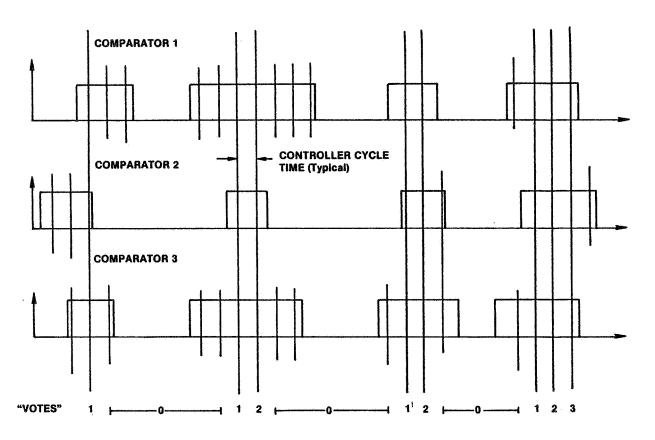


Figure 15. Illustration of FASCOS/Controller Voting Logic

by Tikhonov and Amiartov [RSIC No. QA273], for a comparison of these techniques and enabling assumptions.) Persistence time probability density estimates obtained by these approximations are illustrated in Figure 16, for an idealized white noise plus sine wave input. The curves represent the persistence time distribution of the detected mean-square above a three sigma threshold from the average output. Basic assumptions employed in all three approximations render them most valid for high threshold-to-mean values and short time periods. A theoretical extension of the Rice method was developed to relax these constraints. With regards to the final issue above, the estimation of joint properties between vibration signals appears best approached through empirical simulation. In the absence of such information, however, bounds on system behavior may be obtained by assuming joint properties (total statistical dependence/independence between monitored signals, for example).

By the above approach, a computer program was developed to define the probability of engine cut-off as a function of assigned redline values, turbopump vibration characteristics and FASCOS logic operation. Computer analyses were performed with the above model, based on vibration characteristics provided by MSFC, to estimate engine cut-off probabilities as a function of redline values. Finally, the program was installed on the MASSCOMP processor at the MSFC Systems Dynamics Laboratory. SDL personnel were provided computer program orientation at the conclusion of this task to permit FASCOS parameter evaluations by MSFC. A program listing of this analytical model is included at the end of this section.

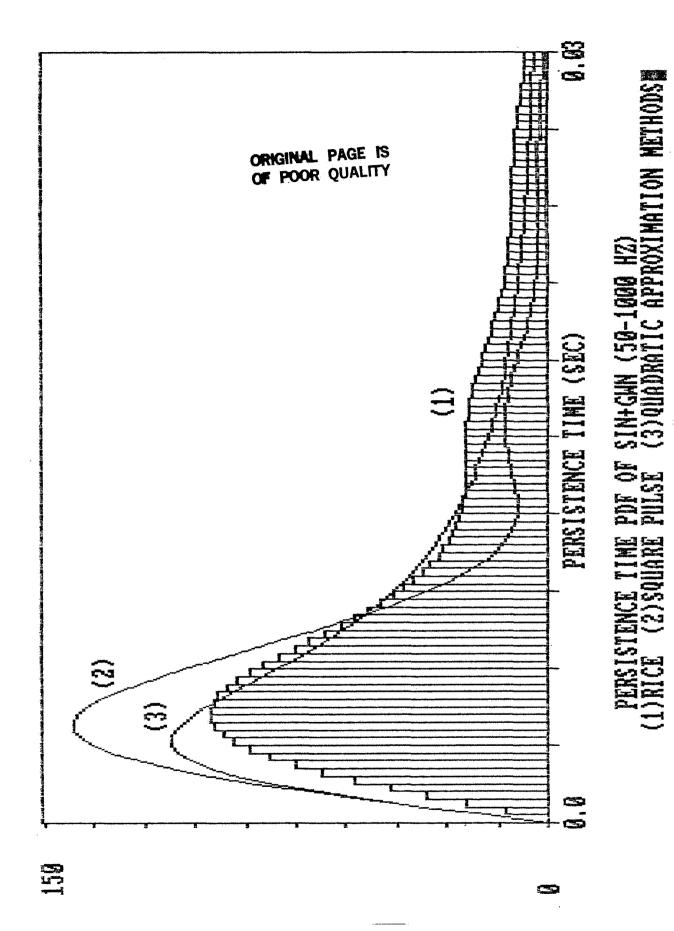


Figure 16. Three Approximations of the Persistence Time Distribution

2.4 Concluding Remarks

This report provides a cursory overview of study objectives and approaches applied by Wyle in the performance of Contract NAS8-33508. As a test/evaluation program, rigid, long term task planning was neither feasible nor desirable. On the contrary, most tasks performed under this contract were initiated on an ad hoc basis, motivated by observed or suspected SSME component failure modes. Continued coordination with the MSFC COTR was therefore maintained to revise task priorities based on SSME test results. Consistent with stringent SSME test schedules, evaluation results were immediately provided the COTR in the form of presentations and informal data packages. A detailed chronology of these evaluations is given in the technical progress reports provided under this contract. To illustrate the diversity of tasks accomplished under this contract, some topics recently investigated by Wyle in support of SSME dynamic evaluations are summarized in Table I at the end of this section. Several representative evaluations performed under this contract are described in the Appendices.

TABLE I. SOME TOPICS RECENTLY INVESTIGATED IN SUPPORT OF SSME DYNAMIC EVALUATIONS

- Pseudoharmonic Study. Performed nonlinear coherence analysis to indicate whether "apparent" harmonics were correlated with synchronous response.
- Pump configuration analysis. Applied linear discrimination analysis to pump measurements to assess statistical difference between design configurations.
- Trimodal density investigation. Performed analysis and simulations to determine time series characteristics yielding three mode probability densities observed in turbopump measurements.
- Source location investigation. Developed and applied analysis to estimate apparent source location based on geometry, wave speed and crosscorrelation measurements.
- FPB oxidizer, ASI line accelerometer and strain gauge evaluation.
- MMC inlet manifold elbow strain gauge analysis for strength calculations.
- Developed algorithm for computer data band program:
 - Computer selection of PSD time slices
 - Cumulative distribution
 - Amplitude indian belt format
- Analysis of internally instrumented pump:
- Transfer functions
 - Evaluation of ballpass frequencies
 - Calculation of contact angle from measured data
- Whirl study. This required compilation of a complete history of the pumps,
 by serial number, response characteristics, and time of occurrence.
- Rubbing model investigation. Statistical moments were derived for random sine wave plus noise processes with asymmetric clipping for comparison with observed turbopump measurements.
- STS-8. Investigation of ASI line malfunction required analysis of previous

test data to determine whether the phenomenon could be detected on the high pressure pumps during ground test firings.

- Calculation of ball train frequency for high-speed ball bearing. An attempt was made to modify frequency equations to include the effect of varying ball size within a single bearing.
- High synchronous study. Evaluated maximum/minimum amplitudes by pump and component serial number to define statistical changes in response levels.
- Developed relationships for data extrapolation as a function of engine power level.
- Cumulative distribution of HPOT. Fit data to normal, Rayleigh and gamma distributions. Gamma was found to be best fit to empirical observations.
- Modulation investigation. The thrust was to determine the time functions that produce certain side-band frequencies which often appear in the data and are usually considered noise. A next step would be to evaluate the physical functions that produce such time histories.

Results of the above investigations have been provided MSFC through technical progress reports, informal data packages and presentations.

FASCOS PROGRAM LISTING

Page 1 02-13-85 08:52:33

```
D Line# 1
                                                   Microsoft FORTRAN77 V3.20 02/84
      1 C
              LINK FASCOS+FFTSUB+FFT842
      2 0
              OUTPUT PSD IS ODE-SIDE PSD OF X5
      3
              DIMENSION BBWW(2)
      4
              CHARACTER*16 FPSD5, FCOR5, F1TO5
      5
              COMMON WTR(4096), WTI(4096), XR(4096), XI(4096), S(4100)
      6
              INTEGER TTI, TTO
      7
              DOUBLE PRECISION NF2. NF3. NF4
      8
              WRITE(*,'(A)')' ENTER VARIANCE OF X1(T) AFTER BANDPASS FILTER'
      9
              READ(*,*)VVV
     10 C
              WRITE(*,'(A)')' ENTER 1 FOR RC AVERAGE FILTER'
     11 C
              READ(*,*)IFRC
              WRITE(*,'(A)')' ENTER 1 FOR ANALOG RC FILTER: 2 FOR DIGITAL RC'
     12 C
     13 C
              READ(*, *) IFAD
     14
              IFAD=2
     15
              IF (IFAD. NE. 1) THEN
     16
              WRITE(*,'(A)')' ENTER MAX FREQ (HZ) ( ENTER SAMPLING FREQ )'
     17
              READ (*, *) FS
              ENDIF
     18
              WRITE(*,'(A)')' ENTER # OF DATA IN OUTPUT PSD NN ( LE 4096)'
     19
     20
              WRITE(*,'(A)')' NOTE: THIS IS UPTO FS (SAMPLING FREQ)'
     21
              WRITE(*,'(A)')'
                                     OUTPUT PSD OF X5 HAS NN/2 DATA UPTO FS/2'
     22
              READ(*,*)NN
     23
              WRITE(*,'(A)')' ENTER FREQUENCY OF SIN WAVE'
     24
               READ(*, *) FSIN
              WRITE(*,'(A)')' ENTER FREQ F1 & F2 OF FASCOS FILTER'
     25
     26
              READ(*,*)F1,F2
              WRITE(*.'(A)')' ENTER AVERAGE TIME IN SEC( =2*RC)'
     27
     28
              READ(*, *)T
     29
              WRITE(*,'(A)')' ENTER SIGNAL TO NOISE RATIO (NASA DEFINITION)'
     30
               READ(*, *)ET
              ET=ET*ET/(1-ET*ET)
     31
              WRITE(*.'(A)')' ENTER CUTOFF FREQ IN POST-RIPPLE FILTER'
     32
              READ(*, *)FC
     33
     34
              WRITE(*,'(A)')' ENTER ORDER OF BUTTERWORTH FILTER'
     35
              READ(*, *) NORDER
              WRITE(*,'(A)')' ENTER 1 FO ANALOG; 2 FOR DIGITAL BUTTERWORTH'
     36
     37
               READ(*, *) IFBW
              WRITE(*,'(A)')' ENTER MAX TIME LAG OF OUTPUT R(T) IN SEC'
     38
     39
               READ(*, *) TMAX
     40
              WRITE(*.'(A)')' ENTER # OF DATA OF OUTPUT R(T) NOUT'
     41
              WRITE(*,'(A)')' NOTE: NN/2+NOUT MUST LE. 4096'
     42
              READ(*, *) NOUT
              WRITE(*,'(A)')' ENTER OUTPUT FILNAM OF PSD OF X5'
     43
     44
               READ(*,'(A)')FPSD5
     45
              WRITE(*,'(A)')' ENTER OUTPUT FILNAM OF R(T), R"(T) & R'(T)'
              READ(*,'(A)')FCOR5
     46
              WRITE(*,'(A)')' ENTER OUTPUT FILNAM AVE & DEV OF X1 TO X5'
     47
     48
               READ(*,'(A)')F1T05
     49
              WRITE(*,'(A)')' ENTER 1 FOR SETTING S(0)=0.'
     50
               READ(*, *) IFSO
     51
              OPEN(2, FILE=FPSD5, STATUS='NEW')
     52
              OPEN(6, FILE=F1TO5, STATUS='NEW')
     53 C
              ********************************
     54
               PI=3.141592653
     55
              NIN=NN/2
     56
               IFRC=1
     57
              FMAX=FS/2.
     58
              DT=1/FS
     59
              RC=T/2.
```

Microsoft FORTRAN77 V3.20 02/84 7 D Line# 1 60 ARC=EXP(-DT/RC) 61 A1RC=(1-ARC)**2 A2RC=1+ARC*ARC 62 63 C2=2*PI*DT C1=2*PI*RC 64 ORIGINAL PAGE IS 65 BW=F2-F1 OF POOR QUALITY DF=FS/(NN-1) 66 67 NNMAX=2*F2/DF 68 FF1=2*F1 69 FF2=BW 70 FF3=BW+FF1 71 FF4=FF3+FF2 72 NF1 = (FF1/DF) + 173 NF2=FF2/DF+1 74 NF3=FF3/DF+1 75 NF4=FF4/DF+1 76 A=VVV*0.5/(BW*(1+ET)) 77 VAR1=2*BW*A 78 A2=A*A 79 T2A2=2*A2 80 T4A2=4*A2 81 S1=-1*T4A2 82 S2=S1/2. 83 S3=-S2 84 S4=S2 85 B1=T4A2*BW 86 B2=T4A2*(BW-2*F1) 87 B3=B2/2. 88 B4=B1/2. 89 NL2=NF2 90 NL3=NF3 91 NL4=NF4 92 C *** 93 IF (NF1. GT. NN) NF1=NN 94 DO 11 I=1, NF1 95 IF (I.GE.NN+1) GOTO 20 96 S(I) = B1 + S1 * (I-1) * DF1 97 11 CONTINUE · 98 IF(NF2.GT.10000) GOTO 20 99 NL2=NF2 100 DO 12 I=NF1+1, NL2 IF (I.GE. NN+1) GOTO 20 1 101 S(I) = B2 + S2 * ((I-1) * DF - 2 * F1)102 1 103 12 CONTINUE 104 IF(NF3.GT.10000) GOTO 20 105 NL3=NF3 106 DO 13 I=NL2+1, NL3 107 IF (I. GE. NN+1) GOTO 20 1 108 S(I) = B3 + S3 * ((I-1) * DF - BW)1 109 13 CONTINUE IF (NF4.6T.10000) GOTO 20 110 111 NL4=NF4 112 DO 14 I=NL3+1, NL4 113 IF (I.GE. NN+1) GOTO 20 1. 114 S(I)=B4+S4*((I-1)*DF-BW-2*F1) 1 115 14 CONTINUE +1 1.16 DO 15 I=NL4+1, NN 117 IF (I.GE. NN+1) GOTO 20 1

118

S(I)=0.

```
Microsoft FORTRAN77 V3.20 02/84
D Line# 1
               7
    119 15
               CONTINUE
1
    120 20
               CONTINUE
    121
               DO 21 I=1, NN
    122
                IF (I.GT.NL4) GOTO 21
1
1
    123
                W=(I-1.)*DF
                IF (W. LT. (F2-FSIN) ) THEN
1
    124
                S(I)=S(I)+8*BW*ET*A2*(
    125
1
1
    126
                ELSE
1
    127
               IF(W.LT.(FSIN-F1).OR.(W.GT.(F1+FSIN).AND.W.LT.(F2+FSIN)))THEN
1
    128
                 S(I)=S(I)+4*BW*ET*A2
    129
1
                 ELSE
    130
                 S(I)=S(I)
1
    131
                 ENDIF
1
1
    132
                ENDIF
    133 21
               CONTINUE
    134
               NC=2*FSIN/DF+1
    135
               S(NC) = (A*BW*ET)**2+S(NC)
    136 C
               WRITE(1,*)(S(I), I=1, NN)
    137
               VRV=S(1)
    138
               IF (IFSO. EQ. 1) VRV=0.
    139
               DO 478 I=2.NN
1
    140
               VRV=VRV+S(I)
    141 478
1
               CONTINUE
    142
               VRV=VRV*2*DF
    143
                SMO=5(1)
    144
                IF (IFSO. EQ. 1) SMO=0.
    145
                F=0
    146
              IF (IFRC. EQ. 1) THEN
    147
                DO 222 I=2,NN
               F=F+DF
    148
1
                  IF (IFAD. NE. 1) THEN
1
    149
    150
                    S(I)=S(I)*A1RC/(A2RC-2*ARC*COS(C2*F))
1
    151
1
                   FLSE
1
    152
                    S(I)=S(I)/(1+(C1*F)**2)
1
    153
                   ENDIF
               SMO=SMO+S(I)
    154 222
1
    155
               ELSE
    156
               DO 22 I=2,NN
    157
                F=F+DF
1
                Q=PI*T*F
1
    158
1
    159
                S(I) = S(I) * ((SIN(Q)/Q) * * 2)
1
    160
                SMO=SMO+S(I)
    161 22
1
                CONTINUE
    162
               ENDIF
               SMO=SMO*2*DF
    163
    164
               AAA=2*A*BW*(1+ET)
               AA4=SGRT(0.5*SGRT(4*AAA*AAA-2*SMO))
    165
     166
               SM4=AAA-AA4*AA4
    167
               DEV1=SQRT(VVV)
               WRITE (*, 121) ZO, VVV, DEV1
    168
    169
               DEV2=SQRT(VRV)
    170
               WRITE (*, 122) VVV, VRV, DEV2
    171
               DEV3=SQRT (SMO)
               WRITE (*, 123) AAA, SMO, DEV3
     172
     173
               DEV4=SQRT (SM4)
               WRITE (*, 124) AA4, SM4, DEV4
     174
     175
               WRITE (6, *) ZO, DEV1
                WRITE(6, *) VVV, DEV2
     176
     177
                WRITE (6, *) AAA, DEV3
```

```
Microsoft FORTRAN77 V3.20 02/84
D Line# 1
    178
              WRITE (6, *) AA4, DEV4
              FORMAT(' AVE1= ', E16.8,' VAR1= ', E16.8,' DEV1= ', E16.8)
    179 121
              FORMAT(' AVE2= ', E16.8,' VAR2= ', E16.8,' DEV2= ', E16.8)
    180 122
              FORMAT(' AVE3= ',E16.8,' VAR3= ',E16.8,' DEV3= ',E16.8)
    181 123
              FORMAT(' AVE4= ', E16.8,' VAR4= ', E16.8,' DEV4= ', E16.8)
    182 124
              FORMAT(' AVE5= ',E16.8,' VAR5= ',E16.8,' DEV5= ',E16.8)
    183 126
    184
              NFFT=NN
    185
              A4=AA4
    186
              NNP2=NFFT+2
    187
              NNPSS=NNPS\S
    188
              A45=A4*A4
    189
              A4F=A45*A45
                                                 ORIGINAL PAGE IS
    190
              bis=5*bi
                                                 OF POOR QUALITY
    191
              TIME=NFFT/FS
    192
              DF=FS/NFFT
    193
              DT=1/FS
    194
              DT2=DT*2
    195
              DF2=DF*2
    196
              IF(IFSO.EQ.1)S(1)=0.
    197
              CALL FFT(S, NNP2, 1)
    198
              DO 601 I=1, NNP22
    199 601
              S(I)=S(2*I-1)*NFFT
1
    200
              DO 602 I=1, NNP22-2
1
    201 602
              S(NNP22+I)=S(NNP22-I)
    202
              S(NFFT+1)=0.
    203
              S(NFFT+2)=0.
              DO 3 I=1, NFFT
    204
    205
              S(I)=DF2*S(I)
1
    206 3
              CONTINUE
              ***** CALCULATE R4(T) FROM R3(T) *******
    207 C
    208
              R30=S(1)
    209
              DO 66 I=1, NFFT
              S(I) = -A4S + 0.5 * SQRT(4 * A4F + 2 * S(I))
    210
1
1
    211 66
              CONTINUE
             R40=S(1)
    212
    213 125
              FORMAT(' R3(0) = 'E16.8,' R4(0) = '.E16.8)
              CALL FFT(S, NNP2, 1)
    214
    215
              DO 606 I=1,NNP22
    216 606
              S(I)=S(2*I-1)*NFFT
1
              DO 607 I=1, NNP22-2
    217
    218 607
              S(NNP22+I)=S(NNP22-I)
    219
              DO 4 I=1, NNMAX
    220 4
              S(I)=S(I)*DT2
1
    221
              S(1)=S(1)/2.
    222
              DO 224 I=NNMAX+1, NFFT
    223 224
1
              S(I)=0.
              WRITE(11,*)(S(1), I=1, NFFT/2) ***** PSD OF X4 ********
    224 C
              CALL POSTR (S, NFFT/2, FC, NORDER, DF, VAR5, FS, IFBW)
    225
    226
              DEV5=SQRT (VAR5)
              WRITE (*, 126) AA4, VAR5, DEV5
    227
              WRITE (6, *) AA4, DEV5
    228
    229
              WRITE(2,*)(S(I), I=1, NIN)
    230 C**************
    231
              FSEQ=1.0
    232
              SIGO=1
              SIGO=FSEQ*ALOG(SIGO)
    233
    234
              DLTSIG=1
    235
              DLTSIG=FSEQ*ALOG(DLTSIG)
    236
              OMEO=O.
```

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```
Microsoft FORTRAN77 V3.20 02/84
D Line# 1
              DLTOMG=FMAX*TMAX/(NIN*NOUT)
    237
    238
              DF=FMAX/(NIN-1)
    239
              DT=TMAX/NOUT
    240
              DF2=DF*2
              PI=4.0*ATAN(1.0)
    241
    242
              PI2=PI*2.
    243
              DFPI2=DF*PI2
    244 ************************
                                ENTER STARTING FREQ IN HZ'
    245 C
              WRITE(*,'(A)')'
    246 C
              READ(*, *) OMEO
              WRITE(*,'(A)')'
                                ENTER ENDING FREQ IN HZ'
    247 C
    248 C
              READ(*, *) FEND
    249 C
              DLTOMG=(FEND-OMEO)/(NOUT-1.)
    250
               OPEN(12, FILE=FCOR5, STATUS='NEW')
    251 C***********************
              NFFT=NIN+NOUT
    252
    253
              DO 30 I=1,12
    254
              NTEST=2**I
1
    255
1
              IF (NTEST. GE. NFFT) GOTO 40
    256 30
              CONTINUE
    257
              WRITE(*,'(A)')' N TOO BIG FOR FFT'
    258
              STOP
    259 40
              NFFT=NTEST
    260 C*********************
    261
               IF (IFSO. EQ. 1) S(1) = 0.
    262
                DO 82 IL=1.NIN
    263
              S(IL)=S(IL)/2.
1
              XR(IL)=S(IL)
1
    264
    265 82
              CONTINUE
              WRITE(*,'(A)')' BEFORE R(T)'
    266 C
    267 C********************** R(T) ********************
    268
              CALL ZERO(XI, NFFT)
    269
              CALL CZT(XR, XI, NIN, NOUT, DLTSIG, DLTOMG, WTR, WTI, SIGO, OMEO,
    270
             1 O.NFFT.FSEQ)
              WRITE(*,'(A)')' FINISH R(T)'
    271 C
    272
              DO 51 I=1, NOUT
    273 51
              XR(I) = XR(I) *DF2
1
    274
              EEE=XR(NOUT) *1.02
    275
              DO 301 I=1, NOUT
    276
              IF (XR(I).LE.EEE) GOTO 302
1
    277 301
1
              CONTINUE
    278 302
              K=0
    279
              BBB=10./(NOUT-I)
              DO 303 J=I,NOUT
    280
1
    281
              K=K+1
Ť
    282
              XR(J) = XR(J) *EXP(-BBB*K)
1
    283 303
              CONTINUE
              WRITE(12, *) (DBLE(XR(I)), I=1, NOUT)
    284
    285 C**************************** R"(T) ***********************
    286
              FF=-DFPI2
              DO 502 I=1, NIN
    287
    288
              FF=FF+DFPI2
1
    289 502
              XR(I)=S(I)*FF*FF
*
              DO 5022 I=NIN+1, NFFT
    290
    291 5022
              XR(I)=0.
              CALL ZERO(XI, NFFT)
    292
    293
              CALL CZT(XR, XI, NIN, NOUT, DLTSIG, DLTOMG, WTR, WTI, SIGO, DMEO,
    294
             1 O, NFFT, FSEQ)
              DO 52 I=1, NOUT
    295
```

```
D Line# 1
                                               Microsoft FORTRAN77 V3.20 02/84
   296 52
             XR(I) = -DF2 * XR(I)
    297
             WRITE(12,*)(DBLE(XR(I)), I=1, NOUT)
    298
             RTTO=-XR(1)
    299
             WRITE (*, 127) RTTO
    300
             WRITE(6, *) RTTO
    301 127
             FORMAT(' VARIANCE OF SLOPE OF RMS TIME SERIES=-R"(0) = ',E16.8)
    302
             WRITE(*,'(A)')' N* = EXPECT # OF UPCROSSING OF R IN TIME T'
             WRITE(*,'(A)')' TBAR= EXPECT PERSISTENCE TIME OF REDLINE R'
   303
    304
             UP=SQRT(RTTO)/(PI2*DEV5)
    305
             UPI=1./UP
    306
            WRITE(*.128)UP
    307
             WRITE(*, 129) UPI
    308 128
             FORMAT(' N* = ', F15.8, ' * T * EXP(-0.5*R**2)')
    309 129
             FORMAT(' TBAR = ',F15.8,' * EXP(0.5*R**2) * ERR(R)')
    310
             WRITE(*,'(A)')' ERR(R) = Pr( X GREATER THEN R ) X IS UNIT NORMAL'
    311 C
             WRITE(*,'(A)')' FINISH R"(T)'
    FF=-DFPI2
    313
    314
             DO 503 I=1.NIN
1
    315
             FF=FF+DFPI2
    316 503
1
             XR(I)=S(I)*FF
    317
             DO 5033 I=NIN+1.NFFT
    318 5033 XR(I)=0.
    319
             CALL ZERO(XI, NFFT)
    320
             CALL CZT(XR, XI, NIN, NOUT, DLTSIG, DLTOMG, WTR, WTI, SIGO, OMEO,
    321
            1 O, NFFT, FSEQ)
    322
             DO 53 I=1, NOUT
    323 53
             XR(I) = DF2 * XI(I)
1
    324
             WRITE(12, *) (DBLE(XR(I)), I=1, NOUT)
            WRITE(*.'(A)')' FINISH R'(T)'
    326 C******************** R""(0) *********************
    327
             R40=0.
    328
             FF=-DFPI2
    329
             DO 504 I=1,NIN
    330
             FF=FF+DFPI2
1
1
    331
             XR(I)=S(I)*FF**4
    332 504
             R40=R40+XR(I)
    333
             R40=R40*DF2
    334
             WRITE(12, *) DBLE(R40)
    336
             CLOSE(2)
    337
             STOP
             END
    338
Name
                   Offset P Class
       Type
      REAL
                      218
AIRC
      REAL
                      146
A2
      REAL
                      225
A2RC
      REAL
                      150
A4
      REAL
                      636
A4F
      REAL
                      652
A45
      REAL
                      648
AA4
      REAL
                      350
AAA
      REAL
                      346
                            INTRINSIC
ALOG
ARC
      REAL
                      142
ATAN
                            INTRINSIC
B1
      REAL
                      254
```

II-35

```
Microsoft FORTRAN77 V3.20 02/84
D Line# 1
               PROGRAM PSTAR.FOR---- 3 STEP MEMORY MARKOV MODELLING OF P.T.
      1 C
      2
               IMPLICIT REAL*8 (A-H, 0-Z)
               REAL*8 A0(50), A1(50), V0(300), PV0(300), PSTAR(20), QSTAR(20)
     *3
      4
               REAL*8 SM(3.3), TM(3), RM(3), SMI(3.3), TP(3), REDV(10)
      5
               DIMENSION L3(3), M3(3)
               REAL*8 MU(20), DEL(20, 20), ERR(1005)
      6
      7
               CHARACTER*16 F1, F2, FRED, FOUT
      8
               COMMON PIZ.ERR
      9
               KK=3
     10
               WRITE(*,'(A)')' ENTER # OF REDLIN'
     11
               READ (*, *) NRED
     12
               IF (NRED. EQ. 1) THEN
     /13
               WRITE(*,'(A)')' ENTER REDLINE ( ? DEV )'
     14
               READ(*, *) REDV(1)
     15
               ELSE
               WRITE(*,'(A)')' ENTER FILNAM OF REDLIN'
     16
     17
               READ(*,'(A)')FRED
               OPEN(11, FILE=FRED, STATUS='OLD')
     18
     19
               READ(11, *)(REDV(I), I=1, NRED)
     20
               CLOSE (11)
     21
               ENDIF
               WRITE (*, '(A)')' ENTER INPUT R(T), R'(T) FILNAM'
     22
               READ(*,'(A)')F1
     23
               WRITE(*,'(A)')' ENTER OUTPUT INFOMATION FILNAM'
     24
               READ(*,'(A)')F2
     25
               WRITE(*.'(A)')' ENTER OUTPUT FILNAM OF PSTAR'
     26
     27
               READ(*.'(A)')FOUT
               WRITE(*,'(A)')' ENTER ORDER OF RICE THEORY=NN (NOT INCLUDE XO)'
     28
     29
               READ(*, *)NN
               WRITE(*,'(A)')' ENTER # OF DATA IN ERROR FUNCTION'
     30
     31
               READ(*, *) NERR
               WRITE (*, '(A)')' ENTER # OF VO'
     32
     33
               READ(*, *)NVO
               WRITE(*,'(A)')' ENTER MAX VALUE OF VO ( ? DEV(VO) )'
     34
     35
               READ(*, *) VOMAX
               WRITE(*,'(A)')' ENTER # OF X'
     36
     37
               READ(*, *)NX
     3A
               NXS=NX*S
     39
               WRITE(*,'(A)')' ENTER MAX VALUE OF X ( ? DEV(X) )'
     40
               READ(*, *) XMAX
               WRITE(*,'(A)')' ENTER 1 FOR PRINTING INNER LOOP PARAMETERS'
     41
     42
               READ(*, *) INNER
     43
               CALL SERR (ERR, NERR)
     44
               OPEN(6, FILE=F2, STATUS='NEW')
     45
               WRITE(6,'(A)')' PROGRAM JEN3'
               WRITE(6,501)KK
     46
     47
               WRITE (6, 502) NERR
     48
               WRITE (6, 503) NN
     49
               WRITE (6, 504) NVO
     50
               WRITE (6, 505) VOMAX
               WRITE (6, 506) NX
     51
               WRITE (6, 507) XMAX
     52
     53 501
               FORMAT (' MEMORY STEP = ', I2)
               FORMAT(' # OF DATA IN ERROR FUNCTION = ', 16)
     54 502
     55 503
               FORMAT(' ORDER OF RICE THEORY = ', 13)
               FORMAT(' # OF INITIAL SLOPE VO = ', I5)
     56 504
     57 505
               FORMAT(' MAX VALUE OF VO = ', F8.4,'
                                                       DEV(VO)1)
               FORMAT(' # OF X = ', I4)
     58 506
               FORMAT(' MAX VALUE OF X = ',F8.4,'
     59 507
                                                       DEV(X))
```

```
D Line# 1
                                                    Microsoft FORTRAN77 V3.20 02/84
     60
               OPEN(1.FILE=F1.STATUS='OLD')
     61
               OPEN (2, FILE=FOUT, STATUS=' NEW')
               READ(1,*)(AO(I), I=0, NN)
     62
     63
               READ(1, *)(A1(I), I=0, NN)
     64
               VARV=A1(0)
                                                         ORIGINAL PAGE IS
     65
                PI=4. DO*DATAN(1. DO)
                                                         OF POOR QUALITY
                PI2=PI*2
     66
     67
                DVO=VOMAX*DSGRT (VARV) /NVO
     6A
                AREA=O.
     69
                DO 1 I=1.NVO
1
     70
                VO(I) = I * DVO
     71
1
                PVO(I)=DEXP(-0.5*VO(I)*VO(I)/VARV)*VO(I)
     72
                AREA=AREA+PVO(I)
1
1
     73 1
                CONTINUE
     74
                DO 2 I=1.NVO
     75 2
                PVO(I)=PVO(I)/AREA
1
     76
                WRITE(*, *) (PVO(I), I=1, NVO)
     77
               DO 3 I=1.NN
1
     78
               DO 3 J=1, NN
2
     79
               DEL(I, J) = AO(IABS(I-J)) - AO(I) * AO(J) - A1(I) * A1(J) / VARV
     80 3
Э
               CONTINUE
     81 C
               DO 1000 NOPQ=1, NRED
     82
1
     83
               CALL DZERO (PSTAR, NN)
     84
               CALL DZERO (QSTAR, NN)
1
4
     85
               RED=REDV(NOPQ)
1
     86
               WRITE (6, *) *
1
     87
               WRITE (6, *) *
1
     88
               IF (INNER, EQ. 1) THEN
4
     PA
               WRITE(6, *) *
1
     90
               WRITE(6, *) '
     91
               WRITE (6, *)
     92
               WRITE (6, *) "
1
               WRITE (6, *) '
1
     93
1
     94
               WRITE (6. *)
     95
1
               ENDIF
     96
               WRITE (6, 606) RED
1
     97
1
               WRITE (*, 606) RED
     98 606
               FORMAT(1X, ************* REDLINE=*, F8.4, * *****************)
     1
               DO 9999 MM=KK+1, NN
1
    100
2
    101
               \Xi
    102
               IF(INNER.EQ.1)WRITE(6,'(A)')' *******************************
2
    103
                BM=DEL (MM, MM)
2
    104
                DO 9991 I=1,KK
3
    105
                TM(I) = DEL(MM, MM-I)
3
    106
                DO 9991 J=1,KK
    107 9991
4
                SM(I,J) = DEL(MM-I,MM-J)
\Xi
    108
                CALL EQUAL3 (SM, SMI, KK)
2
    109
                CALL DMINV(SMI, KK, DTM, L3, M3)
Ξ
    110
                CALL DGMPRD (TM, SMI, TP, 1, KK, KK)
Ξ
    111
                VZM=BM-TP(1)*TM(1)-TP(2)*TM(2)-TP(3)*TM(3)
2
    112
                DZM=DSQRT(VZM)
2
    113
                DEVX1=DSQRT(SM(1,1))
2
    114
                DEVX2=DSQRT(SM(2,2))
                DEVX3=DSQRT(SM(3,3))
\equiv
    115
2
    116
                COR12=SM(1,2)/(DEVX1*DEVX2)
2
    117
                COR13=SM(1,3)/(DEVX1*DEVX3)
2
    118
                COR23=SM(2,3)/(DEVX2*DEVX3)
```

```
7
                                                       Microsoft FORTRAN77 V3.20 02/84
D Line# 1
                CORR=1-COR*COR
Ξ
    119
2
    120
               DX1=XMAX*DEVX1/NX
\Xi
    121
               DX2=XMAX*DEVX2/NX
2
    122
               DX3=XMAX*DEVX3/NX
               QO=DX1*DX2*DX3/(PI2**1.5*DSQRT(DABS(DTM)))
2
    123
\geq
    124
                IF (INNER* EQ&1) WRITE (6, 601) DZM, DEVX1, DEVX2, DEVX3, COR12, COR23,
2
              1 COR13
    125
2
               WRITE (*, 601) DZM, DEVX1, DEVX2, DEVX3, COR12, COR23, COR13
    126
2
    127 601
               FORMAT(1X, 7(E9. 4, 1X))
2
               WRITE(*,'(A)')' BEFORE 999'
    128
2
    129
                 DO 999 II=1,NVO
3
    130
                  DO 991 I=1,NN
                  MU(I) = RED * AO(I) - VO(II) * A1(I) / VARV
4
    131 991
3
    132
                  AM=MU (MM)
3
    133
                  DO 992 I=1.KK
4
    134 992
                  RM(I) = MU(MM-I)
3
    135
                 XMIN1=RM(1)-XMAX*DEVX1
3
    136
                 XMIN2=RM(2)-XMAX*DEVX2
3
    137
                 XMIN3=RM(3)-XMAX*DEVX3
3
    138
                 XMAX1=RM(1)+XMAX*DEVX1
3
    139
                 XMAX2=RM(2)+XMAX*DEVX2
3
    140
                 XMAX3=RM(3)+XMAX*DEVX3
3
    141
                 S1=DMAX1 (RED, XMIN1)
3
    142
                 S2=DMAX1 (RED, XMIN2)
3
    143
                 S3=DMAX1 (RED, XMIN3)
3
    144
                 NS1 = (S1 - XMIN1)/DX1
3
    145
                 NS2=(S2-XMIN2)/DX2
3
    146
                 NS3=(S3-XMIN3)/DX3
   147
3
                 X1=S1-DX1
3
    148
                 PS=0. DO
3
    149
                 QS=0. DO
3
    150
                 IF(S1.GT.XMAX1)GOTO 100
3
    151
                DO 99 JJ=NS1,NX2
4
    152
                 X1 = X1 + DX1
4
    153
                 Q1 = (X1 - RM(1))
    154
                 H1=Q1*Q1*SMI(1,1)
    155
                 WK2=2*Q1*SMI(1,2)
4
    156
                 WK3=Q1*SMI(1,3)
4
    157
                 AZM1=AM+TP(1)*Q1
4
    158
                 IF (S2.GT. XMAX2) GOTO 99
4
    159
                 X2=S2-DX2
4
    160
                DO 9 LL=NS2, NX2
5
    161
                 X5=X5+DX5
5
    162
                 Q2=X2-RM(2)
5
    163
                 H2=H1+Q2*(Q2*SMI(2,2)+WK2)
5
    164
                 WK1=2*(WK3+Q2*SMI(2,3))
5
    165
                 AZM2=AZM1+TP(2)*Q2
5
    166
                 IF(S3.GT.XMAX2)GOTO 9
5
    167
                 X3=S3-DX3
5
    168
                DO 22 IJK=NS3, NX2
6
    169
                 X3=X3+DX3
6
    170
                 Q3=X3-RM(3)
    171
6
                 H3=H2+(WK1+Q3*SMI(3,3))*Q3
6
    172
                 AZM = AZM2 + TP(3) *Q3
6
    173
                 GGG=GG1 ((RED-AZM)/DZM, NERR)
6
    174
                 QQ=DEXP(-H3/2.DO)
6
    175
                 PS=PS+QQ*GGG
6
    176
                 QS=QS+QQ
6
    177 22
                CONTINUE
```

```
· Microsoft FORTRAN77 V3.20 02/84
D Line# 1
                CONTINUE
5
    178 9
    179 99
4
                CONTINUE
3
                PS=PS*QO*PVO(II)
    180 100
3
    181
                QS=QS*QO*PVO(II)
3
    182
                PSTAR (MM) = PSTAR (MM) +PS
3
                QSTAR (MM) =QSTAR (MM) +QS
    183
3
    184
                IF (INNER, EQ. 1) WRITE (6, 602) II, PVO(II), PS, QS, NS1, NS2, NS3,
3
    185
               1 (RM(I), I=1, KK)
3
                WRITE(*,602) II, PVO(II), PS, QS, NS1, NS2, NS3, (RM(I), I=1, KK)
    186
3
    187 602
                FORMAT(1X, 14, 3(1X, E8. 3), 314, 3(1X, E8. 3))
3
    188 999
                CONTINUE
2
                 PQ=PSTAR (MM) /QSTAR (MM)
    189
2
                 IF (MM. EQ. KK+1) THEN
    190
2
                 PP1=PSTAR (MM)
    191
2
                 ELSE
    192
2
                 pp1=pp1*pQ
    193
2
                 ENDIF
    194
2
    195
                IF (INNER. EQ. 1) THEN
2
                WRITE(6, 1(A))) **** MM **** P* **** Q* **** P*/Q* **** PP ****
    196
2
    197
                ENDIF
2
                WRITE (6, 603) MM, PSTAR (MM), QSTAR (MM), PQ, PP1
    198
                WRITE(*, '(A)')'**** MM **** P* **** Q* **** P*/Q* **** PP ****'
2
    199
2
                WRITE(*, 603) MM, PSTAR(MM), QSTAR(MM), PQ, PP1
    200
2
    201 603
                FORMAT (1X, I5, 4E16.8)
2
    202 9999
                CONTINUE
                WRITE(2,*)(PSTAR(I), I=1,NN)
1,
    203 C
1
    204 C
                WRITE(2,*)(QSTAR(I),I=1,NN)
1
    205
                W1=PSTAR(KK+1)
1
    206
                W2=1.
1
    207
                DO 1001 I=KK+2, NN
2
    208
                W1=W1*PSTAR(I)
2
    209 1001
                W2=W2*QSTAR(I)
                IF (W2. NE. O. DO) PP=W1/W2
1
    210
    211 C
                WRITE(2, *) PP
1
1
                WRITE(6,'(A)')' FILNAL PROBABILITY IS:'
    212
1
    213
                WRITE (6, *) W1, W2, PP
1
    214
                WRITE(*,'(A)')' FILNAL PROBABILITY IS:'
    215
                WRITE(*, *) W1, W2, PP
1
                WRITE(2, *) PP
1
    216
1
    217 1000
                CONTINUE
    218
                STOP
    219
                END
                       Offset P Class
Name
         Type
```

	AO	REAL*8	2	
	A1	REAL*8	402	
	AM	REAL*8	10248	
	AREA	REAL*B	9972	
	AZM	REAL*8	10496	
	AZM1	REAL*8	10408	
	AZM2	REAL*8	10456	
	BM	REAL*8	10084	
	COR	REAL*8	10180	
	COR12	REAL*8	10148	
÷	COR13	REAL*8	10156	
	CBR23	REAL*8	10164	
	CORR	REAL*8	10172	
	DABS			INTRI

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70 I damen	# 1 7		
D Line	# 1 7		INTRINSIC
DEL	REAL*8	6402	111111111111111111111111111111111111111
DEVX1	REAL*8	10124	
DEVX2	REAL*8	10132	
DEVX3	REAL*8	10140	
DEXP	1 4 100 1 100 4 100		INTRINSIC
DMAX1			INTRINSIC
DSQRT			INTRINSIC
DTM	REAL*8	10100	
DVO	REAL*8	. 9964	
DX1	REAL*8	10188	
DXS	REAL*8	10196	
DX3	REAL*8	10204	
DZM	REAL*8	10116	
ERR	REAL*8	8	/COMMQQ/
Fi	CHAR*16	9634	
F2	CHAR*16	9650	
FOUT	CHAR*16	9666	
FRED	CHAR*16	9610	
GGG	REAL*8	10504	
H1	REAL*8	10384	
H2	REAL*8	10440	
H3	REAL*8	10488	
Ι	INTEGER*4	9626	
IABS	THE C. I STORY MADE AND ADDRESS OFFICE A. P.	4	INTRINSIC
II	INTEGER*4	10236	
IJK	INTEGER*4	10472	
INNER	INTEGER*4	9718	
J JJ	INTEGER*4 INTEGER*4	9992 10368	
KK	INTEGER*4	9602	
L3	INTEGER*4	6218	
LL	INTEGER*4	10424	
M3	INTEGER*4	6230	
MM	INTEGER*4	10076	
MU	REAL*8	6242	
NERR	INTEGER*4	9686	
NN	INTEGER*4	9682	
NOPO	INTEGER*4	10000	
NRED	INTEGER*4	9606	
NS1	INTEGER*4	10332	
NS2	INTEGER*4	10336	
NS3	INTEGER*4	10340	
NVO	INTEGER*4	9690	
NX	INTEGER*4	9702	
NX2	INTEGER*4	9706	
PI	REAL*8	9956	
PIE	REAL*8	0	/COMMQQ/
pp pp	REAL*8	10614	
PP1	REAL*8	10570	
2Q	REAL*8	10562	
PS PSTAR	REAL*8 REAL*8	10352	
PSIAR	REAL*8	6058 3202	
QO	REAL*8	10212	
Q1	REAL*8	10376	
G2	REAL*8	10432	
Q3	REAL*8	10480	
ଉପ	REAL*8	10520	
	min min min	- 4 m 500 w	

```
D Line# 1
                        10360
QS
        REAL*8
                         5602
QSTAR
        REAL*8
                        10008
RED
        REAL*8
REDV
        REAL*8
                         5978
RM
        REAL*8
                         5954
                                                    ORIGINAL PAGE IS
51
        REAL*8
                        10308
S2
        REAL*8
                        10316
                                                    OF POOR QUALITY
                        10324
, S3
        REAL*8
SM
        REAL*8
                         5762
SMI
        REAL*8
                         5882
TM
        REAL*8
                         5834
TP
        REAL*8
                         5858
VO
        REAL*8
                          802
VOMAX
        REAL*8
                         9694
                         9948
VARV
        REAL*8
VZM
        REAL*8
                        10108
                        10594
W1
        REAL*8
WE
        REAL*8
                        10602
WK1
        REAL*8
                        10448
WK2
        REAL*8
                        10392
WK3
        REAL*8
                        10400
X 1
        REAL*8
                        10344
X2
        REAL*8
                        10416
ΣX
        REAL*8
                        10464
XMAX
        REAL*8
                       9710
XMAX1
        REAL*8
                        10284
                        10292
SXAMX
        REAL*8
EXAMX
        REAL*8
                        10300
                        10260
INIMX
        REAL*8
        REAL*8
                        10268
XMIN2
XMIN3 REAL*8
                        10276
                SUBROUTINE EQUAL3(A, B, N)
     220
     221
                REAL * 8 A(3,3), B(3,3)
     222
                DO 1 I=1, N
     223
1
                DO 1 J=1, N
2
     224 1
                B(I,J)=A(I,J)
     225
                RETURN
     226
                END
                       Offset P Class
Name
          Type
                             0 *
A
        REAL*8
B
        REAL*8
                             4
I
        INTEGER*4
                        10622
        INTEGER*4
                        10630
J
N
         INTEGER*4
                             8 *
                SUBROUTINE SERR(ERR, NERR)
     227
     228 C
                AREA UNDER Nx(0,1) FROM X=0 TO R
     229
                REAL*8 ERR(1), PI, C1, T, TP1, TP2, DT
     230
                PI=4. DO*DATAN(1. DO)
     231
                C1=DSQRT(2.DO*PI)
     232
                DT=5. DO/NERR
     233
                DT2=DT/2.
     234
                T=0.D0
     235
                DO 1 I=1, NERR
```

```
D Line# 1
     236
               T=T+DT
1
     237 1
 1
               ERR(I) = DEXP(-0.5*T*T)/C1
     238
               TP1=ERR(1)
     239
               ERR(1) = (ERR(1) + 1/C1) *DT*0.5
     240
               DO 2 I=2. NERR
1
     241
               TP2=ERR(I)
               ERR(I)=ERR(I-1)+DT2*(TP1+ERR(I))
 1
     242
                                34
     243
               TP1=TP2
     244 2
               CONTINUE
     245
               ERR(0)=0. DO
     246
               RETURN
     247
               END
Name
         Type
                    Offset P Class
        REAL*8
                       10646
C1
DATAN
                                INTRINSIC
DEXP
                                INTRINSIC
DSQRT
                                INTRINSIC
                       10654
DT
        REAL*8
DTZ
        REAL
                       10662
ERR
        REAL *8
                           0 *
 I
        INTEGER*4
                       10674
NERR
        INTEGER*4
                           4 *
 PI
                       10638
        REAL*8
 T
        REAL*8
                       10666
 TP1
        REAL*8
                       10682
 TP2
        REAL*8
                       10694
               DOUBLE PRECISION FUNCTION GG1(XX, NERR)
     248
                  CALCULATE AREA FROM XX TO INFINITE OF Nx(0,1)
     249 C
     250
                IMPLICIT REAL*8 (A-H, O-Z)
     251
                COMMON PI2, ERR
                REAL*8 ERR(1)
     252
                X = DABS(XX)
     253
     254
                NN=X*NERR/5. DO
     255
               IF (NN. GE. NERR) THEN
     256
               GG1=0.5
               GOTO 9
     257
     258
               ENDIF
     259
                GG1=ERR(NN)
     260 9
               CONTINUE
     261
                IF (XX. GT. O. DO) THEN
     262
                GG1=0.5-GG1
     263
                ELSE
                GG1=0.5+GG1
     264
     265
                ENDIF
     266
                RETURN
     267
                END
         Type
                     Offset P Class
 Name
                                INTRINSIC
 DABS
        REAL*B
                           8
                                /COMMQQ/
 ERR
                           4 *
        INTEGER*4
 NERR
                       10710
· NN
       · INTEGER*4
 PI2
        REAL*8
                            0
                               /COMMQQ/
                       10702
 Х
        REAL*8
```

7

```
D Line# 1
ХX
       REAL*8
                            0 *
               SUBROUTINE DZERO(A, N)
    268
               REAL*8 A(1)
    269
    270
               DO 1 I=1, N
               A(I) = 0.00
I
    271 1
               RETURN
    272
    273
               END
                      Offset P Class
Name
         Type
A
        REAL*8
                            0 *
                       10714
I
        INTEGER*4
N
        INTEGER*4
                            4 *
                SUBROUTINE DGMPRD (A, B, R, N, M, L)
    274
    275
                REAL*8 A(1), B(1), R(1)
    276
                IR=0
    277
                IK=-M
    278
                DO 10 K=1.L
1
    279
                IK=IK+M
1
    280
                DO 10 J=1, N
2
    281
                IR=IR+1
2
    282
                JI=J-N
2
                IB=IK
    283
2
    284
                R(IR)=0.
2
    285
                DO 10 I=1, M
3
    286
                N+IL=IL
3
    287
                IB=IB+1
                R(IR)=R(IR)+A(JI)*B(IB)
    288
           10
    289
                RETURN
                END
    290
                      Offset P Class
Name
         Type
\Theta
        REAL*8
                            0 *
В
        REAL*8
                            4 *
                        10754
Ι
        INTEGER*4
                        10750
IB
        INTEGER*4
IK
        INTEGER*4
                        10726
IR
        INTEGER*4
                        10722
J
        INTEGER*4
                        10738
JI
        INTEGER*4
                        10746
К
        INTEGER*4
                        10730
        INTEGER*4
                           20 *
1_
                           16 *
14
        INTEGER*4
N
        INTEGER*4
                           12 *
R
        REAL*8
                            8 *
                SUBROUTINE DMINV(A, N, D, L, M)
     291
     292
                REAL*8 A(1), D, BIGA, HOLD
     293
                DIMENSION L(1), M(1)
                D=1.0
     294
                NX = -N
     295
                DO 80 K=1, N
     296
               NK=NK+N
1
     297
```

```
7
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D Line# 1
                L(K) = K
    298
1
1
    299
                M(K) = K
1
    300
                KK=NK+K
i.
    301
                BIGA=A(KK)
1
    302
                DO 20 J=K, N
2
    303
                IZ=N*(J-1)
2
    304
                DO 20 I=K, N
3
    305
                IJ=IZ+I
3
    306
                IF (DABS (BIGA) - DABS (A(IJ))) 15,20,20
           10
3
           15 BIGA=A(IJ)
    307
3
    308
                L(K)=I
3
    309
                M(K) = J
3
    310
           20 CONTINUE
1
    311
                J=L(K)
1
    312
                IF(J-K) 35,35,25
1
    313
           25
               KI=K-N
1
    314
                DO 30 I=1,N
2
    315
                KI=KI+N
\Xi
    316
                HOLD=-A(KI)
2
                JI=KI-K+J
    317
2
    318
                A(KI)=A(JI)
2
    319
           30 A(JI)=HOLD
1
    320
           35 I=M(K)
1
    321
                IF(I-K) 45,45,38
1
    322
           38
                JP=N*(I-1)
1
    323
                DO 40 J=1, N
\Xi
    324
                JK=NK+J
2
    325
                JI=JP+J
Ξ
    326
                HOLD=-A(JK)
Ξ
    327
                A(JK) = A(JI)
2
    328
           40
               A(JI) = HOLD
                IF (BIGA) 48, 46, 48
4
    329
           45
4
    330
           46
               D=0.0
1
    331
                RETURN
1
    332
           48
                DO 55 I=1, N
Ê
                IF(I-K) 50,55,50
    333
2
    334
           50
                IK=NK+I
2
    335
                A(IK) = A(IK) / (-BIGA)
2
    336
           55
                CONTINUE
1
    337
                DO 65 I=1.N
338
                IK=NK+I
Ξ
    339
                HOLD=A(IK)
\Xi
    340
                IJ=I-N
\Xi
    341
                DO 65 J=1, N
3
    342
                IJ=IJ+N
3
    343
                IF(I-K) 60,65,60
3.
    344
                IF(J-K) 62,65,62
           60
3
    345
                KJ=IJ-I+K
3
    346
                A(IJ) = HOLD * A(KJ) + A(IJ)
3
    347
           65
                CONTINUE
1
    348
                KJ=K-N
                DO 75 J=1, N
j.
    349
Ξ
    350
                KJ=KJ+N
    351
\equiv
                IF (J-K) 70, 75, 70
Ξ
    352
           70
                A(KJ) = A(KJ) / BIGA
2
    353
           75
                CONTINUE
1
    354
                D=D*BIGA
4
    355
                A(KK)=1.0/BIGA
    356
           80
                CONTINUE
```

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OF	POOR	QUALI	TY

1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	367 368 370 371 372 373 375 375 376 377 378 380 381	120	A(JI)= J=M(K) IF(J-K KI=K-N DO 130 KI=KI+ HOLD=F JI=KI-	:-A(JI) :HOLD () 100,1 () I=1,N ()(KI) (-K+J :-A(JI) :HOLD 100), 125
Name		Type		Offset	P	Class
А		REAL*8		_	*	
BIGA		REAL*8		10778		
D DABS		REAL*8		۵	*	INTRINSIC
HOLD		REAL*8		10830		#14131#14##############################
I		INTEGE	₹*4	10798		
IJ		INTEGER	₹*4	10806		
IK	;	INTEGE	₹*4	10858		
ΙZ	:	INTEGE	₹*4	10794		
J		INTEGE	₹*4	10786		
JI		INTEGE		10838		
JK		INTEGE		10850		
JP		INTEGE		10842		
JQ		INTEGE		10878		
JR		INTEGE		10882		
KI		INTEGE! INTEGE!		10766 10822		
KJ VI		INTEGE		10822		
KK		INTEGE		10774		
L		INTEGE		12		
M M		INTEGE		16		
N		INTEGE			*	
NK		INTEGE	₹*4	10762		
Name		Туре		Size		Class
COMM	QQ			8048		COMMON
DGMP						SUBROUTINE
DMIN						SUBROUTINE II-45/46

D Line# 1

357

359

363

364 365

366

367

7

362 108 JQ=N*(K-1)

358 100 K=(K-1)

360 105 I=L(K) 361 IF(I-K

K=N

IF(K) 150, 150, 105

JR=N*(I-1)

JK=JQ+J

JI=JR+J

DO 110 J=1, N

IF(I-K) 120, 120, 108

APPENDIX A

WYLE LABORATORIES - RESEARCH STAFF TECHNICAL MEMORANDUM TM 80-8

EVALUATION OF SPACE SHUTTLE MAIN ENGINE FLUID DYNAMIC FREQUENCY RESPONSE CHARACTERISTICS

APPENDIX A

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EVALUATION OF SPACE SHUTTLE
MAIN ENGINE FLUID DYNAMIC
FREQUENCY RESPONSE CHARACTERISTICS

by

T. G. GARDNER

for

NATIONAL AERONAUTICS AND SPACE ADMINISTRATION GEORGE C. MARSHALL SPACE FLIGHT CENTER MARSHALL SPACE FLIGHT CENTER, ALABAMA 35812

Work Performed Under Contract Number NAS8-33508

FOREWORD

This report was prepared by Wyle Laboratories, Research and Engineering Division, Huntsville, Alabama, under NASA Contract No. NAS8-33508, for the National Aeronautics and Space Administration (NASA), George C. Marshall Space Flight Center. The contract was administered under the technical direction of the Systems Dynamics Laboratory, with Mr. Harry Bandgren acting as the Technical Contracting Officer's Representative. Mr. Duron Cryder was the contract administrator for NASA.

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EVALUATION OF SPACE SHUTTLE MAIN ENGINE FLUID DYNAMIC FREQUENCY RESPONSE CHARACTERISTICS

by

T. G. Gardner

ABSTRACT

In order to determine the POGO stability characteristics of the Space Shuttle main engine (SSME) liquid oxygen (LOX) system, an evaluation of the fluid dynamic frequency response functions between elements in the SSME LOX system was performed, both analytically and experimentally. This report acquaints the reader briefly with the POGO testing program and, more specifically, documents, as a user note, the POGO data analysis software. POGO refers to the effect the dynamic interaction between devices in the LOX system has on fluid/mechanical vibration of the system. For the experimental data evaluation, a software package was written for the Hewlett-Packard 5451C Fourier analyzer. The POGO analysis software consists of five separate segments. Each segment is stored on the 5451C disc as an individual program and performs its own unique function. The POGO analysis software includes two separate data reduction methods, a signal calibration, coherence or pulser signal based frequency response function blanking, and automatic plotting features. The 5451C allows variable parameter transfer from program to program. This feature is used to an advantage and requires only minimal user interface during the data reduction process. Experimental results are also included. Comparison of experimental results with the analytical predictions permits adjustments to the general model in order to arrive at a realistic simulation of the POGO characteristics.

SPACE SHUTTLE MAIN ENGINE SYSTEM DESCRIPTION

The Space Shuttle propulsion system consists of two solid rocket boosters (SRBs) and three main engines (SSMEs). The SSMEs are high-performance, liquid-propellant, variable thrust rocket engines, operating at high temperatures, high pressures, and high rotational speeds. Each SSME operates at a chamber pressure of approximately 3000 psia to produce a sea level thrust of 375,000 pounds and vacuum thrust of 470,000 pounds and operates over a range from 50 to 109 percent of the rated power. Each engine consists of ten major components: two preburners, four turbopumps, the hot-gas manifold, the main injector, a heat exchanger, and the main combustion chamber. All other components are attached structurally to the hot-gas manifold, and the entire arrangement is called the SSME powerhead.

A key to the cost effectiveness of the Space Shuttle concept is hardware reusability. As a result, system reliability is of paramount importance. The SSMEs have been subjected to extensive hot firing and flow tests. Under these extreme operating conditions, system failures and malfunctions have occurred due to the self-induced dynamic environment. These failures have ranged from subcritical wear of component bearings to catastrophic explosion and fire resulting from the intense pressure oscillations and dynamic stresses occurring in pumps, valves, and/or propellent lines. The components in the liquid oxygen (LOX) system include the low pressure oxidizer pump (LPOP), POGO suppression system (or accumulator), the high pressure oxidizer pump (HPOP), and the main combustion chamber (MCC). The LOX flows from the external tank (ET) through the above components and is combined with the liquid hydrogen (LH₂) fuel at the inlet of the MCC by the main injector.

The LPOP is an axial-flow pump driven by a six-stage turbine and powered by the LOX. During engine startup and mainstage, the LPOP maintains sufficient pressure in the LOX line to permit the HPOP to operate at high speeds without an inducer and without cavitation, even under worst-case conditions.

The POGO suppressor is a gas-filled accumulator, which serves as a capacitance in the LOX flow circuit. The unit is designed to prevent low-frequency oscillations, transmitted from the Space Shuttle vehicle, from being transmitted into the HPOP and ultimately to prevent MCC pressure oscillations. To provide suppression protection through the startup and shutdown transients, the accumulator is filled with gaseous helium. During normal engine operation, the heat exchanger provides gaseous oxygen $(G0_2)$, as the compliant medium, to the accumulator. The system consists of a 0.6 cubic-foot accumulator, which is attached to the HPOP inlet duct, an internal stand pipe, helium precharge valve package, gaseous oxygen supply valve package, and recirculation isolation valves. The liquid level in the accumulator is controlled by the stand pipe, which is orificed to regulate the GO, overflow over the engine operating power level range. Excess gaseous and liquid oxygen are recirculated back to the LPOP inlet through the engine oxidizer bleed duct.

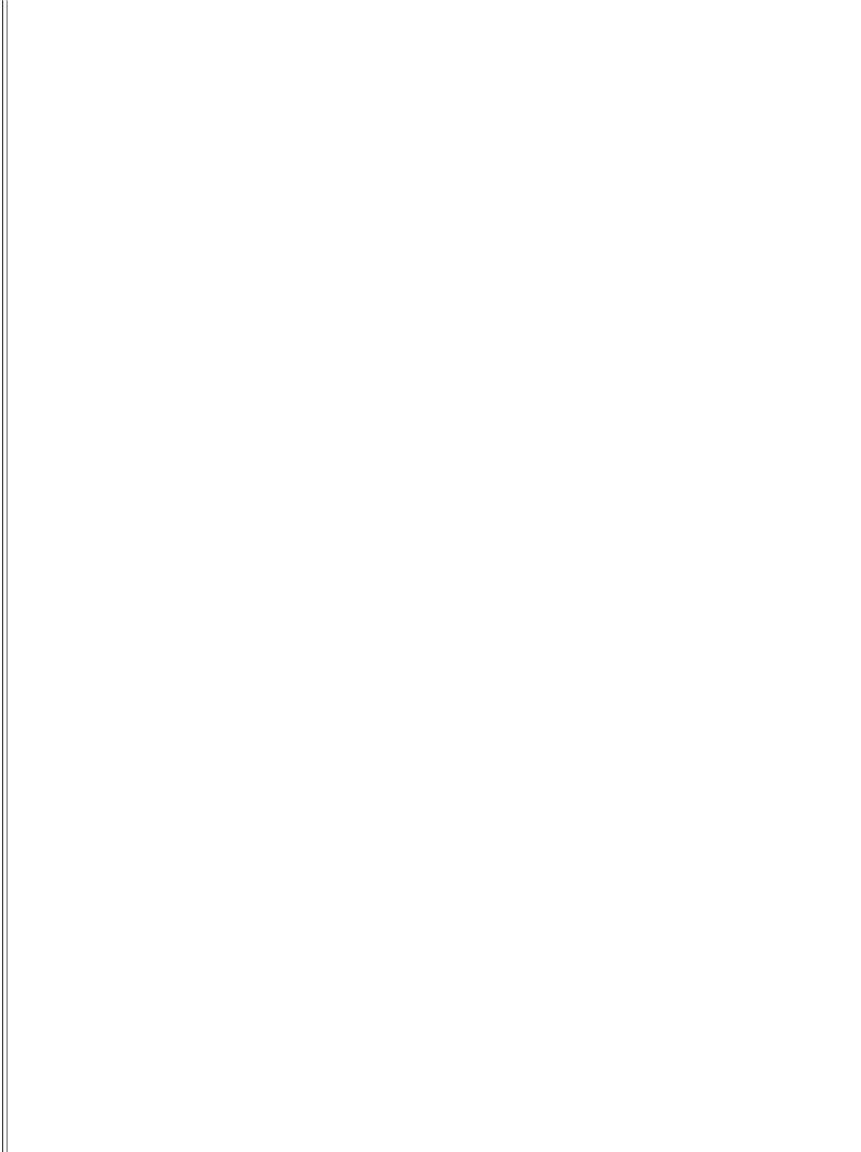
The HPOP consists of two single-stage centrifugal pumps on a common shaft, which is directly driven by a two-stage hot-gas turbine. The main pump receives oxidizer from the LPOP discharge and supplies LOX at increased pressure to the LPOP turbine. The HPOP turbine is powered by hot-gas (hydrogen-rich steam). LOX enters the HPOP main pump through the main pump housing and flows through an inlet with a 50-50 flow split into a double-entry, common outlet impeller. Several sets of guide vanes direct the flow to the impeller inlets. The impeller has four full and four partial blades in each half. After passing through the impeller, the flow is redirected into the HPOP discharge by diffuser vanes. The HPOP is attached to the hot-gas manifold by a flange, which is canted ten degrees out from the engine centerline. The oxidizer then flows into the MCC.

The MCC is a cylindrical structural chamber, which contains the burning propellant gases and is flange-attached to the hot-gas manifold. The MCC consists of a coolant liner, coolant inlet and outlet manifolds, and a structural jacket. The coolant liner, which provides the coolant

flow path of the MCC, contains 390 milled axial coolant channels, which are ported to the coolant inlet and outlet manifolds. This network provides an up-pass circuit for the liquid hydrogen coolant. The chamber jacket provides the structural strength for the MCC and is approximately 20 inches long. The jacket is formed in two matching halves, which are welded together and to the coolant inlet and outlet manifolds. A throat ring is also welded to the jacket at the MCC throat to provide added strength. The MCC throat follows a contraction from the hot-gas manifold of 2.96:1 and is expanded to a ratio of 5:1 before attaching to the engine nozzle.

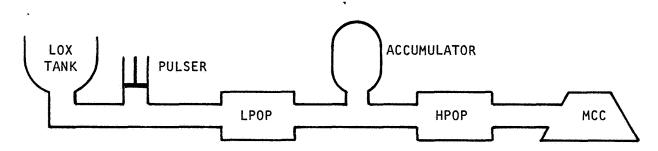
In order to validate system performance and ensure equipment reliability, the SSME and components have been and are presently undergoing extensive development and qualification tests. Testing of the engine and components is conducted at several NASA and contractor locations. Full-scale engine test firings for development and flight acceptance are performed on two single-engine test stands at the National Space Technology Laboratories (NSTL), Bay St. Louis, Mississippi, and one stand operated by Rockwell International near Santa Susana, California. In addition, main propulsion testing is performed at NSTL on a stand designed to accommodate the Shuttle main propulsion system element—the three-engine cluster, external tank, and orbiter systems.

Testing is being performed on a continuing basis. The length of a given test is dependent on specific test objectives and may run from several seconds to over 800 seconds. During each test, comprehensive measurements are acquired to monitor system performance, including vibration, dynamic pressure and strain at critical engine locations. Several of these latter measurements are utilized on-line as emergency cutoff indicators, and all are recorded on magnetic tape for subsequent analysis and evaluation.



SPACE SHUTTLE MAIN ENGINE POGO TEST PROGRAM

As part of a program to determine the POGO stability characteristics of the Space Shuttle Main Engine (SSME) liquid oxygen (LOX) system, POGO tests were conducted by Rocketdyne engineers, in California, on the A3 SSME test stand. In order to define the system fluid dynamic characteristics, frequency response functions [H(f)] between various components are calculated from pressure measurements taken at various locations in the system. To calculate the H(f)s, a known pressure signal must be applied to the system and the system response to this signal measured. A pulser was used to generate this dynamic pressure signal, with the tests usually including both sine sweeps and sine dwells. The first device located downstream of the pulser is the low pressure oxidizer pump (LPOP), followed by the accumulator (or suppressor), the high pressure oxidizer pump (HPOP), and the main combustion chamber (MCC). With the accumulator active in the system, the pulser signal is suppressed such that it does not reach the MCC with sufficient strength to be measured adequately. Consequently, tests were conducted with the accumulator active and inactive. The general system diagram below shows the relative location of these devices. Pressure measurements were made at the pulser, the LPOP inlet, the HPOP inlet, and the HPOP discharge.

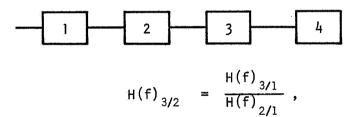


The pulser sine sweeps ranged in frequency from 2 to 40 Hz. At the higher frequencies in the pulser sweep, the displacement of the pulser piston and the corresponding amplitude of the pressure pulse generated were very small. The amplitudes of the pressure signals further down the line were essentially buried in the noise level and very difficult

to measure. For the sine dwells, the magnitude of the pulsed signal can be increased, providing greater dynamic range in the data. The problems associated with the dwell testing are the increased time required to conduct the test and the fact that the frequency response functions can be defined only at the frequencies where the dwells are located. Because of this, a routine that will blank out invalid data in frequency response functions was included in the POGO analysis software. This blanking can be based on either the pulser signal or the coherence function, leaving only the frequency response function data at the frequencies where the pulser was operated. In the initial tests, the dwell frequencies were chosen at approximately 5-Hz intervals. In subsequent tests, the dwells were chosen closer together in order to better define the system frequency response.

POGO DATA ANALYSIS SOFTWARE

For organizational purposes and because of total size, the POGO data analysis software is divided into five segments. Each segment is stored separately on the 5451C disc and runs on the 5451C as an individual program. The 5451C Fourier operating system allows nesting of as many as ten programs. This is the feature that allows these five programs to operate together and perform the total POGO data analysis. The software includes two frequency response function [H(f)] calculation routines. These two data reduction methods are referred to as the RATIO and DIRECT methods for calculating frequency response functions. In the RATIO technique, all H(f)s are initially referenced to the pulser. These H(f)s are then divided, with the resulting quotient being the H(f) across various combinations of devices. For example, the H(f) between devices 2 and 3 in the following schematic may be calculated as the RATIO of the H(f) between devices 1 and 3 and the H(f) between devices 1 and 2.



where $H(f)_{n/1} = \frac{G_{n1}}{G_{11}}$ and n = output, l = input [1, 2]. Here G_{n1} is the cross spectrum between the input and output, and G_{11} is the autospectrum of the input (pulser).

NOTE: The POGO software outputs the auto (power) spectra and cross (power) spectra as functions normalized to the bandwidth (Δf) or as power spectral densities (PSDs) and cross-power spectral densities (XPSDs). However, the 5451C calculates and uses the functions in their nonnormalized form to calculate frequency response functions [H(f)s] and coherence functions [$\gamma^2(f)s$] [2]. In the remainder of this document, all spectral functions will be referred to as PSDs and XPSDs regardless of their actual state of normalization. The reader should understand that all H(f) and $\gamma^2(f)$ calculations are made prior to normalization.

To calculate the $\gamma^2(f)$ that is compatible with the RATIO H(f), the following formula is used [3]:

$$\gamma^{2}(f)_{3/2} = \frac{1}{\frac{1}{\gamma^{2}(f)_{3/1}} + \frac{1}{\gamma^{2}(f)_{2/1}} - 1}$$

where $\gamma^2(f)_{n/1} = \frac{|G_{n1}|^2}{G_{11}G_{nn}}$, and n and 1 are output and input, as above [1, 2].

To arrive at $H(f)_{3/2}$ and $\gamma^2(f)_{3/2}$ using the direct method involves calculating the frequency response function as the XPSD, between devices 3 and 2, and divided by the PSD of device 2. The coherence is calculated as the magnitude squared of the XPSD divided by both the input and output PSDs. These equations are as follows:

$$H(f)_{3/2} = \frac{G_{32}}{G_{22}}$$

$$\gamma^{2}(f)_{3/2} = \frac{|G_{32}|^{2}}{G_{22}G_{33}}$$

where $G_{32} = XPSD$, $G_{22} = input PSD$, and $G_{33} = output PSD$.

The POGO software also calculates frequency response functions, both RATIO and DIRECT, which have been blanked, based on either the coherence or the pulser signal. Blanking means that the frequency response function magnitude and phase are set to zero at those frequencies where the value of the coherence, or pulser signal, does not exceed the user set minimum.

As previously stated, the POGO analysis software consists of five segments, each of which is stored on the 5451C disc in a separate keyboard program file (KPF) record. They are currently stored in successive records (1 - 5) on the Marshall Space Flight Center, Systems Dynamics Lab's 5451C Fourier software disc.

KEYBOARD PROGRAM FILE, RECORD 1

KPF1 contains part 1 of three parts, which perform the RATIO calculations. Part I sets up the data block size, calibration factors, total amount of data to be taken, and delta $f(\Delta f)$ [frequency resolution or bandwidth]. This information is used to calculate both the RATIO and DIRECT H(f)s. The 5451C has a block arithmetic mode, which allows any block of data to be multiplied or divided by any number. This number, however, must be an integer. If this number happens to be a floatingpoint variable parameter (VP), the 5451C simply truncates any part of the VP that lies to the right of the decimal. In reference to this problem, the POGO analysis software first multiplies each calibration factor by 100, then calibrates the appropriate data block, and finally divides the data block by 100. This allows for two decimal places in each calibration factor. The same type procedure is used with regard to the VP that holds the Δf parameter, to allow for one digit to the right of the decimal when calculating PSDs. After the initial setup, KPF1 reads the analog data from the tape and stores it on the ADC Throughput File, beginning at record 0. KPFI then retrieves this time domain data, two channels at a time, and calculates PSDs for each channel. KPF1 also calculates H(f), $\gamma^2(f)$, and XPSDs for the three pairs, LPOP/pulser, HPOP/pulser, and MCC/pulser. This data is stored in data blocks 12 through 27. Program control is then transferred to KPF2, which is part 2 of the POGO analysis software.

KEYBOARD PROGRAM FILE, RECORD 2

KPF2 begins the calculations for the RATIO H(f)s and $\gamma^2(f)$ s. The 5451C has preprogrammed keys that will perform the arithmetic necessary to make these calculations. The keys, however, perform what will be referred to as block arithmetic. The 5451C stores data in blocks internally, in a format Hewlett-Packard calls floating-point-by-block. This means that the data block is actually a group of integers, all with a common scale factor. Because of this method of data handling, the arithmetic operation performed by the block command is not floating point, but is integer arithmetic. These operations involved in the

RATIO calculations are limited to a 40-dB dynamic range. When inverting a number, as that number approaches zero, the inverse approaches infinity. It becomes apparent that if there are any numbers whose value is less than 0.01 in a data block, any number greater than or equal to 1 will be more than 40 dB down when that block is inverted. The 5451C automatically scales up the block scale factor to eliminate overflowing, which causes any number more than 40 dB down to be set to zero. This is a serious problem when doing the type of calculation involved in arriving at the RATIO H(f)s and $\gamma^2(f)s$. In both of these calculations, especially the $\gamma^2(f)$ calculation, the quotient in the formulations is dominated by the small numbers in the denominator. These small numbers are not reliable data points, and the valid data is lost below the 40-dB dynamic range.

The problem was solved in this program by using a floating-point arithmetic scheme in the $\gamma^2(f)$ calculations and a combination of floatingpoint arithmetic and a filtering technique in the H(f) calculations. The floating-point scheme involves extracting each channel (or data point) point-by-point from a data block, putting the value into a floating-point format (via a floating-point variable parameter), executing the arithmetic operation, and finally putting the datum back into the data block. A magnitude filtering technique is used in the H(f)calculation to eliminate a loss of data after the values are put back into the data block. The real and imaginary parts of the H(f) are filtered so that any values outside the range of +7 are set to zero. This allows a polar magnitude maximum of 10. The 40-dB dynamic range then will be 10^{-1} to 10^{1} . This filtering technique is not necessary in the $\gamma^2(f)$ calculations because of the final quantity inversion in the formulation. All the values to be inverted, however, are scanned for values of identically zero before inversion. This is to eliminate any numbers actually going to the upper limit (infinity).

The program loops through the above operation enough times to calculate the RATIO H(f) and γ^2 (f) for each channel in the data block. This loop is nested inside a loop, which allows for all three sets of ratio

calculations to be computed. Part 2 of the POGO analysis software then transfers control to part 3.

KEYBOARD PROGRAM FILE, RECORD 3

KPF3 defines the variable parameter, corresponding to the ratio calculations, necessary to operate the plot routine. KPF3 also performs the calculations involved in the H(f) blanking routine. KPF3 has several entry points, which allow various operations to be performed outside the normal program flow. KPF2 flows into the beginning of KPF3, which jumps to the blanking routine. The blanking routine begins by prompting the user to establish whether the blanking will be based upon the $\gamma^2(f)$ or the pulser PSD. The user will enter either a zero, to establish coherence blanking, or a two, to define pulser blanking. This number (0 or 2) will also be used to establish which labels will be given to the plots of the blanked H(f)s during the plot routine. If pulser blanking is chosen, KPF3 will display the pulser PSD to allow the user an opportunity to view the signal and decide on the minimum value used for the blanking routine. If $\gamma^2(f)$ blanking is chosen, KPF3 skips directly to the next step, which is a prompt, asking for the minimum value in the blanking routine. Next, KPF3 sets up the block that will be used for generating the blanked H(f). KPF3 then enters the blanking loop. This loop operates individually on each channel in the frequency domain data block. In this loop, KPF3 goes to either the pulser or $\gamma^2(f)$ block and gets one channel at a time, beginning with channel one (channel zero is the first channel) and ending with the next to last channel in the data block. The value of this channel is compared with the values of the channel immediately preceding and the channel immediately following. If the value of the channel in question is greatest, it is determined to be a local maximum. The value is then compared with the minimum value specified earlier by the user. If the value of this channel is greater in all three tests, it is chosen as a channel of interest. The corresponding channel in the H(f) data block is gathered into a complex variable parameter and stored in the data block that was prepared previously for the blanked H(f). When the loop is complete, the blanked H(f) will consist of calculated H(f) data only at those frequencies where the

pulser or $\gamma^2(f)$ passed all the necessary tests. The remainder of the blanked H(f) block will be filled with zeros. Because the HP 5451C stores frequency domain data with both real and imaginary information in a combined complex channel, the blanked H(f) contains blanked phase information as well as blanked magnitude. KPF3 then loops three times to generate a blanked version of each H(f), HPOP/LPOP, MCC/HPOP, and MCC/LPOP. KPF3 then jumps to the section that defines the variable parameters necessary to run the plot program. Finally, KPF3 transfers control to KPF5, the POGO plot routine.

KEYBOARD PROGRAM FILE, RECORD 4

KPF4 is a single-part program, which calculates the H(f)s, HPOP/LPOP, MCC/HPOP, and MCC/LPOP by matching the outputs and inputs "directly" rather than ratioing H(f)s, which have all been referenced to the pulser. This program (KPF4) uses several variable parameters, which must have been previously defined by running the first three files containing the RATIO software. These variable parameters are VP1 = block size; VP2 = number of ADC Throughput records; VP2000 through VP2003 = calibration factors for channels A through D, respectively; VP2004 = frequency resolution (Δf); and VP2030 = minimum value for the blanking routine. KPF4 also retrieves time domain data from the ADC Throughput File. These data must have been written previously on the disc (starting with record zero) via KPF1 (RATIO software, part 1). The data may be written to the disc and the necessary variable parameters defined independently of the RATIO software. It is recommended, however, that all programs be operated in sequence. The direct POGO analysis software (KPF4) writes over the data blocks generated via the RATIO software. This program therefore should not be initiated until all the required ratio data blocks have been reproduced. These data blocks include all PSDs and XPSDs (ref. pulser), which are not recalculated by the DIRECT software. Immediately after clearing the data blocks, KPF4 begins a loop that operates three times. The loop reads the correct data channels from the disc, Fourier transforms the data, calibrates the data, and calculates averaged PSDs via the special subroutine of the 5451C. KPF4 then calculates the H(f) and $\gamma^2(f)$ from the

averaged PSD data. The H(f), $\gamma^2(f)$, and XPSDs are then stored in the appropriate data blocks. (See "DIRECT POGO Program Menu," appendix C.)

KPF4 now transfers control to KPF3 at the point where the H(f) blanking loop begins. Before jumping to KPF3, KPF4 defines the variable parameters that describe the location of the DIRECT H(F)s. Once in KPF3 the blanked H(f)s are calculated using the same minimum value specified by the user during the RATIO calculations. If the user has entered the POGO software in the DIRECT calculations and wishes to change the minimum blanking value, the user simply jumps to label 43 of KPF4.

Upon returning from the blanking routine, KPF4 defines the variable parameters necessary to operate the POGO plot program (KPF5). KPF4 then transfers control to the plot routine.

KEYBOARD PROGRAM FILE, RECORD 5

KPF5 is entitled "POGO Plot Software." This software operates with both the RATIO and the DIRECT software. KPF5 uses several variable parameters that must be defined by the respective software whose data is to be plotted. The program is organized into several separate routines, including a plot routine, a hard copy routine, a delay routine, and a routine that sets up and plots all the H(f)s in three different formats. The program sets up and automatically plots all the data generated by the respective RATIO and DIRECT programs. The KPF5 prints a data block menu and allows the user to replot any of the data blocks. The plot program is geared to run with a Tektronics 4052 graphics terminal and a Tektronics hard copy unit. Because of various incompatibilities between the 5451C and the Tektronics terminal with respect to the time required to transmit plot commands and the time required to execute them, a delay routine is incorporated in the plot program. This subroutine simply counts from one to 50 and returns. The routine is called in several locations where a time delay between plot commands is necessary.

The plot program uses several variable parameters that establish which program (RATIO or DIRECT) has generated the data being plotted. The

plot program also labels each plot with test ID information in the upper right-hand corner of the plot. This information is stored as message number one in each of the text buffers one and two. Text buffer #1 is used for the RATIO data, while text buffer #2 is used with the DIRECT data. Message #1 should be changed for each new set of test data. The message may be changed by executing the following set of operations from the 5451C terminal:

Step #	Command	5451C Status
1	Y 5403 (n1)	busy

This command calls text buffer ni (1 for RATIO, 2 for DIRECT) into the computer core and activates the editing commands.

This command tells the 5451C to replace message #1.

3	01	busy
4	(Test ID)	busy
5	/ *	busy

This sequence of commands results in the test ID being recognized as message 01. The /* defines the end of the message.

This command terminates the text buffer edit mode.

To allow the user to enter the program flow for special purposes, the POGO software has many labels throughout the five KPFs. Listed below are the various jump commands and their uses.

J 0 1

This command starts the POGO software, initially setting up the calibration factors, etc, and reading the analog data.

J 10 1

This command enters POGO Software Part 1 after all the initial values have been entered and the analog data has been stored on disc in the ADC Throughput File. If this command is to be executed, the user must first be sure that the variable parameters that contain the values for the blocksize, calibration factors, number of records of data, and frequency resolution (Δf) are defined correctly and that the correct time domain data is stored on the ADC Throughput File.

J 20 2

This command begins the RATIO calculations for H(f)s and $\gamma^2(f)$ s. This command may be executed if the proper data blocks reside in core in the correct block numbers. The data blocks necessary are

H(f)	LPOP/Pulser	Block 12
$\gamma^2(f)$	11	Block 13
H(f)	HPOP/Pulser	Block 14
$\gamma^2(f)$	U	Block 15
H(f)	MCC/Pulser	Block 16
$\gamma^2(f)$	1.1	Block 17

H 30 3

This command may be used when the user wishes to recalculate the blanked RATIO frequency response functions. The user will have the opportunity to re-establish the type of blanking [pulser or $\gamma^2(f)$] and/or the minimum value for that blanking. The RATIO autoplot parameters are defined and the program control is transferred to the plot routine.

J 31 3

This command is preliminary to the POGO Plot Routine. This command enters KPF3 and defines the variable parameters necessary to run the automatic plot portion of the plot routine. After these parameters are defined, program control is automatically transferred to the plot routine. This command should be used only when the user wishes to enter the autoplot routine with RATIO data blocks. This command might be useful if, for example, the user wants to change the test ID message in the RATIO text buffer after the POGO software has completed the data calculations. The user can stop program execution and edit the text buffer, then return to the autoplot sequence.

J 40 4

This command begins the DIRECT POGO Software. This should be used only after the RATIO program has been run, defining the appropriate variable parameters, and writing the time domain data on the ADC Throughput File.

J 43 4

This command enters KPF4 where necessary variable parameters are defined just prior to transferring control to the H(f) blanking routine in KPF3. This command will allow the user to calculate DIRECT blanked H(f)s.

J 44 4

This command causes the computer to begin execution in KPF4 at the point where the variable parameters that control the autoplot routine for DIRECT data blocks are defined. Program control is automatically transferred to the plot routine.

J 53 5

This command will cause the plot program to display on the terminal the appropriate menu corresponding to the data stored in the data blocks. The plot program prompts the user to set the display scale as desired, then press the continue button to allow the program to plot the data block on the graphics terminal. This command is useful when the user wishes to return to the plot program after the machine has been idled and the plot routine pointers have been changed.

Appendix A describes the flow of the POGO software. Appendix B contains a complete list of all the program steps along with a description of each. Appendix C contains a listing of the text record messages used with the POGO software. Appendix D contains a listing of both text buffers used with the POGO software. Appendix E contains sample data output from the POGO software.

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- 1. Bendat, J. S., and A. G. Piersol. Random Data: Analysis and Measurement Procedures. John Wiley & Sons, New York, 1971.
- Schiesser, W. E. Statistical Uncertainty of Frequency Response Determined from Random Signals. Weston-Boonshaft and Fuchs, NASA Bulletin 711-C2.
- 3. Hewlett-Packard. 5451C Fourier Analyzer System Manual (Binder No. 1). Mar. 1979.

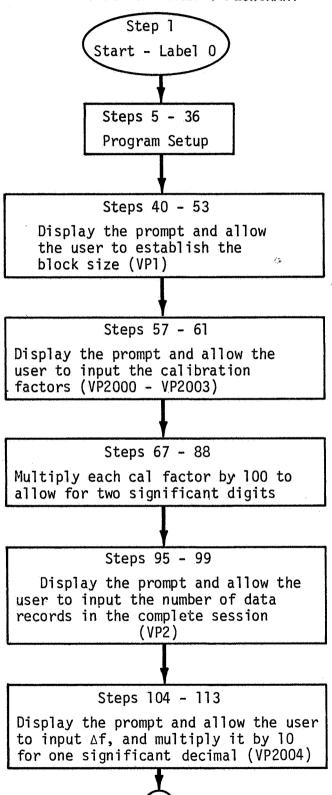
APPENDIX A

POGO SOFTWARE FLOWCHART

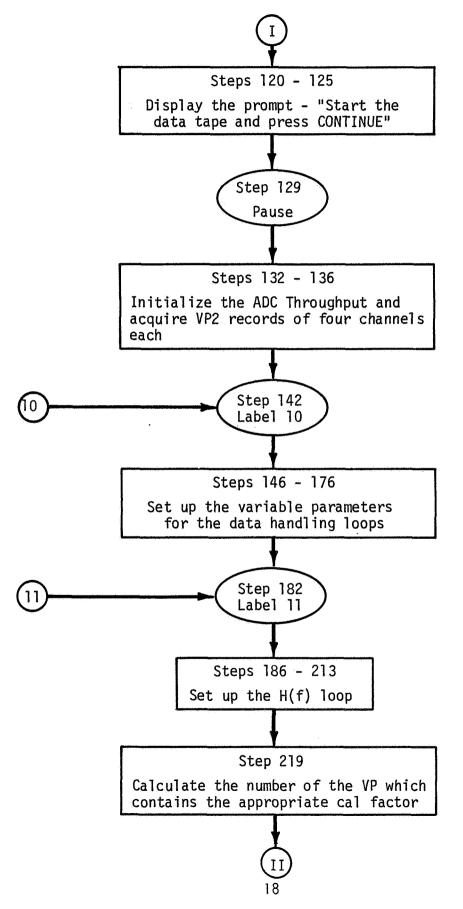
APPENDIX A

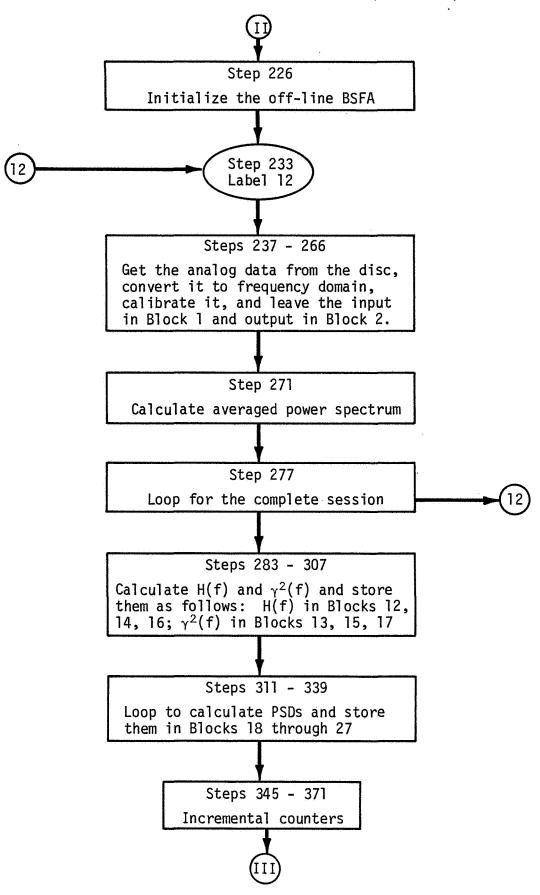
POGO SOFTWARE FLOWCHART

RATIO POGO SOFTWARE - PART 1 FLOWCHART

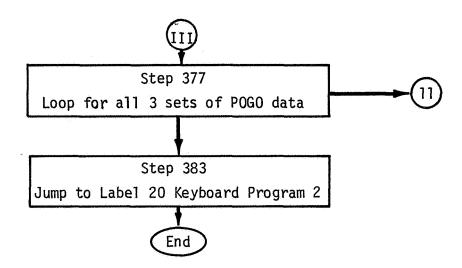


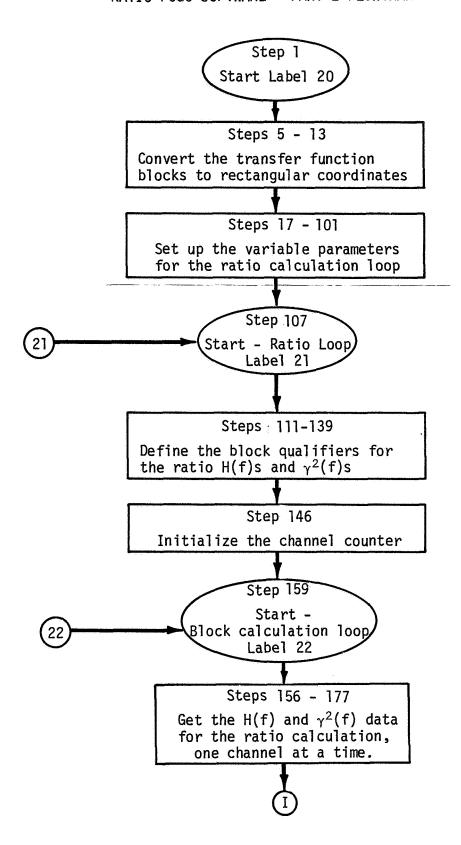
RATIO POGO SOFTWARE - PART 1 FLOWCHART (Continued)

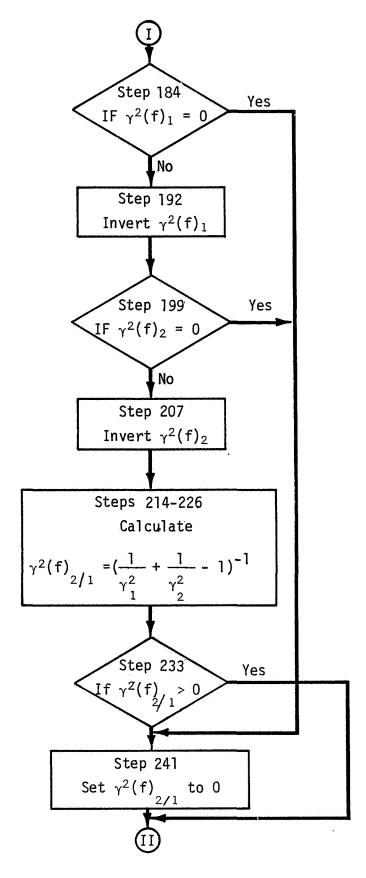


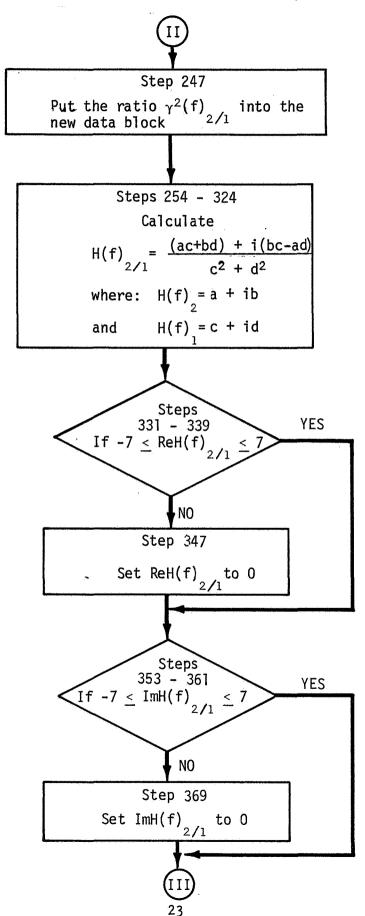


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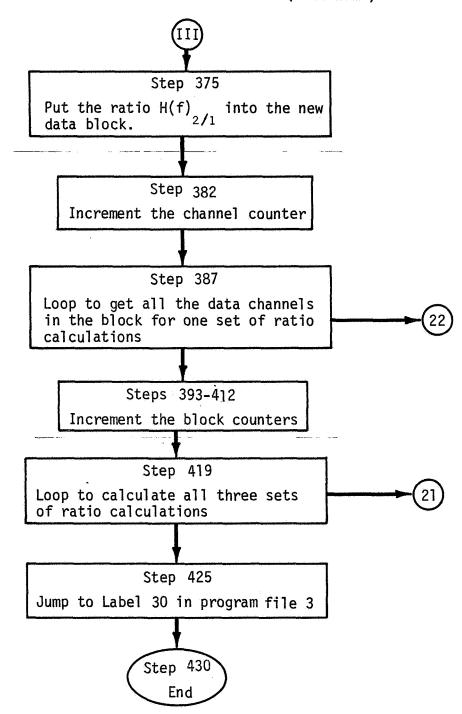




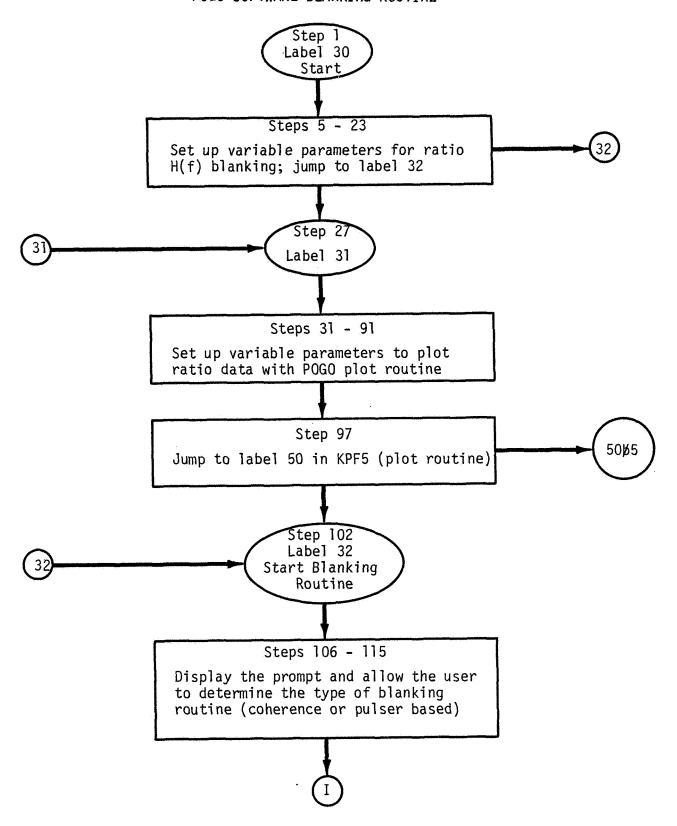


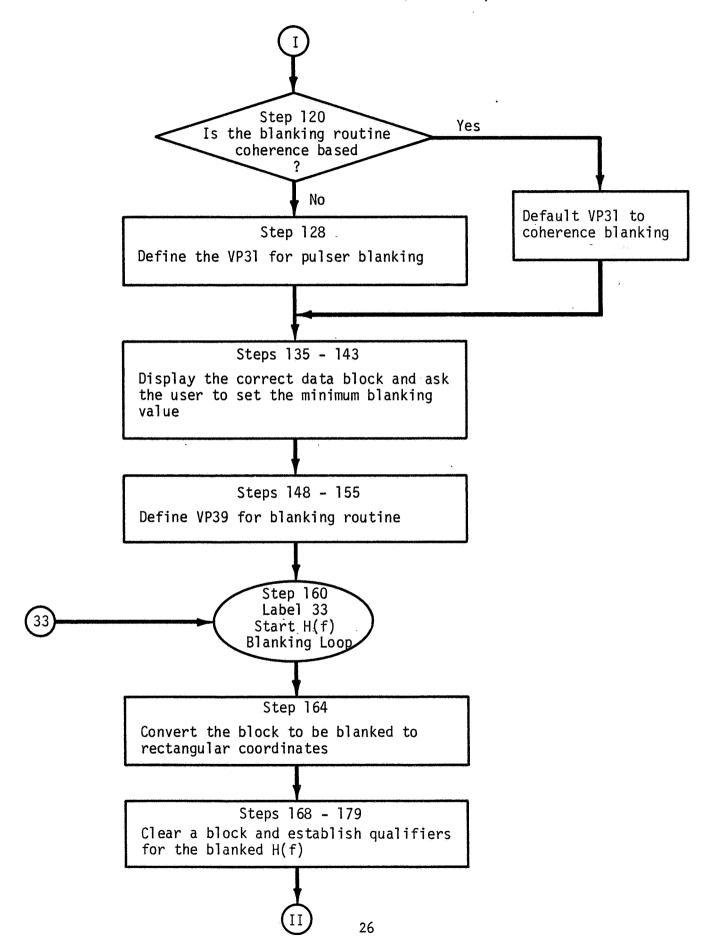


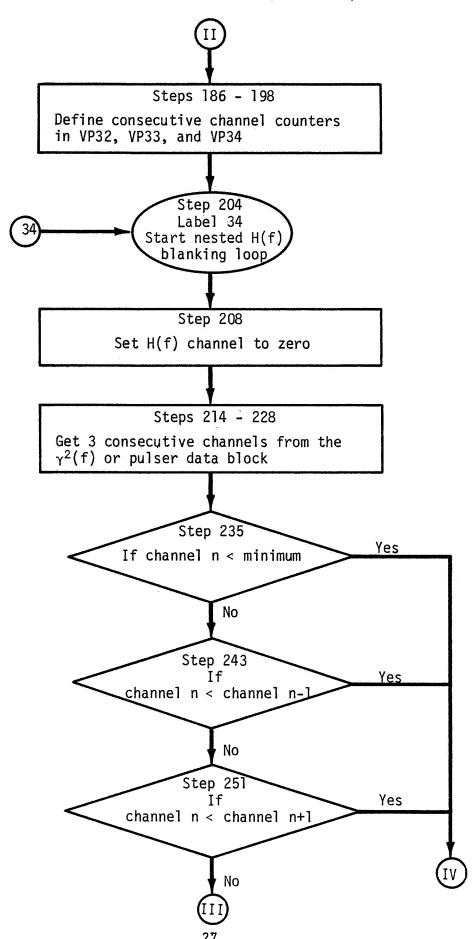
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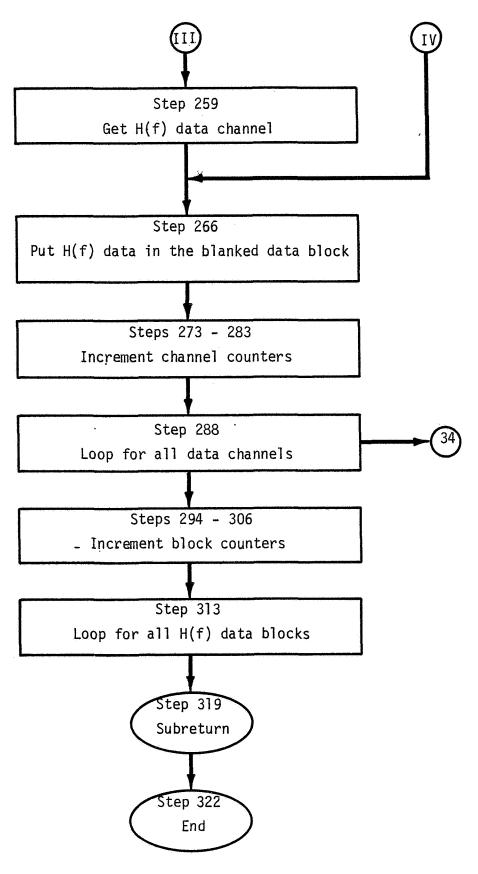


POGO SOFTWARE BLANKING ROUTINE

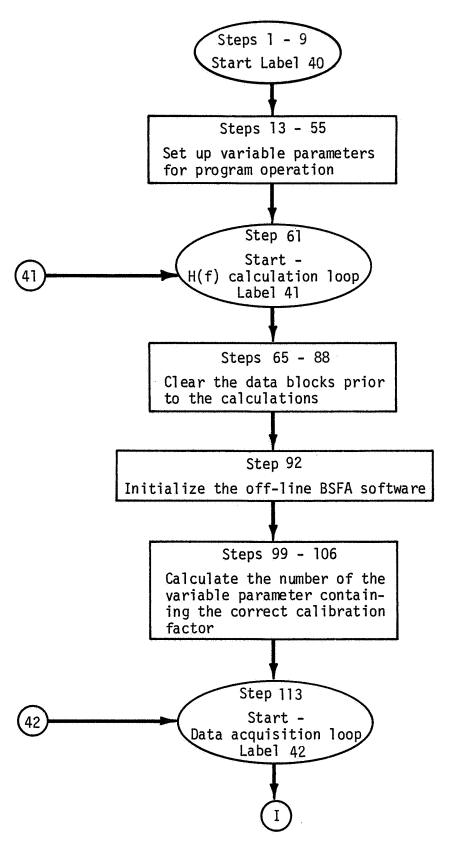


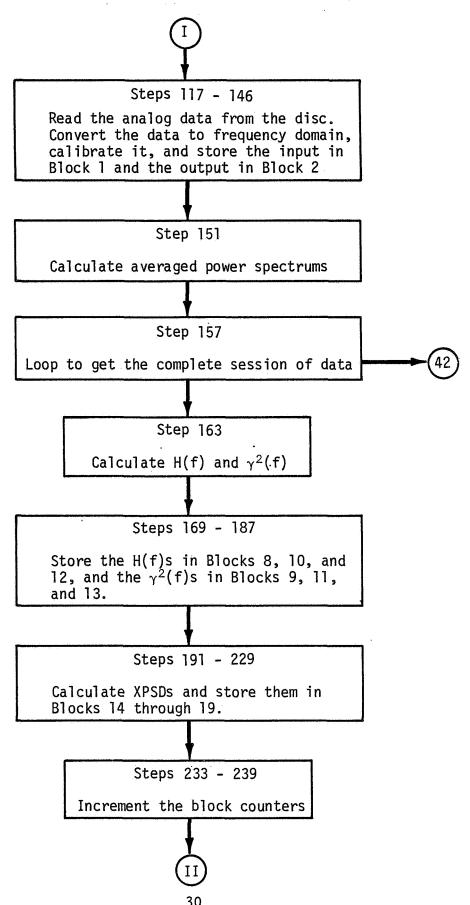




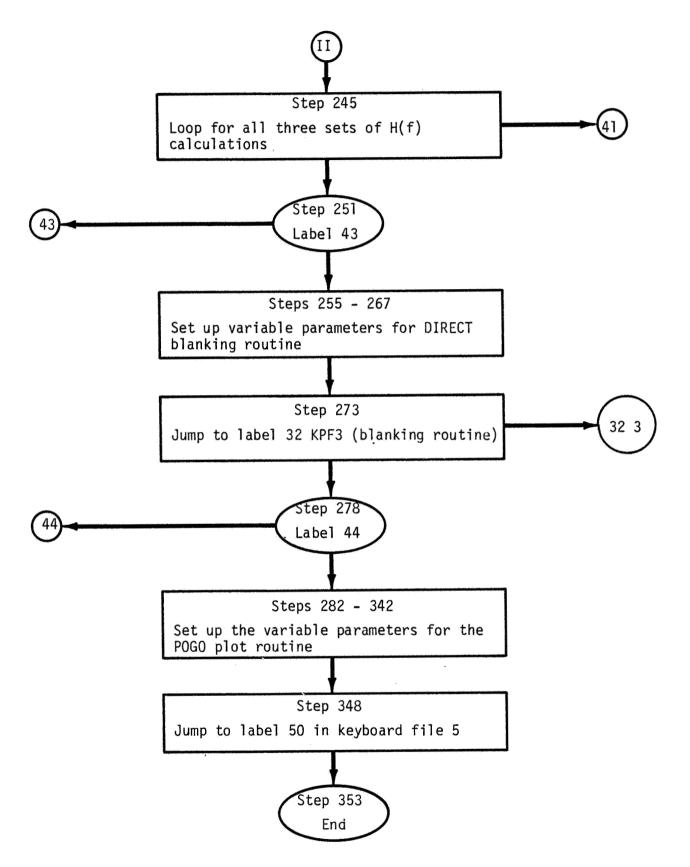


DIRECT POGO SOFTWARE FLOWCHART

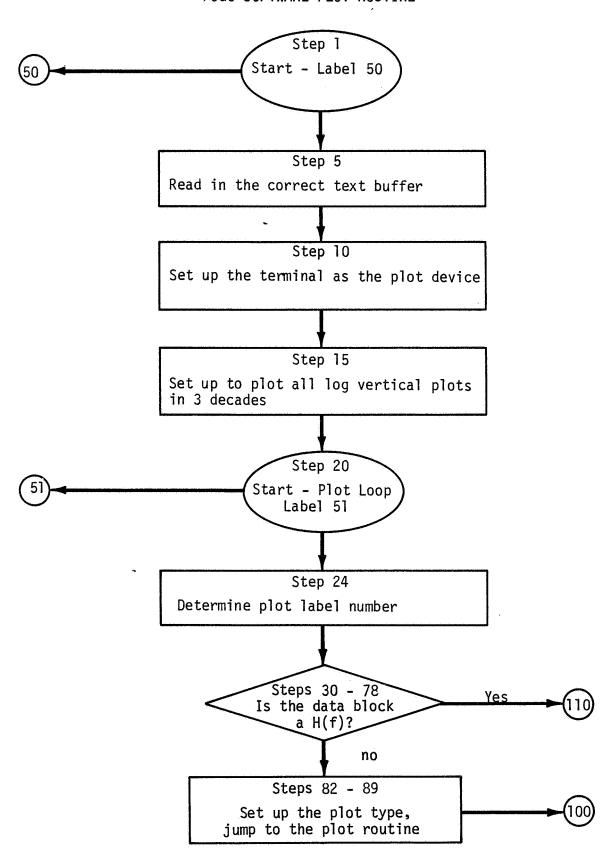


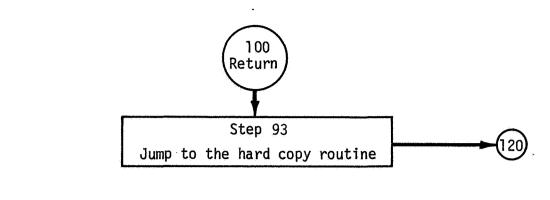


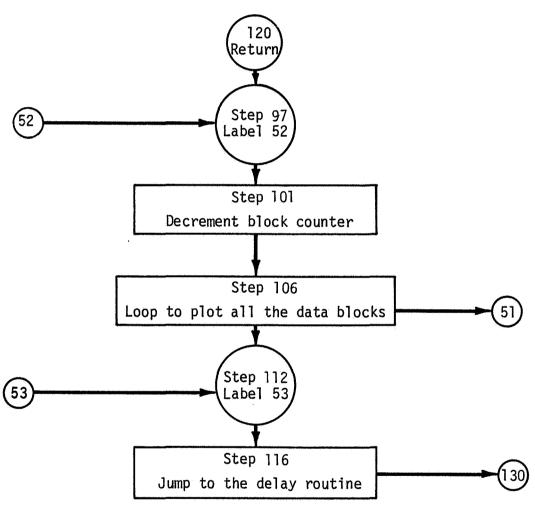
DIRECT POGO SOFTWARE FLOWCHART (Concluded)

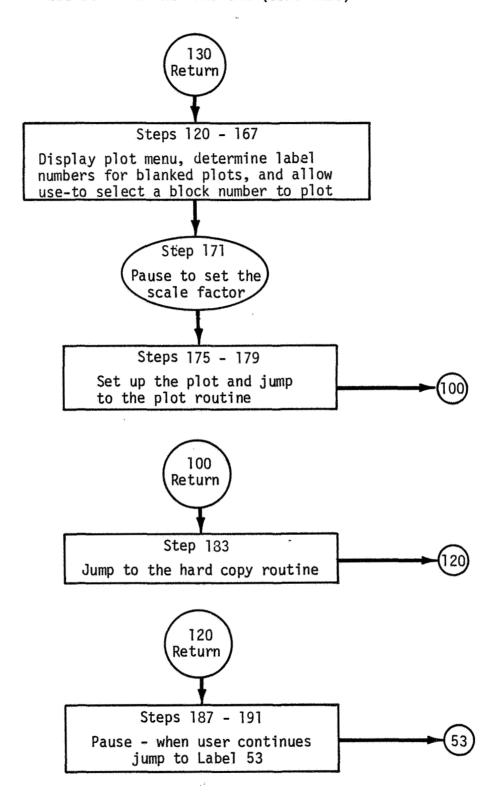


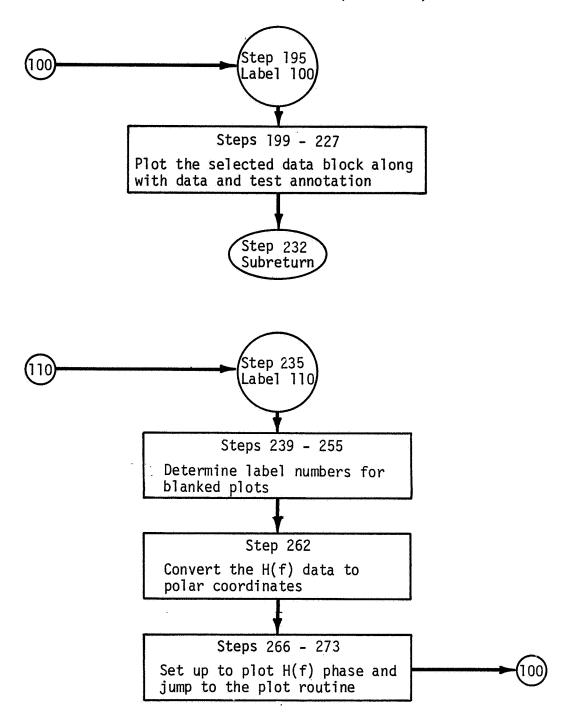
POGO SOFTWARE PLOT ROUTINE

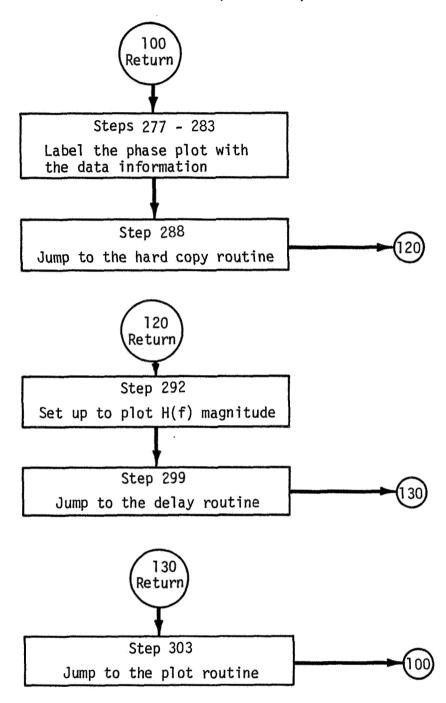


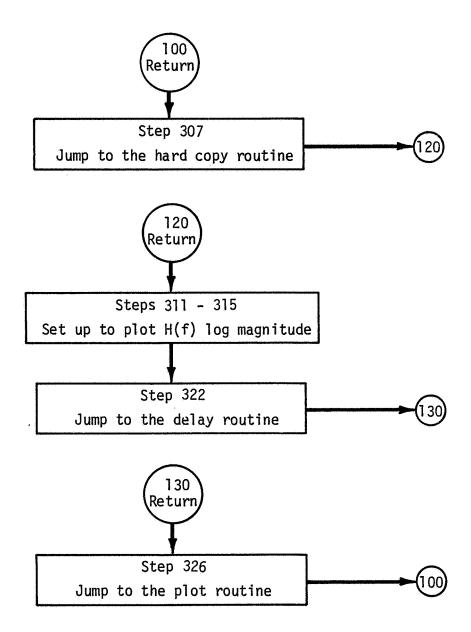


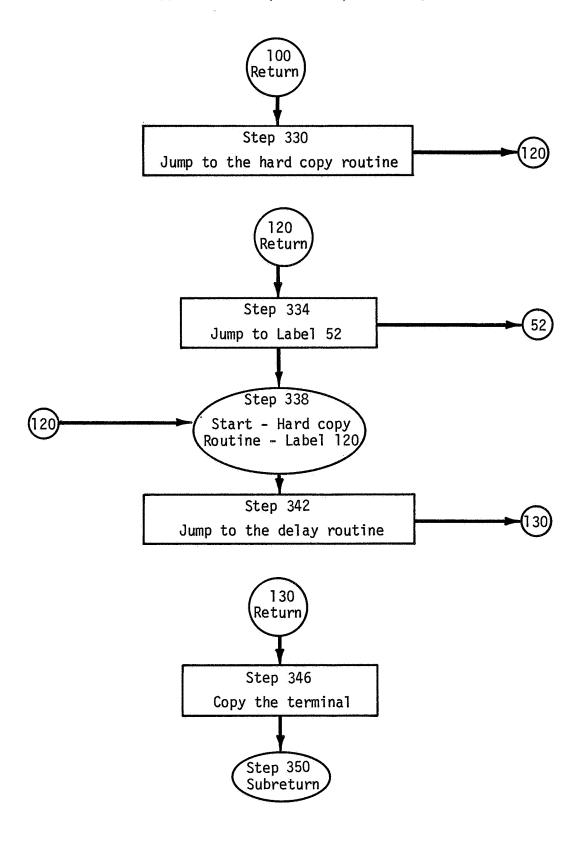


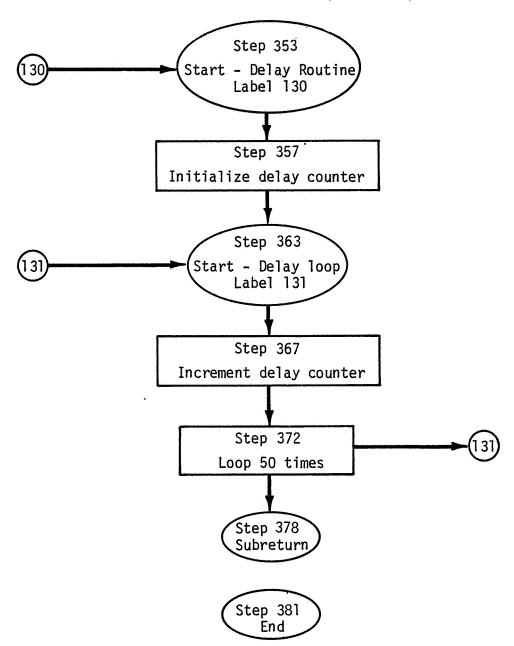












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APPENDIX B

POGO SOFTWARE LISTING

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APPENDIX B

POGO SOFTWARE LISTING

KEYBOARD FILE 1 - RATIO POGO SOFTWARE PART 1

1	L	0			Label 0
5	BS	4096			Set blocksize to 4096
9	CL				
12	CL	1			
16	CL	2			
20	CL	3			Clear blocks O through 6
24	CL	4			
28	CL	5			
32	CL	6			
36	Υ	5814			Call user program 5414 (blank terminal screen)
40	MS	34			Set text record pointer to zero (default)
44	MS	14			Read next text record (message #1)
48	Y R	1			<pre>Input from terminal VP1+ (blocksize)</pre>
53	BS	10			Set blocksize to VP1
57	MS	14		•	Read next text record (message #2)
61	Y R	2000	2003		Input from terminal VP2000, VP2001, VP2002, and VP2003 (calibration factors)
67	γ *	2000	2000D	100	VP2000 = VP2000 * 100
74	γ *	2001	2001D	100	VP2001 = VP2001 * 100
81	γ *	2002	2002D	100	VP2002 = VP2002 * 100
88	γ *	2003	2003D	100	VP2003 = VP2003 * 100
95	MS	14			Read next text record (message #3)
99	Y R	2			Input from terminal VP2 (number of data acquisition loops)
104	MS	14			Read next text record (message #4)
108	Y R	2004			Input from terminal VP2004 (Δf)

⁺This means the variable of parameter 1.

KEYBOARD FILE 1 - RATIO POGO SOFTWARE PART 1 (Continued)

113 Y *	2004	2004D	10			VP2004 = VP2004 * 10
120 MS	34	20				Set text record pointer to 20
125 MS	14					Read next text record (message #7)
129 D						Display block O (used as program pause)
132 MS	32					Set ADC Throughput File pointer to O
136 MS	22	4	2D			Write analog data to the ADC throughput file. No. of records = 2D (4 channels each)
142 L	10					Label 10
146 Y _	3	18				Set VP3 to 18
152 Y _	4	19				Set VP4 to 19
158 Y _	5	22				Set VP4 to 22
164 Y _	6	23				Set VP6 to 23
170 Y _	7	2				Set VP7 to 2
176 Y _	8	12				Set VP8 to 12
182 L	11					Label 11
186 CL						
189 CL	7					
193 CL	2					
197 CL	3					Clear blocks O through 6
201 CL	4					
205 CL	5					
209 CL	6					
213 Y _	9	3				Set VP9 to 3
219 Y A+	10	7D	1999			VP10 = VP7 + 1999
226 Y	41	0	0	0		Call user program 41; nl=0= center frequency of the band of interest, n2=0=width of the band of interest, n3=0=ADC throughput start record. (Initializes off-line BSFA)
233 L	12					Label 12
237 Y	45	2	0	7D	l o	Call user program 45; n1=2=block number where the data will be stored, n2=0=number of Hannings applied to the data, n3=VP7= channel that will be read from the disc. (Off-line BSFA)

KEYBOARD FILE 1 - RATIO POGO SOFTWARE PART 1 (Continued)

244 Y	45	1	.0	7	Call user program 45; nl=1, n2=0, n3=1
251 *	2	-10D			Multiply block 2 by VP(VP10) [†]
256:	2	100			Divide block 2 by 100
261 *	1	2000D			Multiply block 1 by VP2000
266:	1	100			Divide block l by 100
271 SP	1	2	2		Compute the average auto- and cross-power spectrums, where block nl=input data block and block nl+l=output, n2=2 specifies dual channel, n3=2 specifies double precision
277 #	12	2D	0		Loop through label 12 VP2 times
283 CH	1	2	2		Calculate transfer function data where nl=input data block, n2=2 specifies dual channel, n3=2 specifies double precision
289 X<	1				Load block 1 into block 0
293 X>	8D				Store block O into block VP8 [H(f)]
297 Y A+	8				VP8 = VP8 + 1
303 X<	2				Load block 2 into block 0
307 X>	8D				Store block 0 into VP8 $[\gamma^2(f)]$
311 L	13				Label 13
315 :	9D	2004D			Divide block VP9 by VP2004
320 *	9D	20			Multiply block VP9 by 20
325 X<	9D				Load block VP9 into block O
329 X>	-9D				Store block O into block VP(VP9)
333 Y A+	9				VP9 = VP9 + 1
339 #	13	4	0		Loop through label 13 four times
345 Y A+	4				VP4 = VP4 + 1
351 Y A+	5	5D		2	VP5 = VP5 + 2
358 Y A+	6	6D		2	VP6 = VP6 + 2
365 Y A+	7				VP7 = VP7 + 1

[†]The minus sign in front of the VP number means to use the value in the VP that is specified by the value of the VP given (i.e., the value of the VP specified by VP10).

В4

KEYBOARD FILE 1 - RATIO POGO SOFTWARE PART 1 (Concluded)

371 Y A+	8			VP8 = VP8 + 1
377 #	11	3	0	Loop through label 11 three times
383 J	20	2		Jump to label 20 in keyboard stack 2
388 .				End

KEYBOARD FILE 2 - RATIO POGO SOFTWARE PART 2

1 L	20			Label 20
5 TR	12			Convert blocks 12)
9 TR	14			Convert blocks 14 (to rectangular coordinates
13 TR	16			Convert blocks 16
17 Y _	3	3		Set VP3 to 3
23 Y _	4	6		Set VP4 to 6
29 Y _	5	7		Set VP5 to 7
35 Y _	6	14		Set VP6 to 14
41 Y _	7	12		Set VP7 to 12
47 Y _	8	16		Set VP8 to 16
53 Y _	9	14		Set VP9 to 14
59 Y _	10	16		Set VP10 to 16
65 Y _	11	12		Set VP11 to 12
71 Y _	12	13		Set VP12 to 13
77 Y _	13	15		Set VP13 to 15
83 Y :	14	10	2	VP14 = VP1/2
90 Y A+	14			VP14 = VP14 + 1
95 Y _	15	17		Set VP15 to 17
101 Y _	17	13		Set VP17 to 13
107 L	21			Label 21
111 Y TR	21	-5D	0	Get the block qualifiers from block VP(VP5) and put them in VP21 - VP25
118 Y TR	21	3D .	1	Put the block qualifiers stored in VP21 - VP25 into block VP3
125 Y TR	21	4D	1	Put the block qualifiers into block VP4
132 Y TR	21	-12D	0	Get the block qualifiers from block VP(VP12) and put them into VP21 - VP25
139 Y TR	21	5D	1	Put the block qualifiers into block VP5
146 Y _	0	0		Set VPO to O
152 L	22			Label 22
156 Y X<	3000	-4D	OD	Get the complex data from block VP(VP4), channel VPO, and put the values into complex VP3000

KEYBOARD FILE 2 - RATIO POGO SOFTWARE PART 2 (Continued)

163 Y X<	3001	-5D	OD		Get the complex data from block VP(VP5), channel VPO and put them into complex VP3001
170 Y X<	2005	12D	OD		Get the real data from block VP12, channel VPO and put it into VP2005
177 Y X<	2006	-12D	OD		Get the real data from block VP(VP12), channel VPO and put it into VP2006
184 Y IF	2005	0	7	0	If VP2005 = 0, skip seven steps
192 Y:	2005	1	2005D		VP2005 = 1/VP2005
199 Y If	2006	0	5	0	If VP2006 = 0, skip five steps
207 Y:	2006	1	2006D		VP2006 = 1/VP2006
214 Y A+	2007	2005D	2006D		VP2007 = VP2005 + VP2006
221 Y A-	2007				VP2007 = VP2007 - 1
226 Y:	2007	1	2007D		VP2007 = 1/VP2007
233 Y IF	2007	0	7	2	If VP2007 > 0, skip one step
241 Y _	2007	0			Set VP2007 to 0
247 Y X>	2007	5D	OD		Put VP2007 into the real part of block VP5, channel VP0
254 Y *	2009	2900D	2902D		VP2009 = VP2900 * VP2902 (ac)
261 Y *	2010	2901D	2903D		VP2010 = VP2901 * VP2903 (bd)
268 Y *	2011	2901D	2902D		VP2011 = VP2901 * VP2902 (bc)
275 Y *	2012	2900D	2903D		VP2012 = VP2900 * VP2903 (ad)
282 Y *	2013	2902D	2902D		$VP2013 = (VP2902)^2 (c^2)$
289 Y *	2014	2903D	2903D		$VP2014 = (VP2903)^2 (d^2)$
296 Y A+	2015	2013D	2014D		$VP2015 = VP2013 + VP2014 (c^2+d^2)$
303 Y A+	2016	2009D	2010D		VP2016 = VP2009 + VP2010 (ac+bd)
310 Y A-	2017	2011D	2012D		VP2017 = VP2009 - VP2012 (bc-ad)
317 Y:	2904	2016D	2015D		$VP2904 = VP2016/VP2015 \left[\frac{(ac+bd)}{(c^2+d^2)} \right]$
324 Y :	2905	2017D	2015D		VP2905 = VP2017/VP2015 $i \left[\frac{(bc-ad)}{(c^2+d^2)} \right]$
331 Y IF	2904	7	1	2	If VP2094 > 7, skip one step
339 Y IF	2904	- 7	1	1	If VP2904 \geq -7, skip one step
347 Y _	2904	0			Set VP2904 to 0

KEYBOARD FILE 2 - RATIO POGO SOFTWARE PART 2 (Concluded)

353 Y IF	2905	7	1	2	If VP2905 > 7, skip one step
361 Y IF	2905	- 7	1	1	If VP2905 \geq -7, skip one step
369 Y _	2905	0			Set VP2905 to 0
375 Y X>	3002	4D	OD		Put complex VP3002 into block VP4, channel VP0
382 Y A+	0				VPO = VPO + 1
387 #	22	14D	0		Loop through label 22 VP14 times
393 Y A+	3	•			VP3 = VP3 + 1
398 Y A+	4	4D	2		VP4 = VP4 + 2
405 Y A+	5	5D	2		VP5 = VP5 + 2
412 Y A+	12	12D	2		VP12 = VP12 + 2
419 #	21	3	0		Loop through label 21 three times
425 J	30	3			Jump to label 30, keyboard stack 3
430 .					End

KEYBOARD FILE 3 - RATIO POGO SOFTWARE PART 3

1 L	30				Label 30
5 Y _	31	7			Set VP31 to 7
11 Y _	35	6			Set VP35 to 6
17 Y _	36	3			Set VP36 to 3
23 J	32				Jump to label 32
27 L	31				Label 31
31 Y _	3	1			Set VP3 to 1
37 Y _	4	27			Set VP4 to 27
43 Y	5	16			Set VP5 to 16
49 Y _	6	14			Set VP6 to 14
55 Y _	7	12			Set VP7 to 12
61 Y _	8	10			Set VP8 to 10
67 Y _	9	8			Set VP9 to 8
73 Y _	10	6			Set VP10 to 6
79 Y _	11	25			Set VP11 to 25
85 Y _	12	24			Set VP12 to 24
91 Y _	13	125			Set VP13 to 125
97 J	50	5			Jump to label 50 in Keyboard File 5
102 L	32				Label 32
106 MS	34	82			Set the text record pointer to 82
111 MS	14				Read next text record (type of blanking routine
115 Y R	30				Input from terminal VP30
120 Y IF	30	0	1	2	IF VP30>0, skip l step
128 Y A+	31	31D	11		VP31 = VP31 + 11
135 X<	31D				Load blanking block (VP31)
139 MS	14				Read the next text record (minimum blanking value)
143 Y R	2030				Input from terminal VP2030
148 Y :	39	10D	2		VP39 = VP1/2
155 Y A-	39				VP39 = VP39 - 1
160 L	33				Label 33
164 TR	35D				

KEYBOARD FILE 3 - RATIO POGO SOFTWARE PART 3 (Concluded)

168 CL	36D				Clear block BP36
172 Y TR	21	35D	0		Get the block qualifiers from block VP35 and put them into VP21 - VP25
179 Y TR	21	36D	1		Put the block qualifiers stored in VP21-VP25 into block VP36
186 Y _	32	0			Set VP32 to 0
192 Y _	33	1			Set VP33 to 1
198 Y _	34	2			Set VP34 to 2
204 L	34				Label 34
208 Y _	3000	0			Set VP3000 to 0
214 Y X<	2032	31D	32D		Get the real data from block VP31, channel VP32 and store it in VP2032
221 Y X<	2033	31D	33D		Get the real data from block BP31, channel VP33 and store it in VP2033
228 Y X<	2034	310	34D		Get the real data from block VP31, channel VP34 and store it in VP2034
235 Y IF	2033	2030D	3	-2	If VP2033 <vp2030, 3="" skip="" steps<="" td=""></vp2030,>
243 Y IF	2033	2032D	2	-2	lf VP2033 <vp2032, 2="" skip="" steps<="" td=""></vp2032,>
251 Y IF	2033	2034D	1	-2	If VP2033 <vp2034, 1="" skip="" step<="" td=""></vp2034,>
259 Y X<	3000	35D	33D		Get the complex data from block VP35, channel VP33 and store it in VP3000
266 Y X>	3000	36D	33D		Put the complex data stored in VP3000 into block VP36, channel VP33
273 Y A+	32				VP32 = VP32 + 1
278 Y A+	33				VP33 = VP33 + 1
283 Y A+	34				VP34 = VP34 + 1
288 #	34	39D			Loop through label 34 VP39 times
294 Y A+	35	35D	2		VP35 = VP35 + 2
301 Y A+	36				VP36 = VP36 + 1
306 Y A+	31	31D	30D		VP31 = VP31 + VP30
313 #	33	3			Loop through label 33 three times
319 <					Subreturn
322.					End

KEYBOARD FILE 4 - DIRECT POGO SOFTWARE

1 L	40				Label 40
5 X<	18				Load block 18 into block 0
9 X>	20				Store block 0 into block 20
13 Y	3	8			Set VP3 to 8
19 Y _	4	14			Set VP4 to 14
25 Y _	8	3			Set VP8 to 3
31 Y _	10	4			Set VP10 to 4
37 Y _	12	4			Set VP12 to 4
43 Y _	14	2			Set VP14 to 2
49 Y _	16	3			Set VP16 to 3
55 Y _	18	2			Set VP18 to 2
61 L	41				Label 41
65 CL					
68 CL	1				
72 CL	2				
76 CL	3				Clear blocks O through 6
80 CL	4				
84 CL	5				
88 CL	6				
92 Y	41	0	0	0	Call User Program 41, where nl=n2=n3=0 (Initialize off-line BSFA)
99 Y A+	5	-4D	1999		VP5 = 1999 + VP(VP4)
106 Y A+	7	-3D	1999		VP7 = 1999 + VP(VP3)
113 L	42				Label 42
117 Y	45	2	0	- 3D	Call User Program 45; n1=2, n2=0, n3=VP(VP3) (off-line BSFA)
124 Y	45	Ţ	0	-4D	Call User Program 45; n1=1, n2=0, n3=VP(VP4)
131 *	2	-7D			Multiply block 2 by VP(VP7)
136:	2	100			Divide block 2 by 100
141 *	1	-5D			Multiply block 1 by VP(VP5)
146:	1	100			Divide block 1 by 100
151 SP	1	2	2		Calculate averaged 2-channel- double precision power spectrum

KEYBOARD FILE 4 - DIRECT POGO SOFTWARE (Continued)

157 #	42	2D	0	Loop through label 42 VP2 times
163 CH	1	2	2	Calculate $H(f)$ and $\gamma^2(f)$ from the averaged power spectrum data
169 X<	1			Load block l into block O [H(f)]
173 X>	3D			Store block O into block VP3
177 Y A+	3			VP3 = VP3 + 1
183 X<	2			Load block 2 into block 0 $[\gamma^2(f)]$
187 X>	3D			Store block O in block VP3
191 :	5 2	2004D		Divide block 5 by VP2004
196 *	5	20		Multiply block 5 by 20
201 :	6 2	2004D		Divide block 6 by VP2004
206 *	6	20		Multiply block 6 by 20
211 X<	5			Load block 5 into block 0
215 X>	4D			Store block 0 in block VP4
219 Y A+	4			VP4 = VP4 + 1
225 X<	6			Load block 6 into block 0
229 X>	4D			Store block O into block VP4
233 Y A+	3			VP3 = VP3 + 1
239 Y A+	4			VP4 = VP4 + 1
245 #	41	3	0	Loop through label 41 three times
251 L	43			Label 43
255 Y _	31	9		Set VP31 to 9
261 Y _	35	8		Set VP35 to 8
267 Y _	36	5		Set VP36 to 5
273 J	32	3		Jump to label 33 in Keyboard File 3
278 L	44			Label 44
282 Y _	3	2		Set VP3 to 2
288 Y _	4	19		Set VP4 to 19
294 Y _	5	12		Set VP5 to 12
300 Y _	6	10		Set VP6 to 10
306 Y _	7	8		Set VP7 to 8
312 Y _	8	8		Set VP8 to 8
318 Y _	9	8		Set VP9 to 8

B12

KEYBOARD FILE 4 - DIRECT POGO SOFTWARE (Concluded)

324 Y _	10	8	Set VP10 to 8
330 Y _	11	15	Set VP11 to 15
336 Y _	12	58	Set VP12 to 58
342 Y _	13	150	Set VP13 to 150
348 J	50	5	Jump to lable 50 in Keyboard File 5 (Plot Routine)
353 .			End

KEYBOARD FILE 5 - POGO PLOT ROUTINE

1	L	50					Label 50
5	Υ	5838	3D				Call User Program 5838; nl=VP3 (Read text buffer VP3 into core)
10	Y	5821	6				Call User Program 5821; nl=6 (Set up the terminal as the plot device)
15	Υ	5865	3				Call User Program 5865; n1=3 (Set log plots to plot 3 decades, vertical scale)
20	L	51					Label 51
24	Υ _	26	4D				Set VP26 to the value of VP4
30	Y IF	4	5D	5	()	If VP4 = VP5, skip five steps
38	Y IF	4	6D	4	C)	If VP4 = VP6, skip four steps
46	Y IF	4	7D	.3	()	If VP4 = VP7, skip three steps
54	Y IF	4	8D	2	()	If VP4 = VP8, skip two steps
62	Y IF	4	9D	1	(כ	If VP4 = VP9, skip one step
70	Y IF	4	10D	1	2	2	If VP4 > VP10, skip one step
78	J	110					Jump to label 110
82	Y	5809	0.	0	-0		Call User Program 5809; nl=0, n2=0, n3=0 (Set up to plot real/magnitude, linear horizontal scale, scale switch at 12 o'clock)
89	J	100					Jump to label 100
93	J	120					Jump to label 120
97	L	52					Label 52
101	Y A-	4					VP4 = VP4 - 1
106	#	51	11D	0			Loop through label 51 VPll times
112	L	53					Label 53
116	J	130					Jump to label 130
120	Υ	5814					Call User Program 5814 (Blank the terminal screen)
124	MS	34	12D				Set the text record pointer to VP12
129	MS	14					Read the next message (plot menu)
133	ΥR	- 4					Input VP4 (data block number to be plotted

KEYBOARD FILE 5 - POGO PLOT ROUTINE (Continued)

138	Υ	26	4D				Set VP26 to the value of VP4
144	Y IF	4	10D		2	1	If VP4 \geq VP10, skip 2 steps
152	Y IF	30	0		1	0	<pre>If VP30 = 0, skip 1 step</pre>
160	Y A+	26	26D		30		VP26 = VP26 + 30
167	MS	14					Read the next message (Set the scale and press "CONTINUE")
171	D	4D					Display block VP4
175	Y	5809					Call User Program 5809; nl=n2= n3=default (Set up the plot according to the display switches)
179	J	100					Jump to label 100
183	J	120					Jump to label 120
187	D	4D					Display block VP4
191	J	53					Jump to label 53
195	L	100					Label 100
199	Υ	5814					Call User Program 5814
203	Υ	5829					Call User Program 5829 (Plot the full data block)
207	Υ	5815	4D				Call User Program 5815; nl=VP4 (Plot the data from block VP4)
212	Υ	5816					Call User Program 5816 (Plot the defaulted axis)
216	Y	5817	26D				Call User Program 5817; n1=VP26 (Label the vertical axis with text buffer message VP4 and the horizontal axis with the default label)
221	Υ	5808	975	600			Call User Program 5808; nl=970, n2=600 (Position the cursor to y=97.0% of the vertical plot window and x=60.0% of the horizontal plot window)
227	Ý	5819	1				Write text buffer message #1
232	<						Subreturn
235	L	110					Label 110
239	Y IF	4	1.0D		2	1	If VP4 > VP10, skip 2 steps
247	YIF	30	0		1	0	If VP30 = 0, skip l step

255	Y A+	26	26D	30		VP26 = VP26 + 30
262	TP	4D				Convert block VP4 to polar coordinates
266	Υ	5809	1	0	0	Call User Program 5809; nl=1, n2=0, n3=0 (Set up to plot imaginary/phase, linear horizontal, scale switch to 12 o'clock)
273	J	100				Jump to label 100
277	Υ	5808	970	13D		Call User Program 5808; nl=970, n2=VP13
283	Υ	5819	26D			Call User Program 5819; n1=VP26
288	J	120				Jump to label 120
292	Y	5809	0	0	0	Call User Program 5809; nl=0, n2=0, n3=0
299	J	130				Jump to label 130
303	J	100				Jump to label 100
307	J	120				Jump to label 120
311	TL	4D				Convert block VP4 to log polar coordinates
315	Υ	5809	0	0	0	Call User Program 5809; nl=0, n2=0, n3=0
322	J	130				Jump to label 130
326	J	100				Jump to label 100
330	J	120				Jump to label 120
334	J	52				Jump to label 52
338	L	120				Labe1 120
342	J	130				Jump to label 130
346	Y	5820				Call User Program 5820 (Hard copy the terminal)
350) <					Subreturn
353	3 L	130				Label 130
357	γ Υ _	19	1			Set VP19 to 1
363	3 L	131				Label 131
367	7 Y A+	- 19				VP19 = VP19 + 1
372	2 #	131	50	0		Loop through label 131 fifty times
378	3 <					Subreturn
387	١.,					End

APPENDIX C

POGO SOFTWARE TEXT RECORDS (FILE 4a)

APPENDIX C

POGO SOFTWARE TEXT RECORDS (FILE 4a)

Line #	Contents							
	Message #1							
0								
1 2 3 4 5 6 7	This is a 5451C program, written for POGO data analysis. The program reads 4 analog channels simultaneously and writes them directly to the disc via the ADC Throughput. The time domain data is then called from the disc and H(f)s calculated re. Pulser. H(f)s across devices are calculated by ratios.							
7 8 9	Setup the ADC for the desired frequency resolution (Delta f), and input signal-to-noise ratio. Then, enter Blocksize. (INTEGER LE 1024) /*							
	Message #2							
10 11	<pre>Enter a calibration factor for each channel. (4 - FLOATING POINT) /*</pre>							
	Message #3							
12 13	<pre>Enter the number of data acquisition loops: (INTEGER) /*</pre>							
	- Message #4							
14 15	Enter Delta f as specified by the ADC. (FLOATING POINT) $/*$							
	Message #7							
20 21	Start the data tape. Press "CONTINUE." /*							

```
C2
```

Line

Contents

Message #8 RATIO POGO DATA PLOT MENU

24	The program output is located in core memory as follows:
25 26	BLOCK# DATA
27 28 29 30 31 32 33 34 35 36 37 38 39 40 41 42 44 45 47 48 49 50 51 55 55 55	3 Weighted H(f) HPOP/LPOP 4 Weighted H(f) MCC/HPOP 5 Weighted H(f) MCC/LPOP 6 H(f) HPOP/LPOP 7 Coh(f) " 8 H(f) MCC/HPOP 9 Coh(f) " 10 H(f) MCC/LPOP 11 Coh(f) " 12 H(f) LPOP/Pulser 13 Coh(f) " 14 H(f) HPOP/Pulser 15 Coh(f) " 16 H(f) MCC/Pulser 17 Coh(f) " 18 PSD Pulser 19 PSD LPOP 20 PSD HPOP 21 PSD MCC 22 Re XPSD LPOP/Pulser 23 Im XPSD " 24 Re XPSD HPOP/Pulser 25 Im XPSD " 26 Re XPSD MCC/Pulser 27 Im XPSD " Please enter the Block# you wish to plot. /*
56 57	Set the scale and press "CONTINUE." /*

```
Line #
```

Contents

Message #10

DIRECT POGO DATA PLOT MENU

```
58
        The program output is located in core as follows:
59
60
             BLOCK#
                               DATA
61
                     Weighted H(f) HPOP/LPOP
                5
62
                     Weighted H(f) MCC/HPOP
Weighted H(f) MCC/LPOP
63
                6
64
                7
                8
65
                      H(f)
                              HPOP/LPOP
                      Coh(f)
66
                9
               10
                      H(f)
67
                               MCC/HPOP
68
               11
                      Coh(f)
69
               12
                      H(f)
                               MCC/LPOP
               13
70
                      Coh(f)
               14
                      Re XPSD HPOP/LPOP
71
72
               15
                      Im XPSD
                      Re XPSD MCC/HPOP
73
               16
74
               17
                      Im XPSD
                      Re XPSD MCC/LPOP
75
               18
               19
                      Im XPSD
76
77
        Please enter the block # you wish to plot.
78
79
        /*
                                    Message #11
80
        Set the scale and press "CONTINUE".
81
        /*
                                    Message #12
82
                        Coherence blanking (enter 2)
         Do you want:
83
                        Pulser blanking (enter 0)?
         /*
84
                                    Message #13
85
         Enter the minimum blanking value (floating point).
         /*
86
```

APPENDIX D

POGO SOFTWARE TEXT BUFFERS (FILE 4b)

APPENDIX D

POGO SOFTWARE TEXT BUFFERS (FILE 4b)

Text Buffer #1

RATIO POGO PLOT LABELS

```
01
(TEST ID)
13
 HPOP/LPOP Ratio H(f)
 Pulser Blanked
04
 MCC/HPOP Ratio H(f)
 Pulser Blanked
 MCC/LPOP Ratio H(f)
 Pulser Blanked
 HPOP/LPOP Ratio H(f) - Polar
07
 HPOP/LPOP Ratio Coh(f)
80
 MCC/HPOP Ratio H(f) - Polar
09
 MCC/HPOP Ratio Coh(f)
  MCC/LPOP Ratio H(f) - Polar
 MCC/LPOP Ratio Coh(f)
```

Text Buffer #1 (Continued)

```
12
 LPOP/Pulser H(f) - Polar
 LPOP/Pulser Coh(f)
14
 HPOP/Pulser H(f) - Polar
15
 HPOP/Pulser Coh(f)
 MCC/Pulser H(f) - Polar
17
 MCC/Pulser Coh(f)
18
 Pulser PSD
LPOP PSD
20
 HPOP PSD
21
  MCC PSD
 LPOP/Pulser Real XPSD
 LPOP/Pulser Imag XPSD
  HPOP/Pulser Real XPSD
```

Text Buffer #1 (Concluded)

```
HPOP/Pulser Imag XPSD
26
 MCC/Pulser Real XPSD
27
 MCC/Pulser Imag XPSD
33
  HPOP/LPOP Ratio H(f)
  Coherence Blanked
34
  MCC/HPOP Ratio H(f)
  Coherence Blanked
35
  MCC/LPOP Ratio H(f)
  Coherence Blanked
                                 Text Buffer #2
                             DIRECT POGO PLOT LABELS
01
(TEST ID)
/*
05
  HPOP/LPOP Direct H(f)
  Pulser Blanked
 /*
 06
  MCC/HPOP Direct H(f)
Pulser Blanked
 /*
  MCC/LPOP Direct H(f)
Pulser Blanked
```

Text Buffer #2 (Continued)

```
80
 HPOP/LPOP Direct H(f) - Polar
09
 HPOP/LPOP Direct Coh(f)
 MCC/HPOP Direct H(f) - Polar
11
 MCC/HPOP Direct Coh(f)
12
 MCC/LPOP Direct H(f) - Polar
 MCC/LPOP Direct Coh(f)
14
  HPOP/LPOP Direct Real XPSD
15
 HPOP/LPOP Direct Imag XPSD
 MCC/HPOP Direct Real XPSD
17
  MCC/HPOP Direct Imag XPSD
18
  MCC/LPOP Direct Real XPSD
/*
19
  MCC/LPOP Direct Imag XPSD
/*
  HPOP/LPOP Direct H(f)
  Coherence Blanked
```

Text Buffer #2 (Concluded)

```
36
MCC/HPOP Direct H(f)
Coherence Blanked
/*

37
MCC/LPOP Direct H(f)
Coherence Blanked
/*
```

APPENDIX E

POGO SOFTWARE SAMPLE OUTPUT

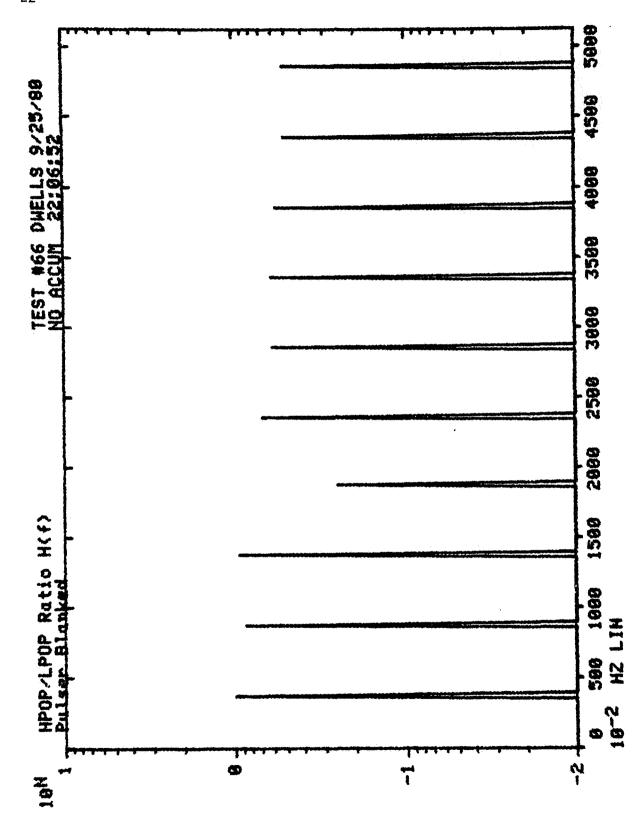
This is a 5451C program, written for POGO data analysis. Ine program reads 4 analog channels simultaneously and writes them directly to the disc via the ADC Throughbut. The time domain data is then called from the disc and H(f)s calculated re. Pulser. H(f)s across devices are Setup the ADC for the desired frequency resolution (Delta f), and input signal-to-noise ratio. Then, enter Blocksize. (INTEGER LE 1024) 28 JANUARY

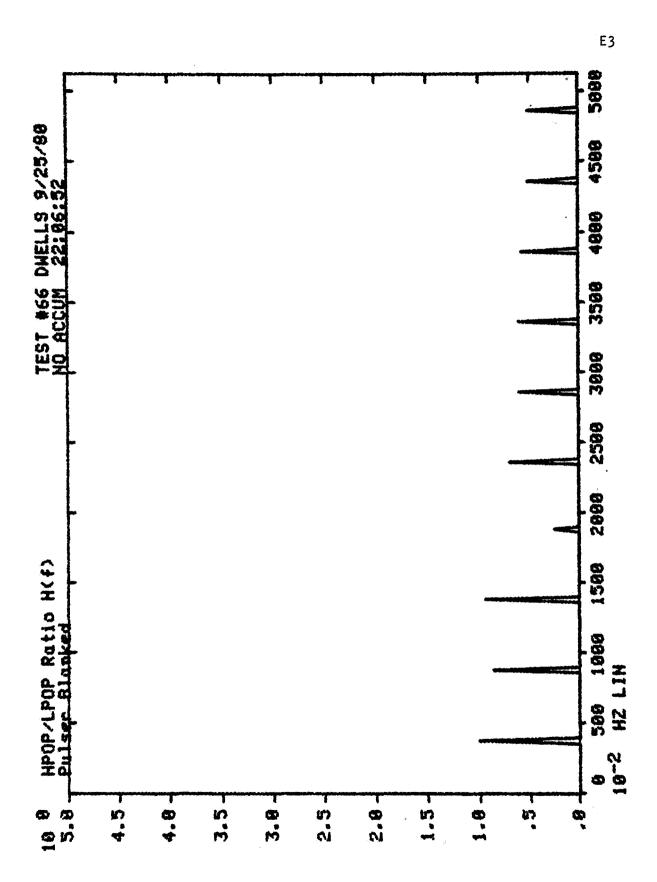
(4 - FLOATING POINT) Enter a calibration factor for each channel. 12.4 16.36 22.6 16.83

(INTEGER) Enter the number of data acquisition loops. CFLOATING POINT> Enter Delta f as specified by the ADC. 8.2

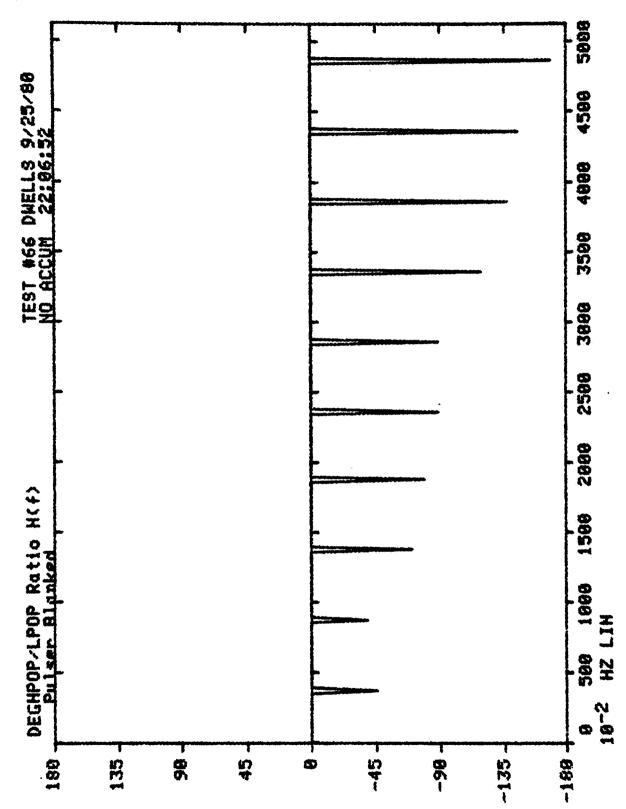
Start the data tape. Press "CONTINUE".

Do you want: Coherence blanking (enter 2) Pulser Blanking (enter 8) Enter the minimum blanking value. (Floating Point) 8.8837

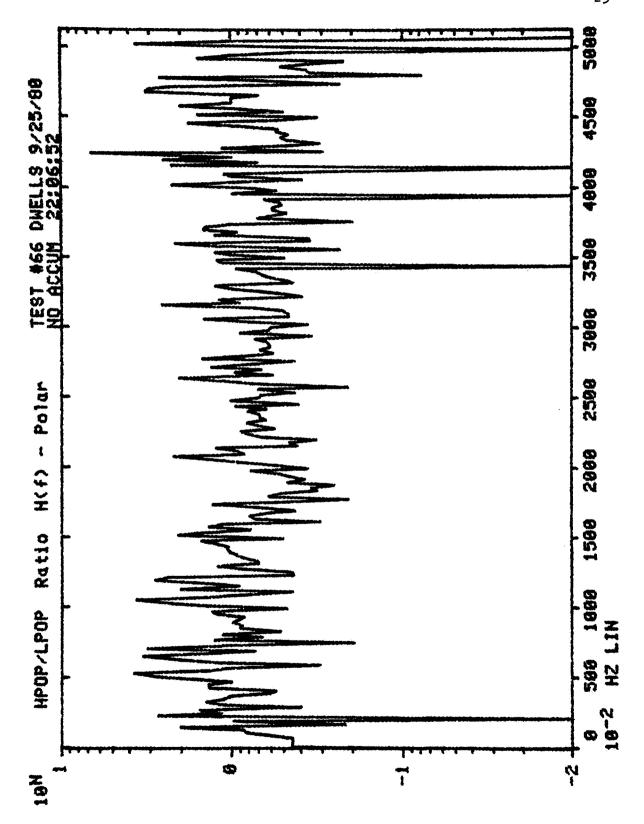


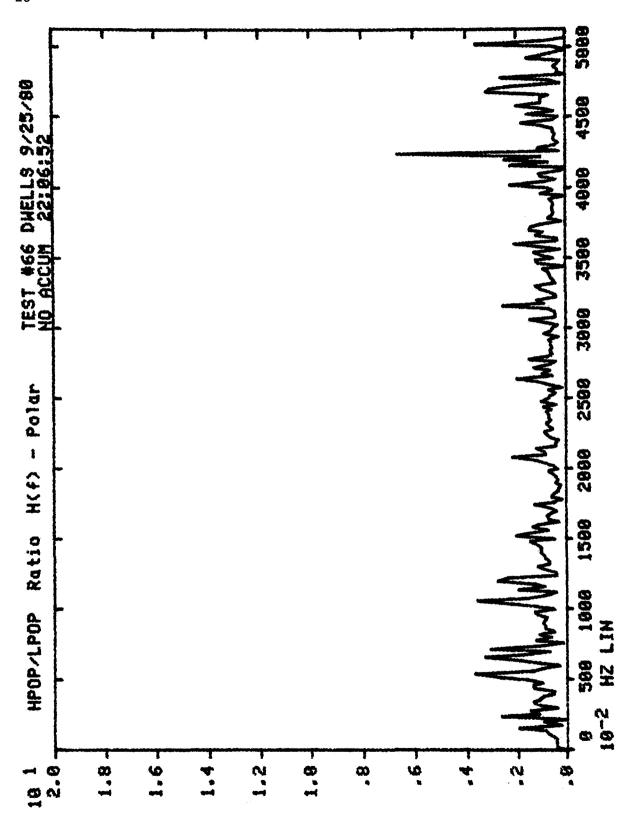


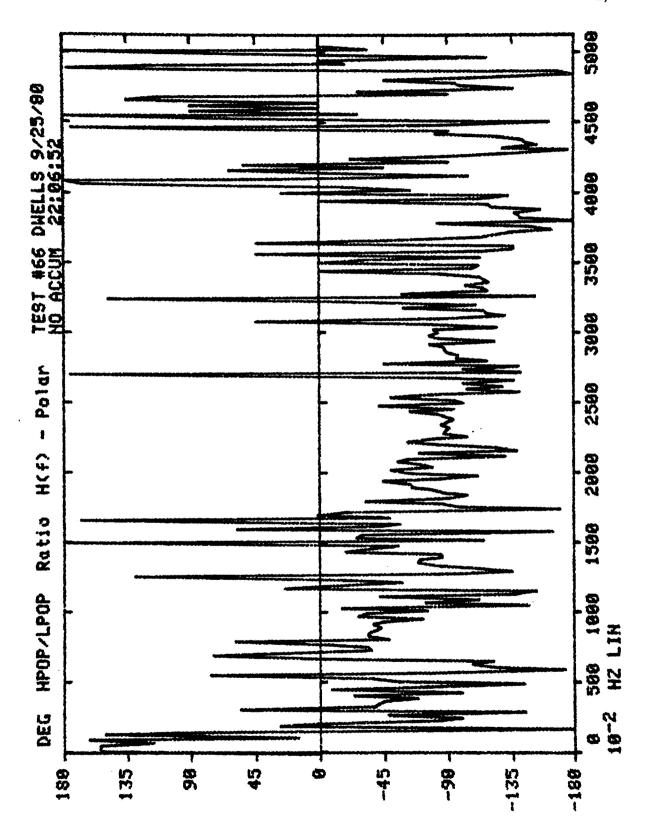




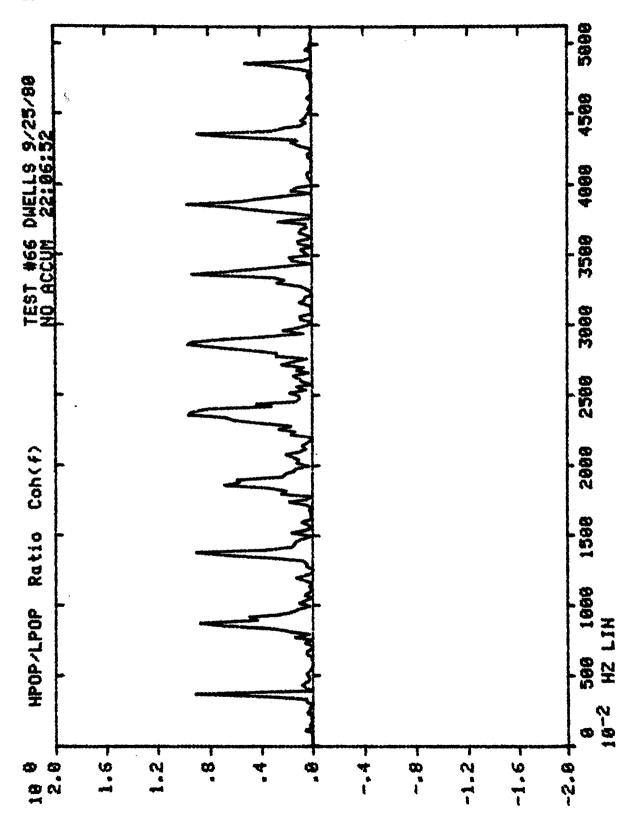




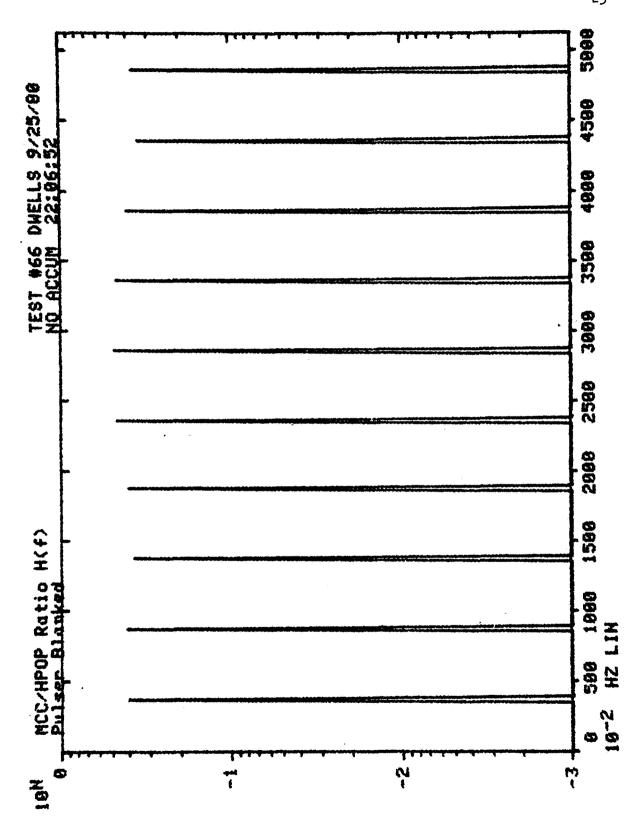




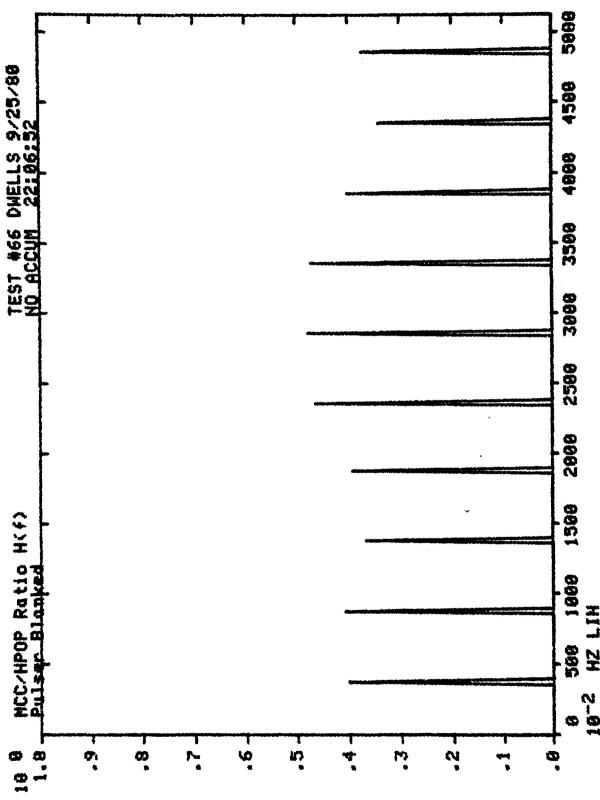




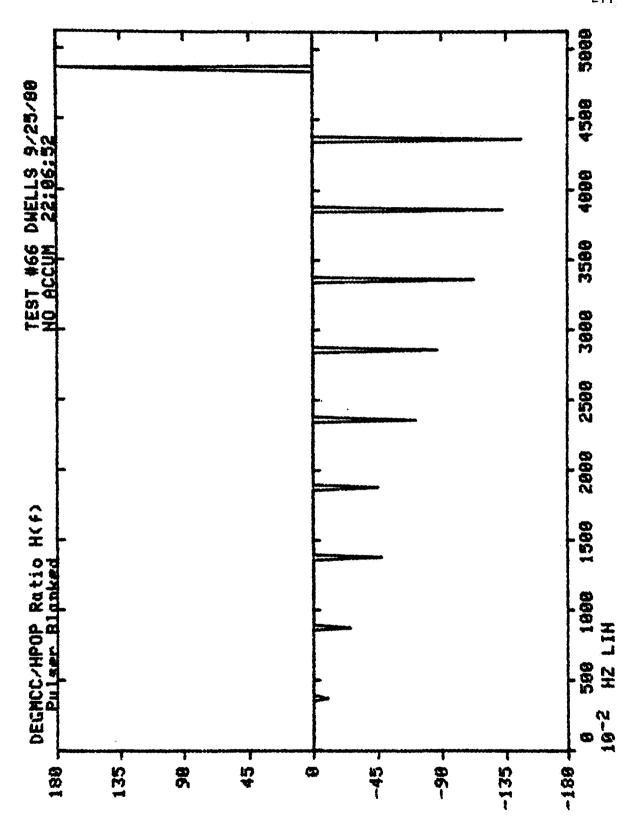


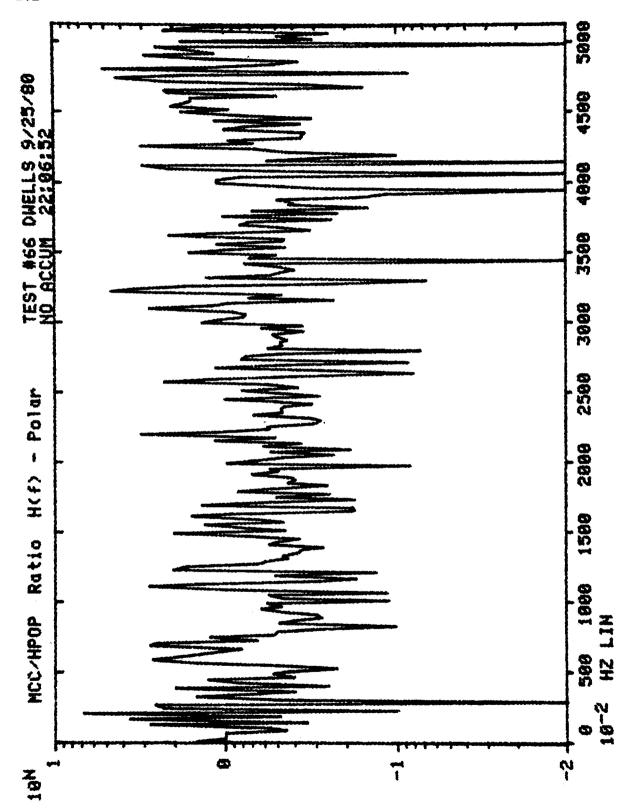




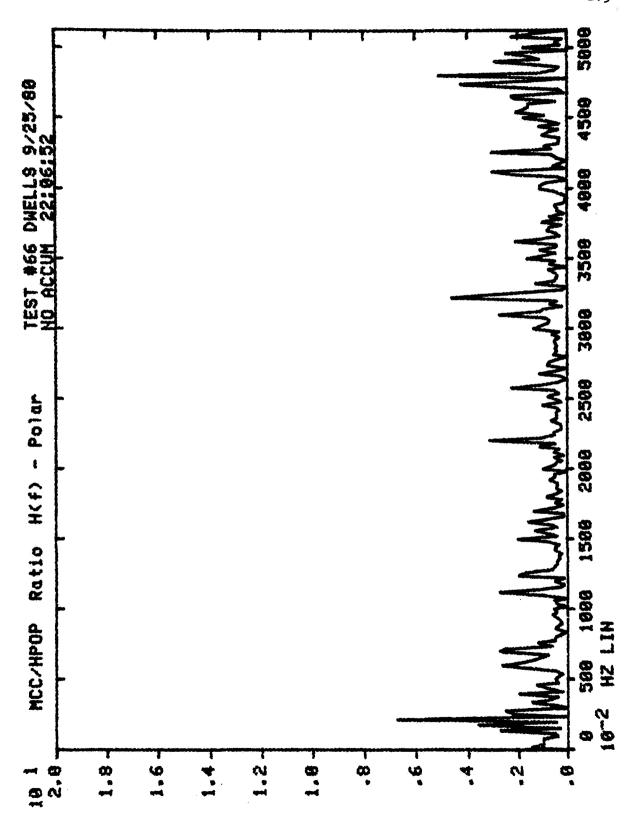


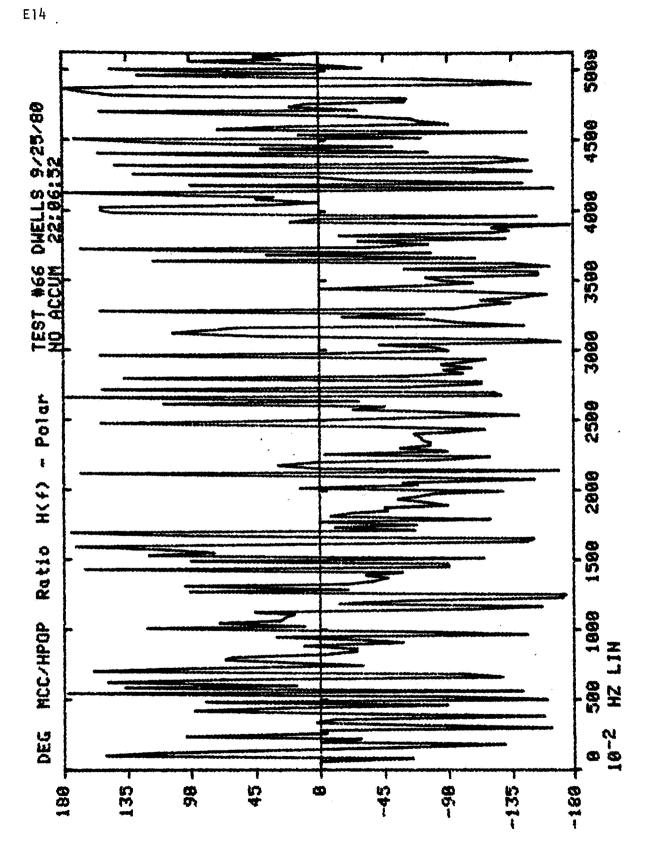


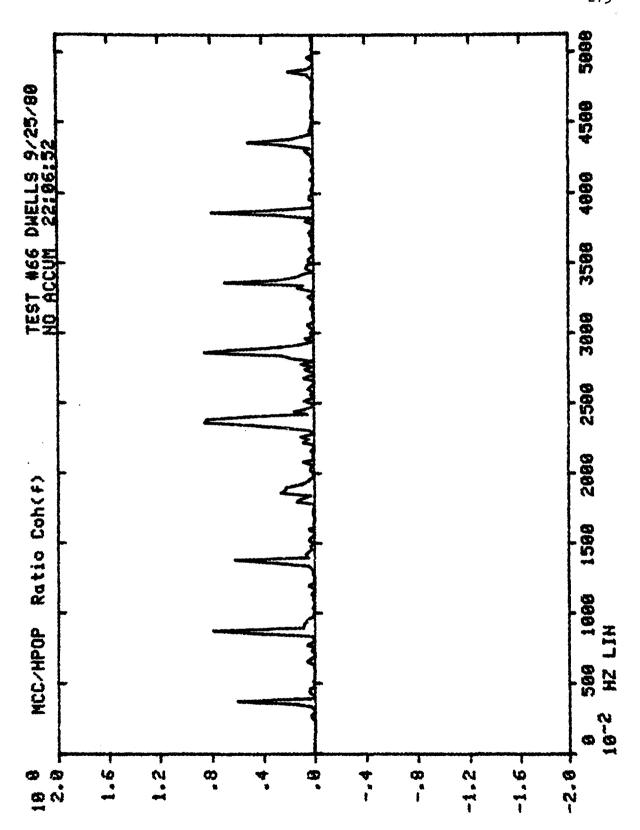


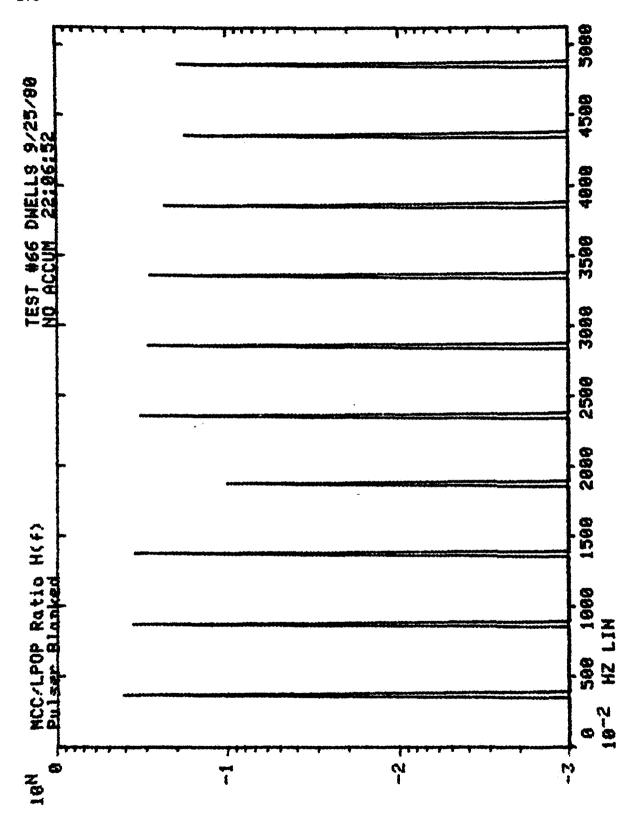




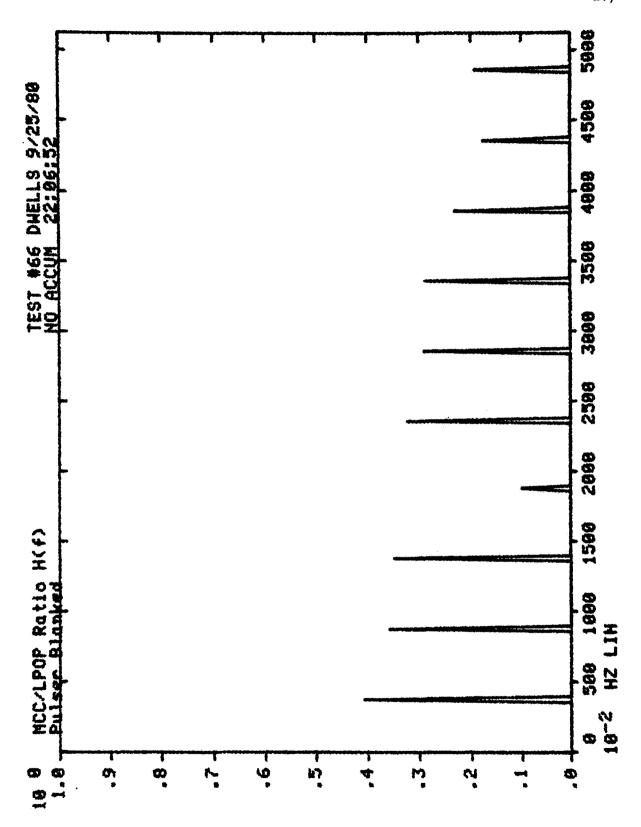


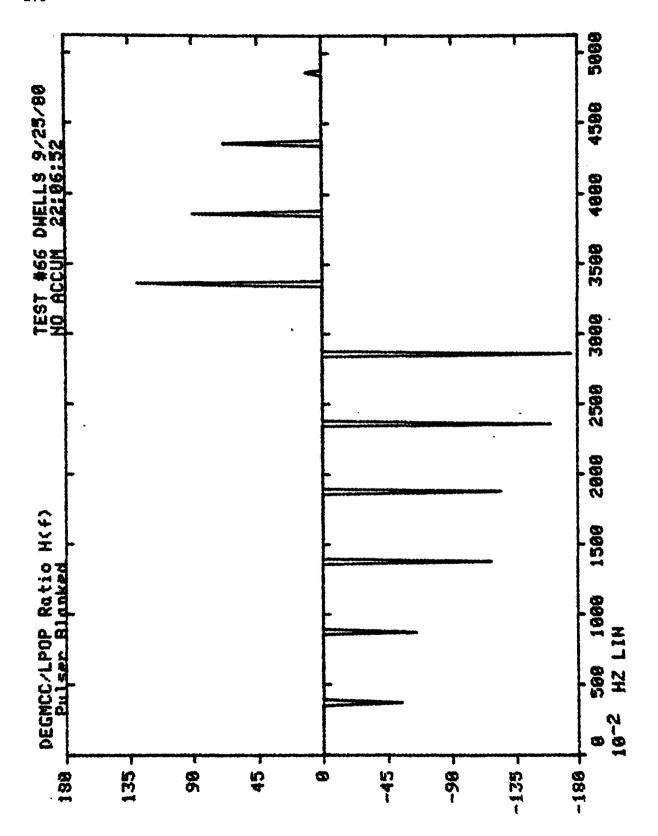




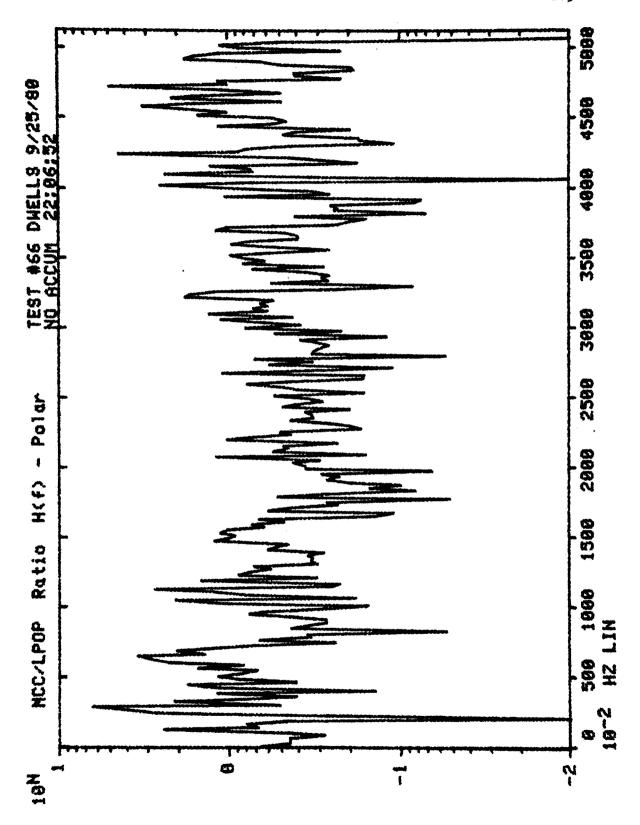




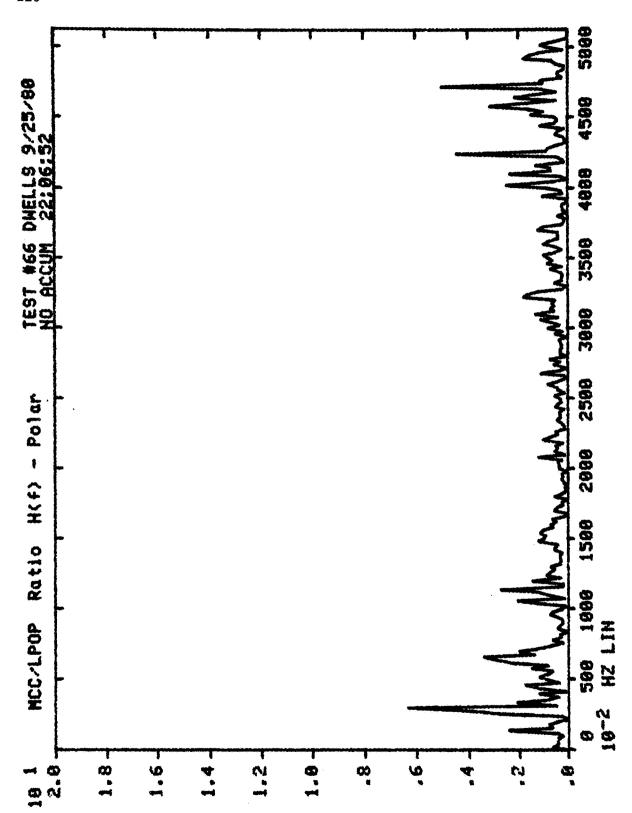


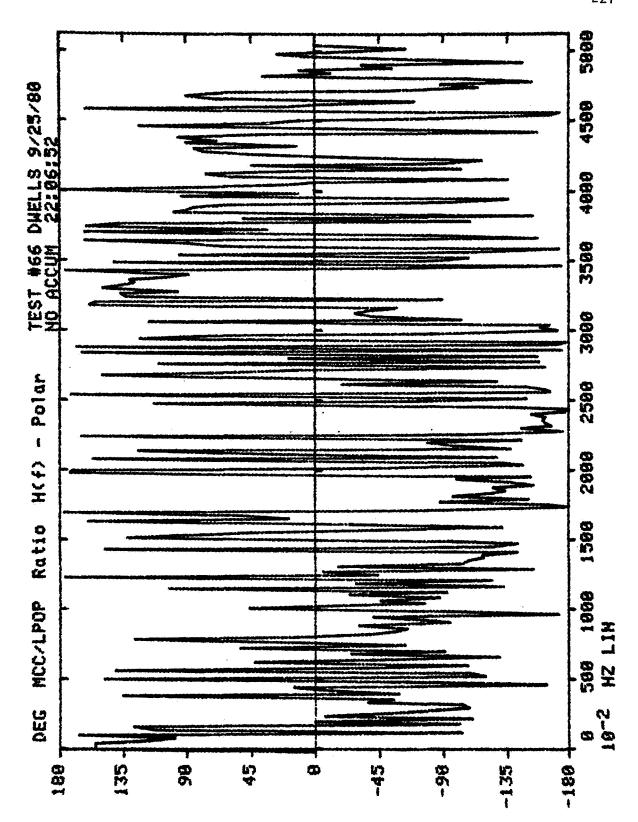


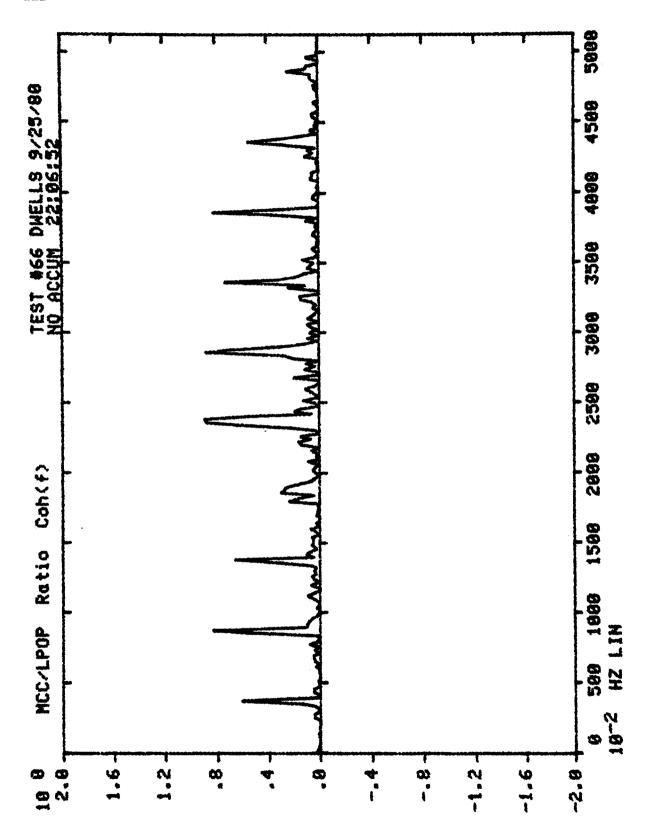




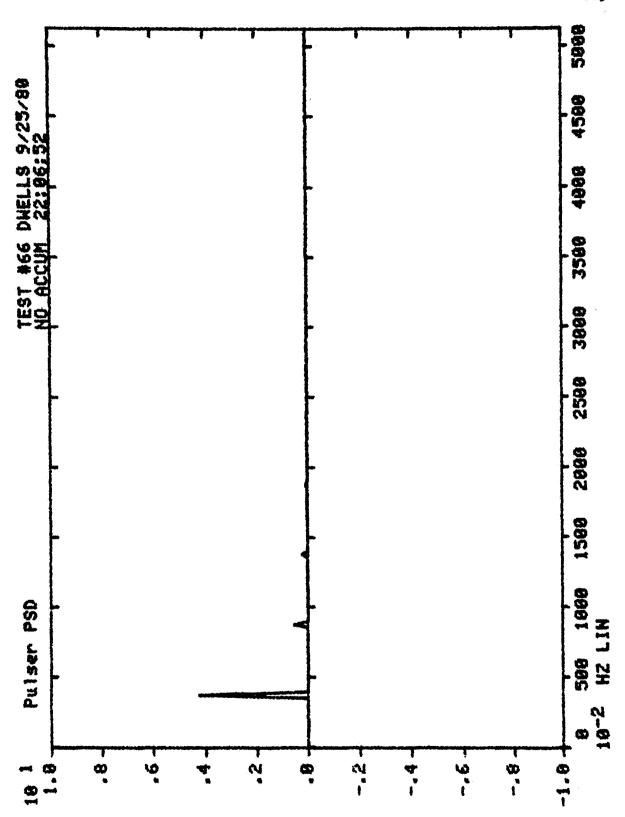


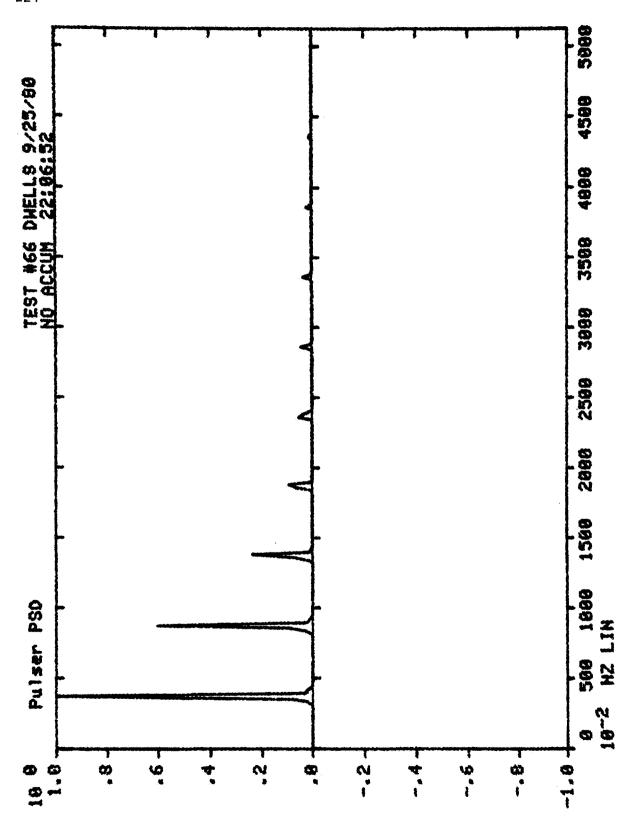


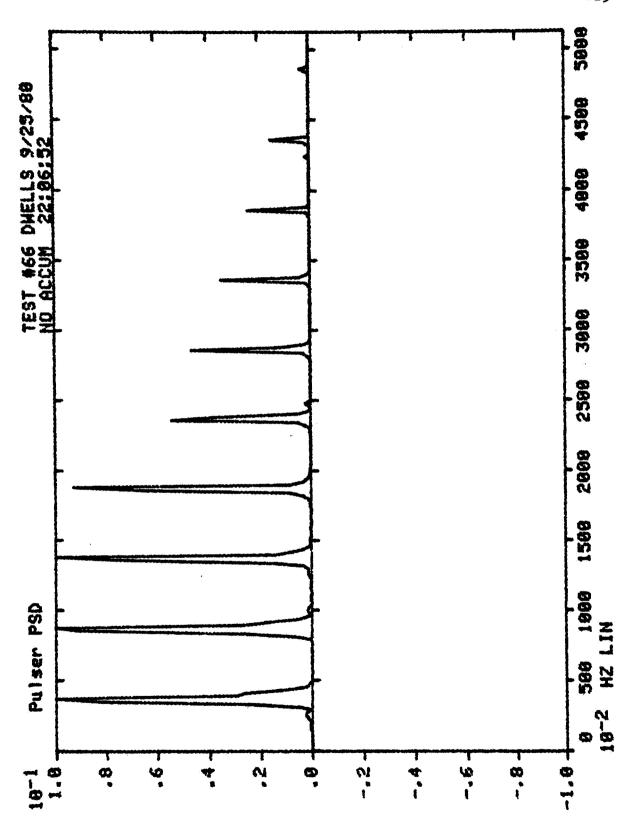


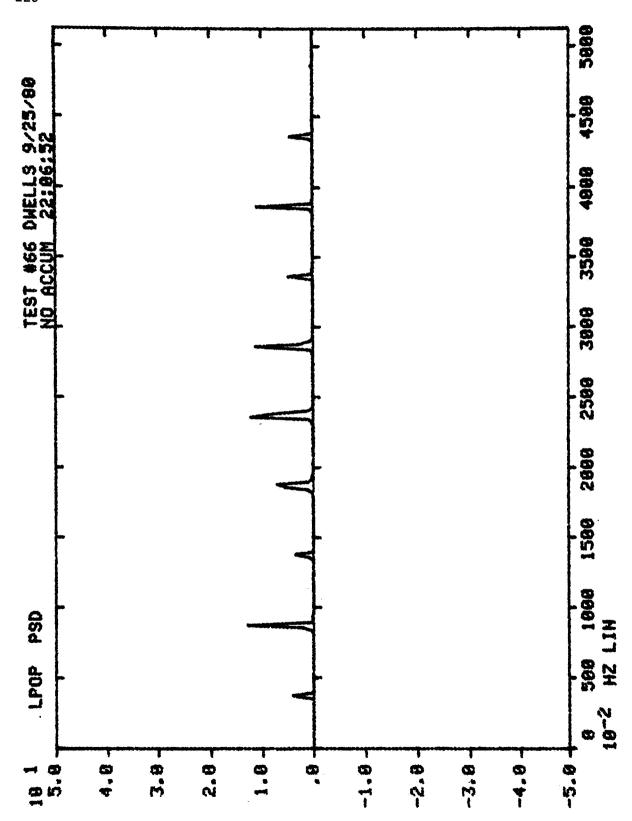


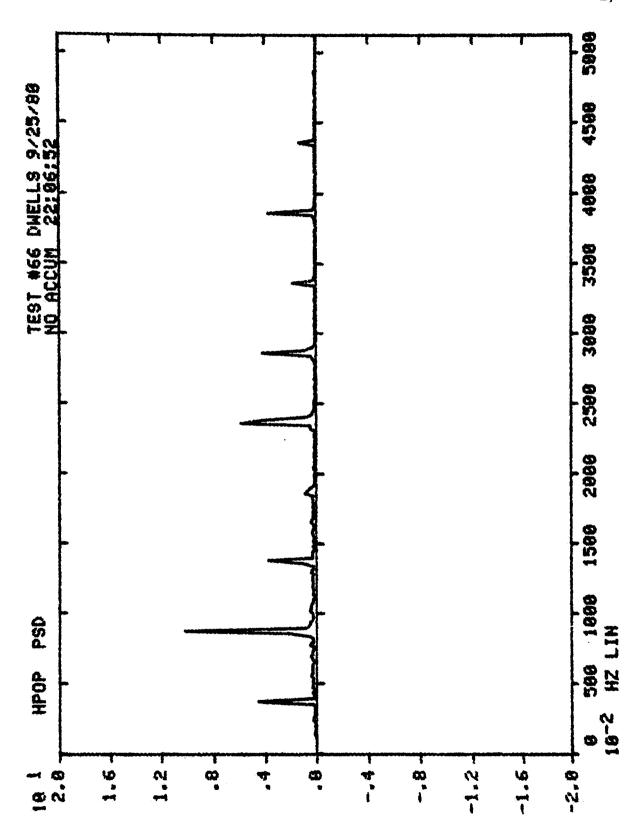


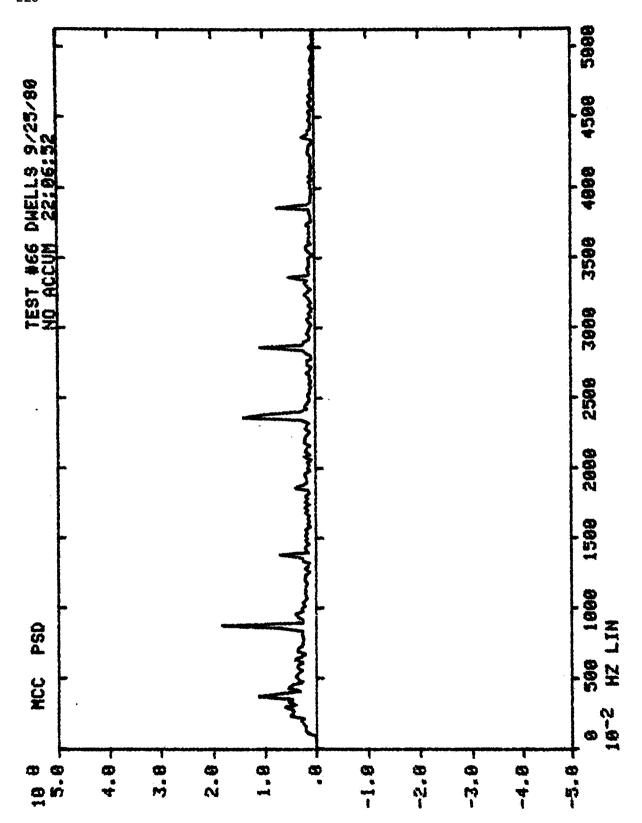


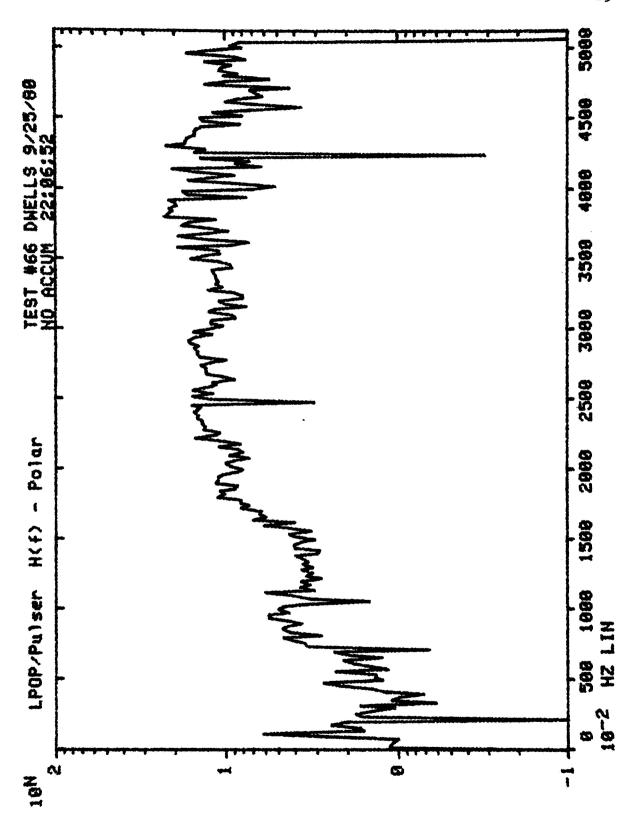


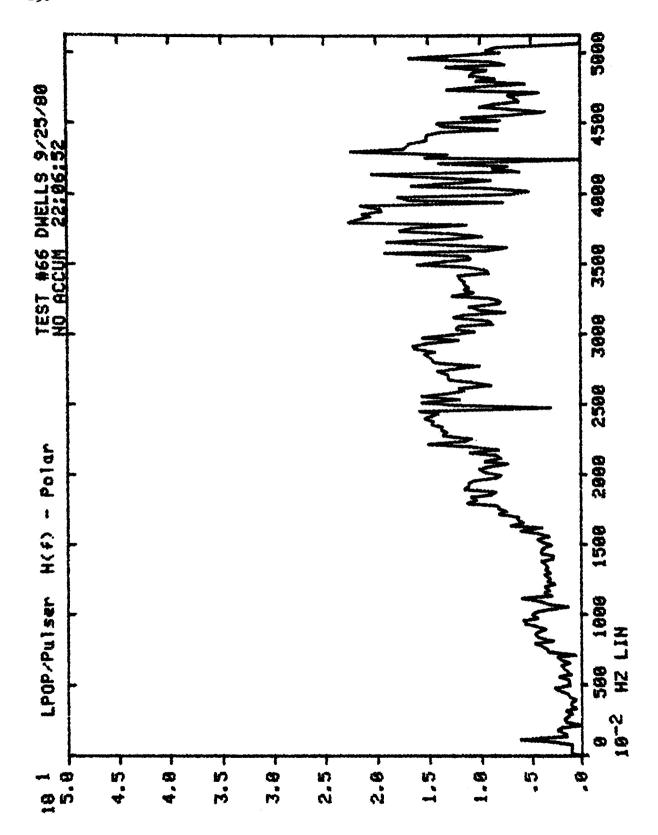




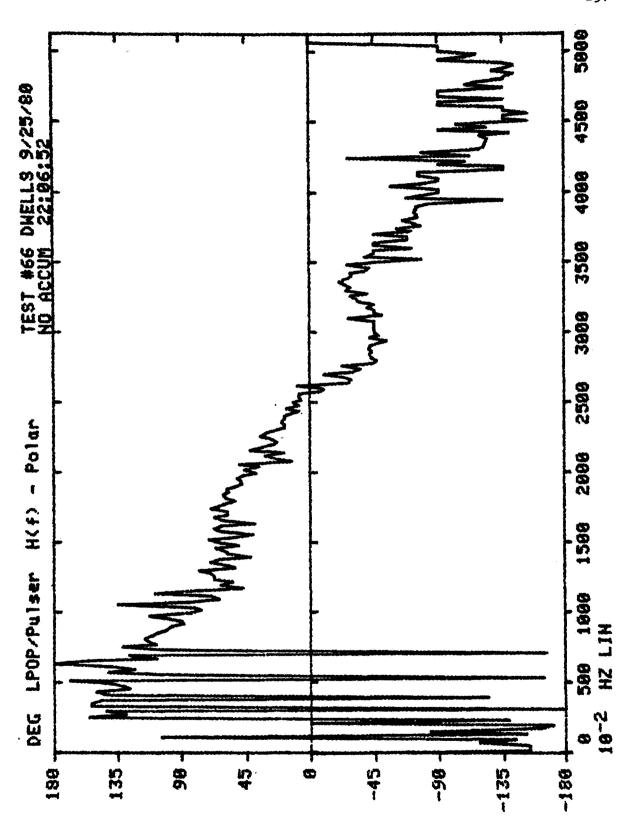


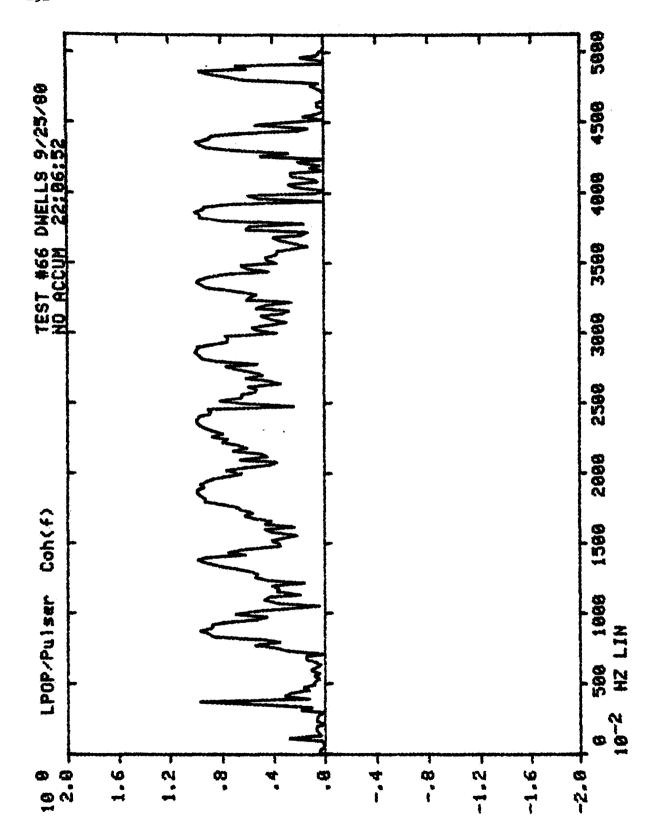


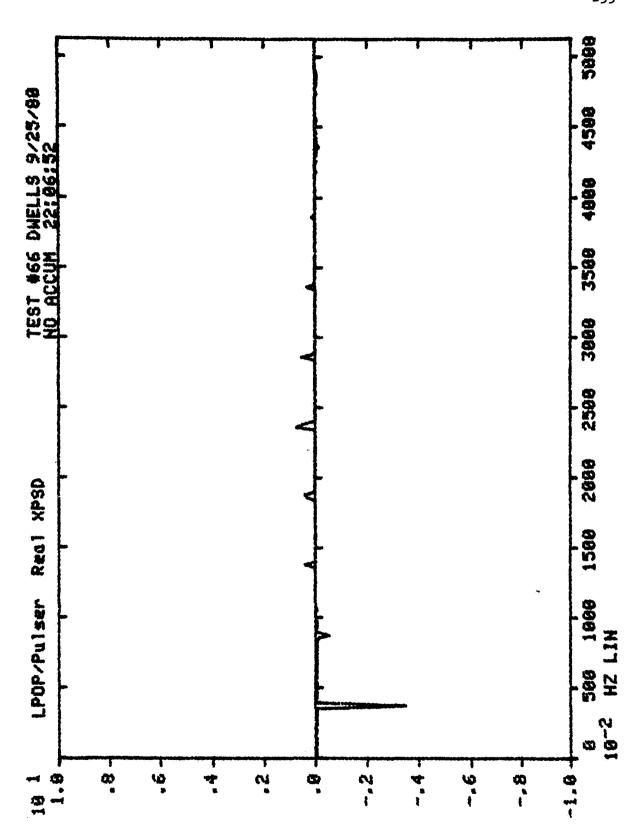


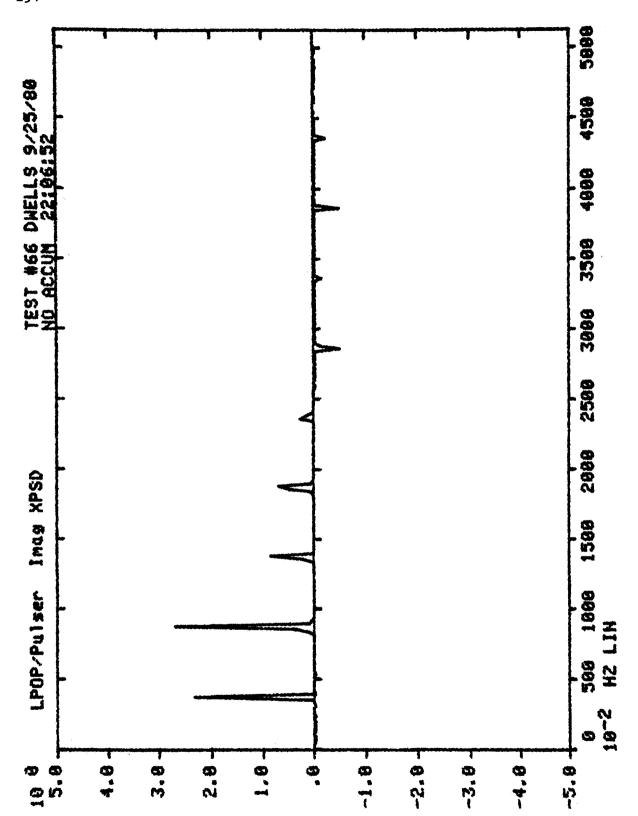


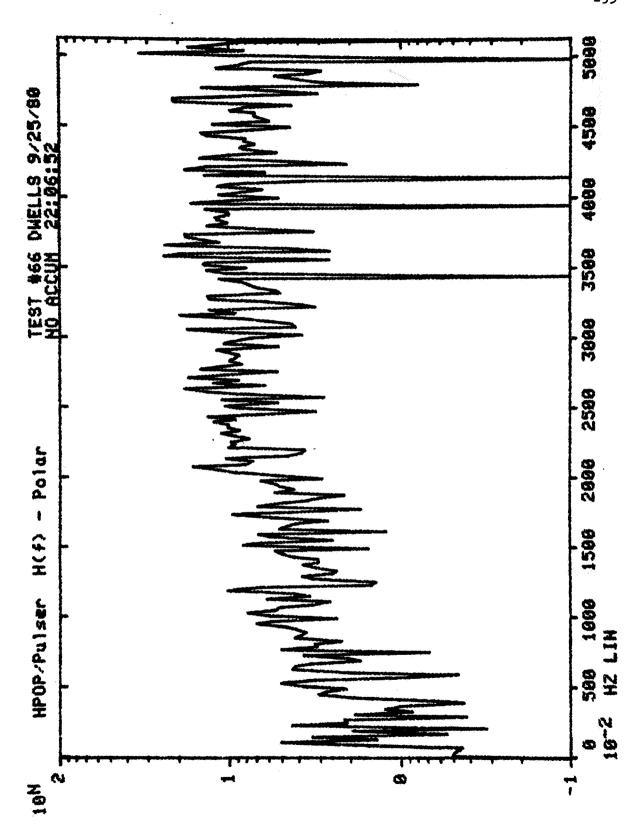




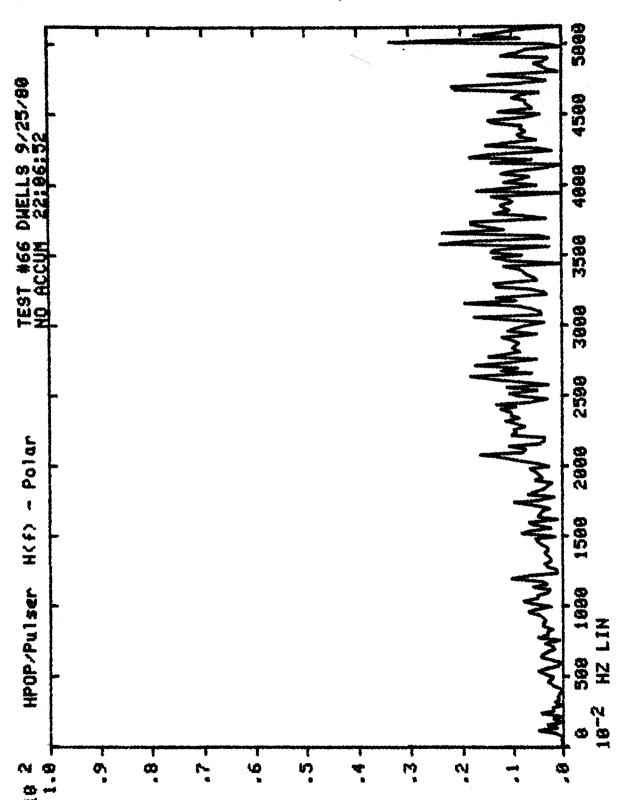


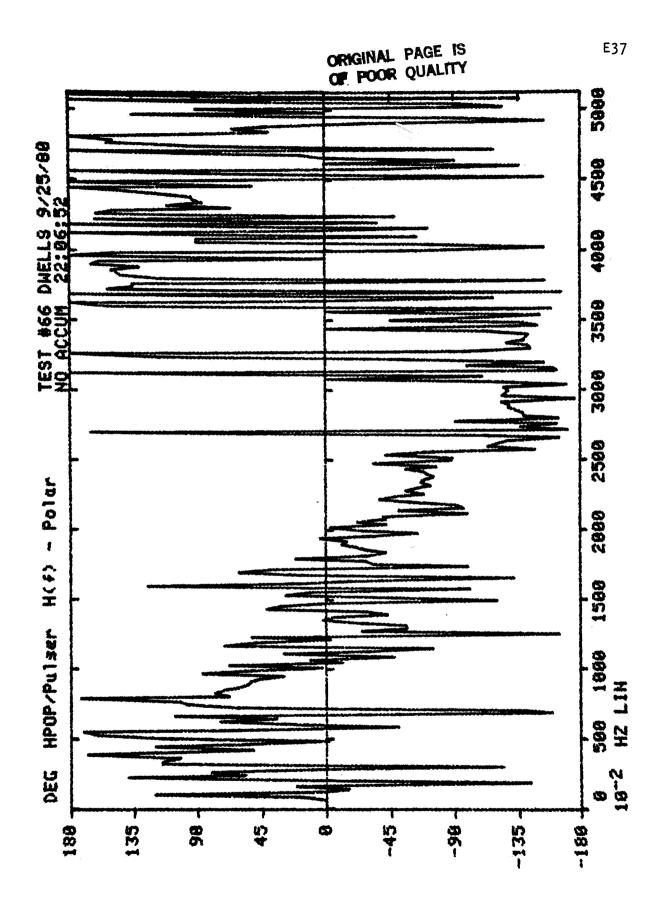


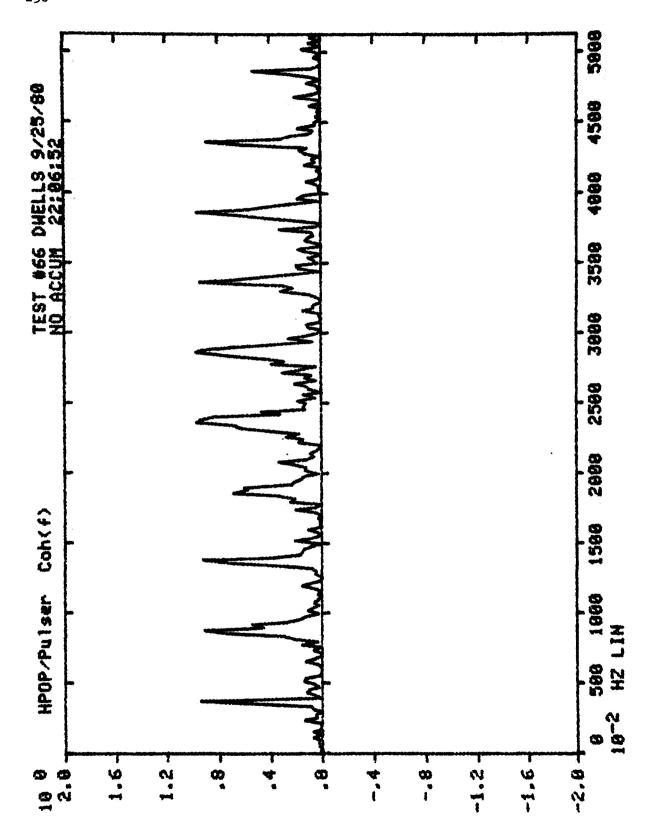




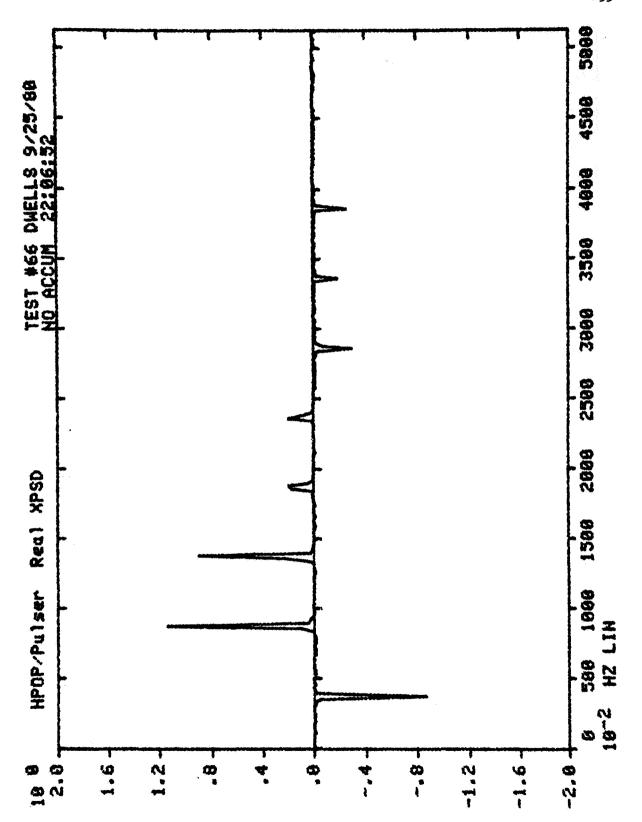




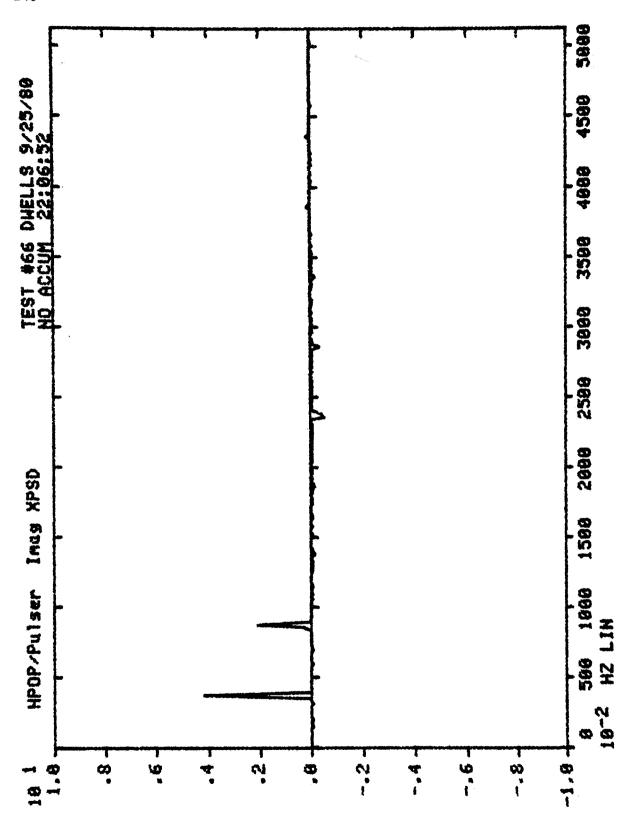


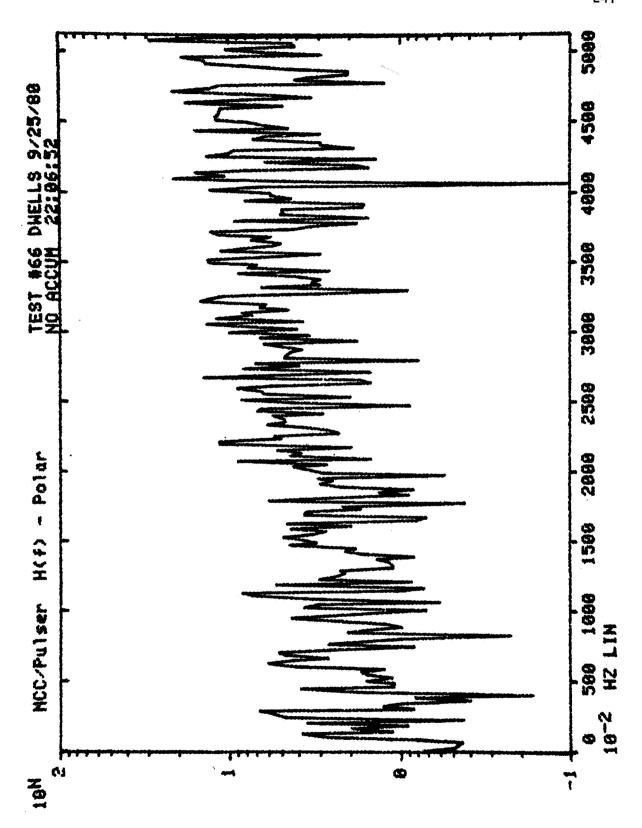


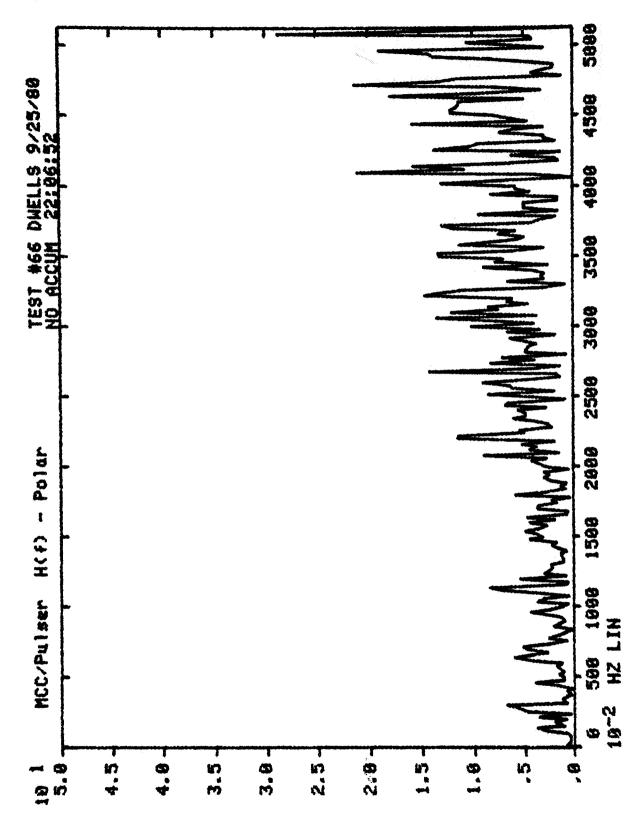


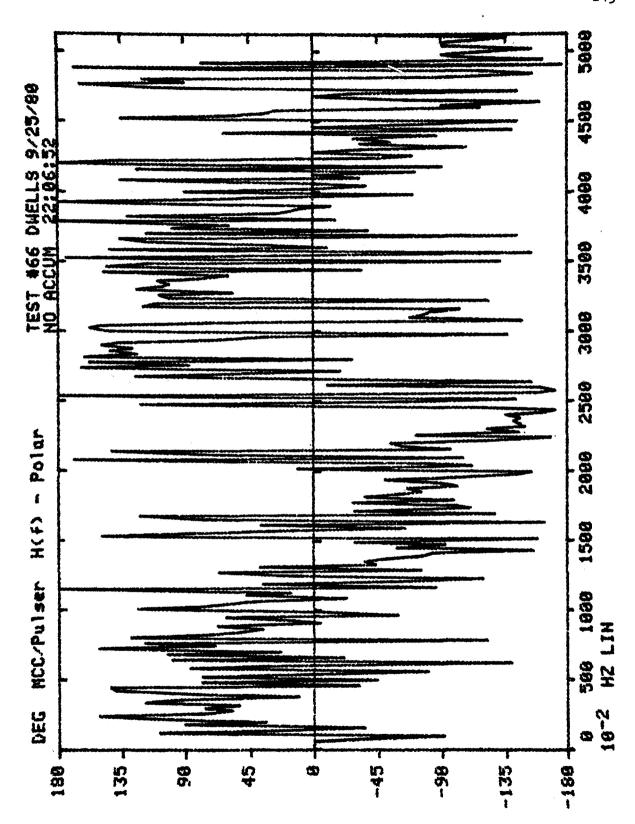


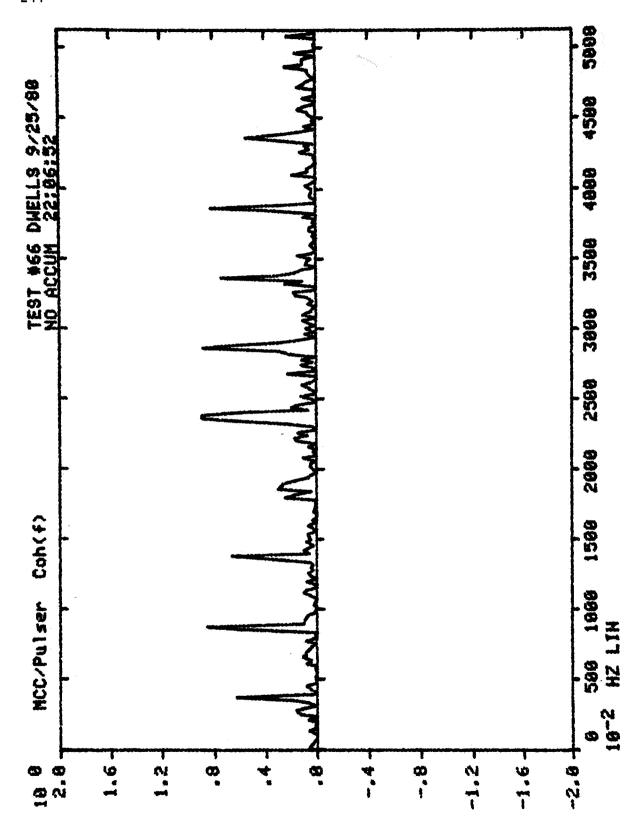




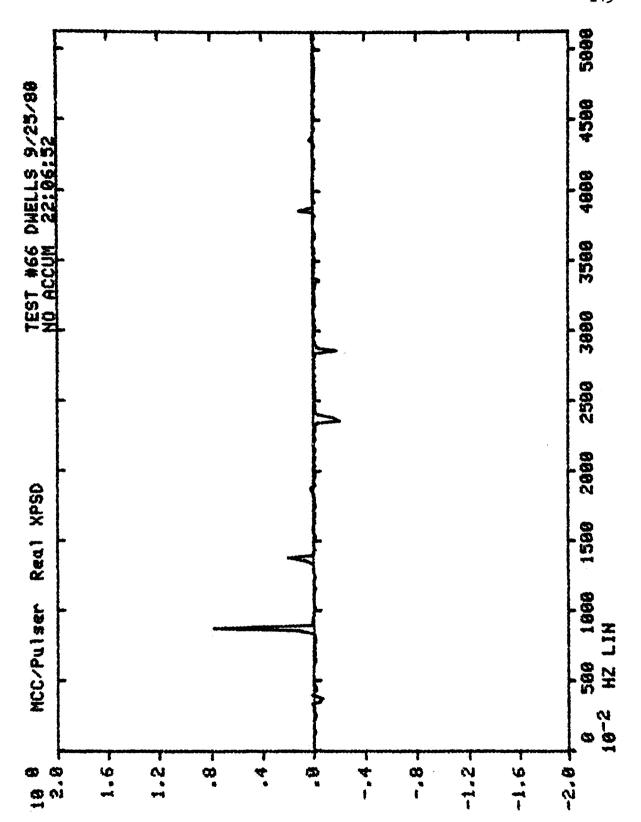




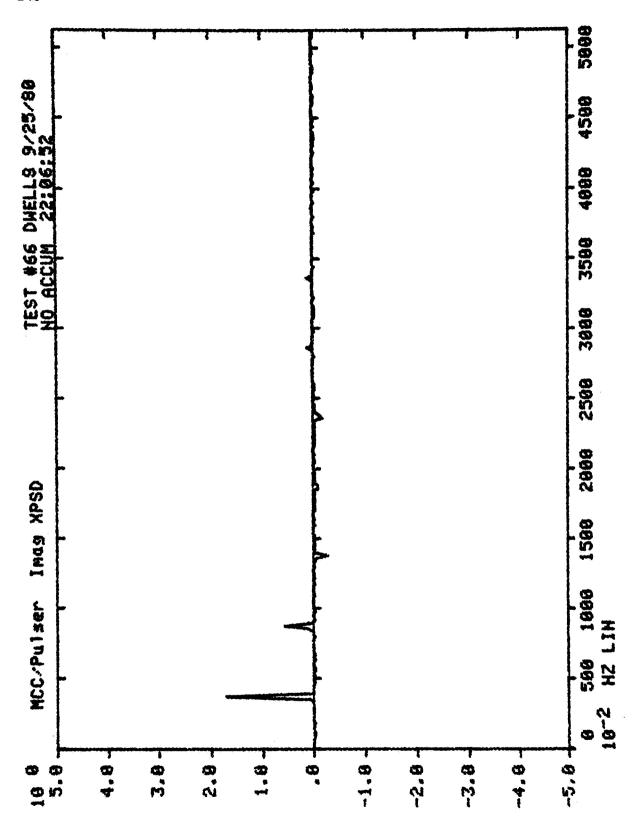


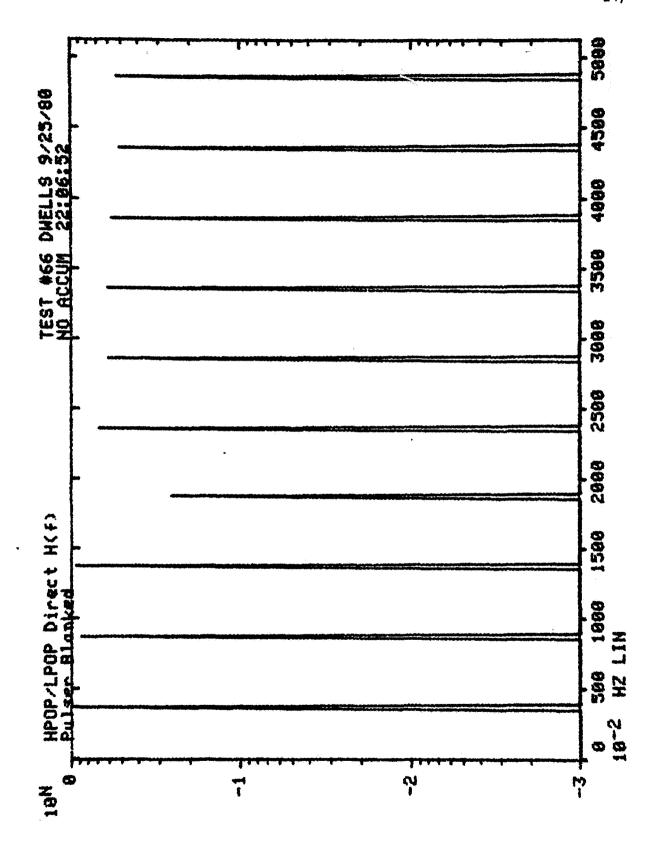


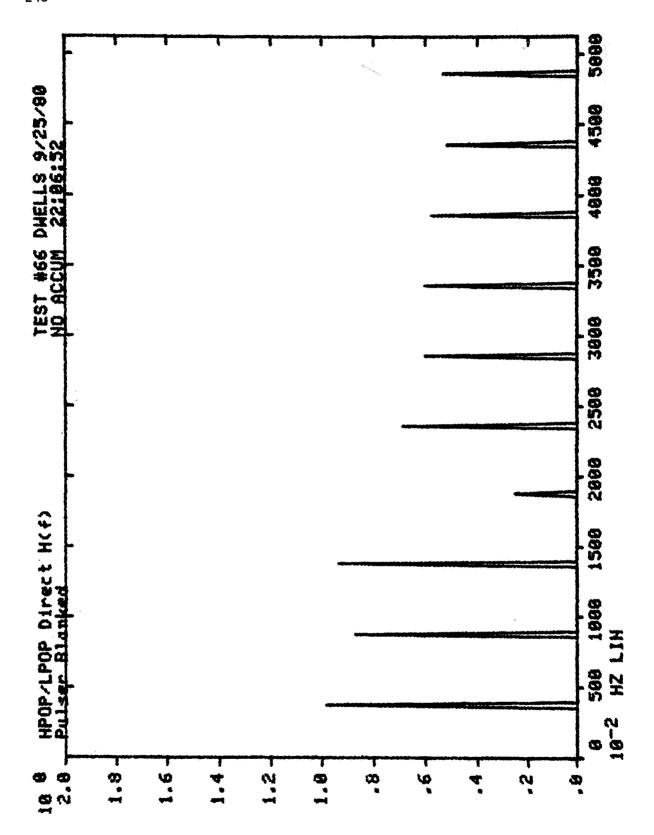


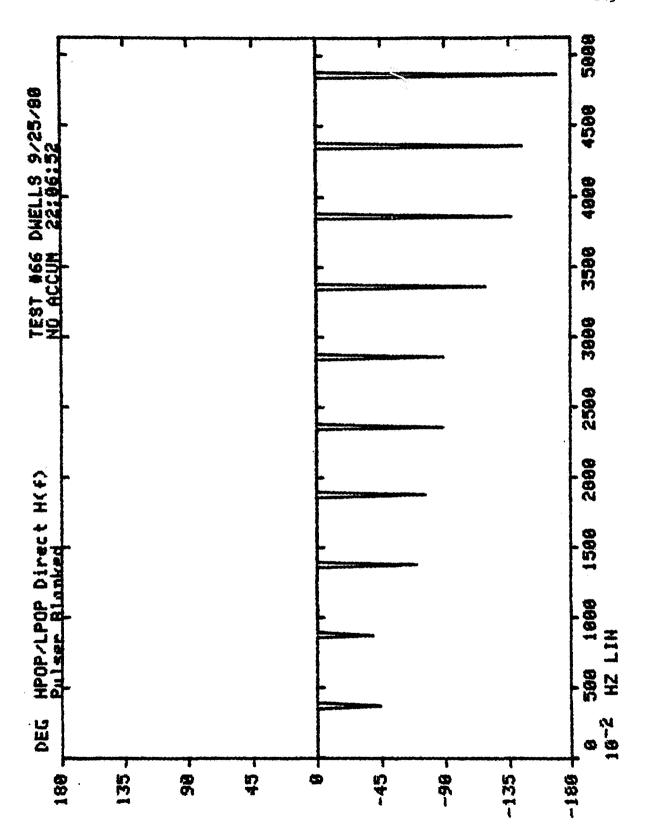


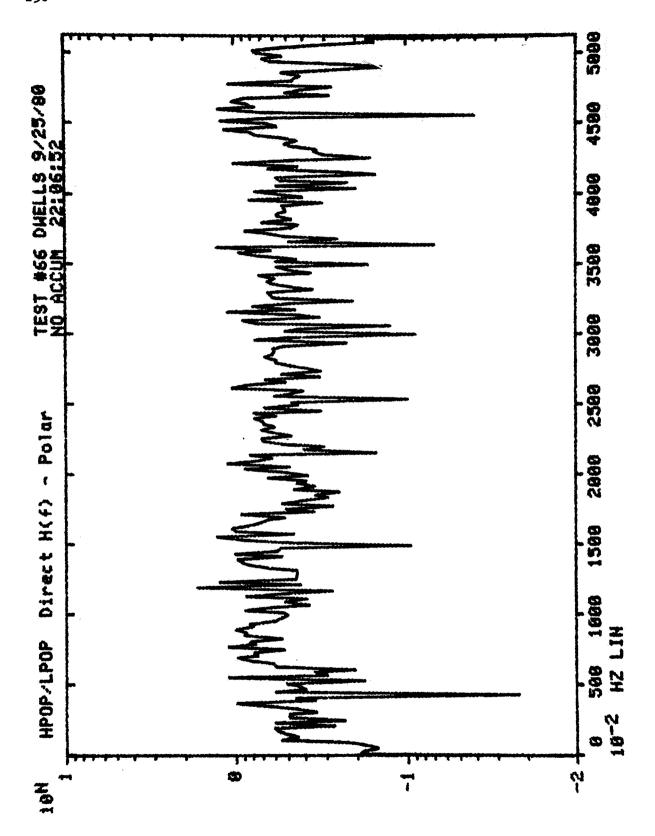


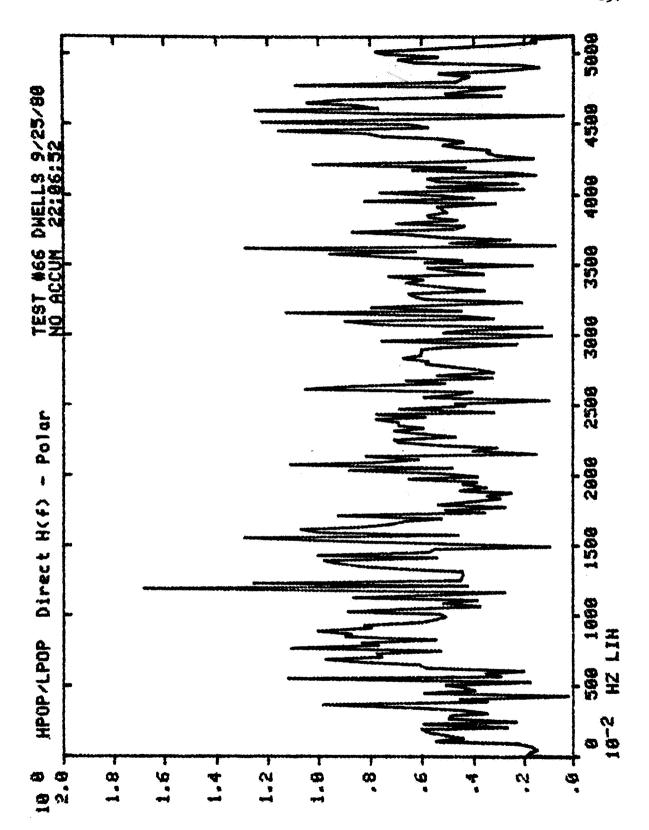


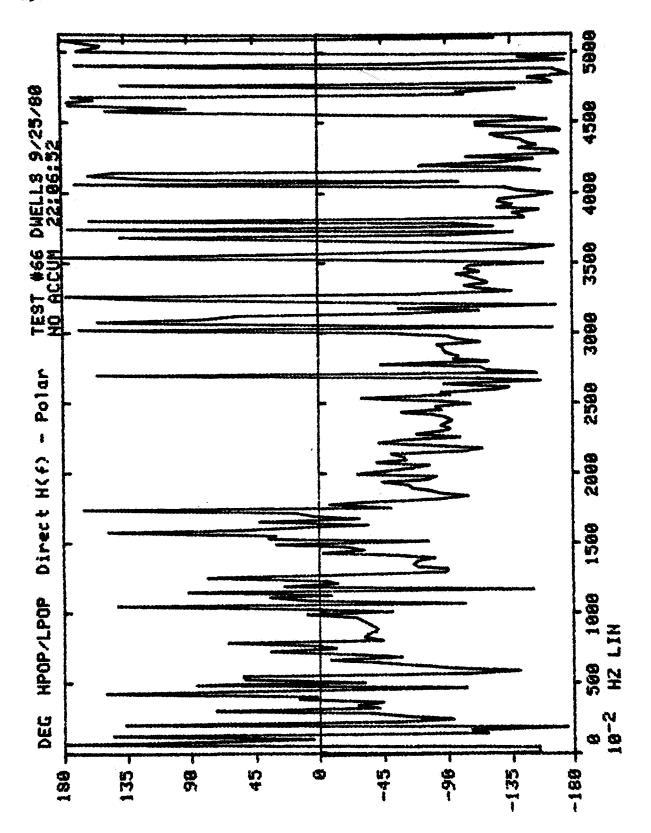




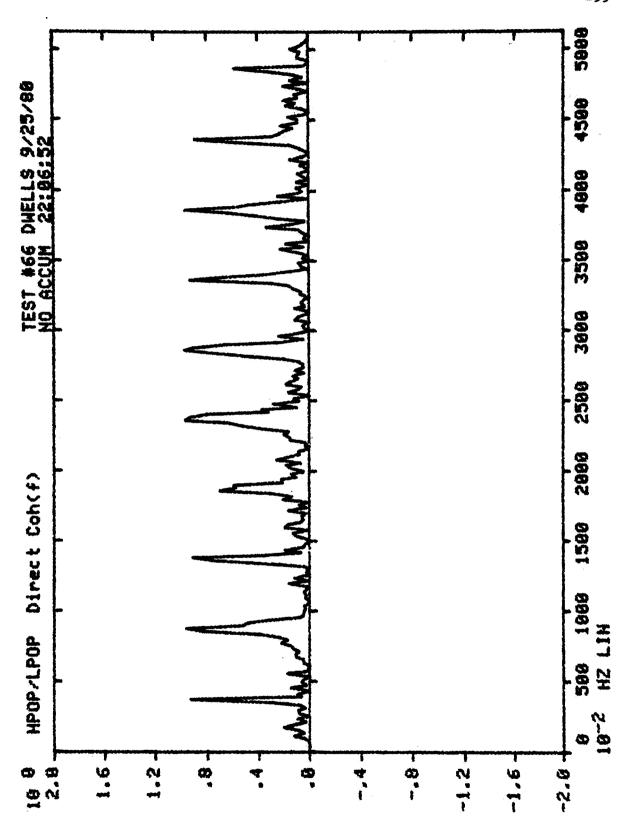




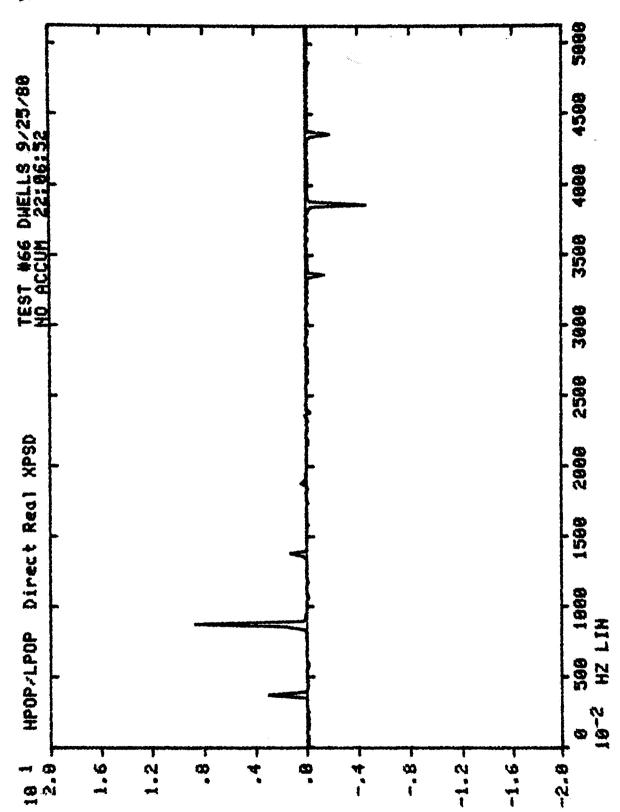


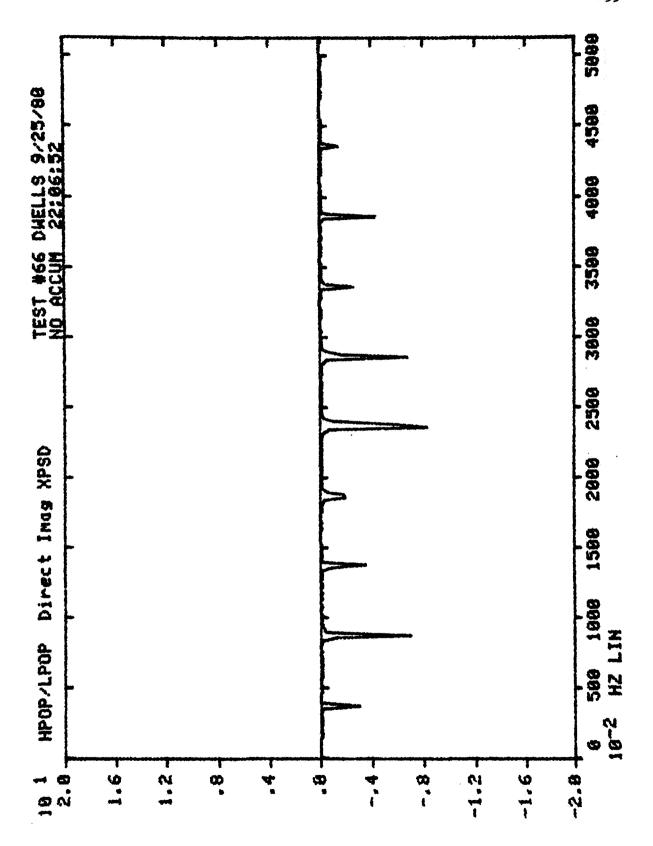


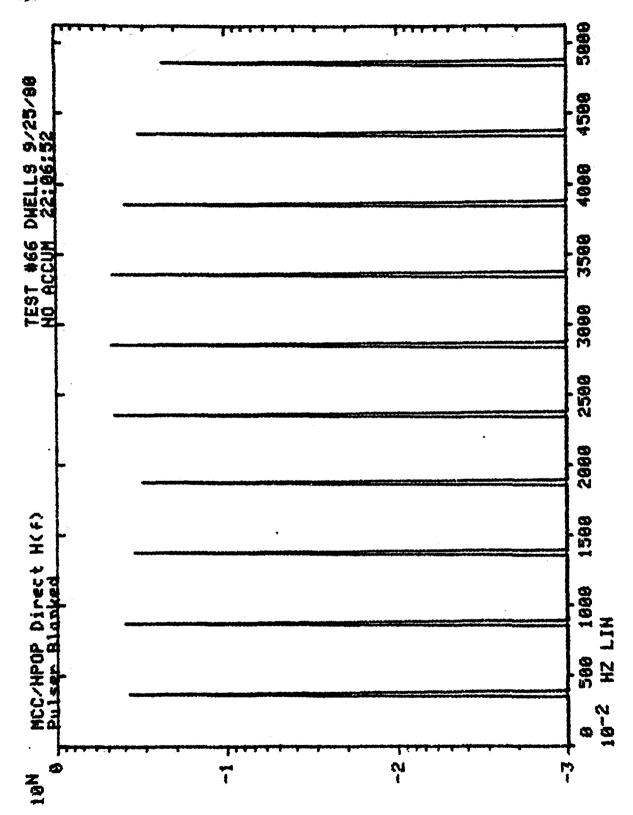


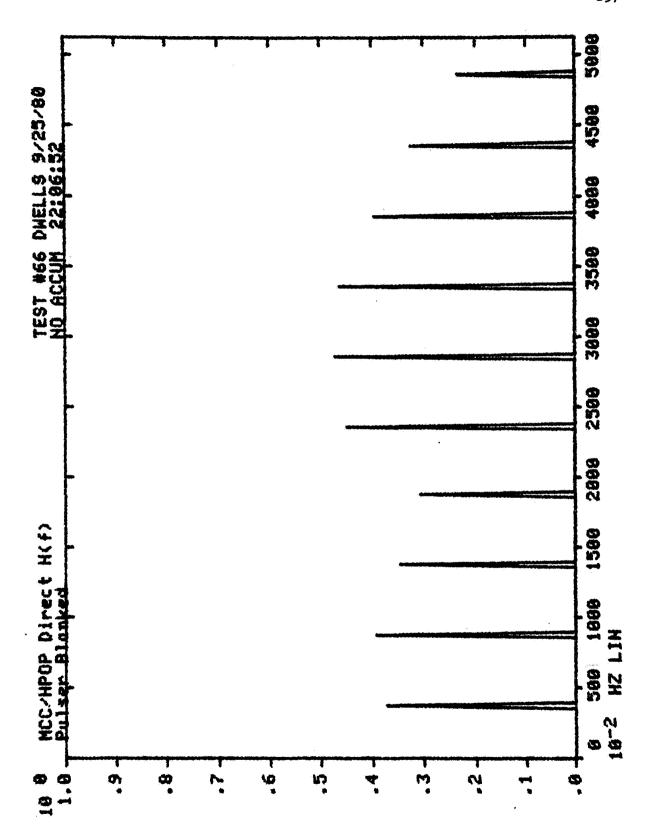


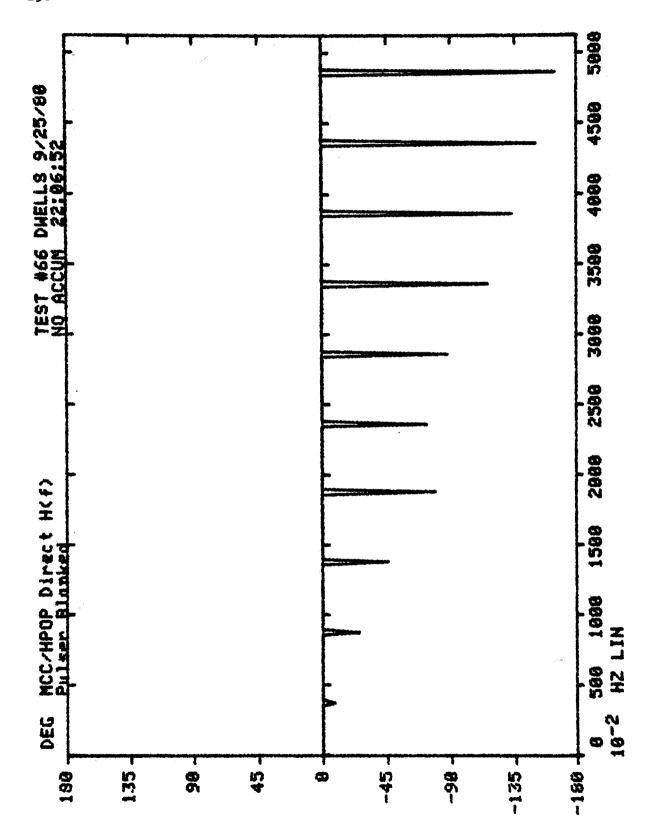


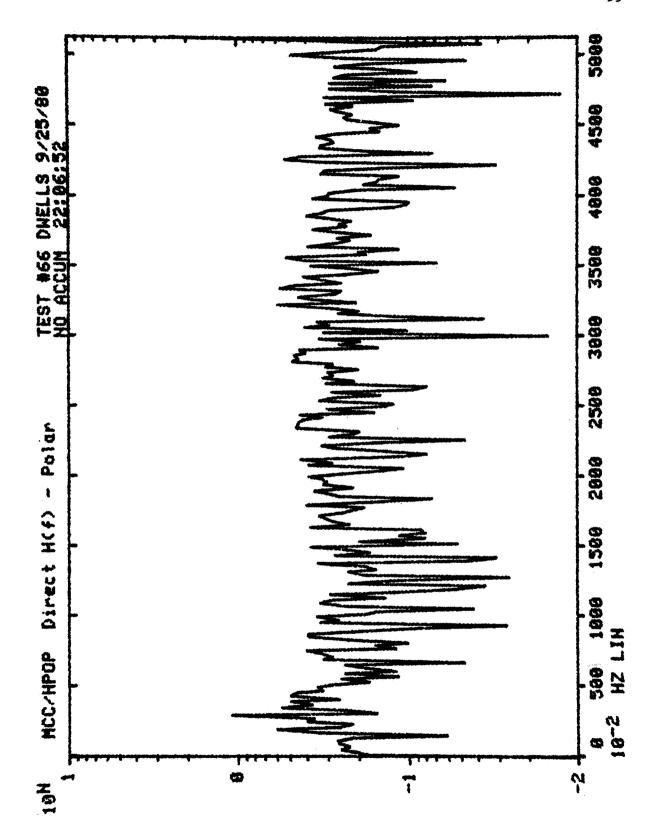


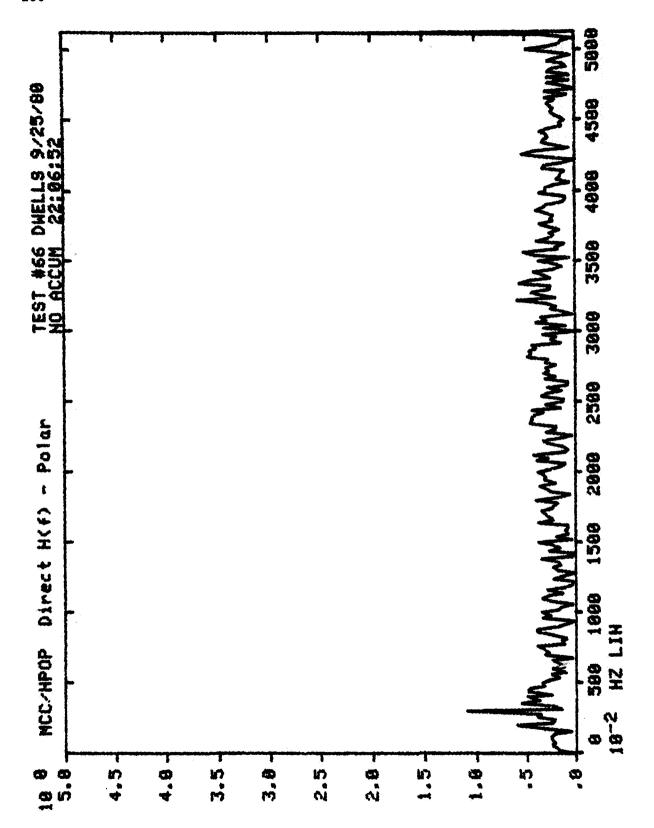


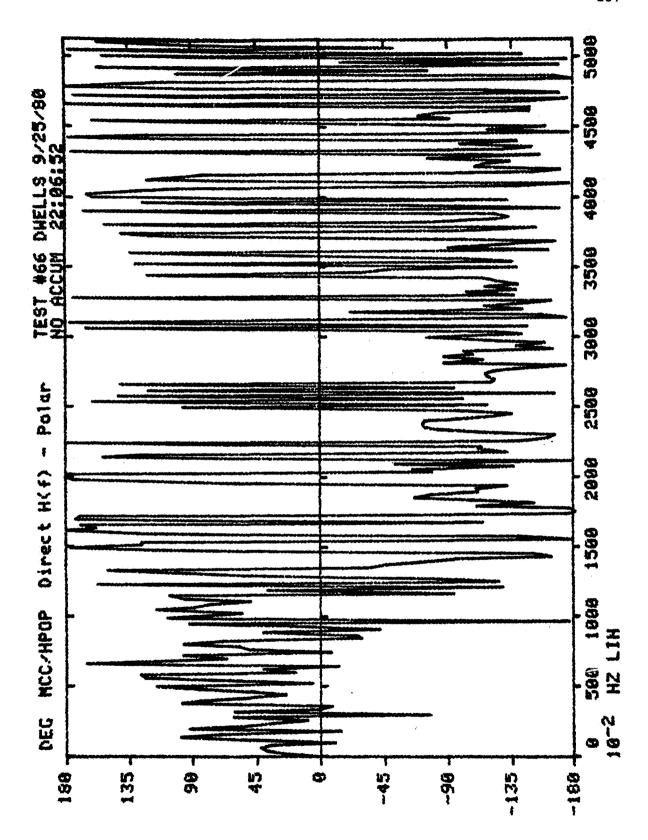


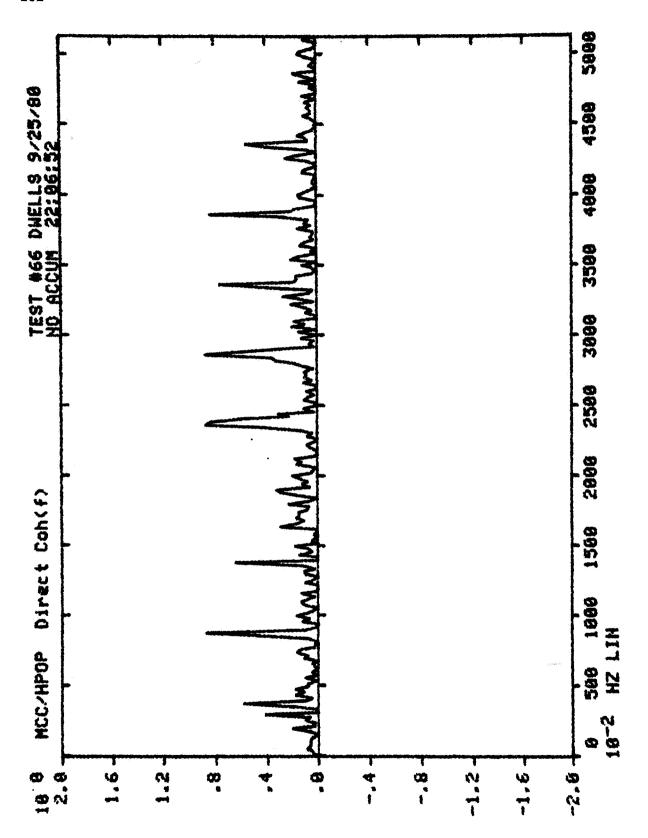




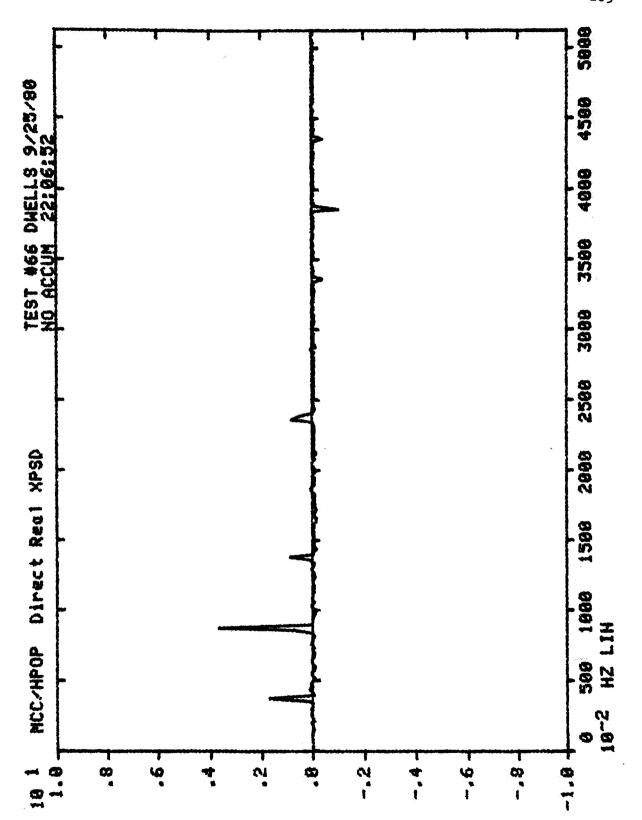


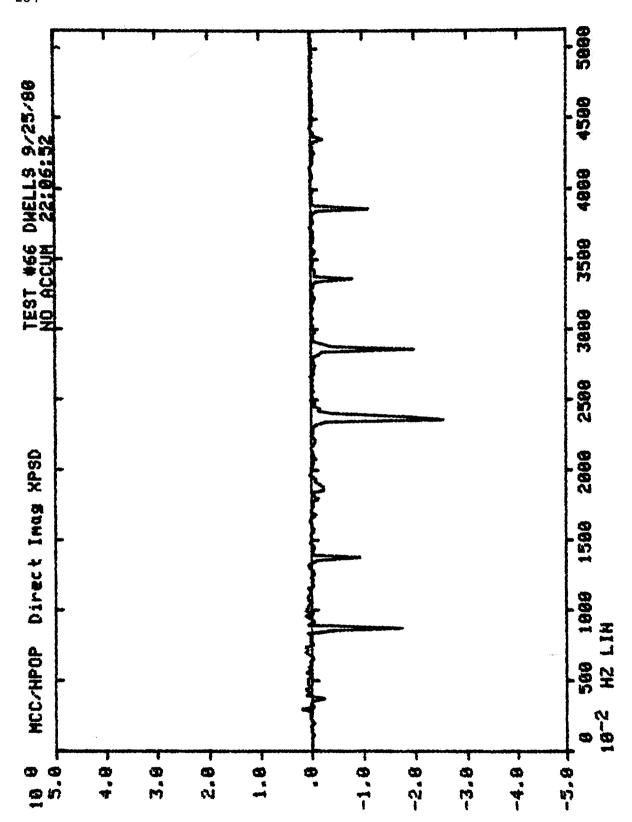


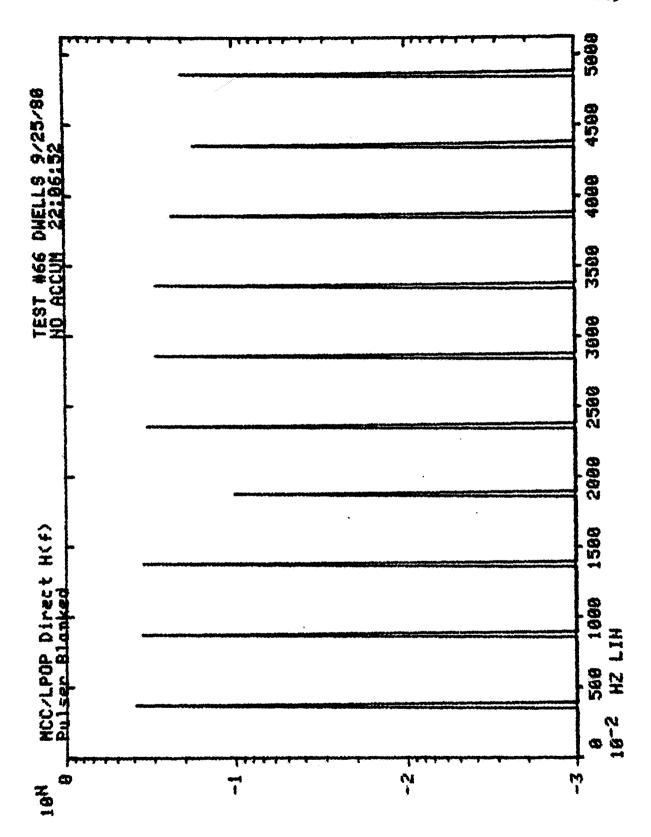


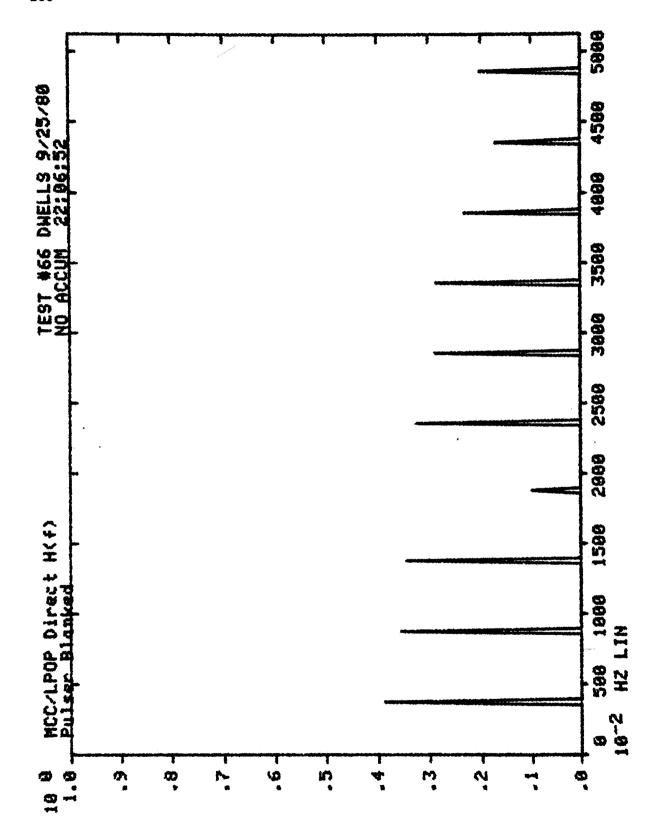




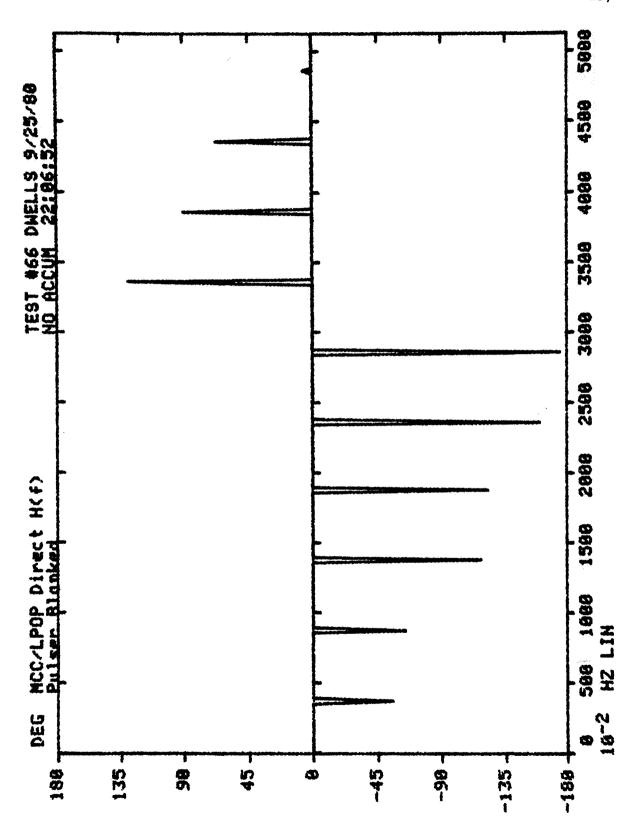


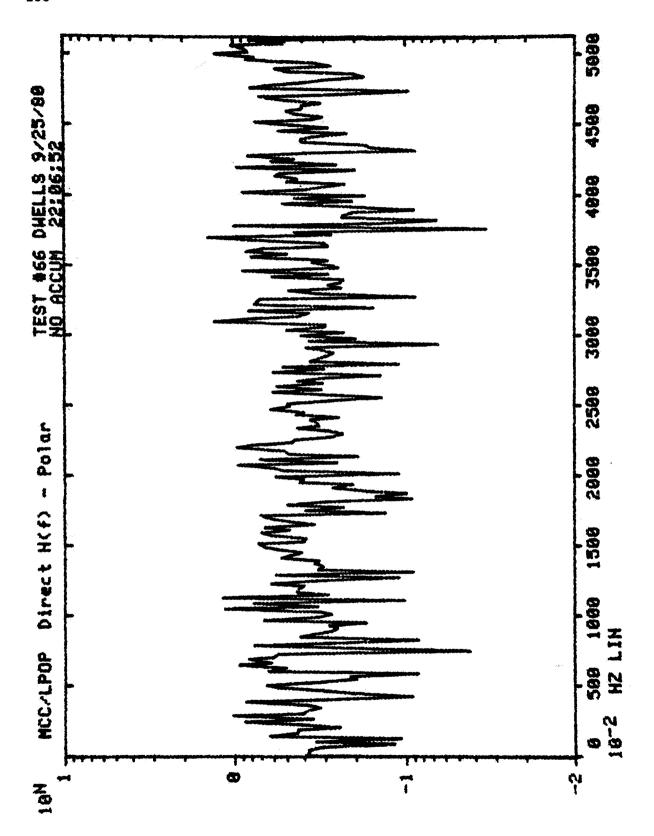


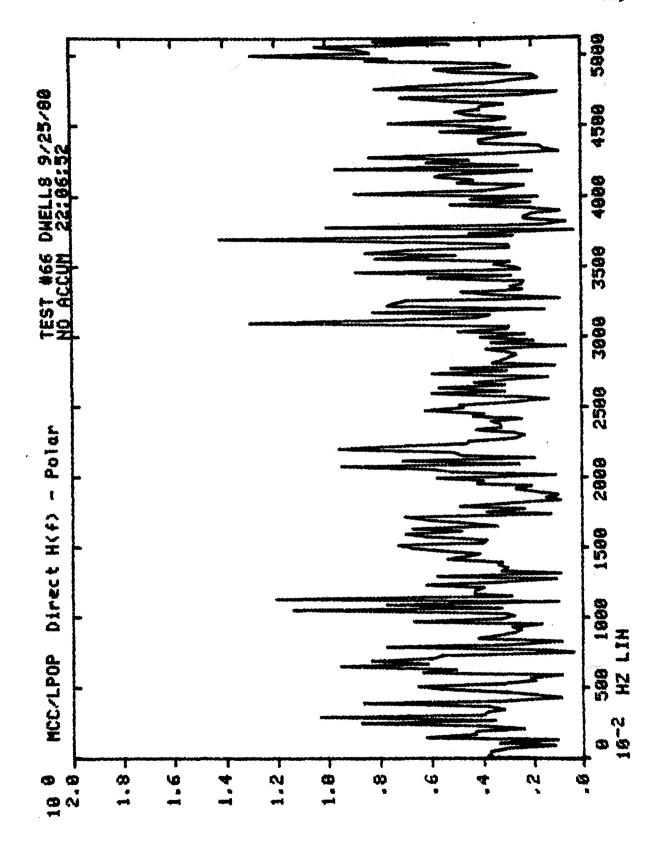






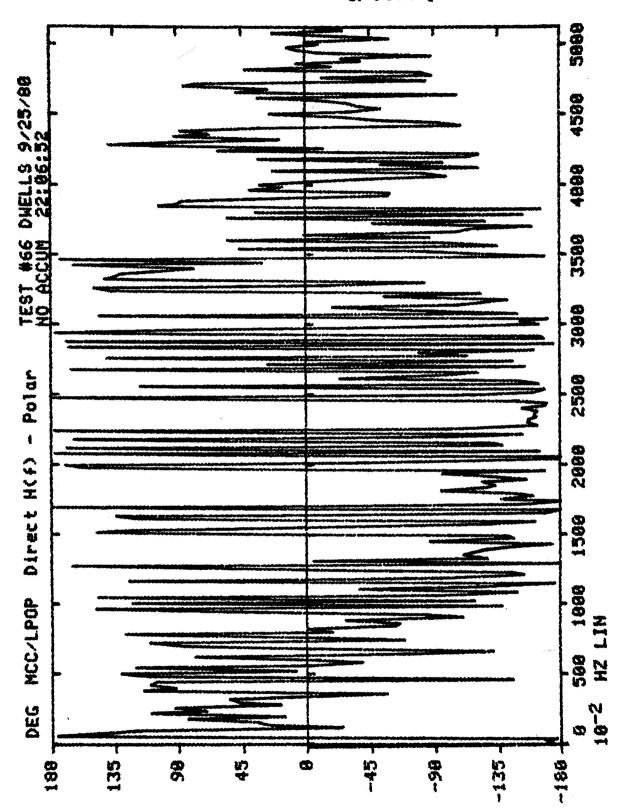


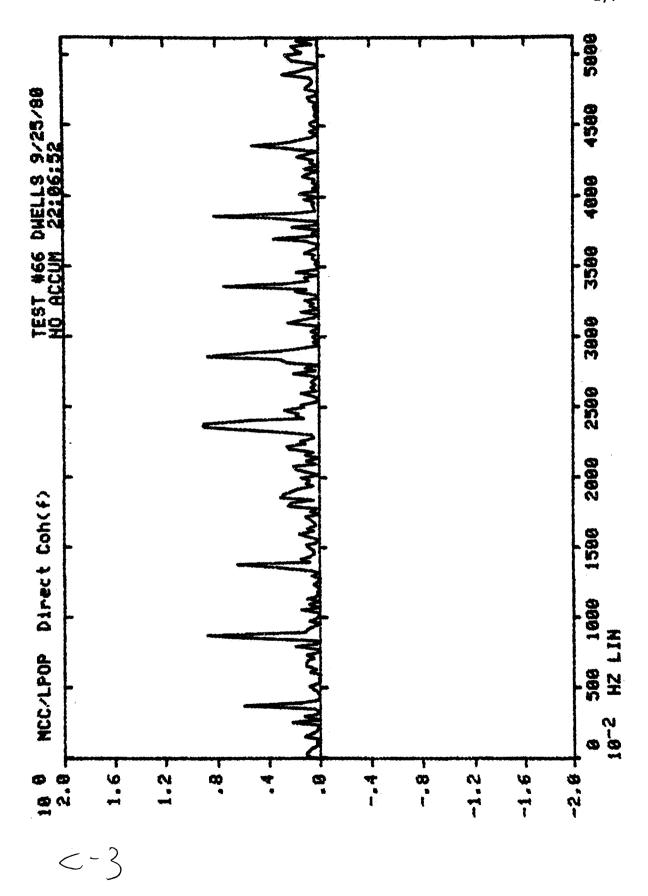


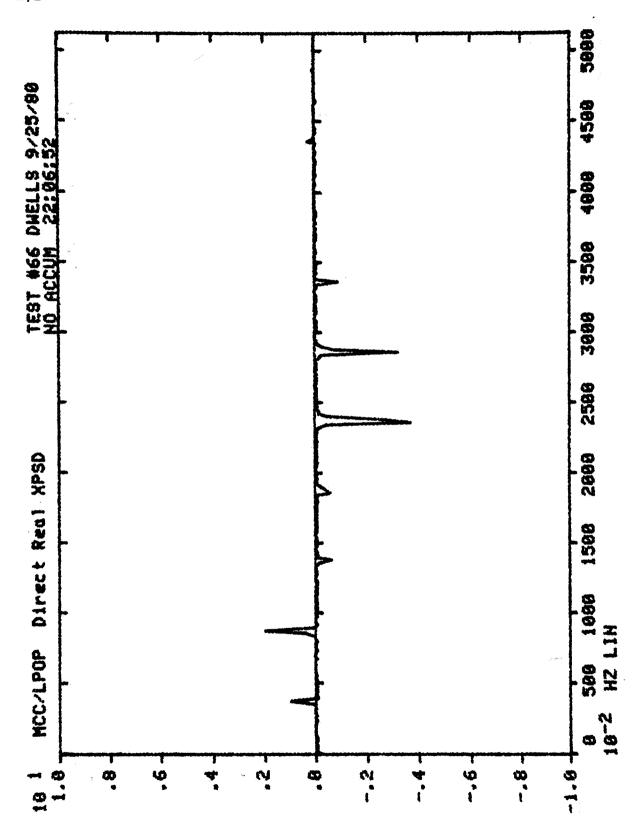


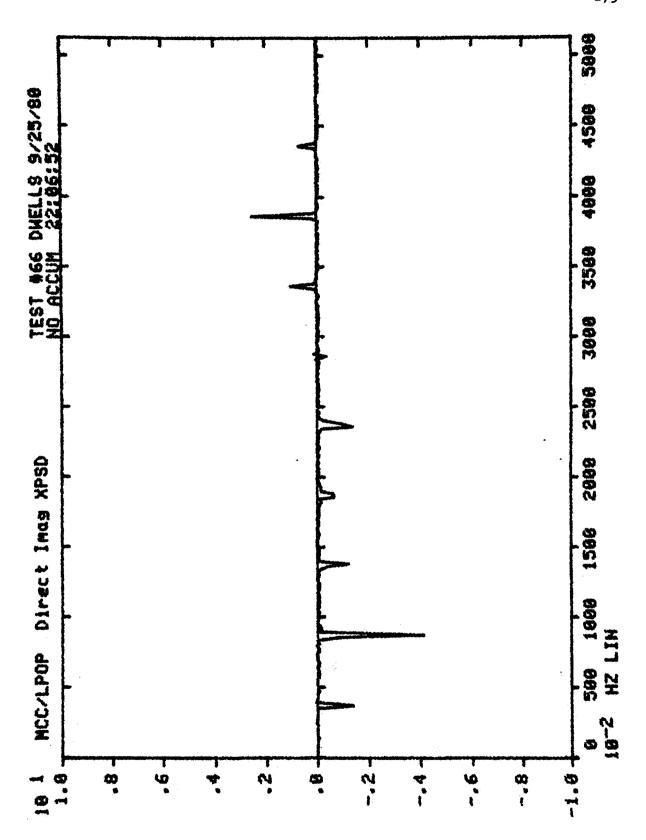


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APPENDIX B

WYLE LABORATORIES - RESEARCH STAFF TECHNICAL MEMORANDUM TM 84-03

ROLLING BEARING ELEMENT ROTATIONAL SPEEDS FOR THE SSME HIGH PRESSURE FUEL AND LOX TURBOPUMPS

APPENDIX B

WYLE LABORATORIES - RESEARCH STAFF TECHNICAL MEMORANDUM TM 84-03

ROLLING BEARING ELEMENT ROTATIONAL SPEEDS FOR THE SSME HIGH PRESSURE FUEL AND LOX TURBOPUMPS

by

Wayne L. Swanson

An interim report of work performed under contract NAS8-33508

for

NATIONAL AERONAUTICS AND SPACE ADMINISTRATION GEORGE C. MARSHALL SPACE FLIGHT CENTER MARSHALL SPACE FLIGHT CENTER, ALABAMA 35812

FOREWORD

Wyle Laboratories' Scientific Services & Systems Group has prepared this report for the George C. Marshall Space Flight Center, National Aeronautics and Space Administration. The work was performed under contract NAS8-33508, entitled "Dynamic Analysis of SSME Vibration and Pressure Data." Technical direction and computer program coding for this study were provided by ED24 personnel of the Systems Dynamics Laboratory.

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INTRODUCTORY SUMMARY

This report consists of a series of charts, equations, and the computer program listing for determining the frequencies associated with the roller bearings of the SSME high pressure fuel turbopump (HPFTP) and high pressure oxygen turbopump (HPOTP). The frequencies are in terms of speed ratio normalized by the rotational speed of the shaft. Speed ratio was calculated for the cage, ball spin, outer race, and inner race for the different bearing parameters of the SSME HPFTP and HPOTP.

Several methods of data presentation are provided for ease in interpretation. This includes charts for the change in contact angle for both the inner and outer race, constant inner race contact angle versus outer contact angle, and charts of inner contact angle equal to outer contact angle, which is only applicable for the case of slow rotational speed and/or applied radial load of large magnitude.

The data from two static firing tests are also included where the cage and outer race frequencies were noted on internal strain gages mounted directly on the bearing holder. Several attempts were made using different analysis techniques (including adaptive filtering, cross PSDs, etc.) to isolate these frequencies in the external accelerometer data. To date these efforts have not been successful.

TECHNICAL DISCUSSION

The speed ratio for the cage, ball spin, and outer and inner race are defined as follows:

Cage Speed Ratio =
$$\frac{1 - \gamma' \cos \alpha_i}{1 + \cos (\alpha_i - \alpha_0)}$$

Outer Race Speed Ratio =
$$\frac{N_b (1-\gamma' \cos \alpha_i)}{1 + \cos (\alpha_i - \alpha_o)}$$

Inner Race Speed Ratio =
$$\frac{N_b \cos(\alpha_i - \alpha_o) + \gamma^t \cos \alpha_i}{1 + \cos(\alpha_i - \alpha_o)}$$

Ball Spin Ratio =
$$\left\{ \left[(\cos \alpha_0 + \tan \beta \sin \alpha_0) (1 + \gamma' \cos \alpha_0)^{-1} + (\cos \alpha_1 + \tan \beta \sin \alpha_1) (1 - \gamma' \cos \alpha_1)^{-1} \right] \gamma' \cos \beta \right\}^{-1}$$

where
$$\tan \beta = \frac{\sin \alpha_0}{\cos \alpha_0 + \gamma^1}$$

and α_{o} = outer raceway contact angle

 α_i = inner raceway contact angle

 $\gamma' = D/d_m$

D = ball diameter

d_m = pitch diameter

 N_{h} = number of balls

¹Tedric A. Harris. Rolling Bearing Analysis, John Wiley & Sons, New York, 1966.

The bearing parameters used for this study are as follows:

High Pressure Fuel Turbopump (HPFTP)

Pump and turbine bearings:

Ball diameter = 0.343750 inch

Pitch diameter = 2.34 inches

Number of balls = 14

Thrust bearings:

Ball diameter = 0.656250 inch

Pitch diameter = 3.84 inches

Number of balls = 13

High Pressure Oxygen Turbopump (HPOTP)

Turbine end bearings:

Ball diameter = 0.50 inch

Pitch diameters = 3.196, 3.17, 3.20, and 3.19 inches

Number of balls = 13

Pump end bearings:

Ball diameter = 0.4375 inch

Pitch diameter = 2.56 inches

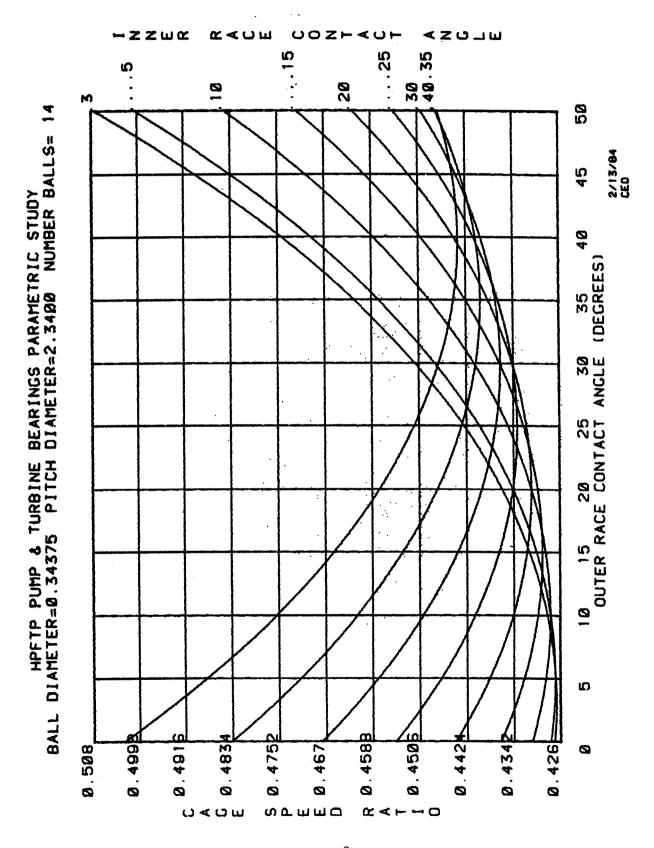
Number of balls = 13

SPEED RATIO OF HPFTP PUMP AND TURBINE BEARINGS

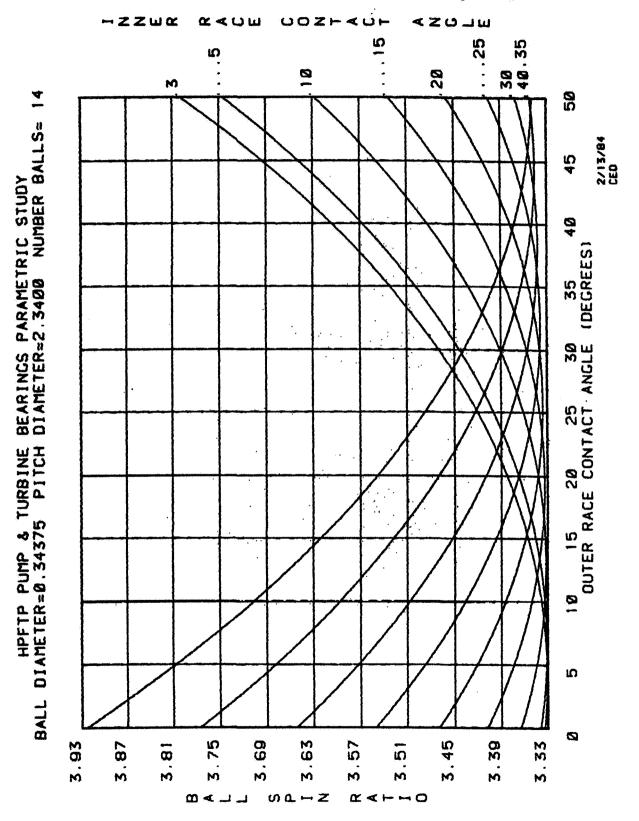
Ball Diameter = 0.343750 inch

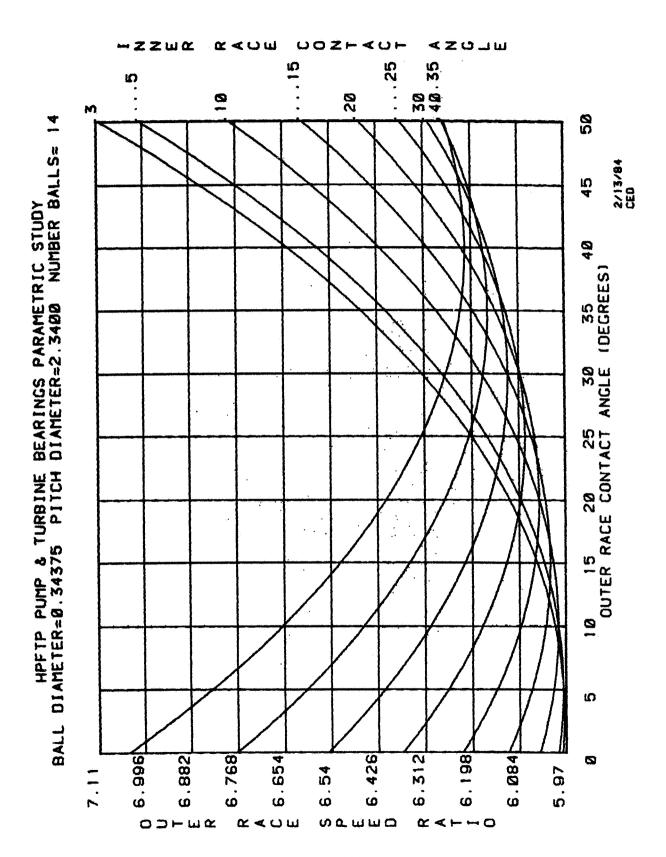
Pitch Diameter = 2.34 inches

Number of Balls = 14



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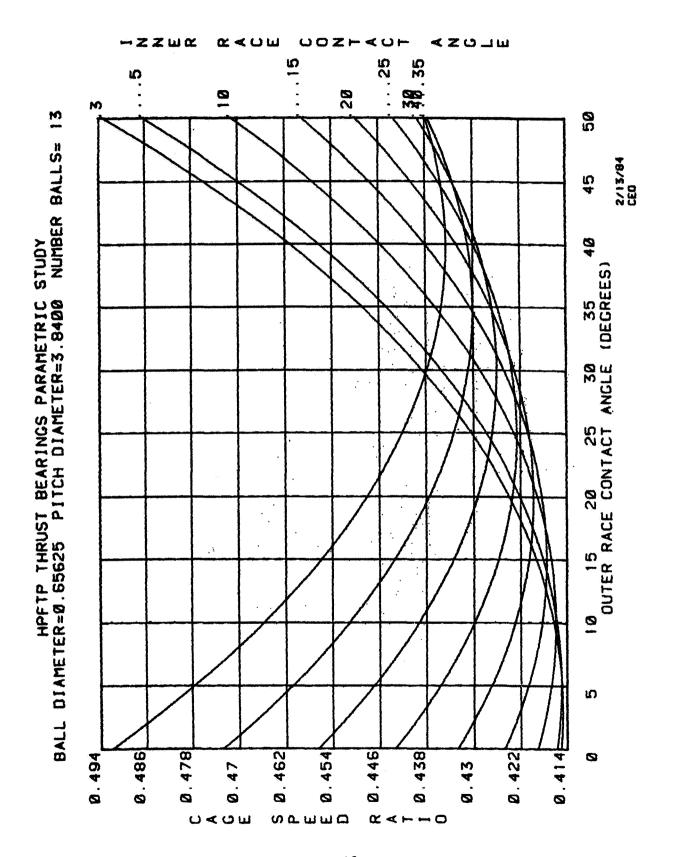
-ZZWC R K C III UOZH 4UF **WLOZ** 5 40.35 30 . . . 25 ري : 20 9 M 50 HPFTP PUMP & TURBINE BEARINGS PARAMETRIC STUDY BALLS= 14 2/13/84 CE0 45 40 1 15 20 25 30 35 OUTER RACE CONTACT ANGLE (DEGREES) 9 S 7.802 7.574 7.346 7.232 7.118 7.916 7.688 7.004 0 7.46 6.83 8.03 **∢**∪ш œ œ Q Π Π Π Π

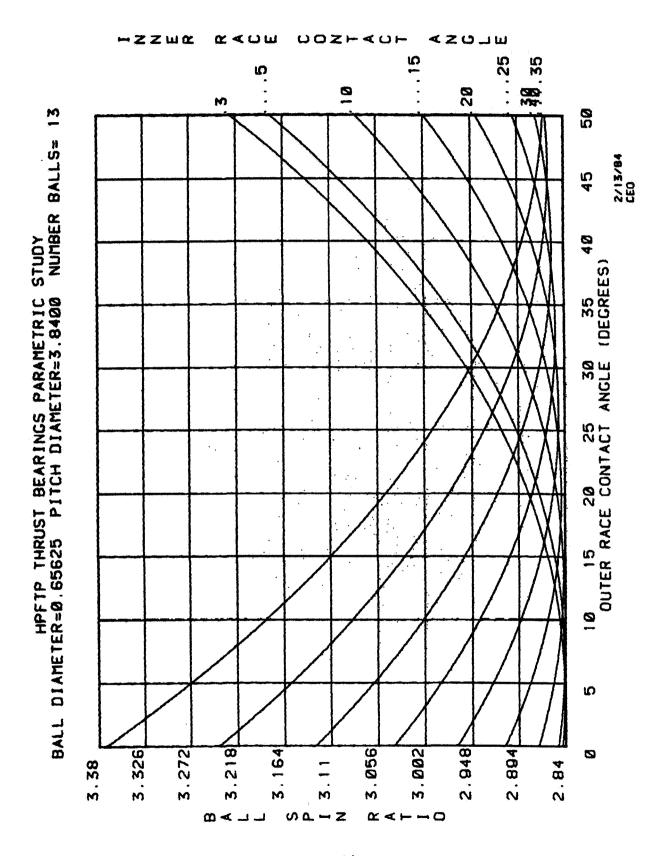
SPEED RATIO OF HPFTP THRUST BEARINGS

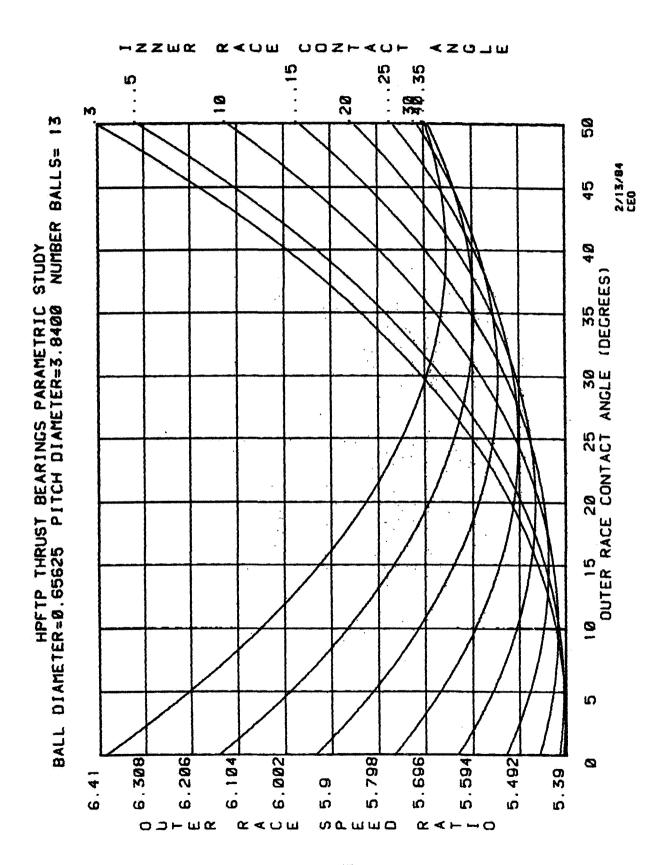
Ball Diameter = 0.656250 inch

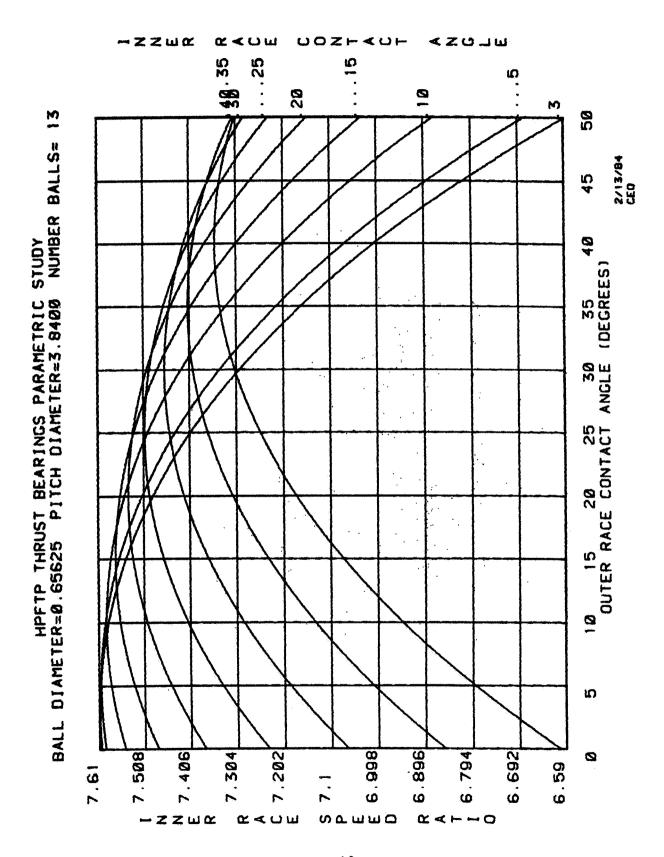
Pitch Diameter = 3.84 inches

Number of Balls = 13







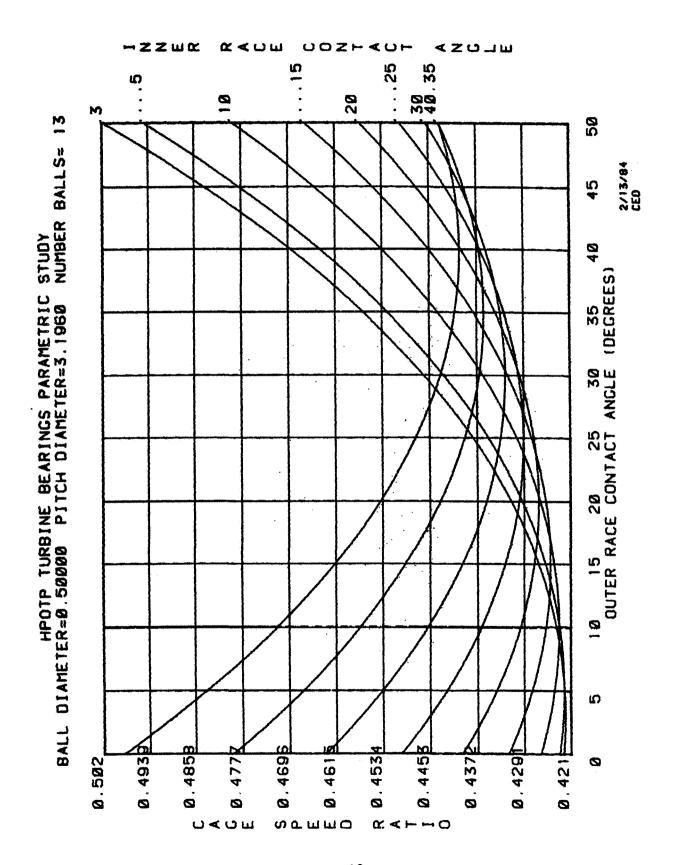


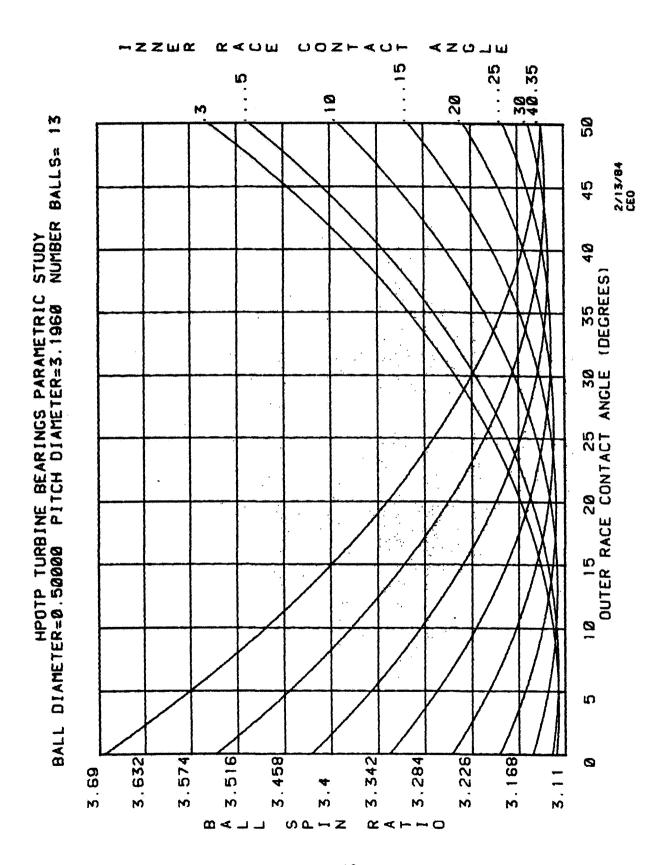
SPEED RATIO OF HPOTP TURBINE BEARINGS

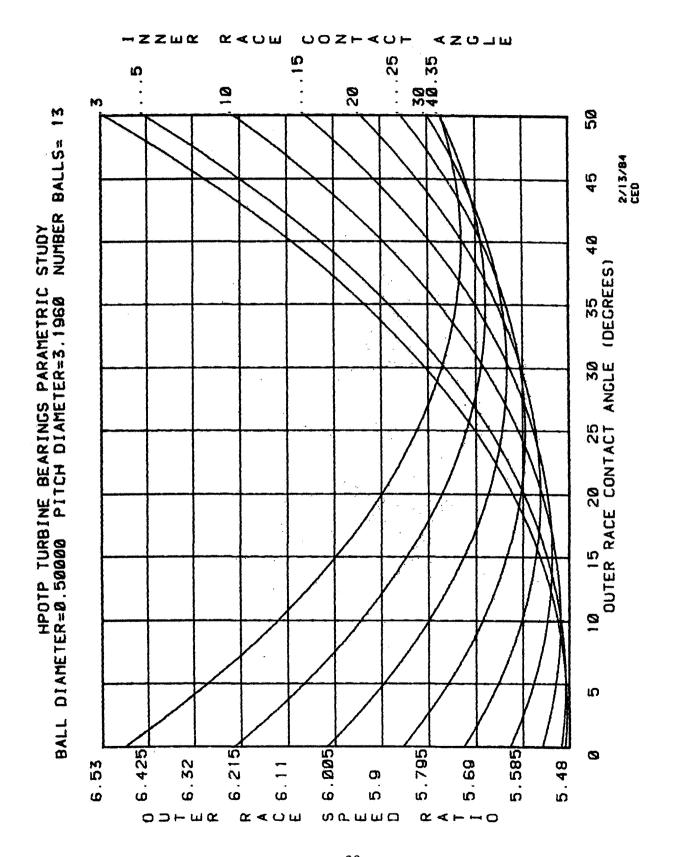
Ball Diameter = 0.50 inch

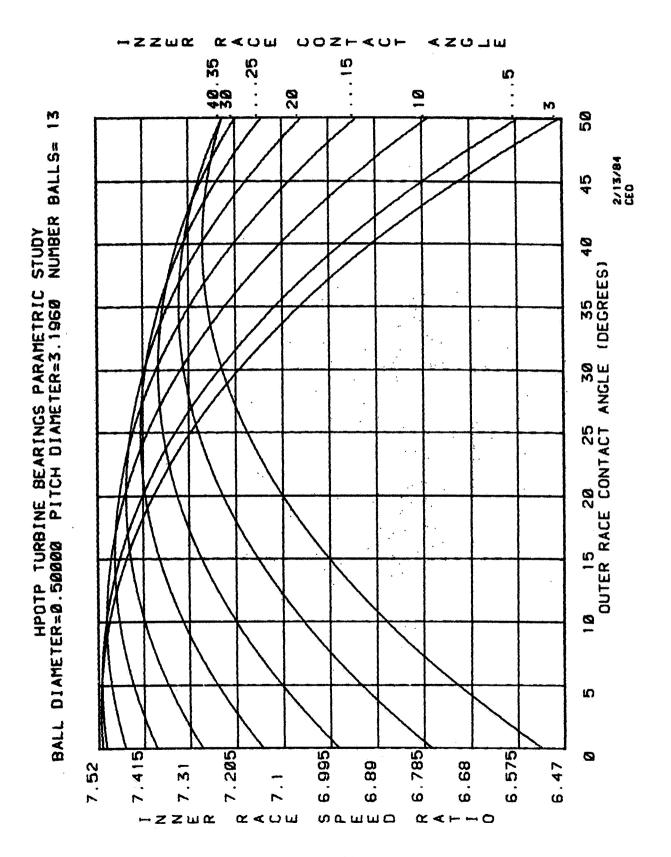
Pitch Diameter = 3.196 inches

Number of Balls = 13







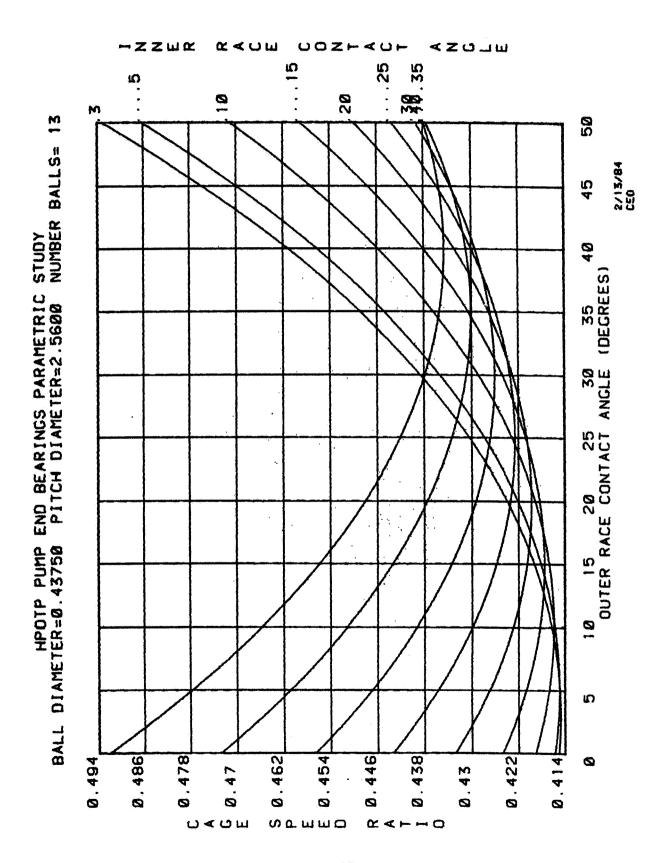


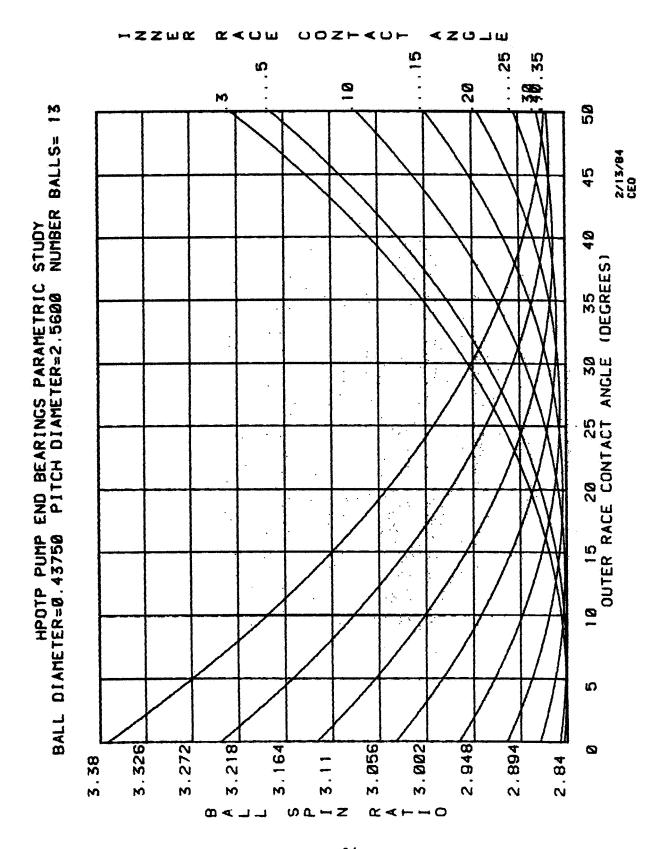
SPEED RATIO OF HPOTP PUMP END BEARINGS

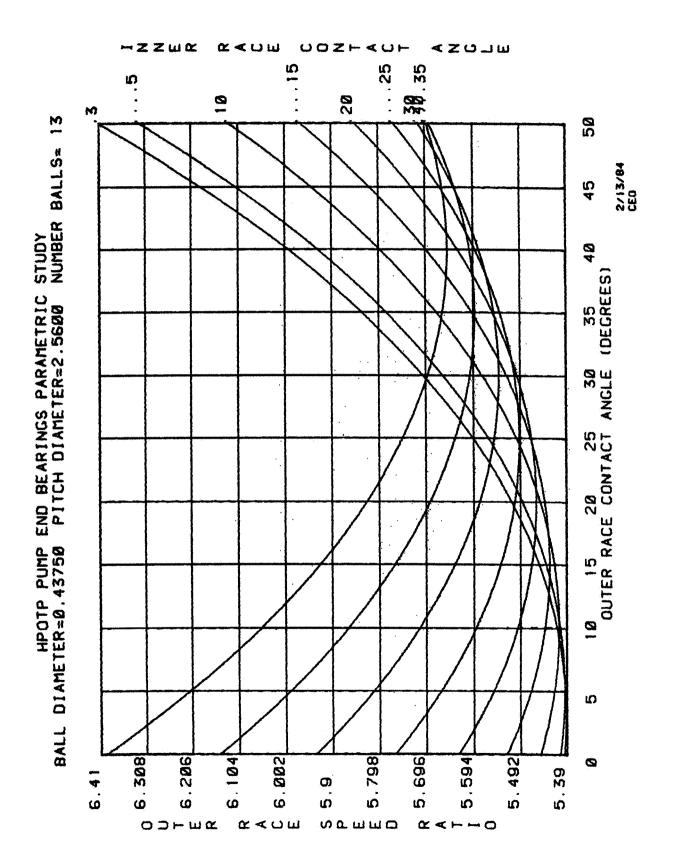
Ball Diameter = 0.4375 inch

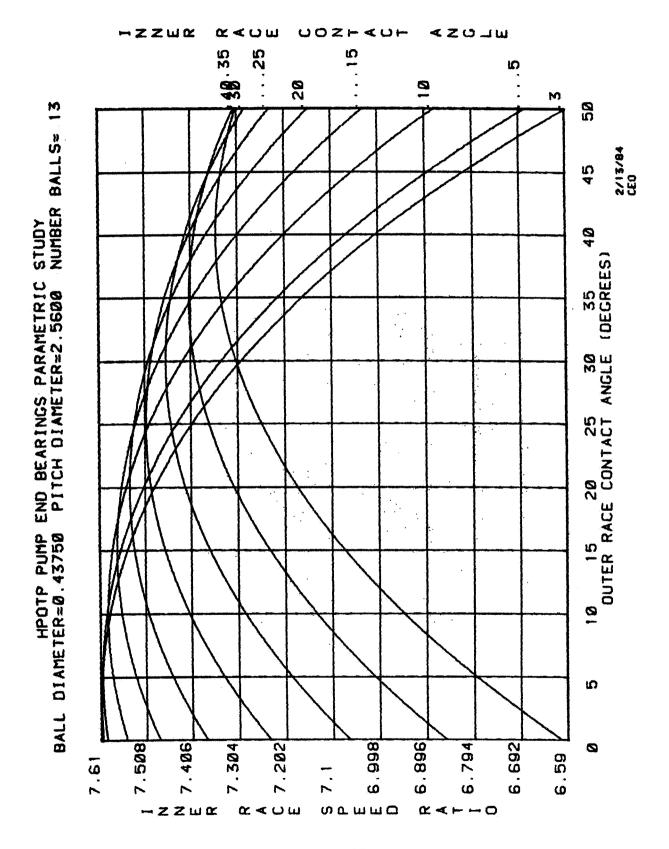
Pitch Diameter = 2.56 inches

Number of Balls = 13







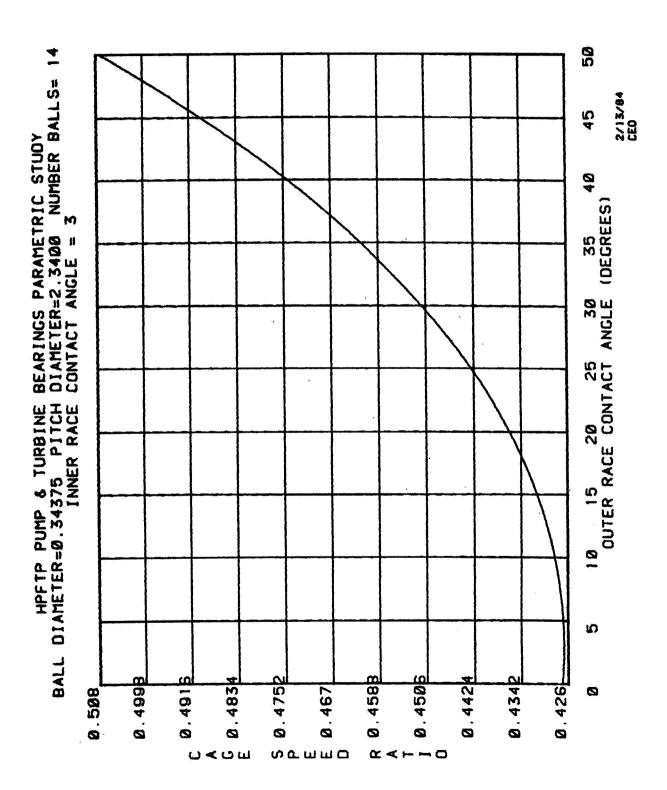


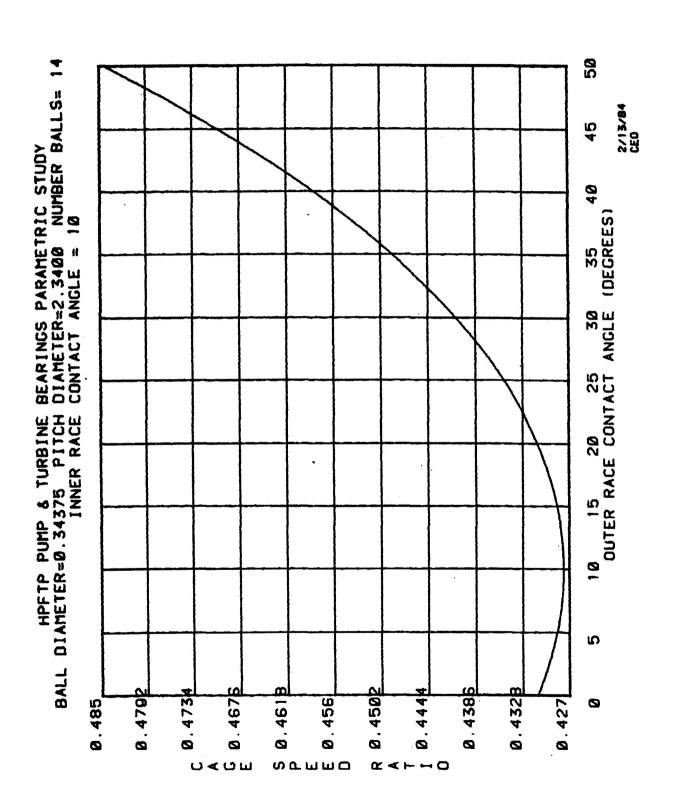
SPEED RATIO OF HPFTP PUMP AND TURBINE BEARINGS 3-, 10-, 20-, AND 30-DEGREE α_i (Inner Race Contact Angle)

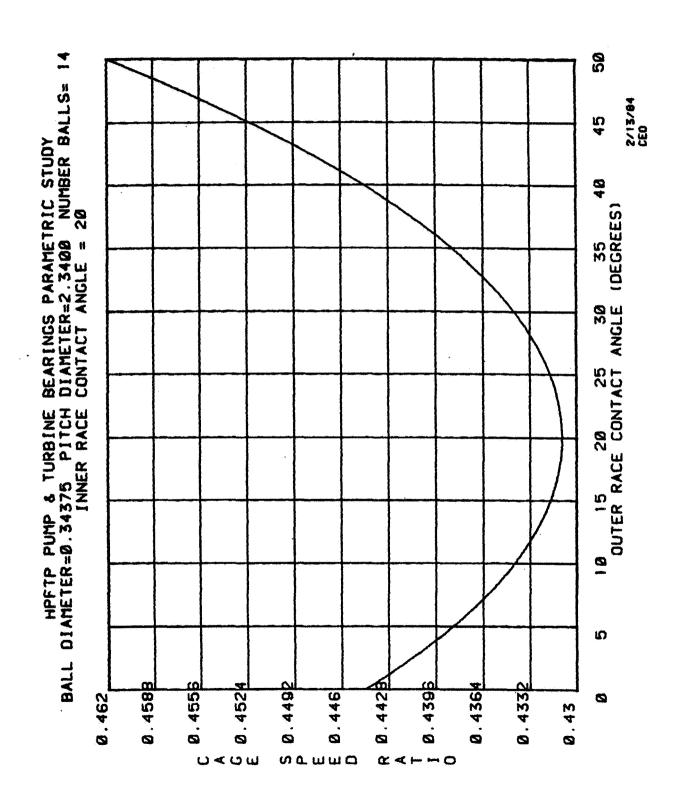
Ball Diameter = 0.343750 inch

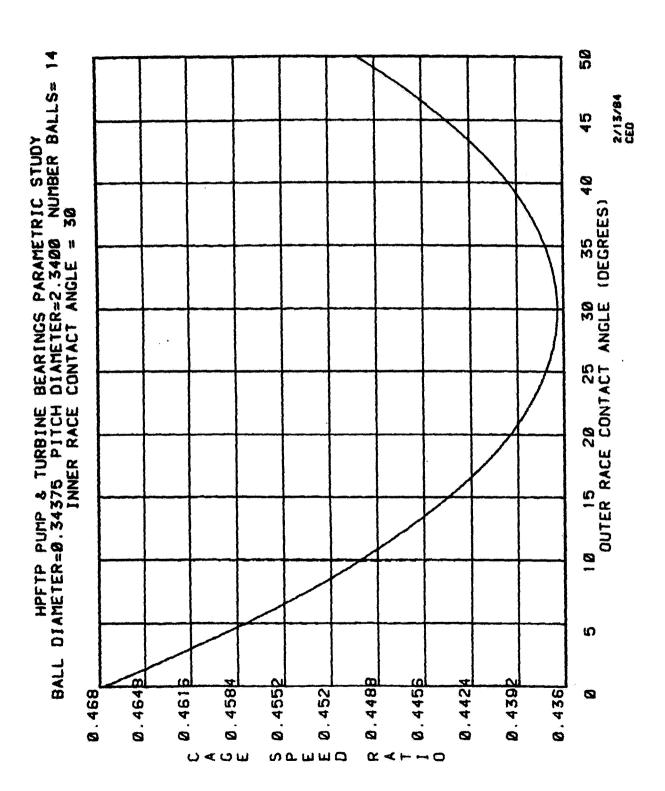
Pitch Diameter = 2.34 inches

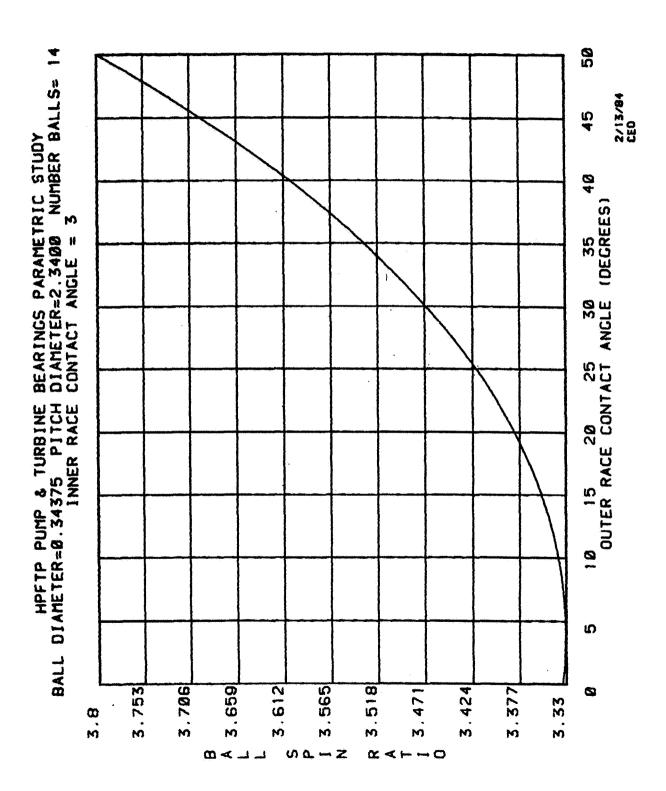
Number of Balls = 14

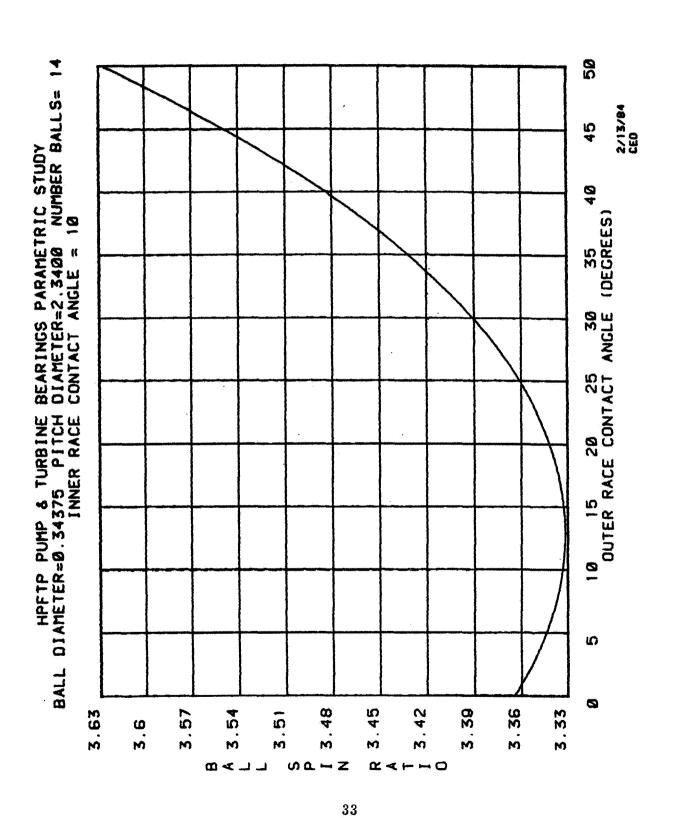


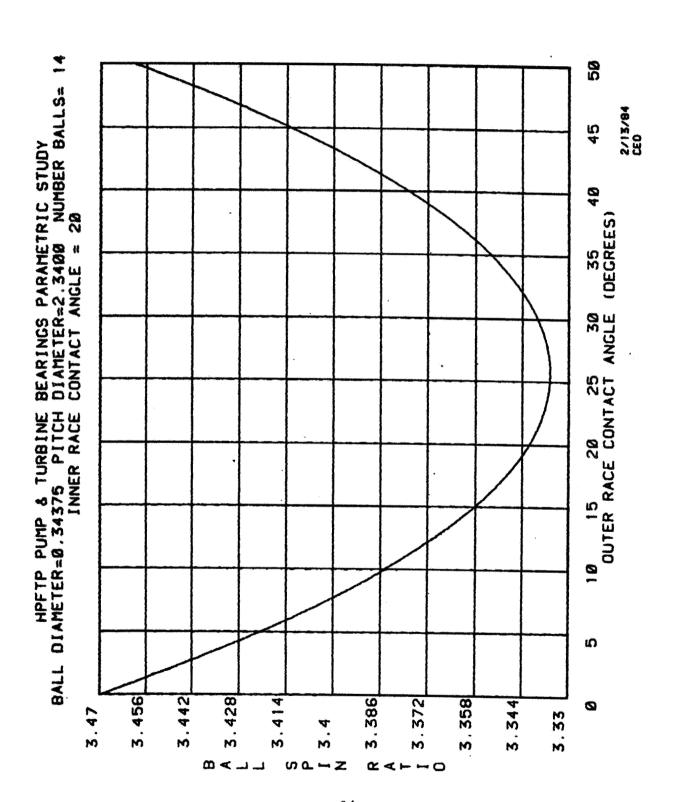


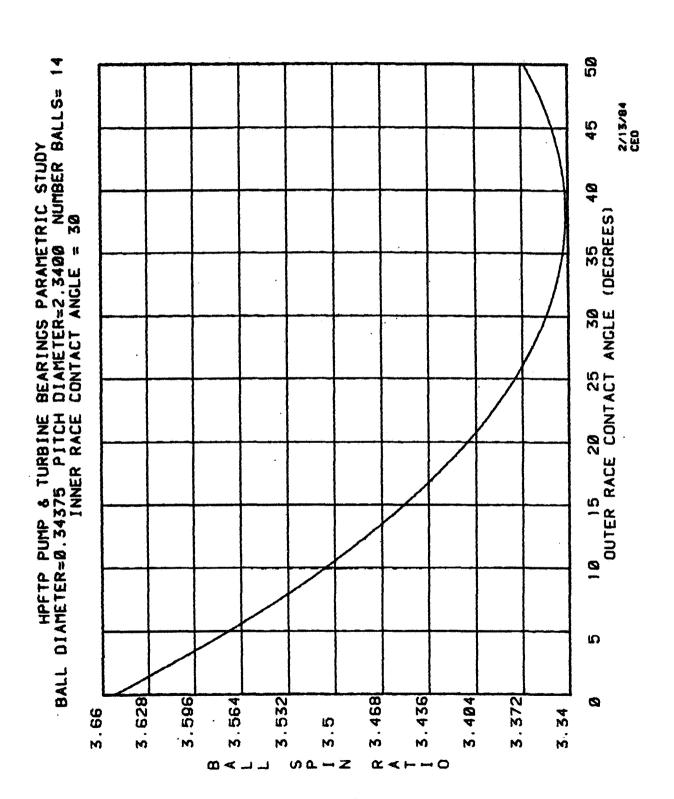


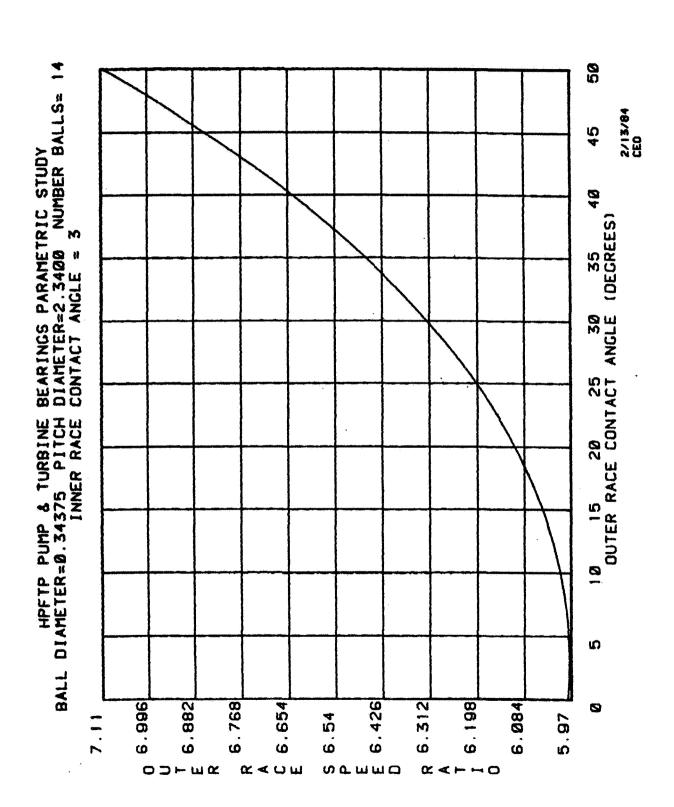


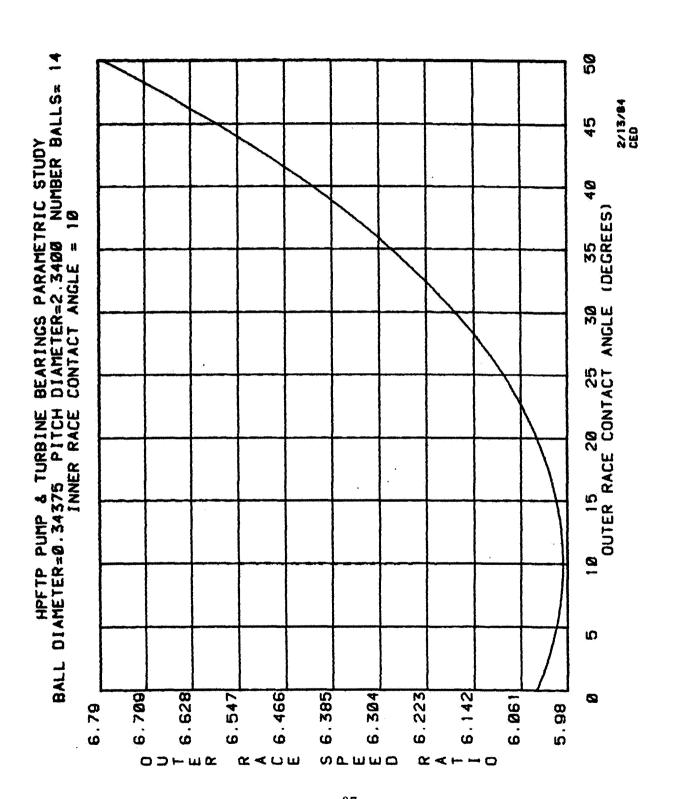


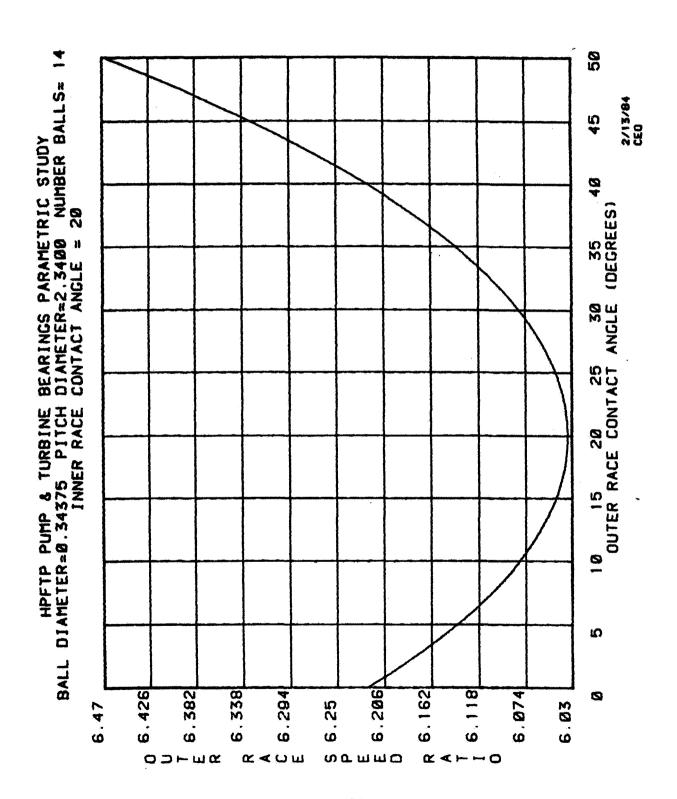


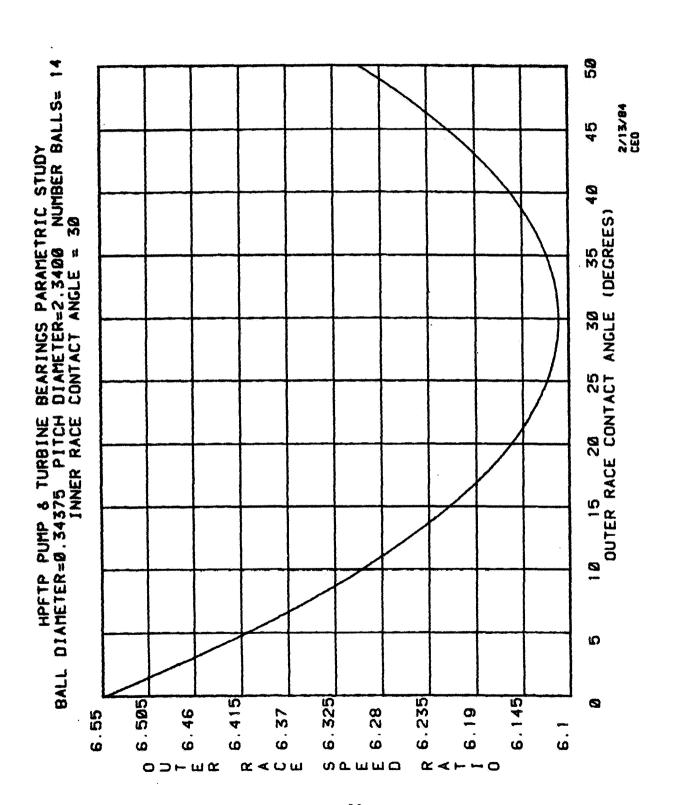


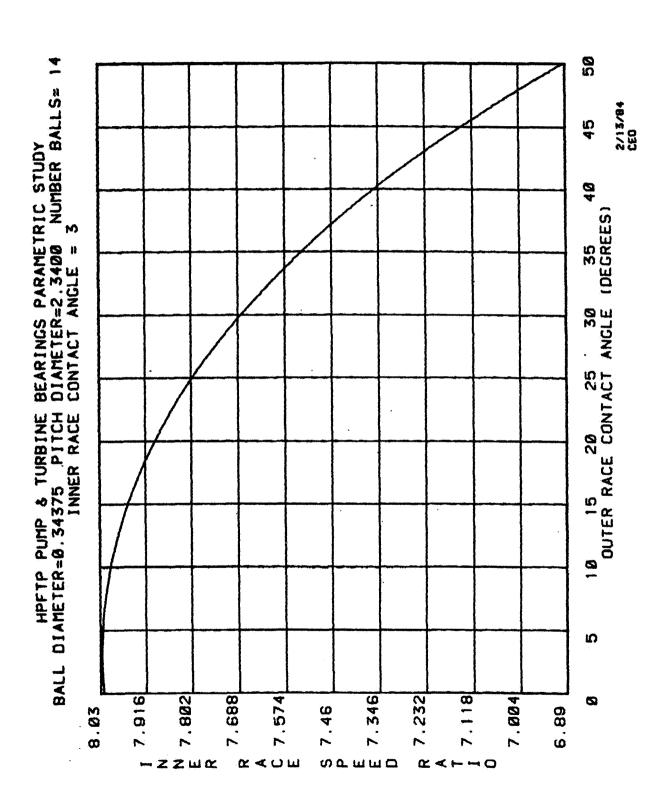


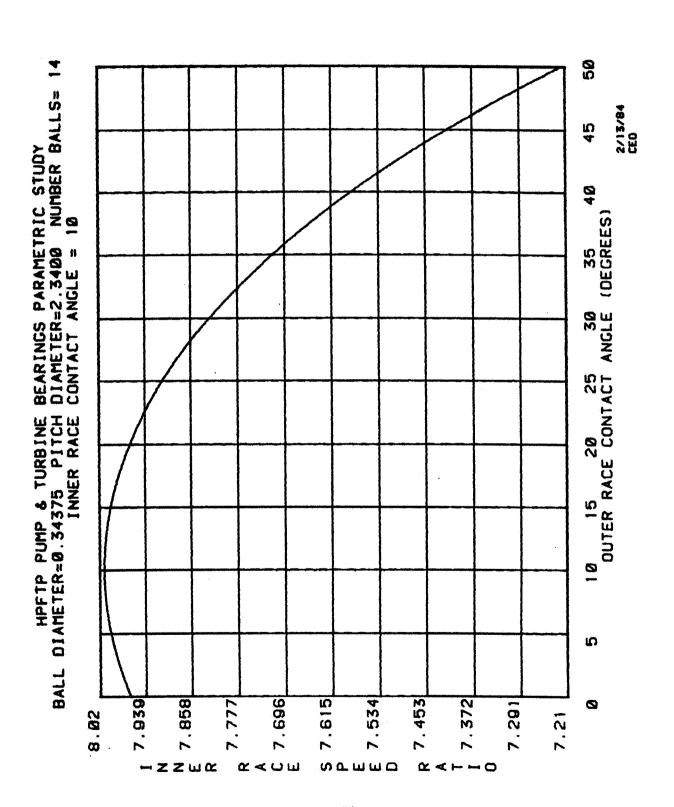


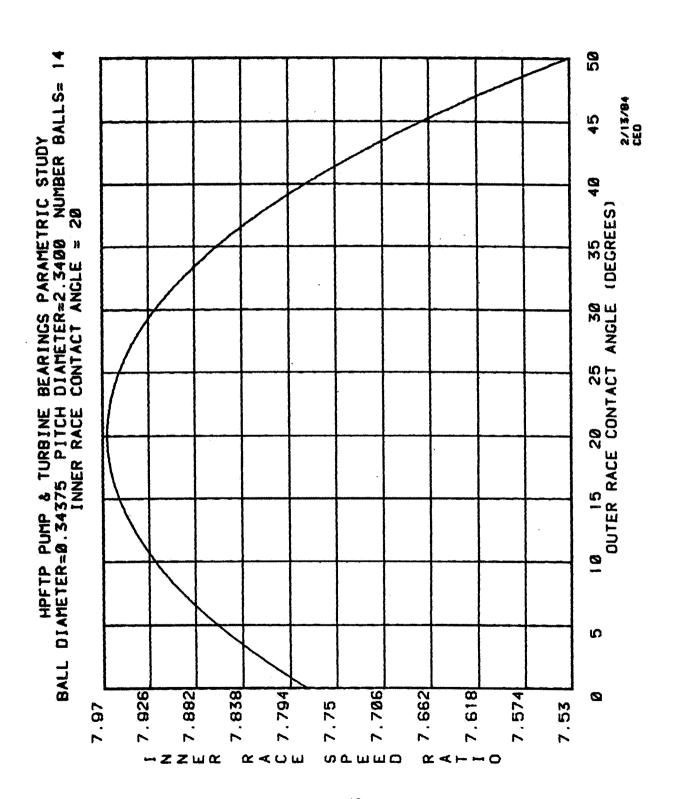


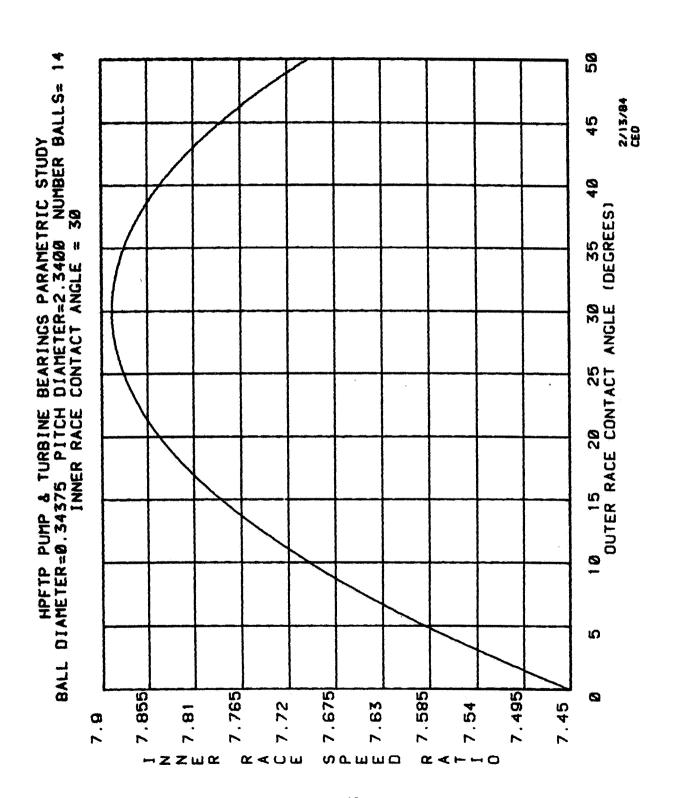










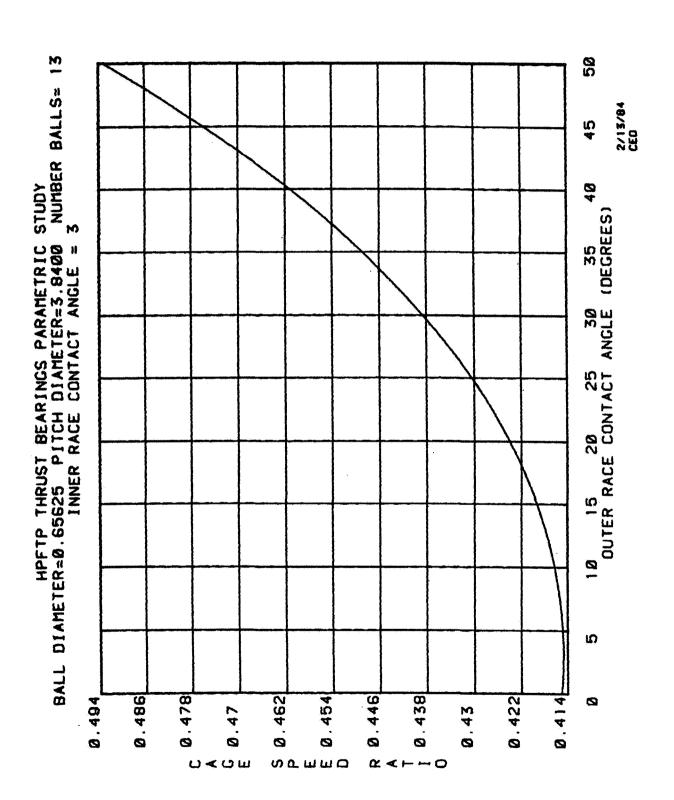


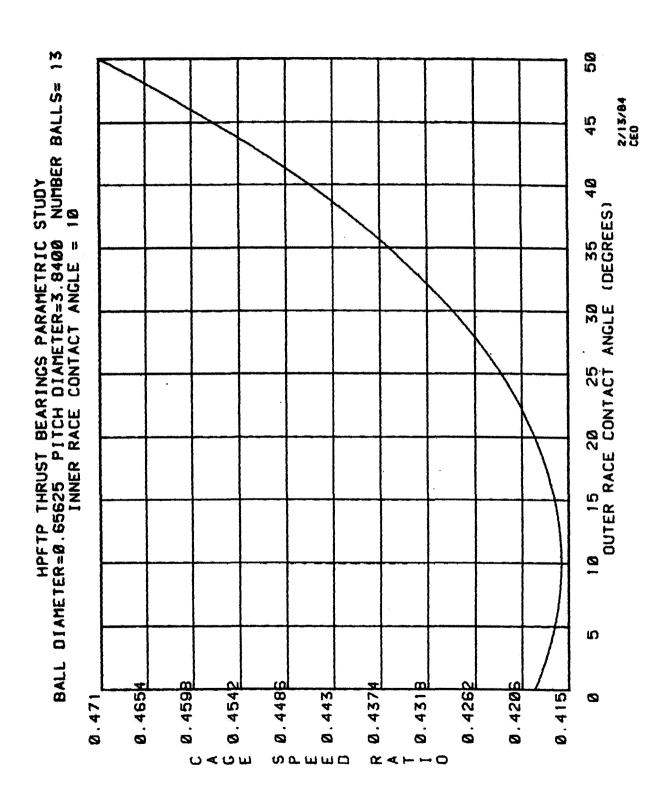
SPEED RATIO OF HPFTP THRUST BEARINGS 3-, 10-, 20-, AND 30-DEGREE α_{i} (Inner Race Contact Angle)

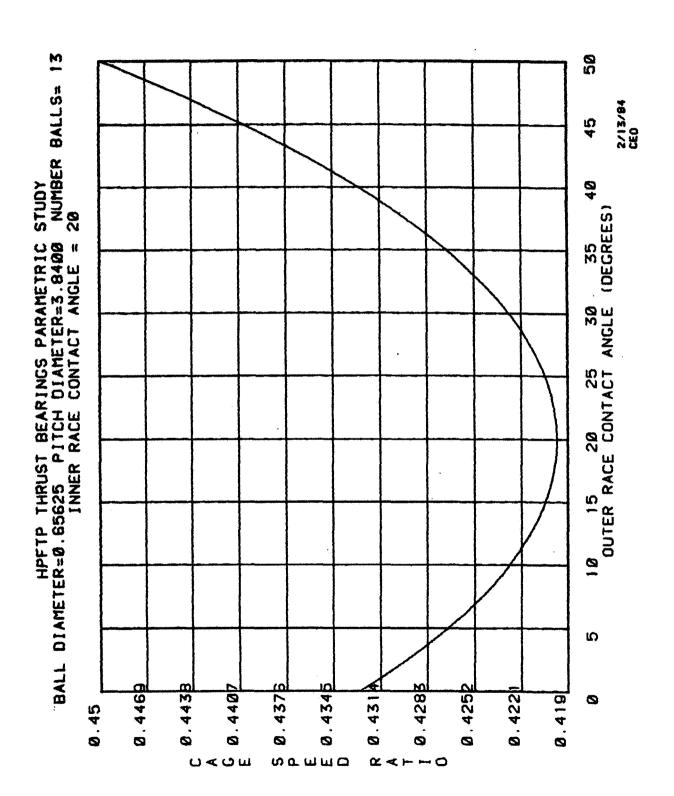
Ball Diameter = 0.656250 inch

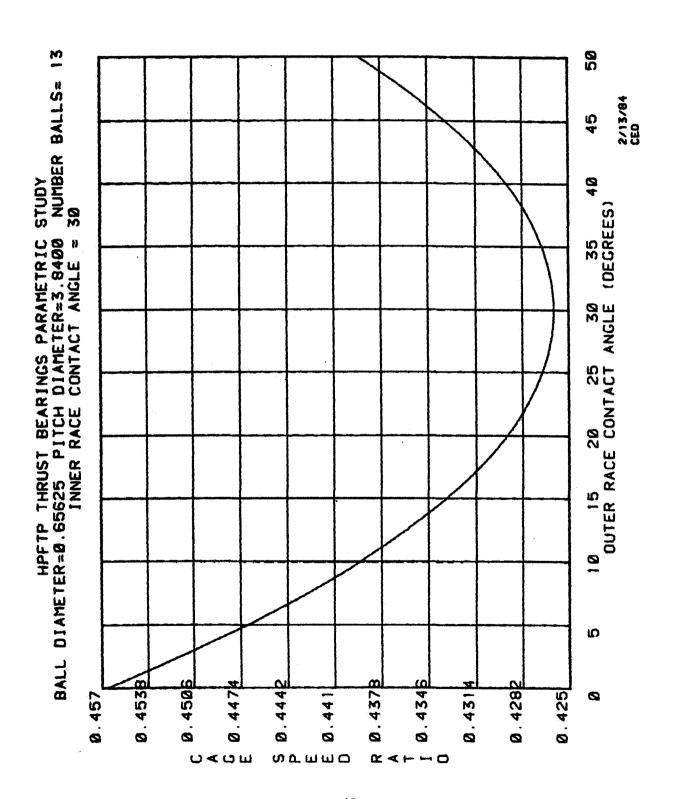
Pitch Diameter = 3.84 inches

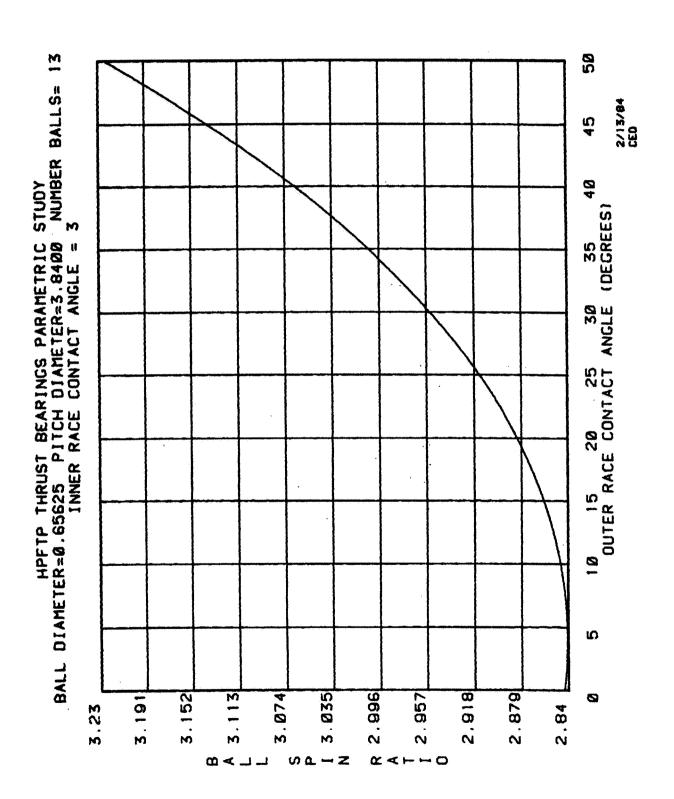
Number of Balls = 13

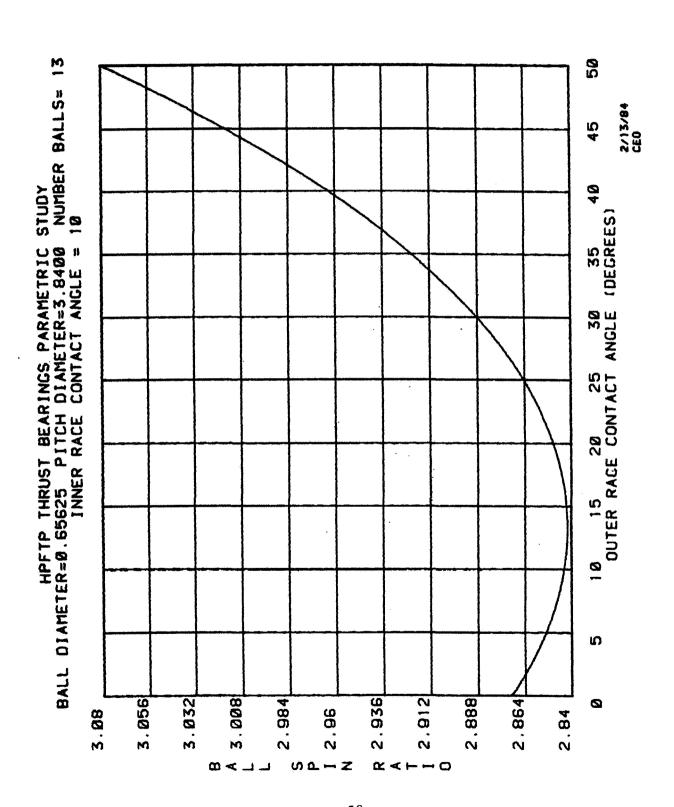


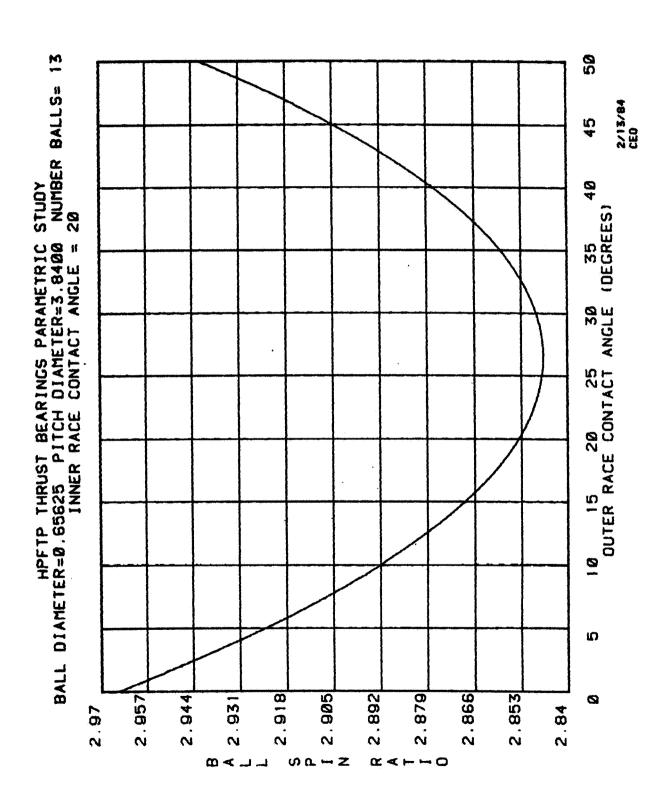


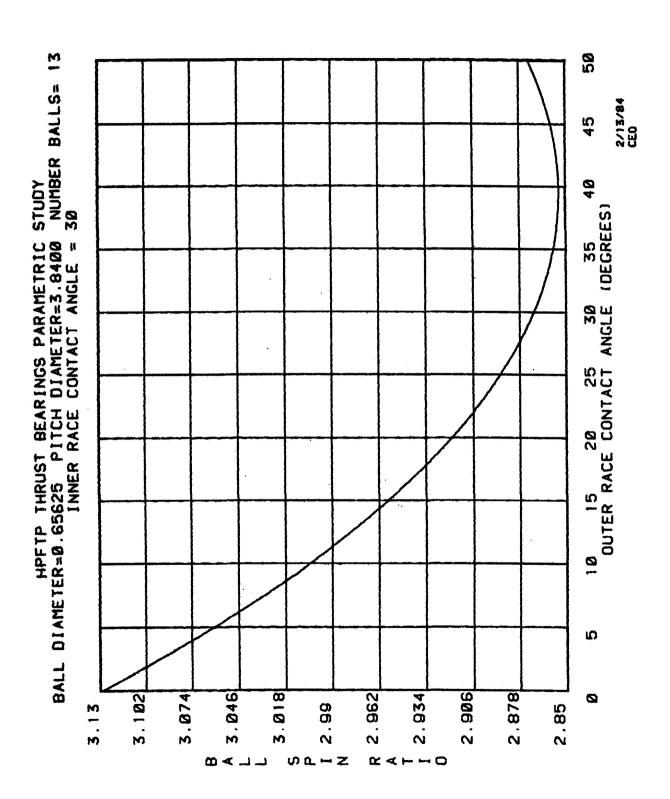


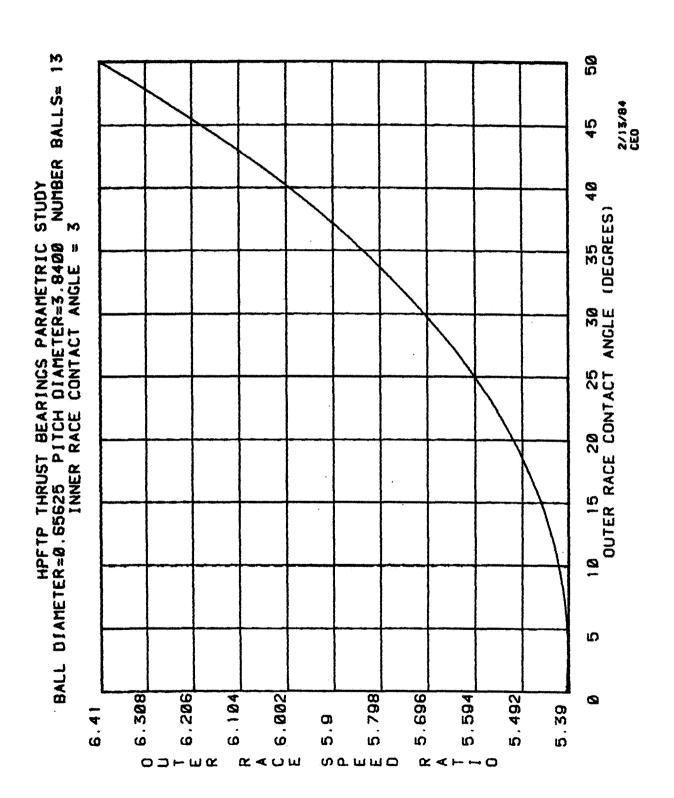


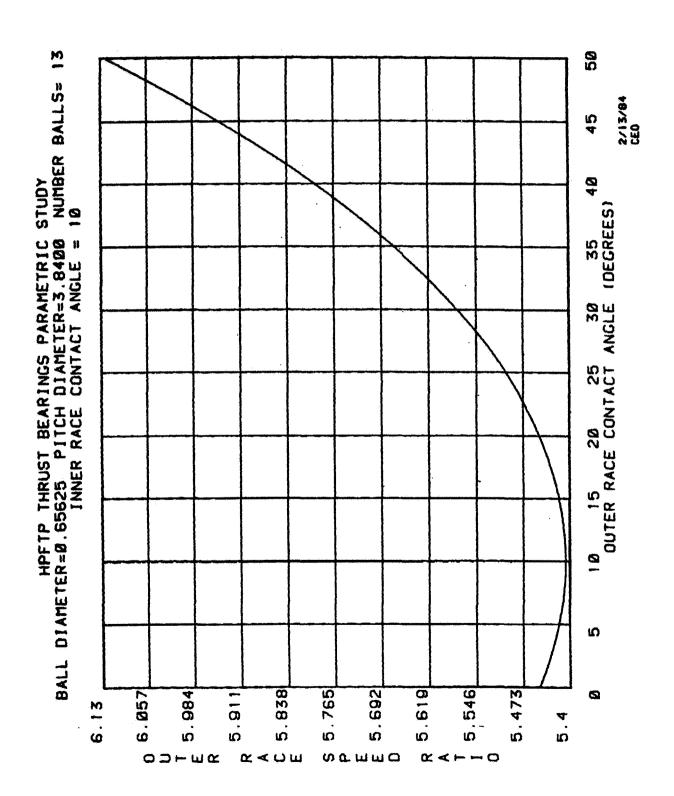


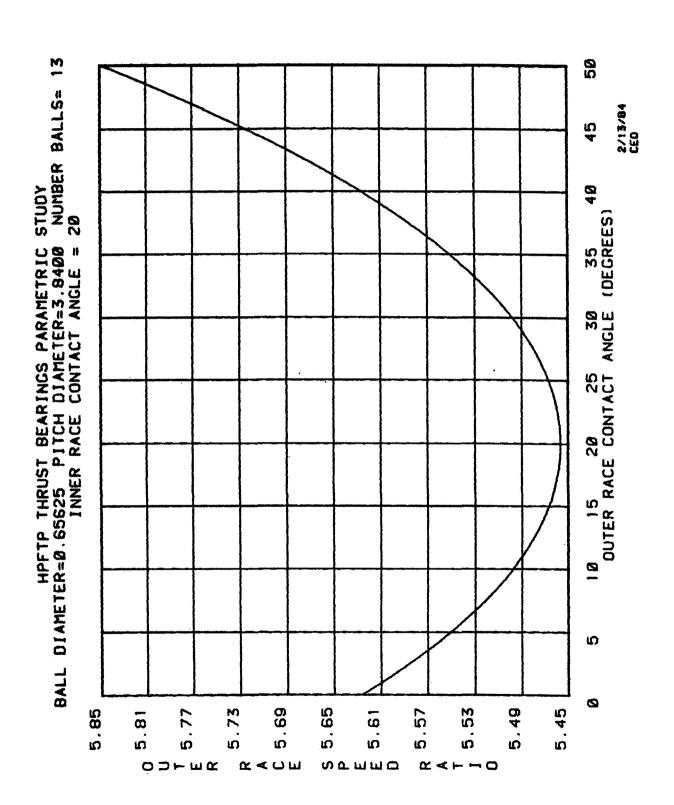


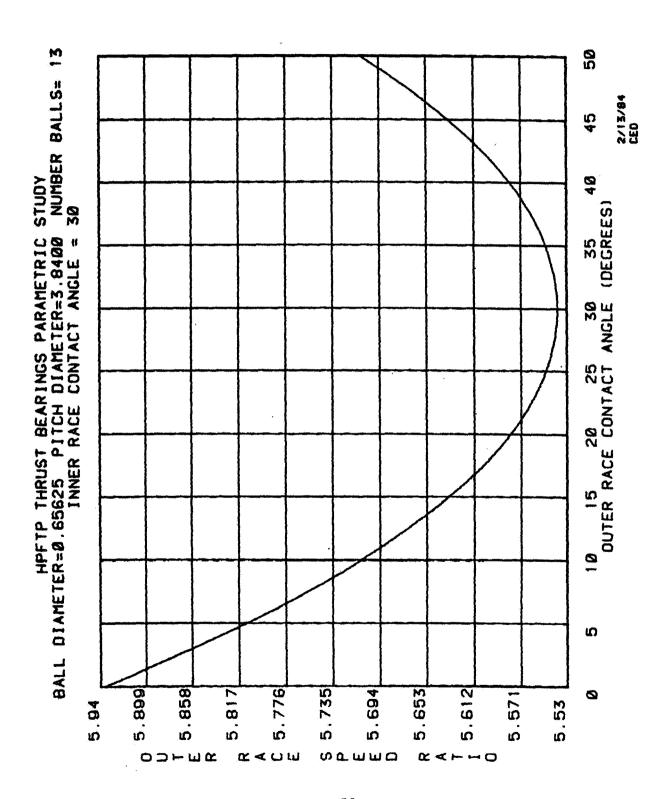


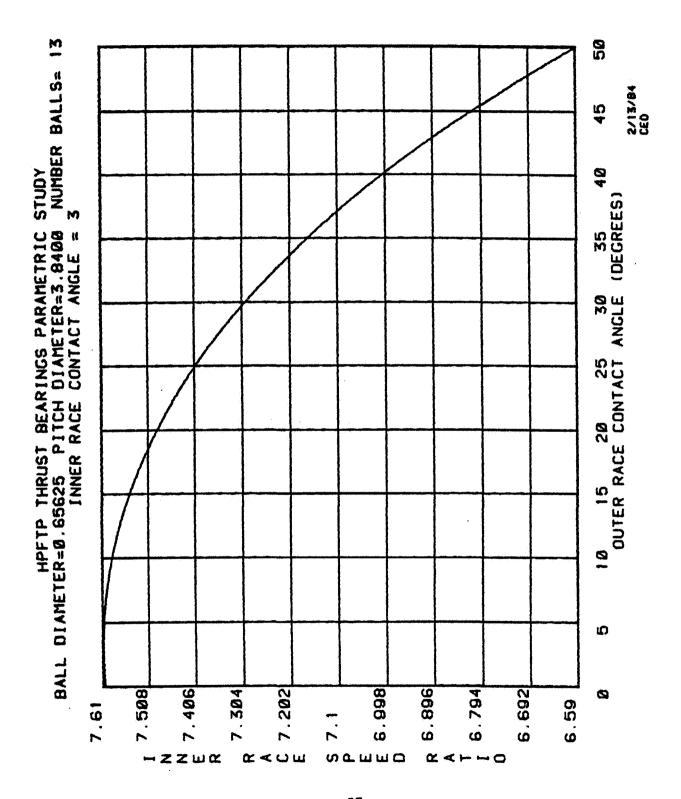


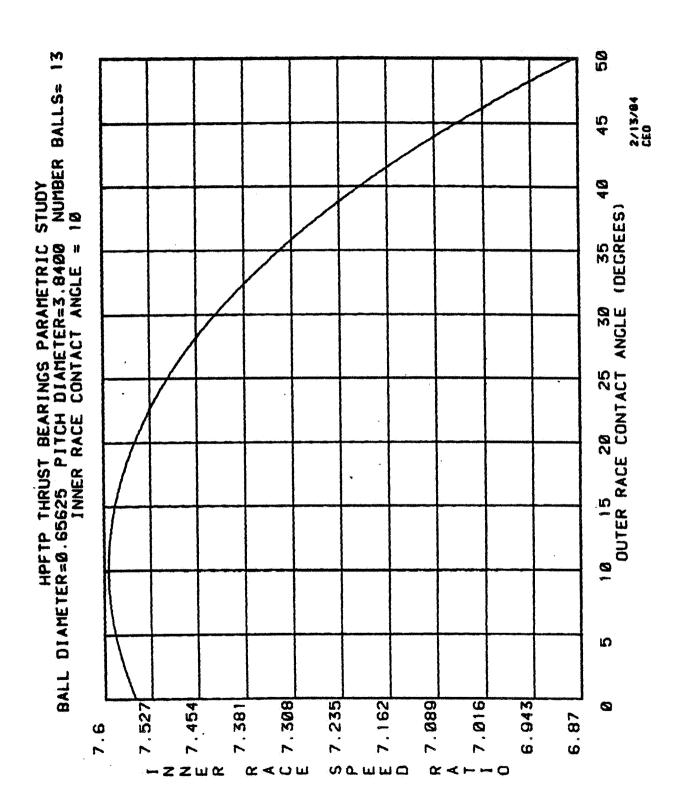


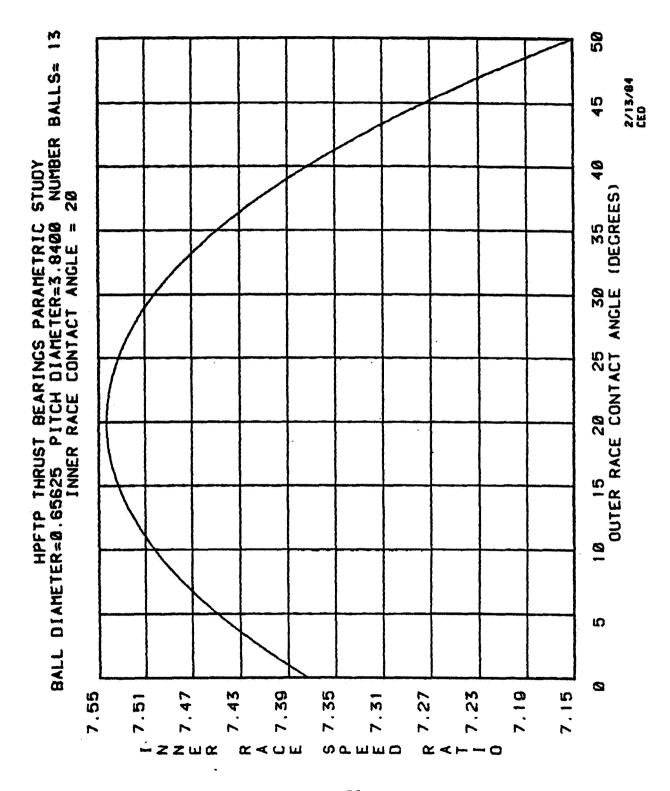


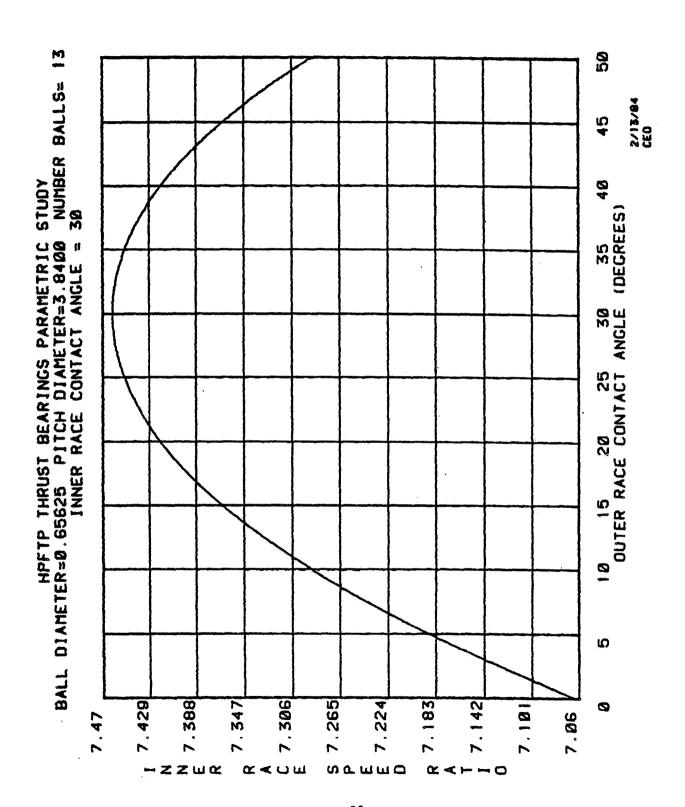










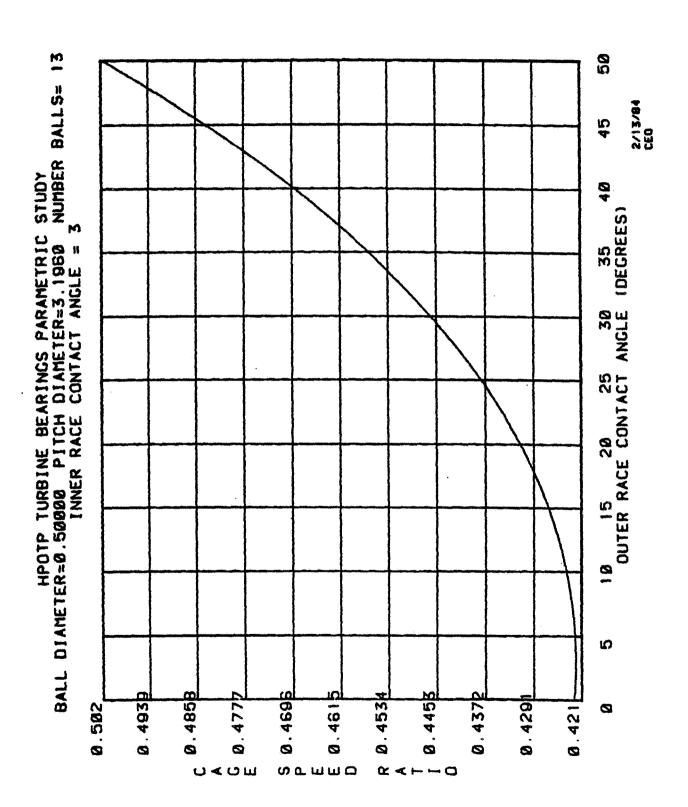


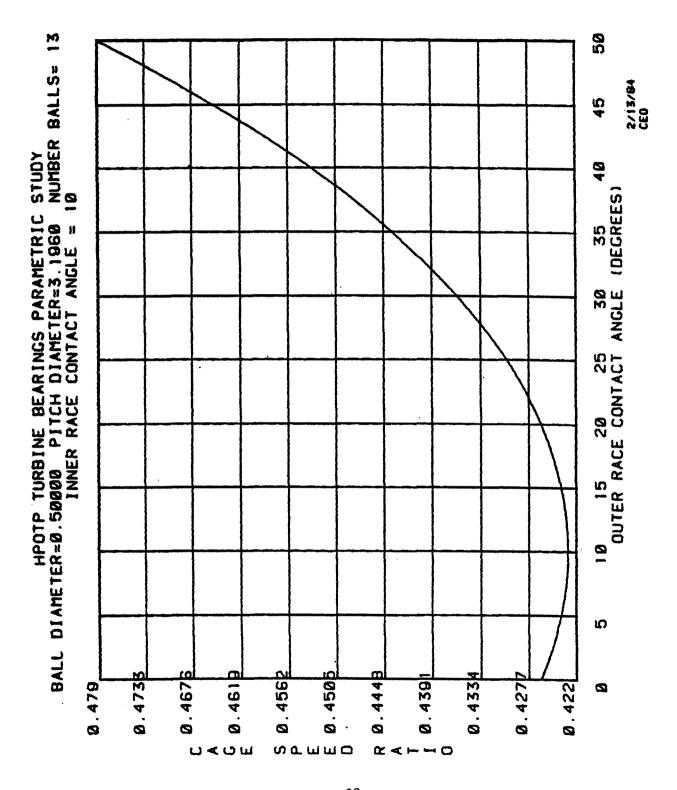
SPEED RATIO OF HPOTP TURBINE BEARINGS 3-, 10-, 20-, AND 30-DEGREE α_{i} (Inner Race Contact Angle)

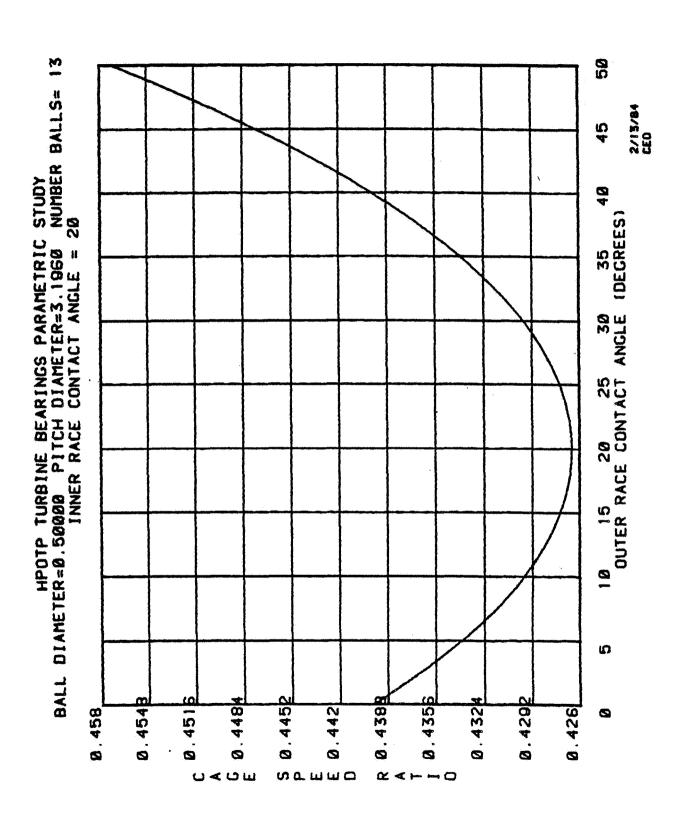
Ball Diameter = 0.50 inch

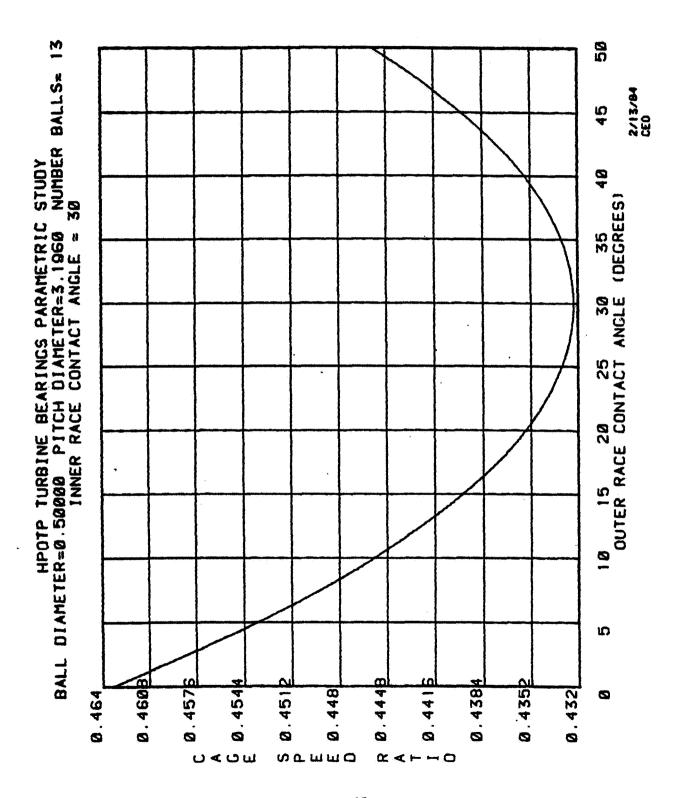
Pitch Diameter = 3.196 inches

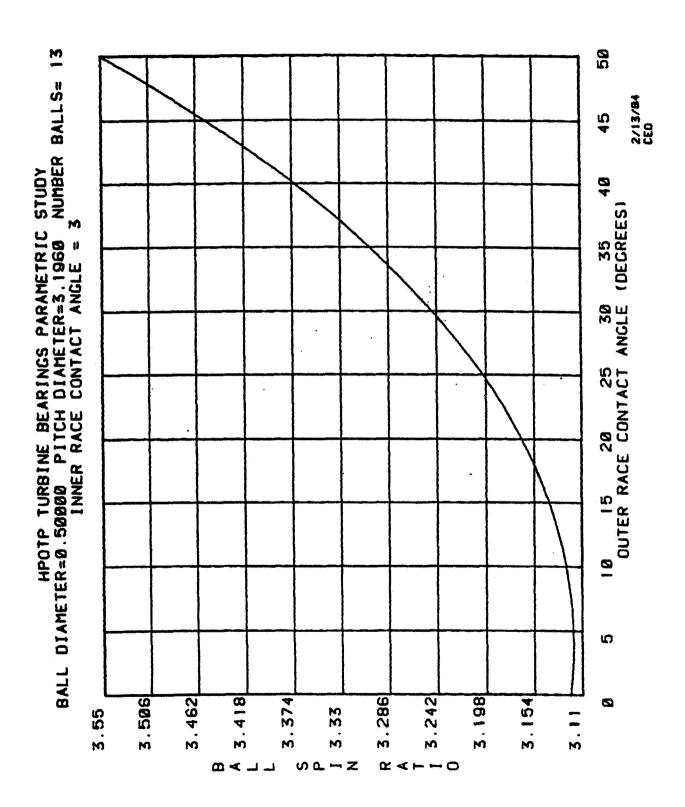
Number of Balls = 13

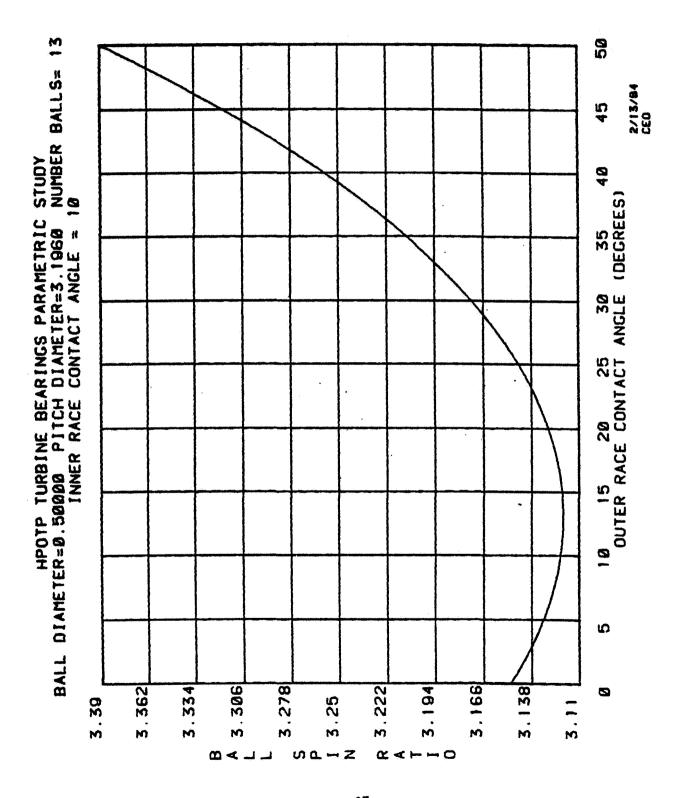


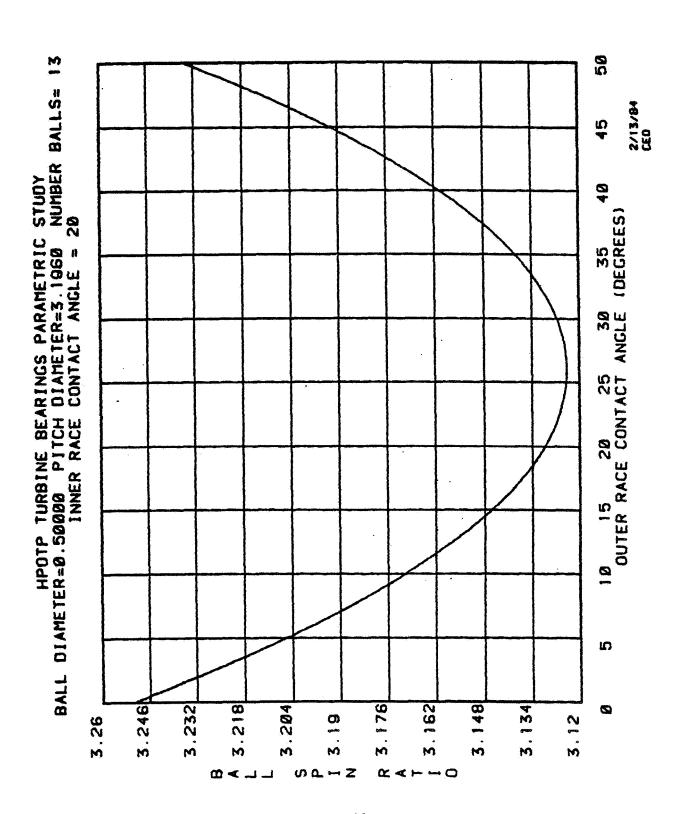


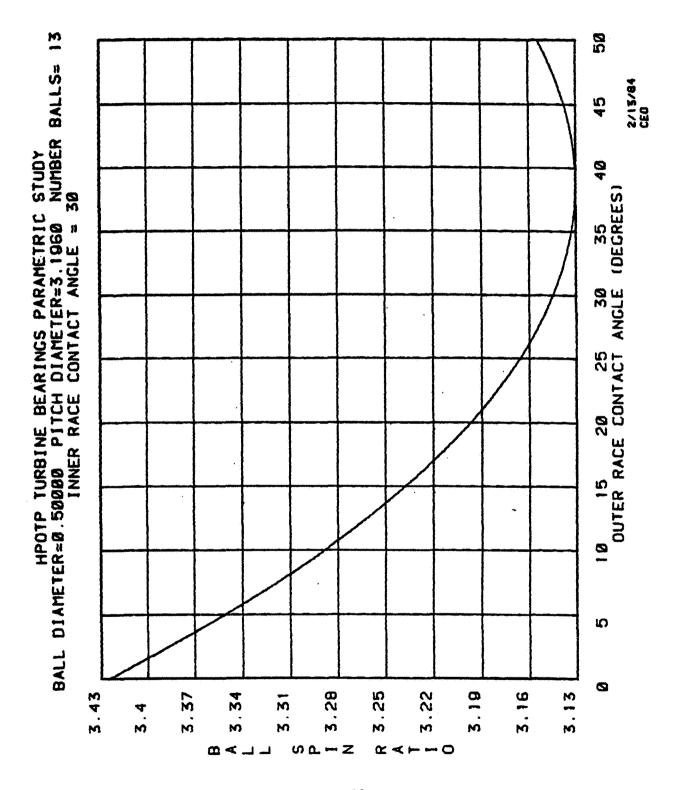


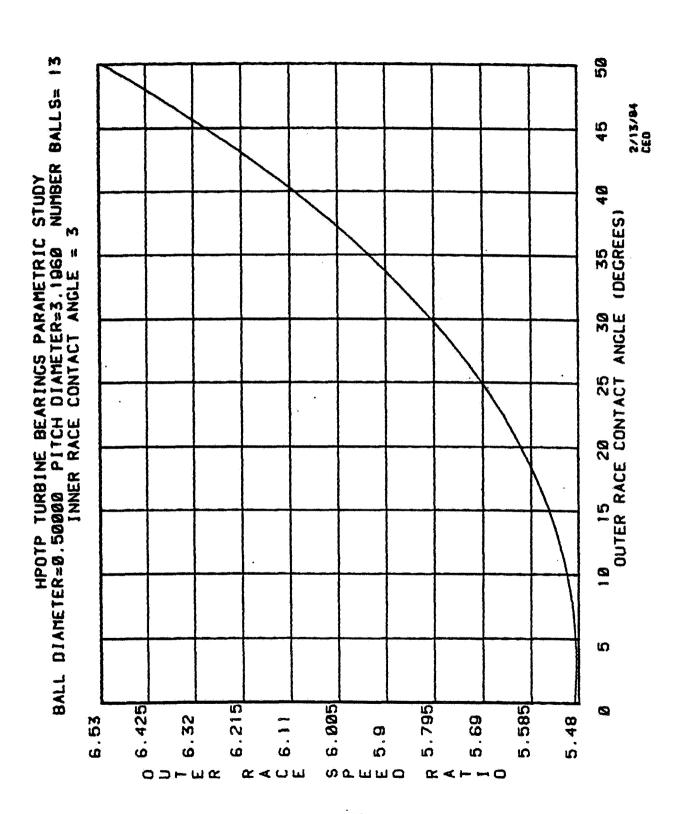


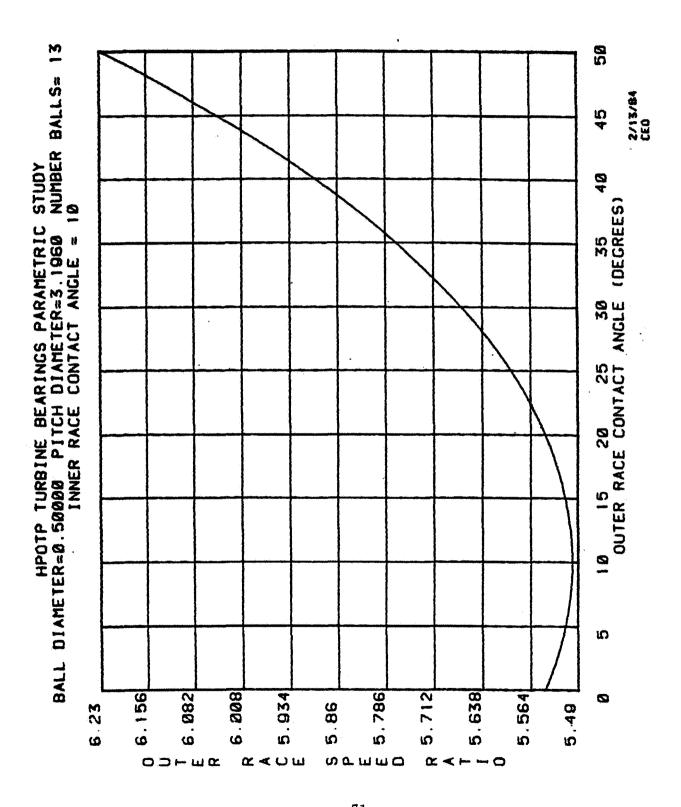


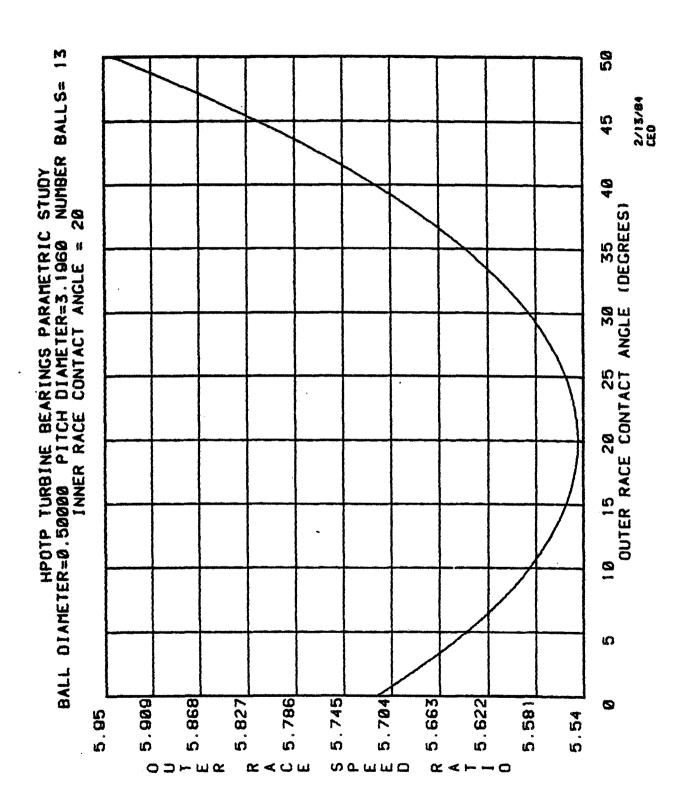


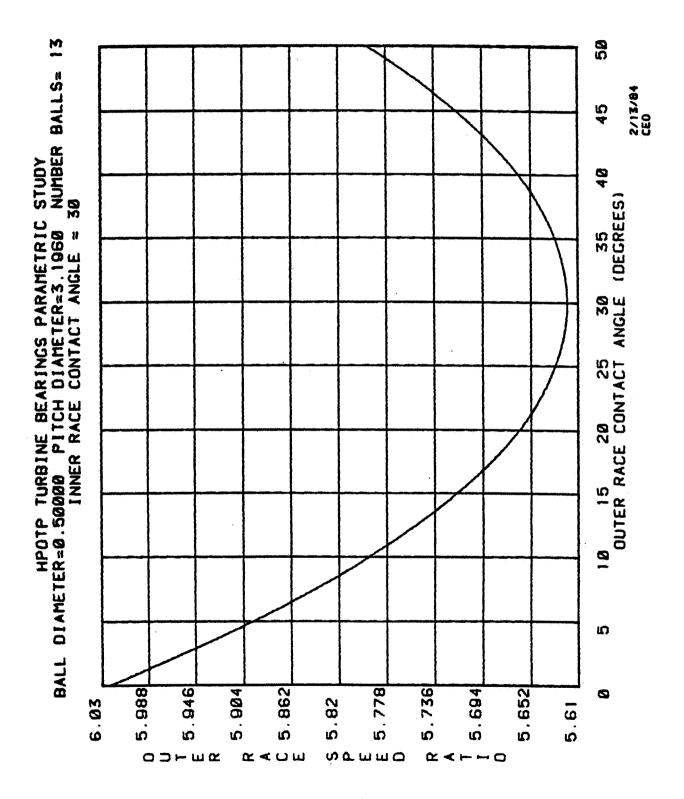


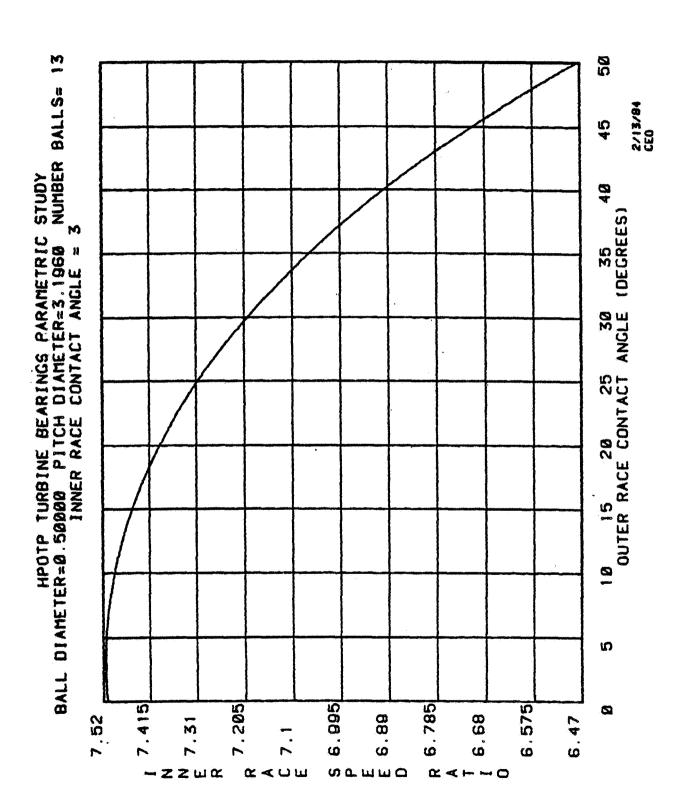


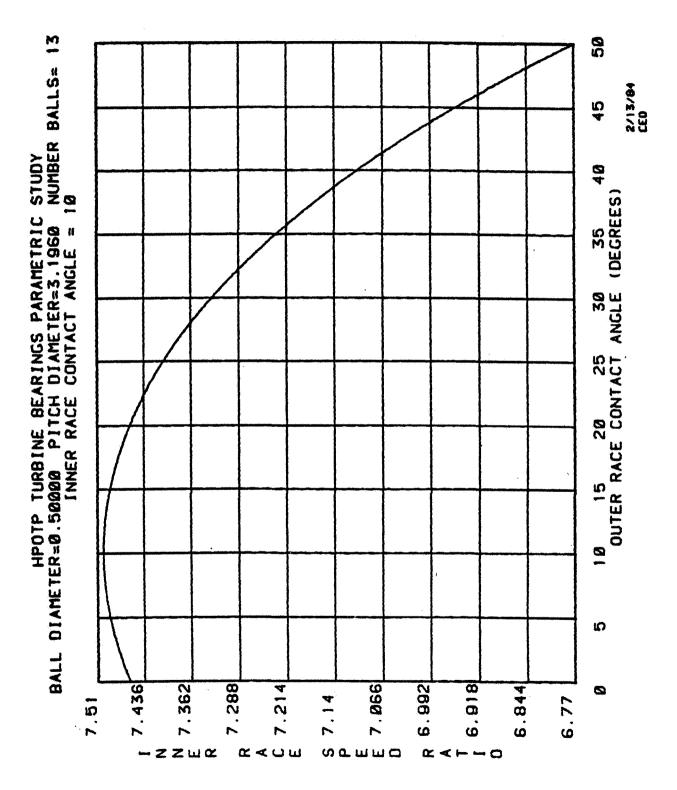


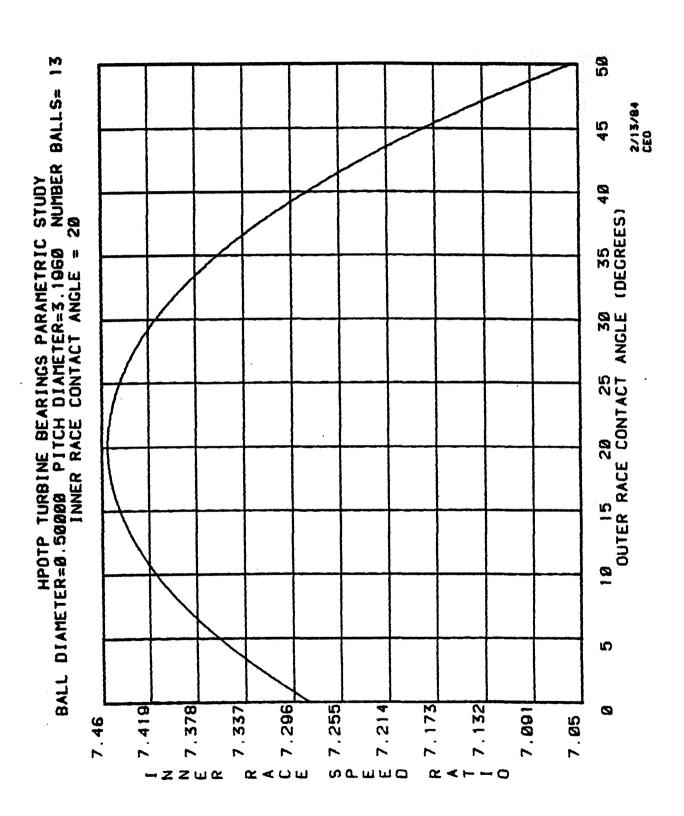


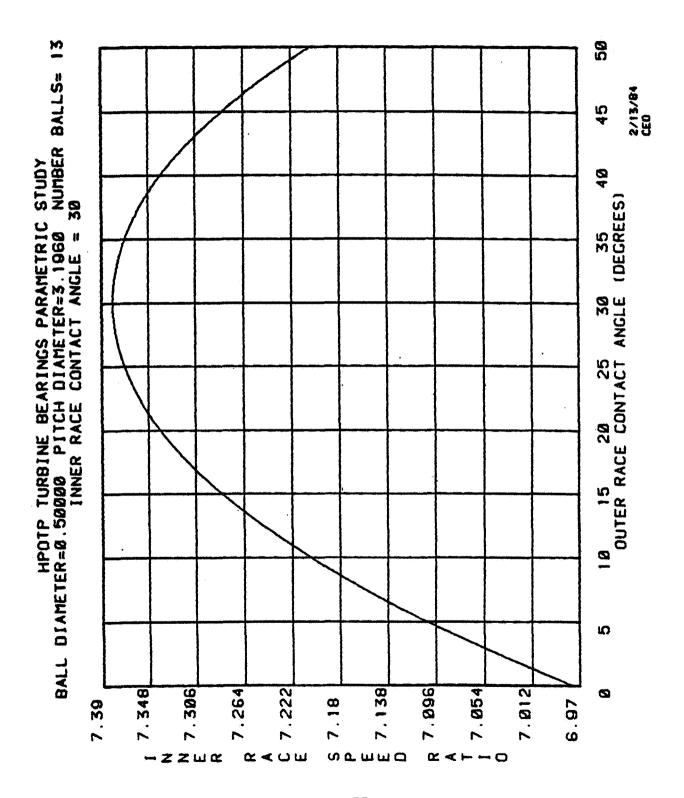










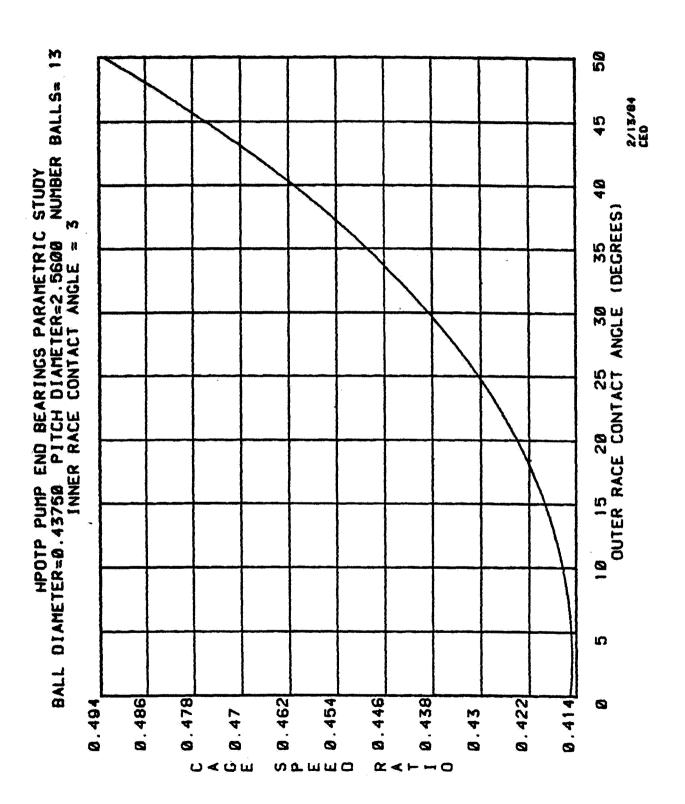


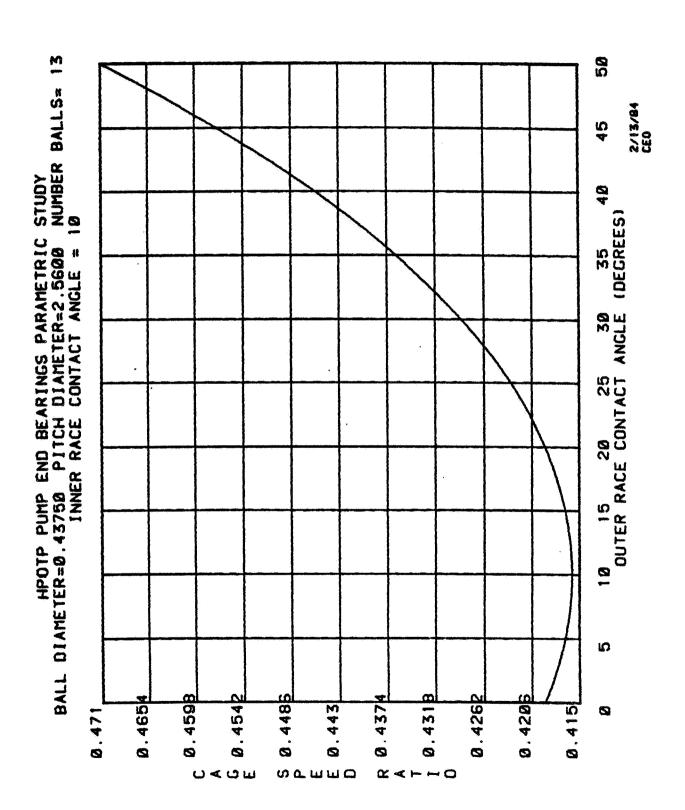
SPEED RATIO OF HPOTP PUMP END BEARINGS 3-, 10-, 20-, AND 30-DEGREE $^{lpha}_{\ \ i}$ (Inner Race Contact Angle)

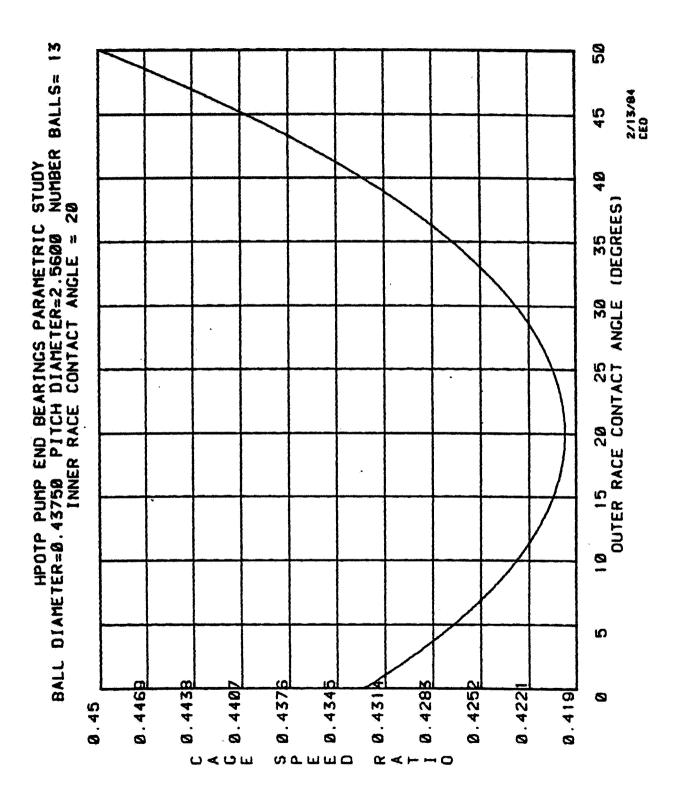
Ball Diameter = 0.4375 inch

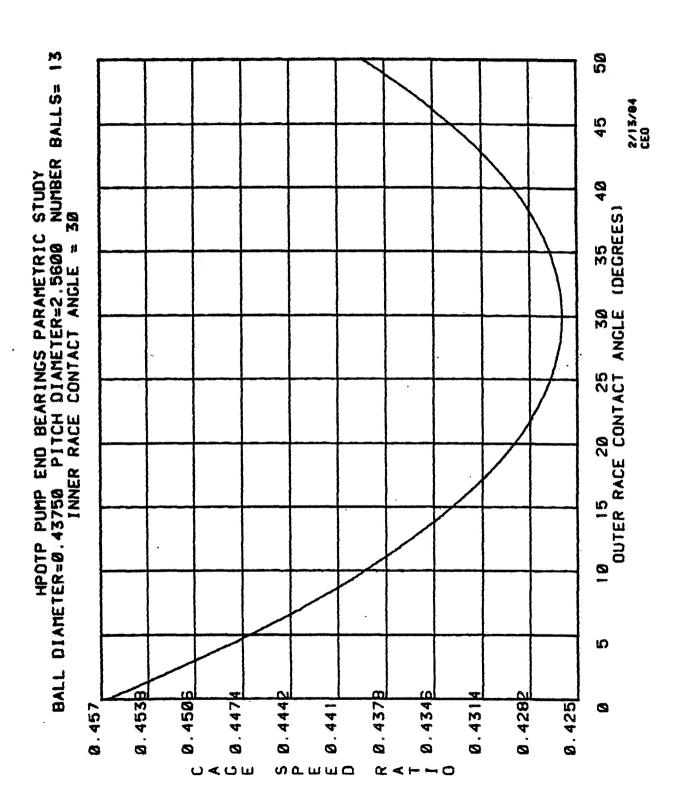
Pitch Diameter = 2.56 inches

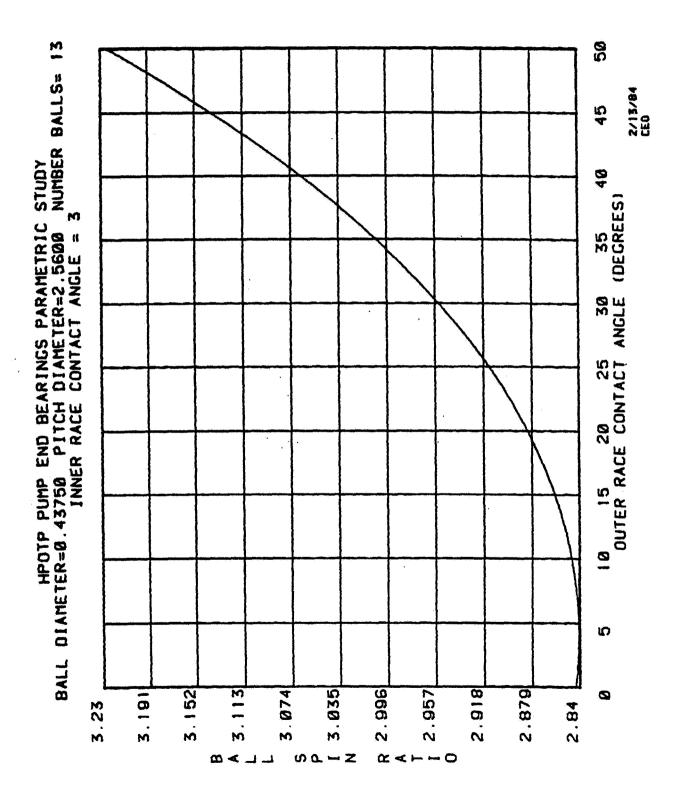
Number of Balls = 13

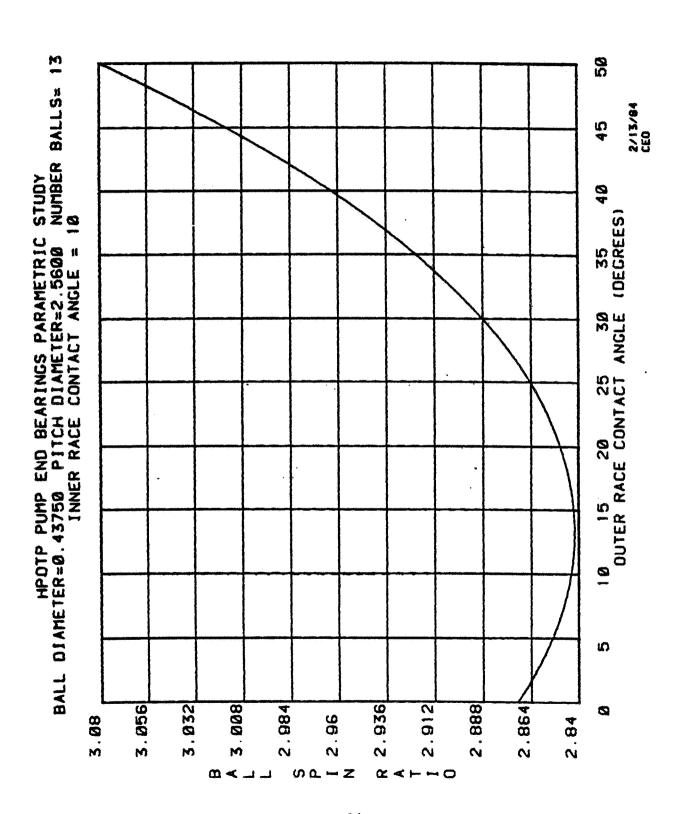


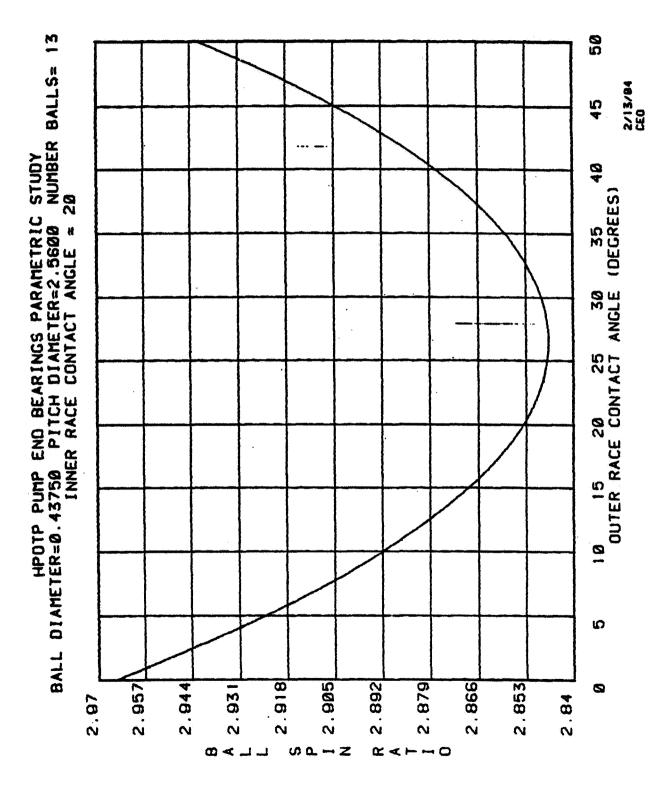


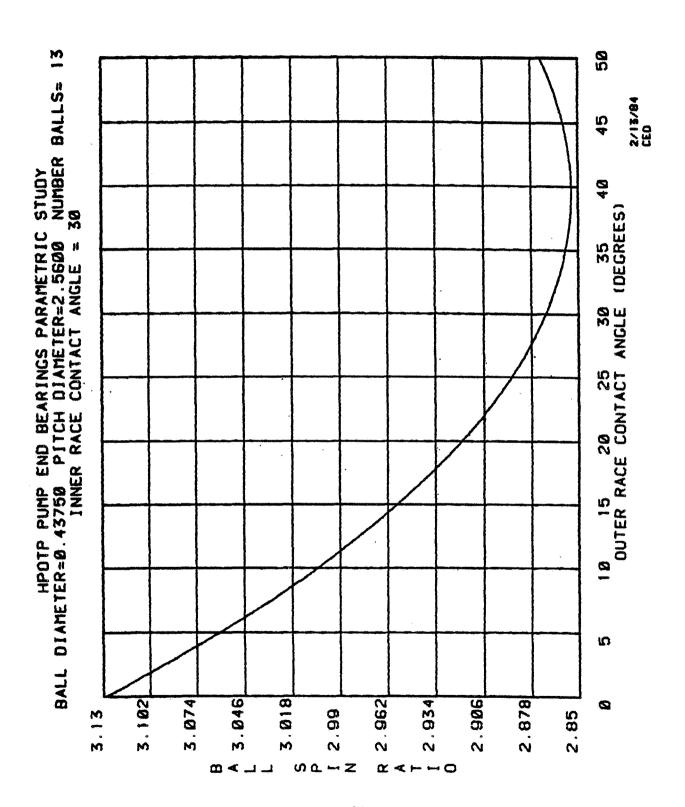


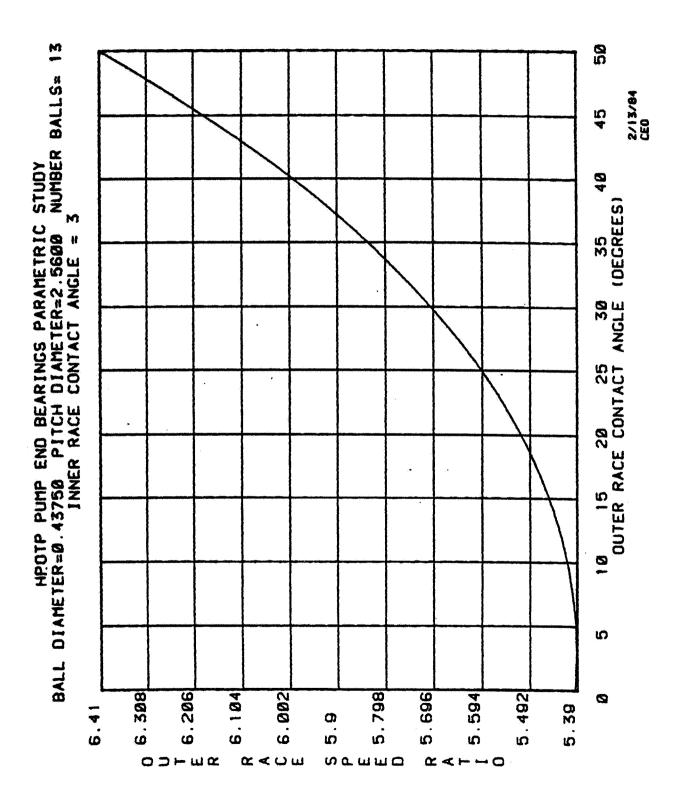


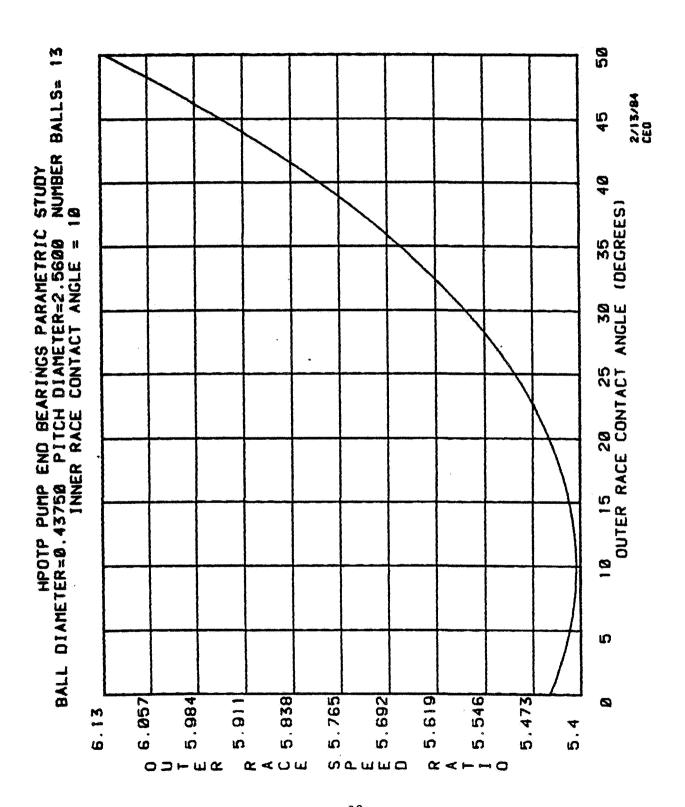


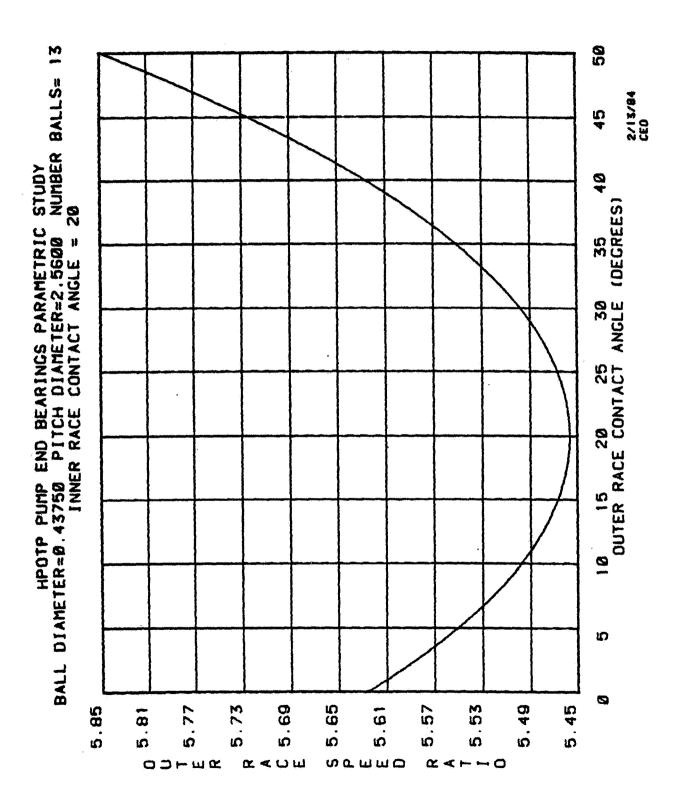


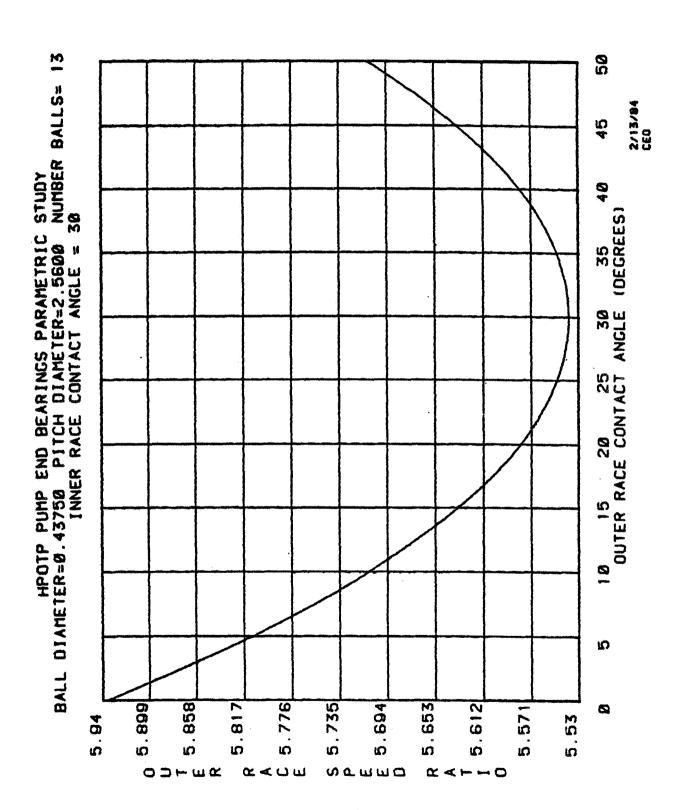


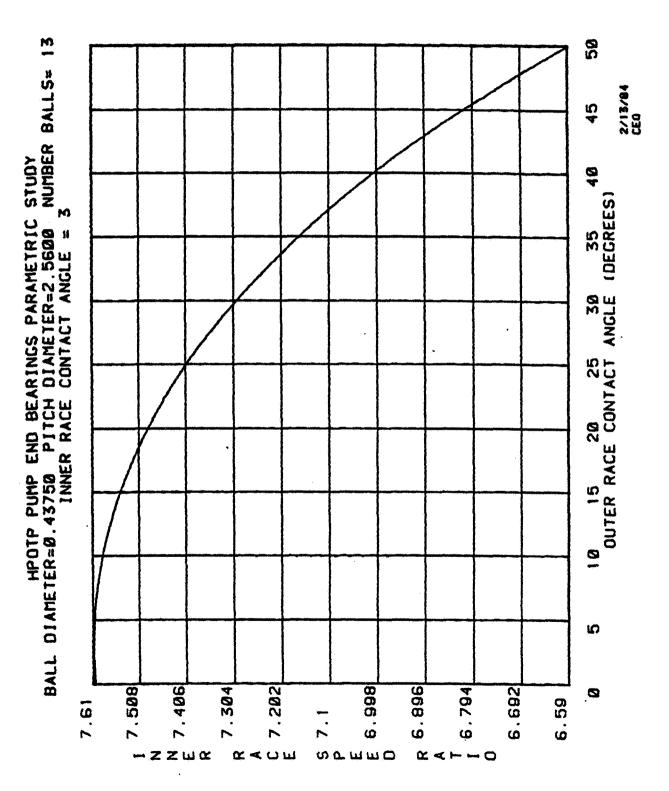


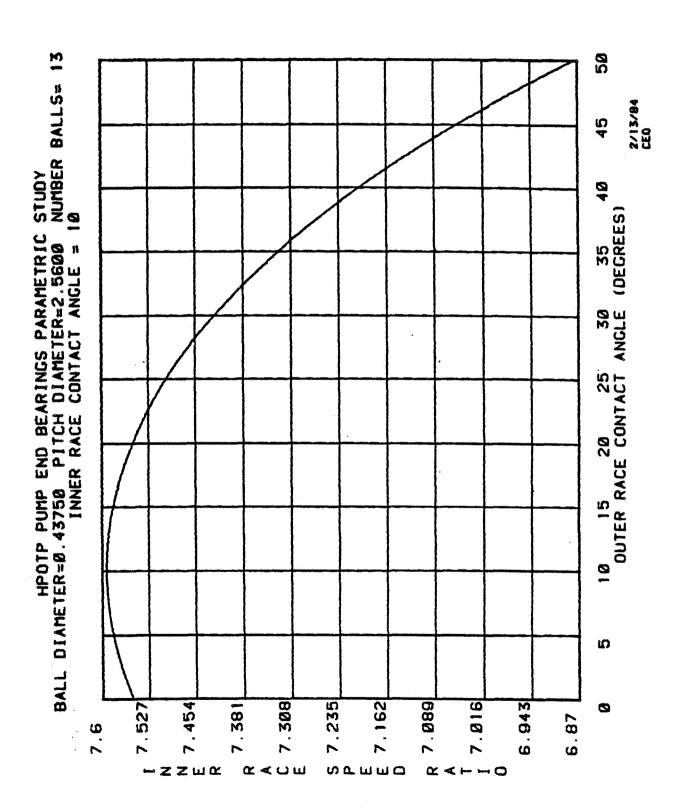


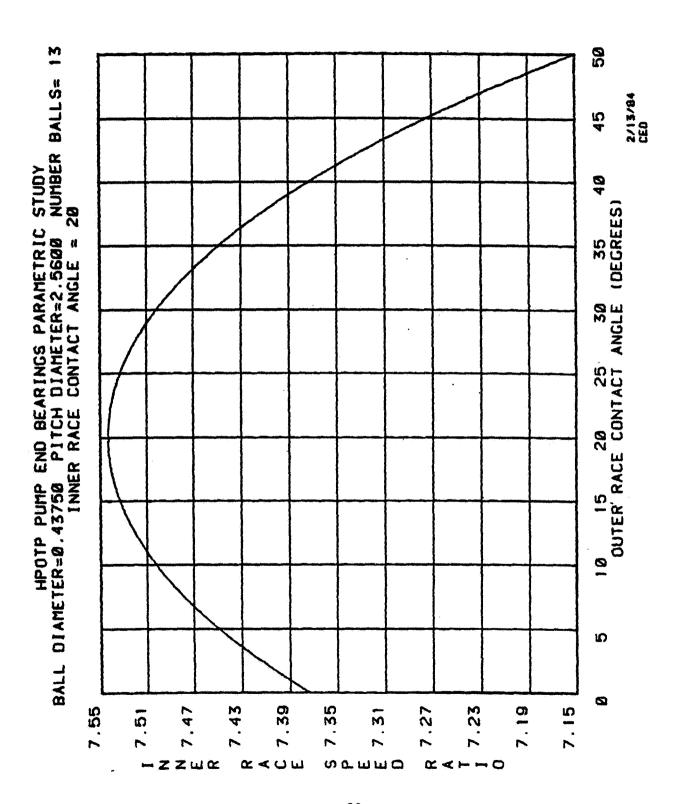


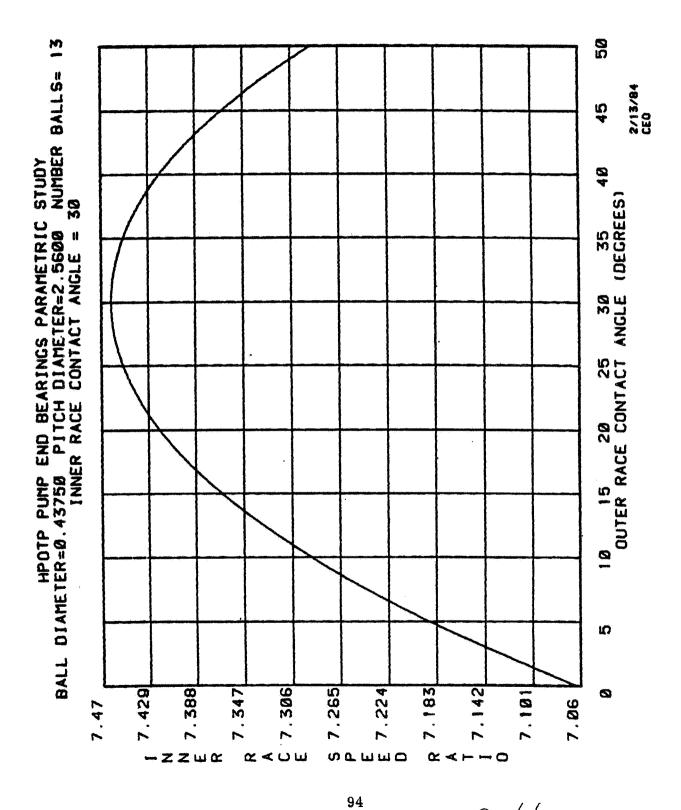












C-4

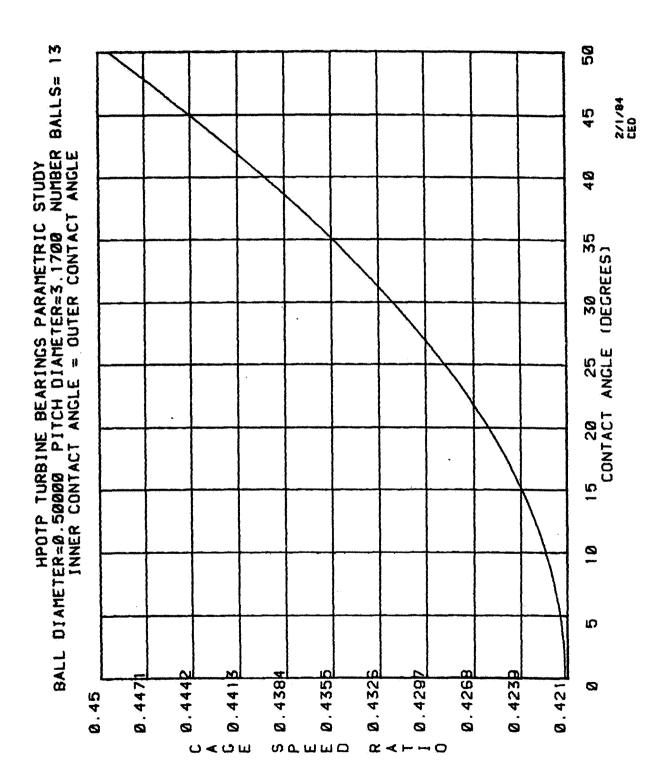
SPEED RATIO OF DIFFERENT PITCH DIAMETERS OF HPOTP TURBINE BEARINGS

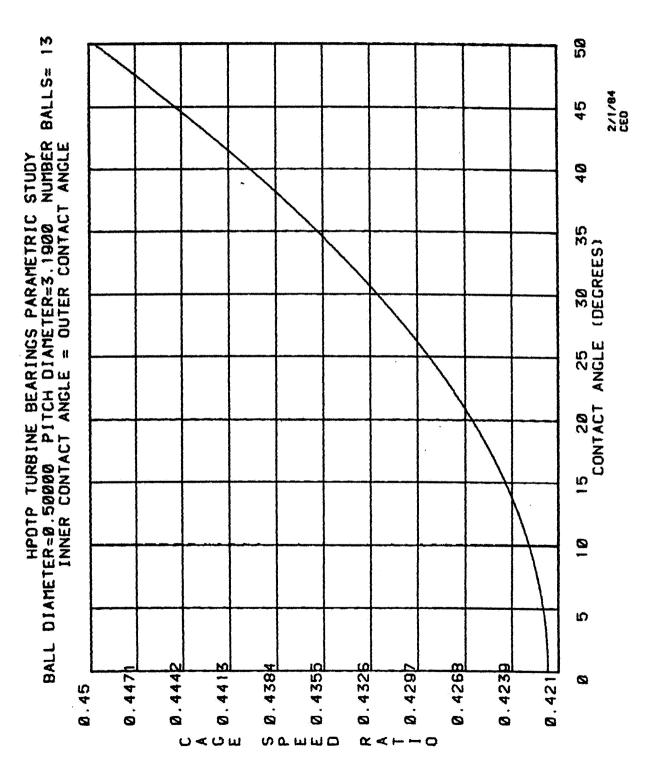
Ball Diameter = 0.50 inch

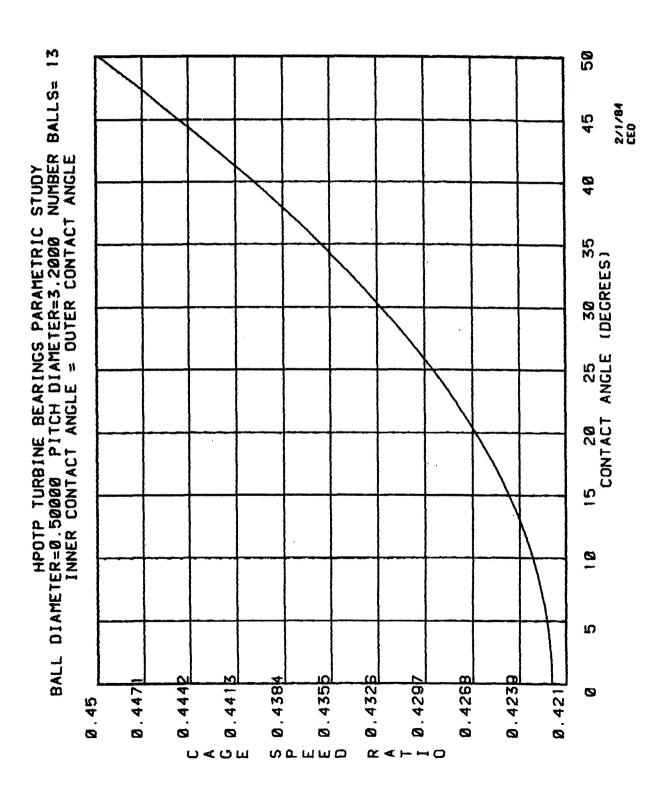
Pitch Diameter = 3.17, 3.19, and 3.20 inches

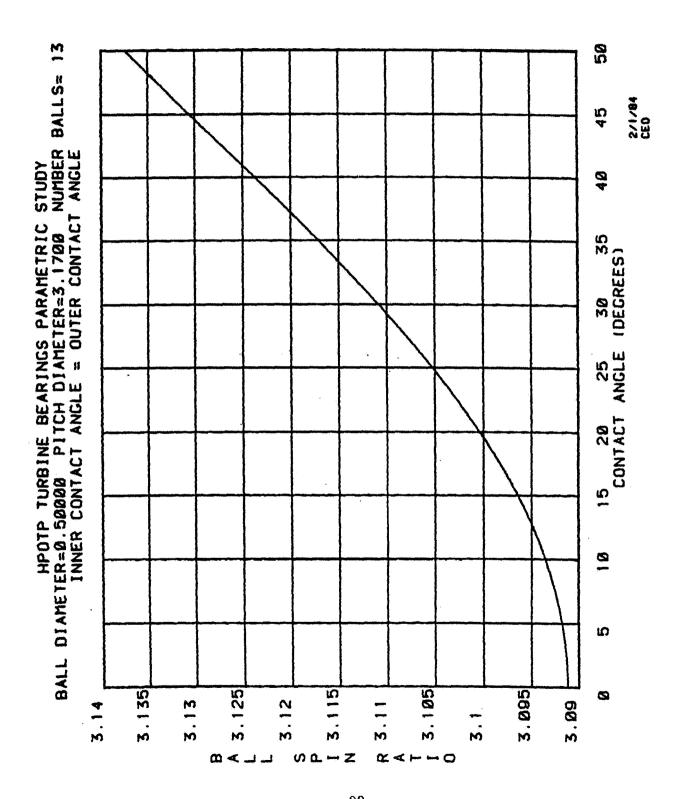
Number of Balls = 13

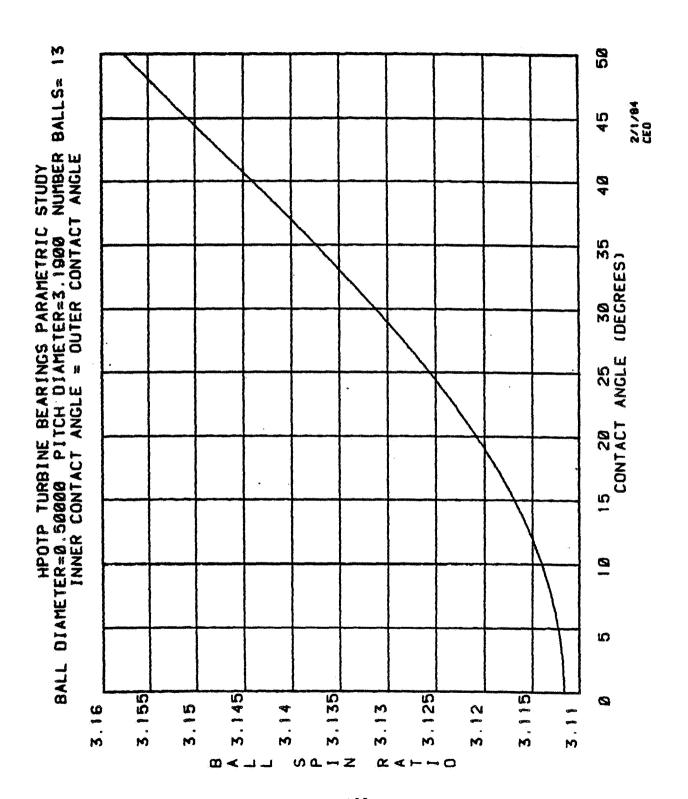
Inner Contact Angle = Outer Contact Angle

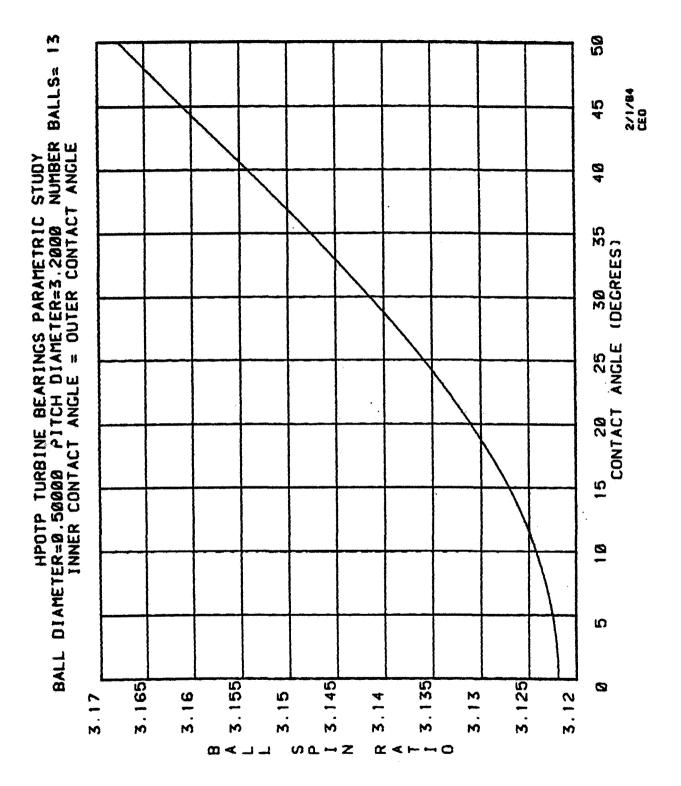


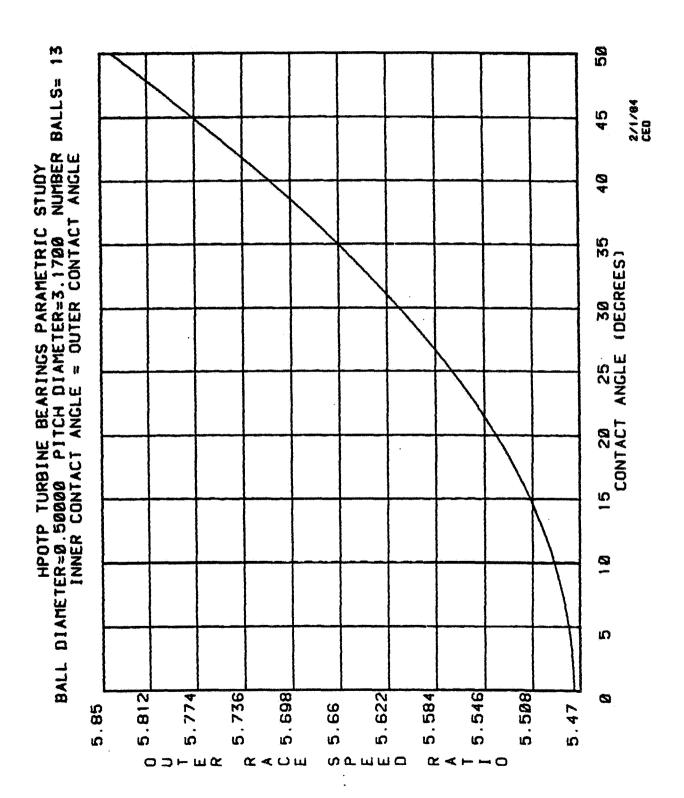


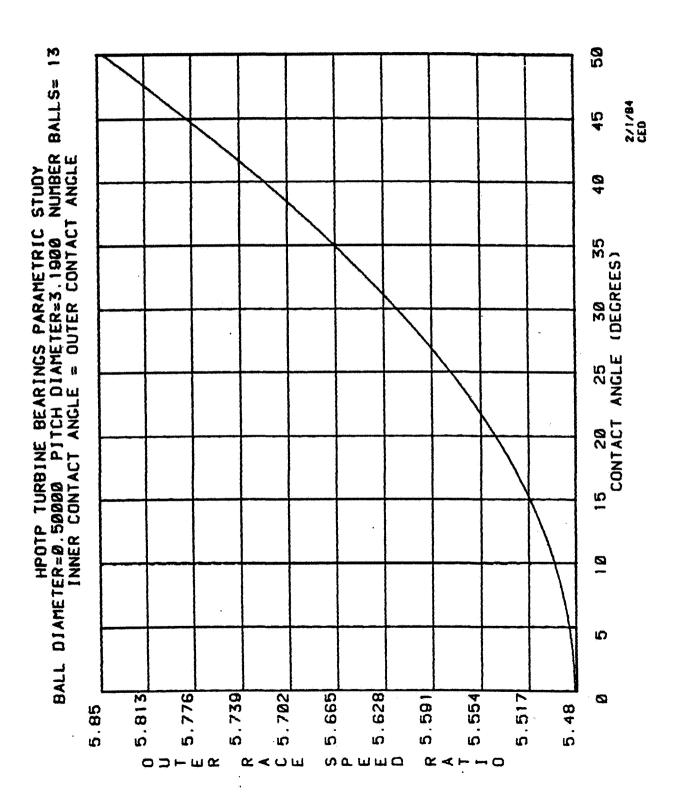


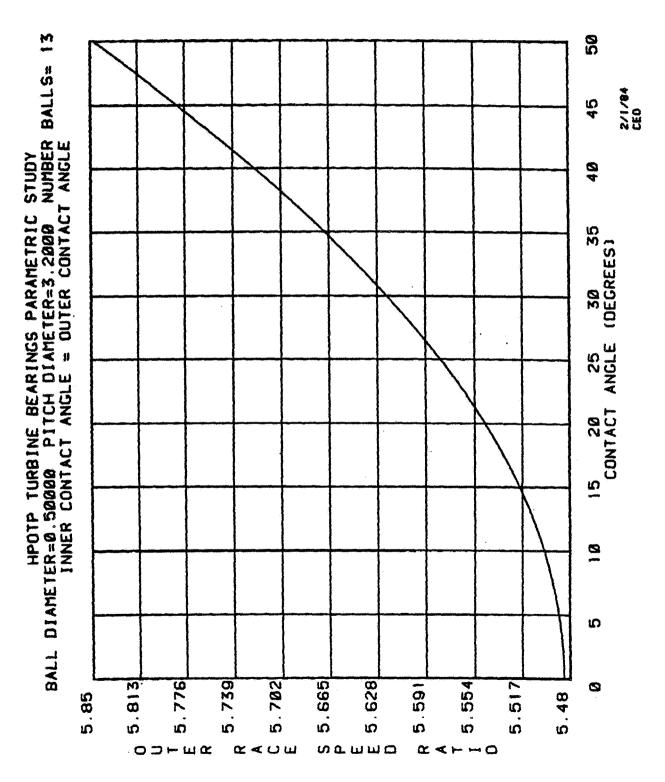


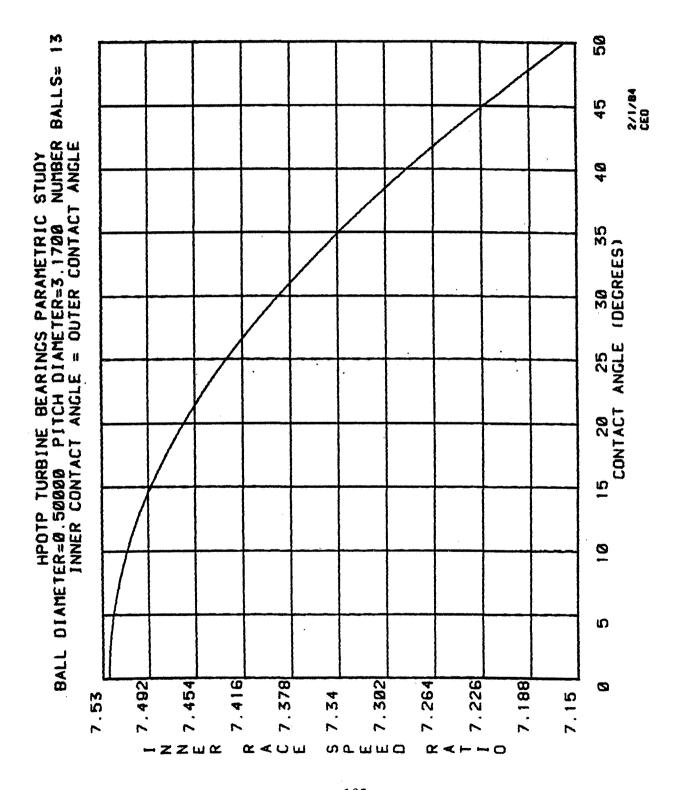


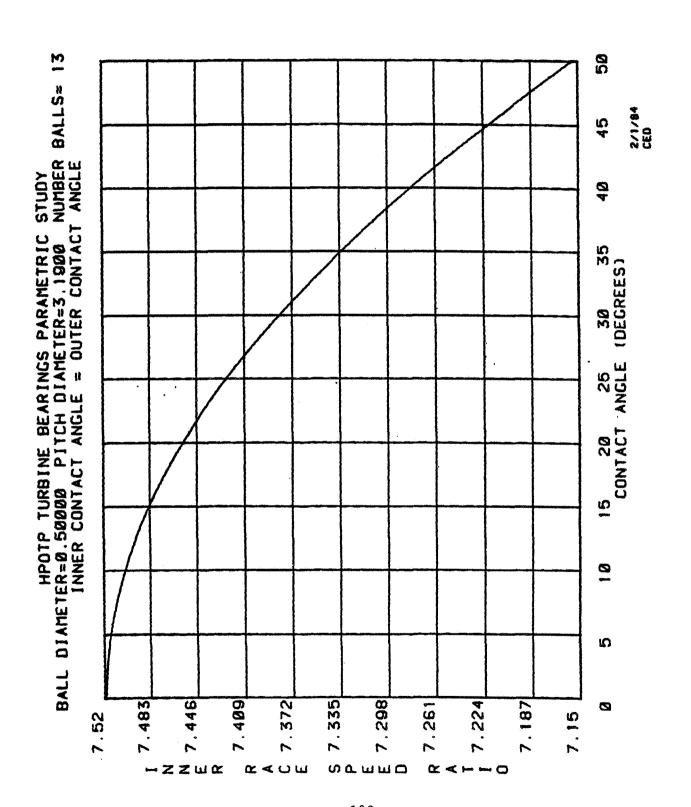


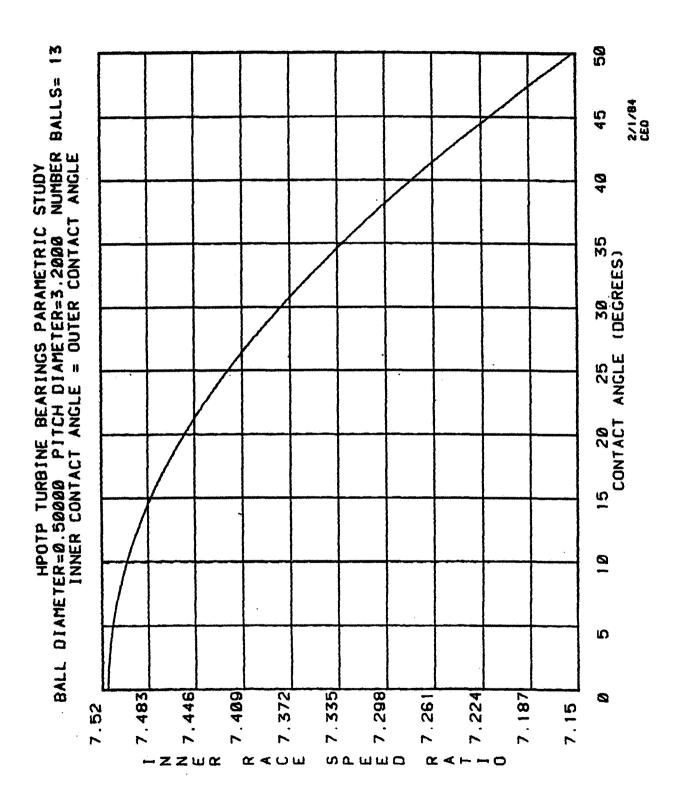












SPEED RATIO WITH DYNAMIC EFFECTS NEGLECTED

Charts of this section are for simple rolling motion, which is only applicable for the case of slow rotational speed and/or applied radial load of large magnitude. The dynamic effects were neglected: i.e., outer contact angle equal to inner contact angle. The equations for this case are as follows:

Cage speed ratio = $1/2 (1 - D/d_m \cos \phi)$

Outer race speed ratio = $N_b/2 (1 - D/d_m \cos \phi)$

Inner race speed ratio = $N_b/2 (1 + D/d_m \cos \phi)$

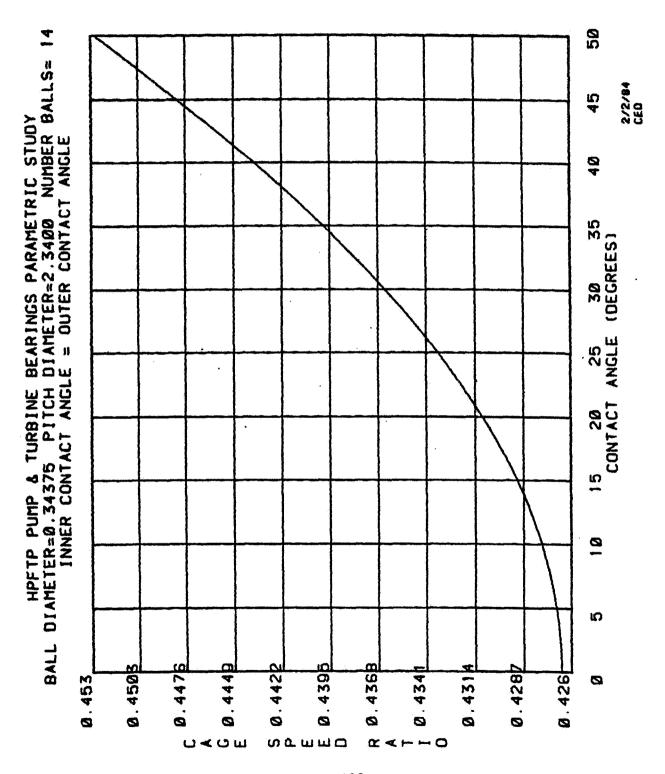
Ball spin ratio = $1/2 d_{\text{m}}/D \left[1 - (D/d_{\text{m}})^2 \cos^2 \phi \right]$

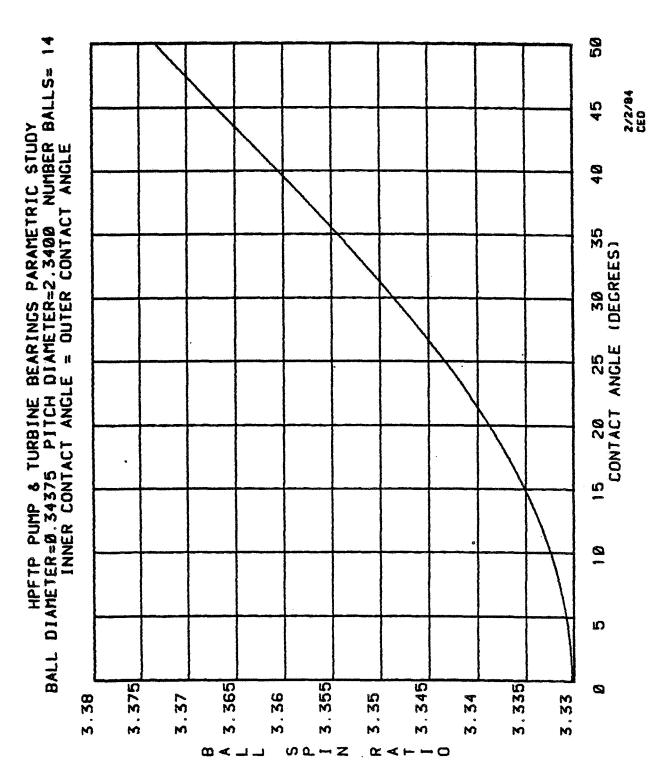
D = Ball diameter

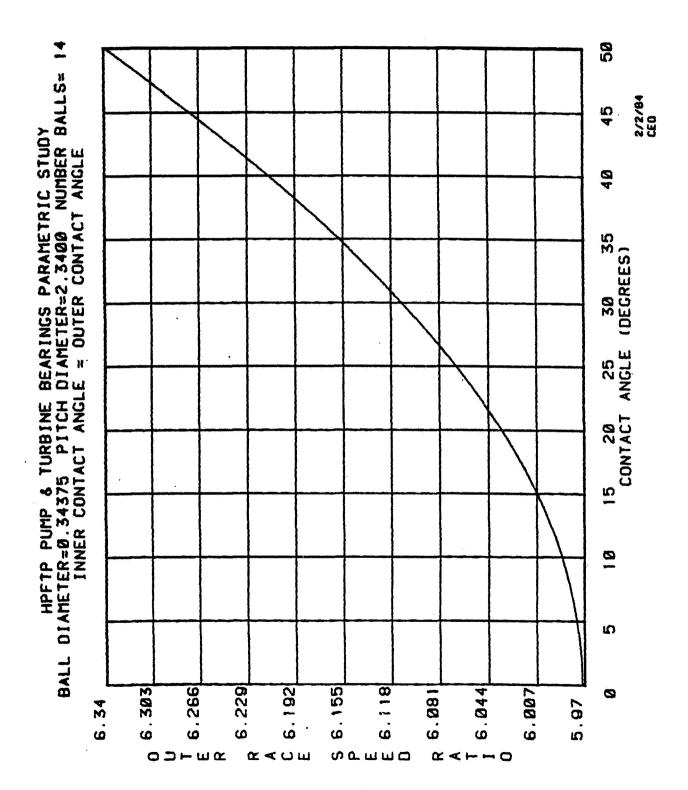
d_m = Pitch diameter

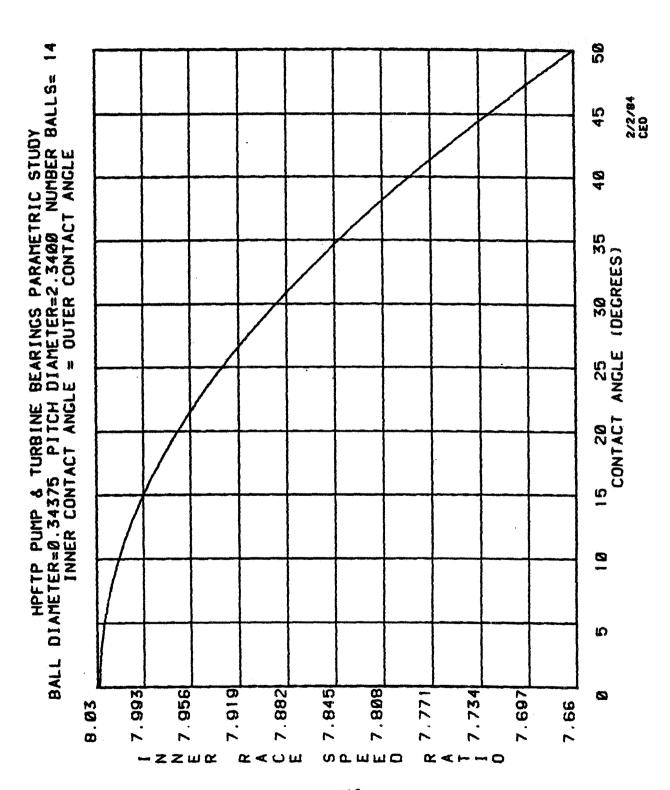
 $N_b = Number of balls$

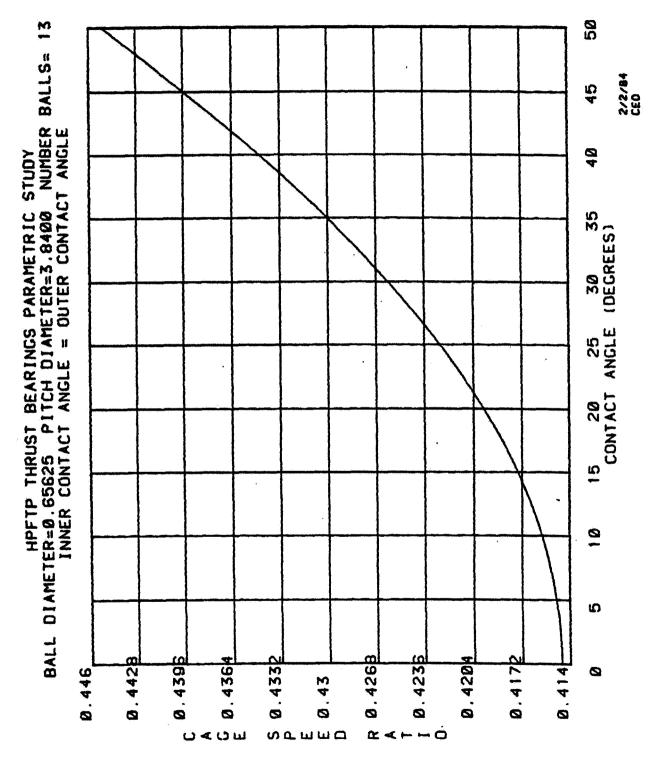
 ϕ = Contact angle

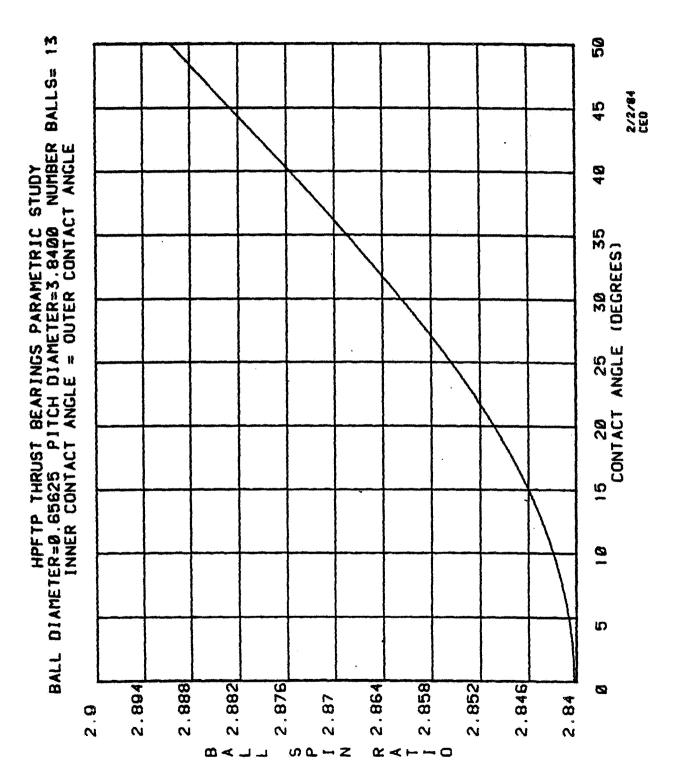


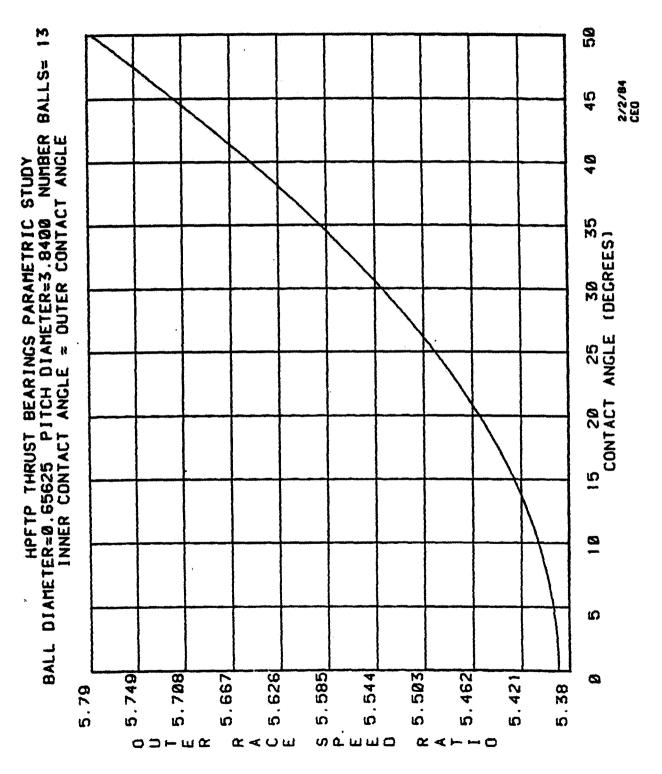


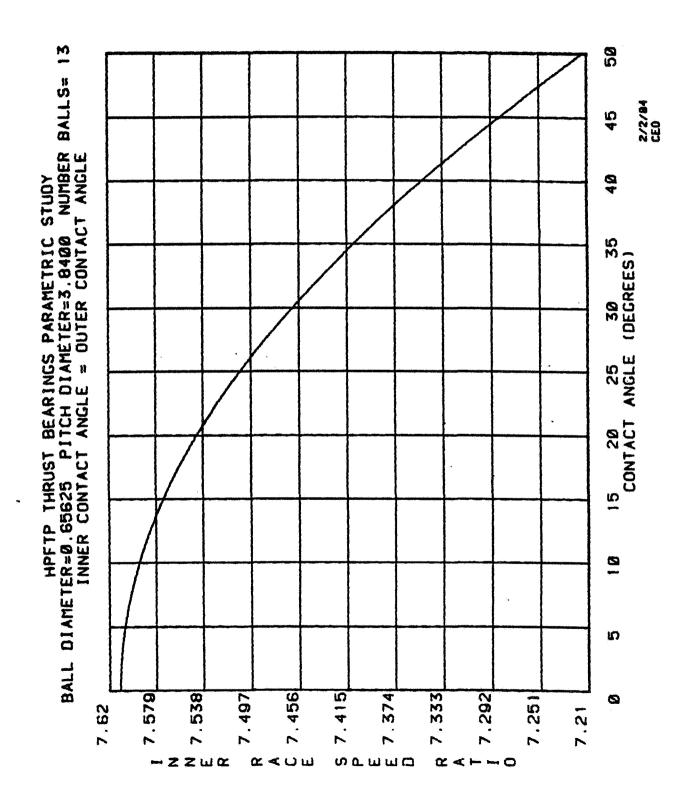


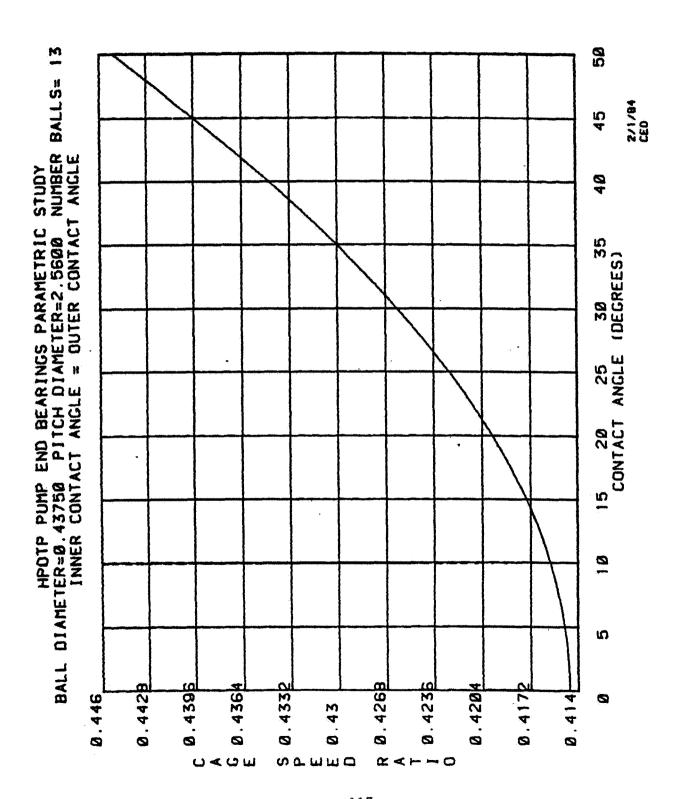


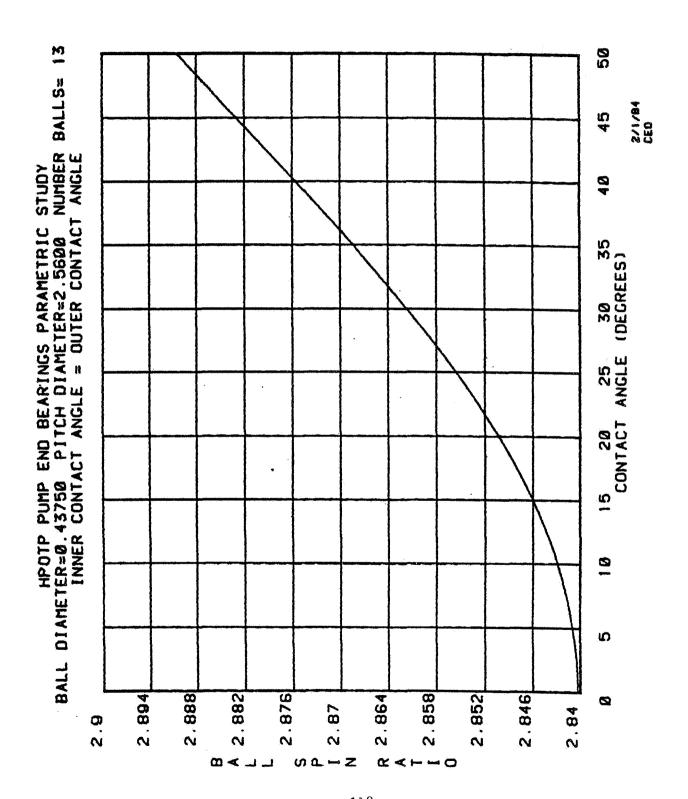


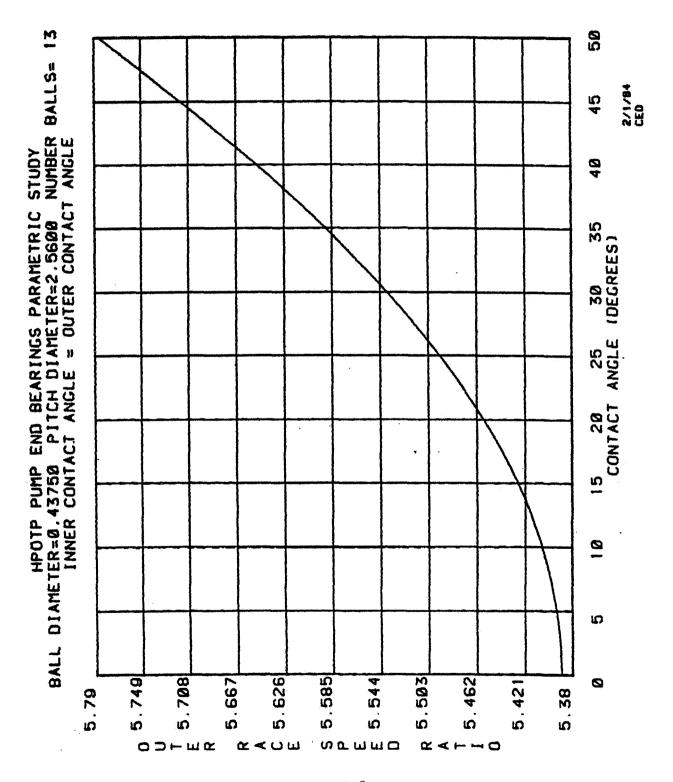


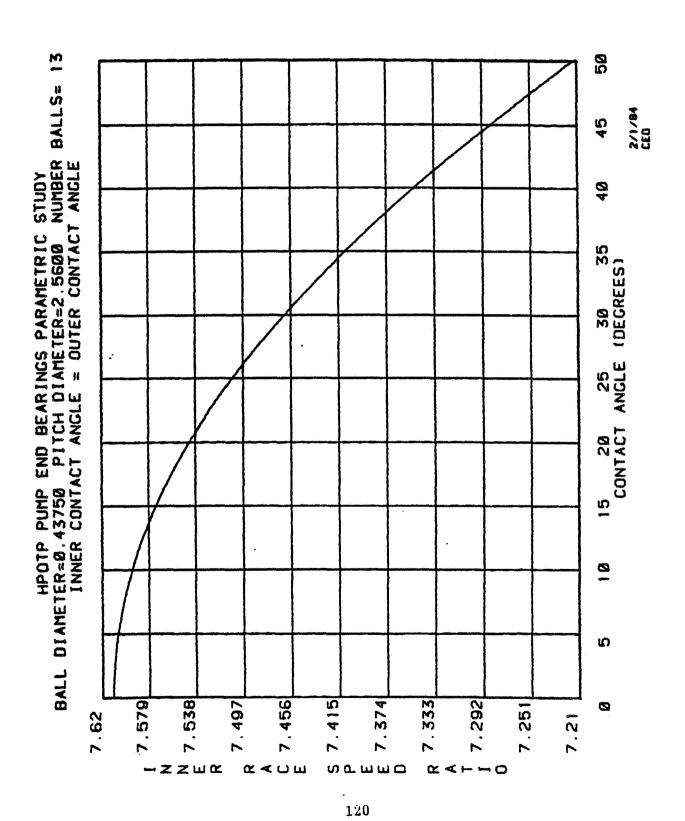


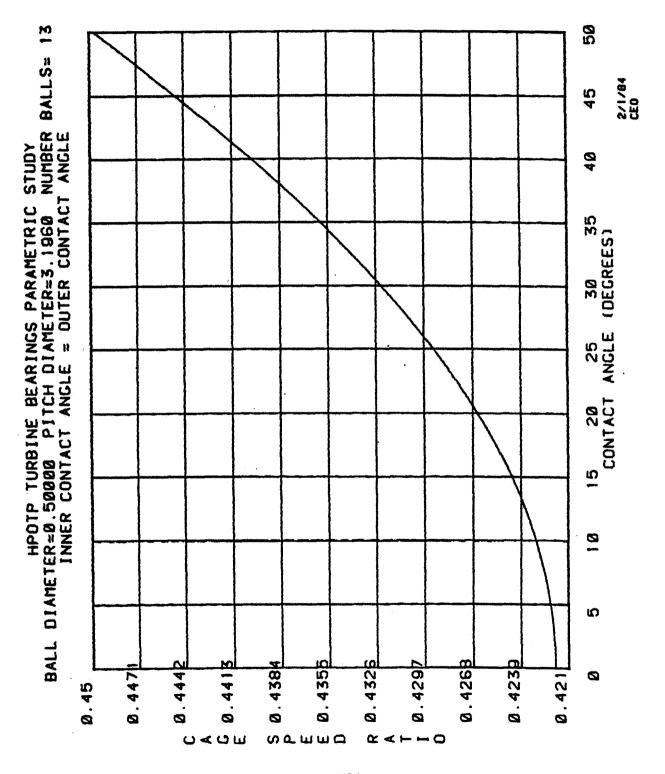


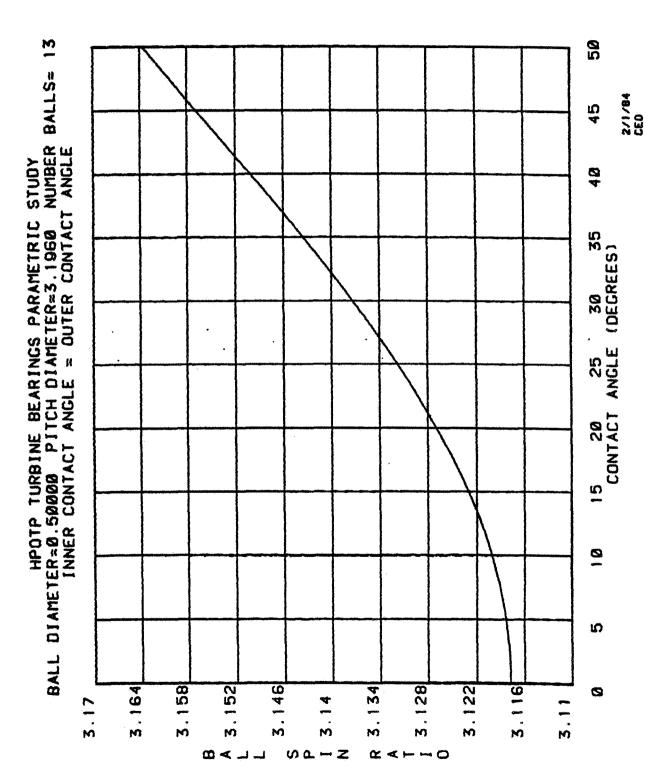


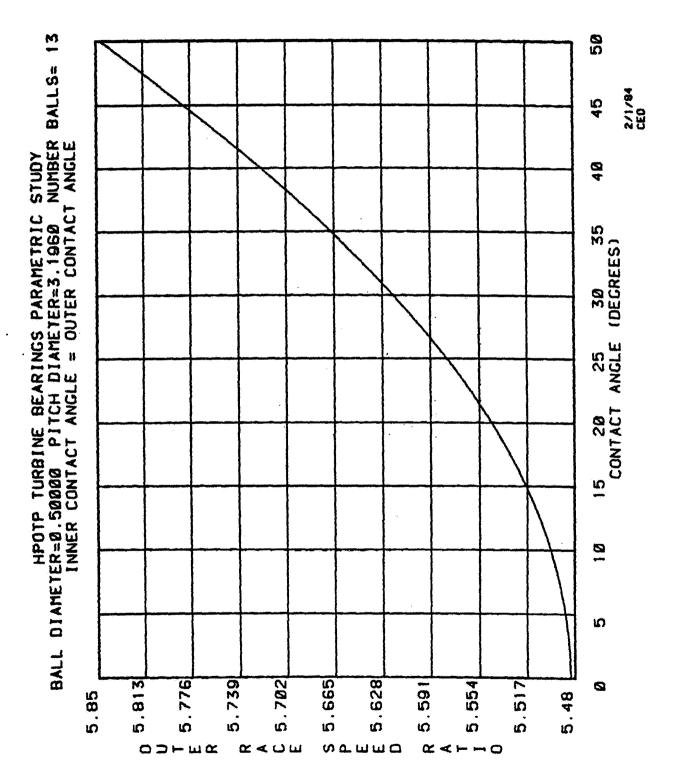


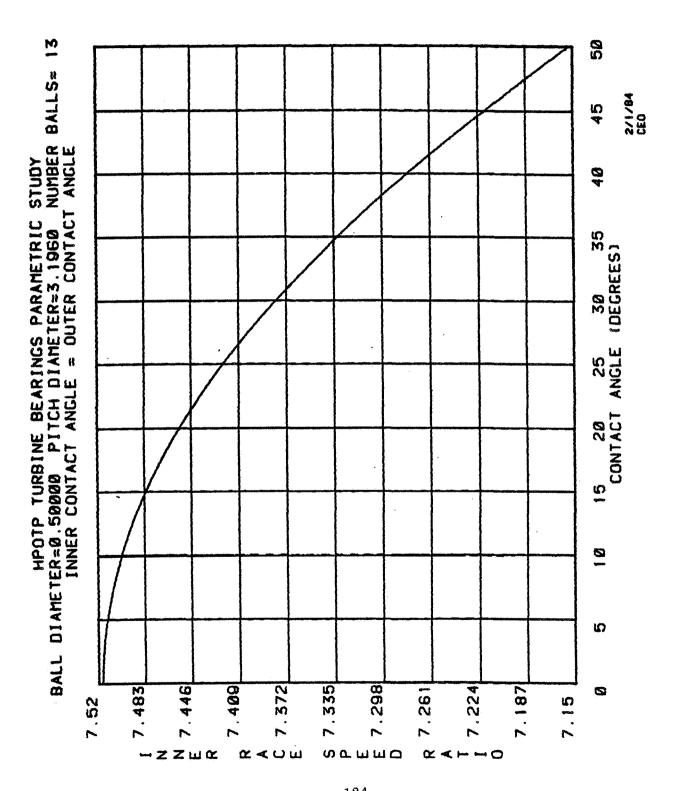












COMPUTER PROGRAM LISTING

5	,	OF POOR QUALITY	70 K
FLOT EQUATIONS	* * *	•	**** **** **** **** ** *** *** *** *** *** *** *** *** *** *** *** *** ** *** *** *** *** *** *** *** *** *** *** *** *** ** *** *** *** *** *** *** *** *** *** *** *** *** ** *** *** *** *** *** *** *** *** *** *** *** *** ** *** *** *** *** *** *** *** *** *** *** *** *** ** *** *** *** *** *** *** *** *** *** *** *** *** ** *** *** *** *** *** *** *** *** *** *** **
1072 01	**************************************	STUDY" CT ANGLE" "ECT DATE CS	****** ******* VAUE ARINGS
r KUGKATII	5E PARAMETERS ************ ***********************	CT ANGLE = OUTER CONTACT ANGLE" CONTACT ANGLE = " CONTACT ANGLE = " CONTACT ANGLE (DEGREES)" 0.5 0.5 LUT CORRECT DATE 0.3	#*************************************
USE T.	2 ************************************	THRUST BEARING CONTACT ANGLE RACE CONTACT A RACE CONTACT A 21:100,5 21:100,3	SEARINGS FOR TURBINE BEARINGS
00	REEN REEN REEN REEN REEN REEN REEN REEN	NATER SOLUTION OF THE SOLUTION	# # # # # # # # # # # # # # # # # # #
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UDK 2 ASAIN TO CHECK

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REM ********************************
                                                                                                                                                                                                                                      B*="INNER CONTACT ANGLE = OUTER CONTACT ANGLE"
                                                                                                        AS="HPOTP TURBINE BEARINGS PARAMETRIC STUDY"
                                                                                                                          C&="INNER RACE CONTACT ANGLE = "
X*="OUTER RACE CONTACT ANGLE (DEGREES)"
                           = INNER RACE CONTACT ANGLE
= BALL DIAMETER
                                                        NUMBER OF BALLS
                                               PITCH DIAMETER
                                                                                                                                                                 | PRINT "2/13/84"
| PRINT "52,21,100,3
| PRINT "CEO"
| SET DEGREES
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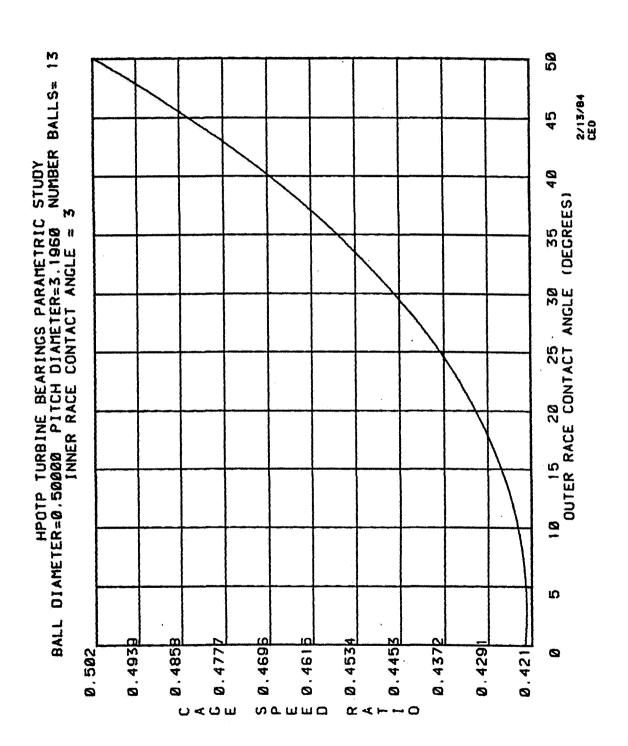
INNER CONTACT ANGLE = OUTER CONTACT ANGLE

1....CAGE SPEED RATIO
2....INNER RACE SPEED RATIO
3....OUTER RACE SPEED RATIO
4....BALL SPIN RATIO

4....BALL SPIN RATIO INNER CONTACT ANGLE = A CONSTANT

5....CAGE SPEED RATIO
6....INNER RACE SPEED RATIO
7....OUTER RACE SPEED RATIO
8....BALL SPIN RATIO
5

ALL SPIN RATIO

ENTER 1-8 AND HIT RETURN THE PROGRAM WILL PLOT THE FRUATION YOU CHOSE. 

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11 END
12 END
12 END
13 END
14 END
15 END
15
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100 PRINT "3 ... OUTER RACE SPEED RATIO"

100 PRINT "4 ... BALL SPIN RATIO"

100 PRINT "5 ... CAGE SPEED RATIO"

100 PRINT "5 ... CAGE SPEED RATIO"

100 PRINT "5 ... CAGE SPEED RATIO"

100 PRINT "6 ... INNER RACE SPEED RATIO"

100 PRINT "6 ... INNER RACE SPEED RATIO"

100 PRINT "6 ... INNER RACE SPEED RATIO"

100 PRINT "7 ... OUTER RACE SPEED RATIO"

100 PRINT "7 ... OUTER RACE SPEED RATIO"
4 REN CHOOSE & PLOT EON <<<< UDX 1 >>>>
5 GD 10 228
8 REN LIST PARAMETERS <<<< UDX 2 >>>>
19 RGE
10 LIST 1310,1558
11 END
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K (4) ± 10
REH **** AUTORANGE *******
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IF Z>B AND Z<9 THEN 388
PRINT "G"
CO TO 228
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619 FOR 1=1 TO LENIABA/2
628 PRINT 'Y':
628 PRINT 'Y':
629 PRINT 'Y':
620 PRINT GEAL
720 PRINT G
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| Y4="BALL SPIN RATIO"
| 1=SIN(X)/(COS(X)+81/P!)
| 1=(COS(X)+1*SIN(X))/(1+COS(X)+81/P!)
| 1=(COS(X)+1*SIN(X))/(1+COS(X)+81/P!)
| Y=1/((J+L)*COS(ATN(I))*81/P!)
| RETURN
                      188 RETURN
1798 RETURN
1798 RETURN
1810 Y=N1/2#11-B1/P1#COS(X))
1810 Y=N1/2#11-B1/P1#COS(X))
1810 Y=N1/2#11-B1/P1#COS(X))
1820 RET COMPUTE VALUE
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1850 RET COMPUTE VALUE
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1860 RET COMPUTE VALUE
1860 RET COMPUTE VALUE
1860 RET COMPUTE VALUE
1860 RET COMPUTE VALUE
1870 Y#="INNER RACE SPEED RATIO"
1860 RET COMPUTE VALUE
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1870 Y#="INNER RACE SPEED RATIO"
1860 RET COMPUTE VALUE
1870 Y#="INNER RACE SPEED RATIO"
1870 RETURN
1870 
788 RETURN

789 RET COMPUTE VALUE

808 Y** DUTER RACE SPEED RATIO*

318 Y=N1/2#(1-81/P1#COS(X))

320 RETURN

130 RETURN

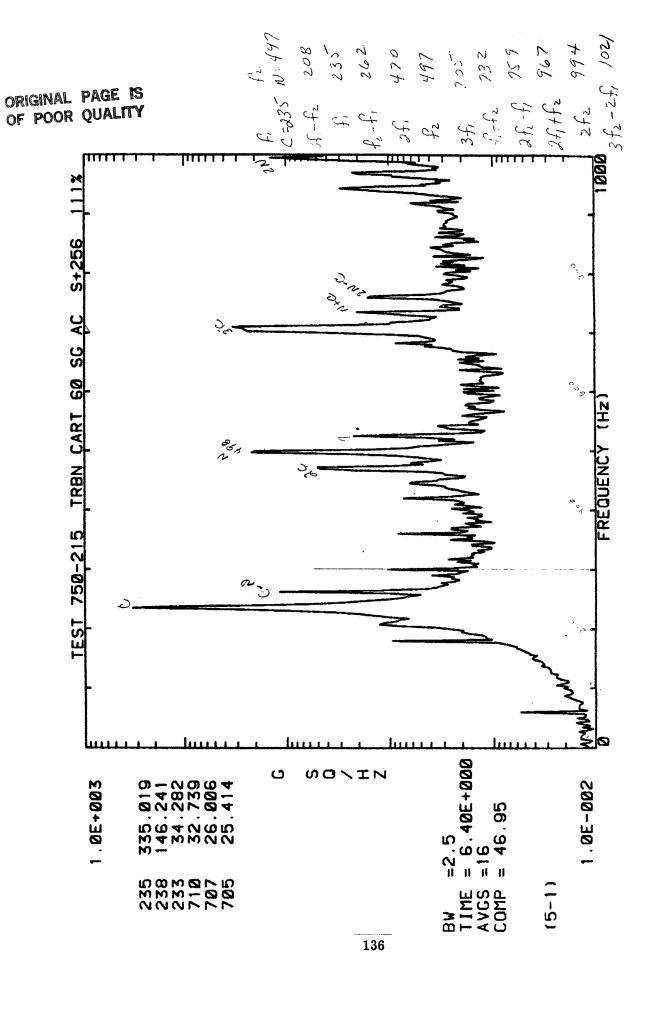
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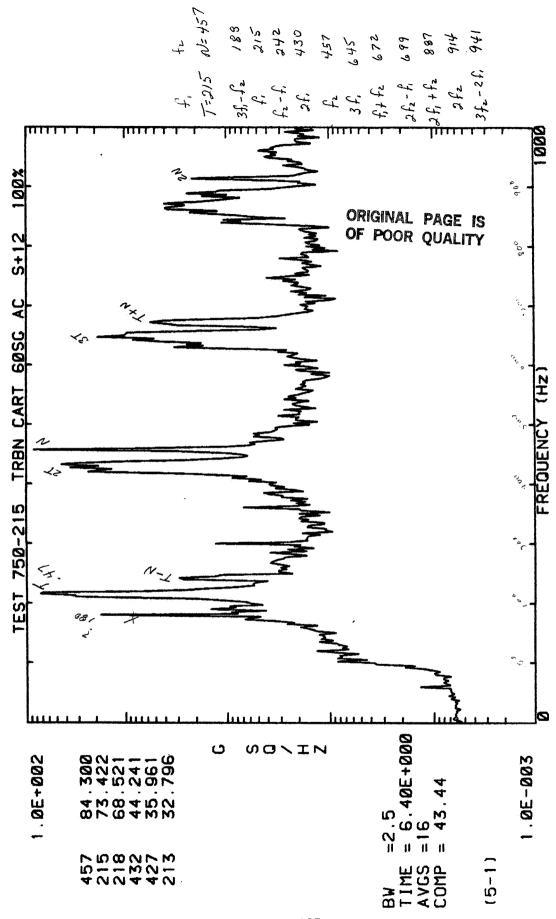
580 Y=P1/12#81)#(1-(81/P1)†2#COS(X)†2)

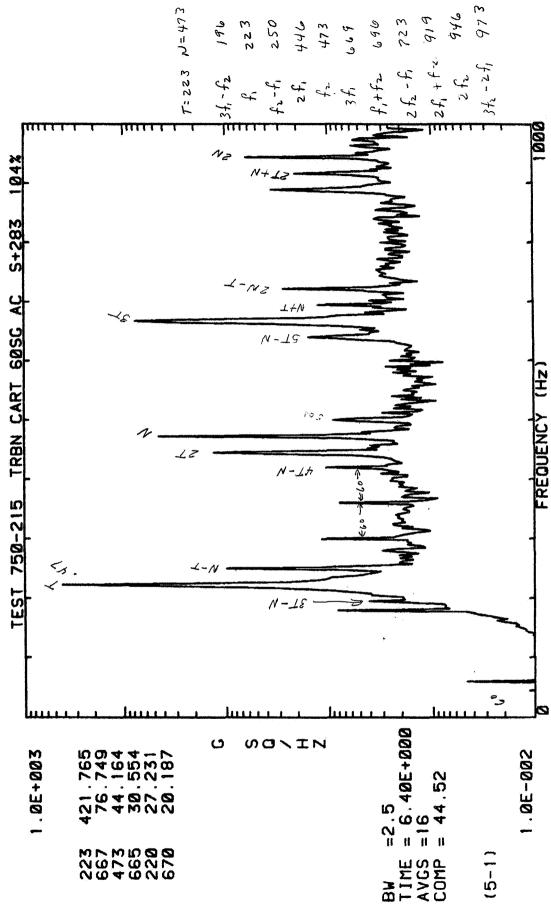
580 RETURN
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FOR Z=5 TO 8
GOSUB 380
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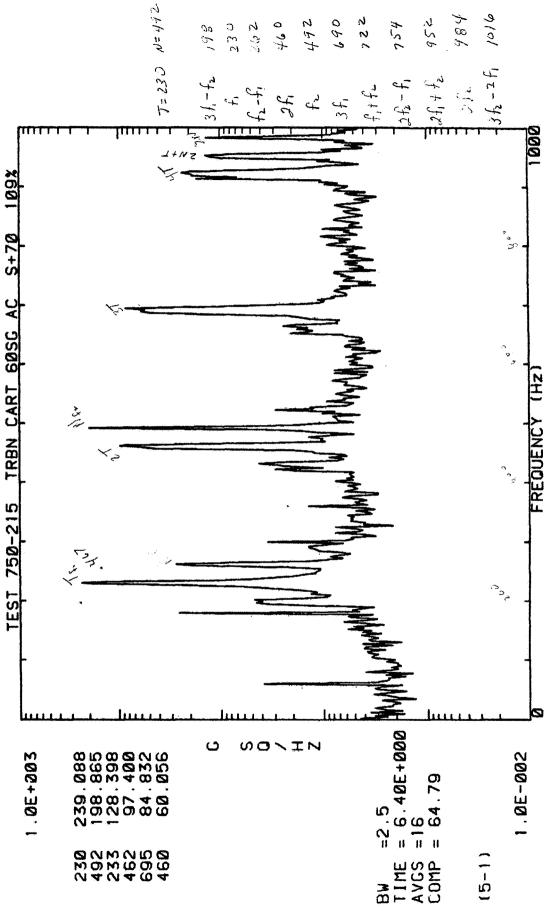
INTERNALLY MEASURED BEARING FREQUENCIES OF TWO STATIC TEST FIRINGS

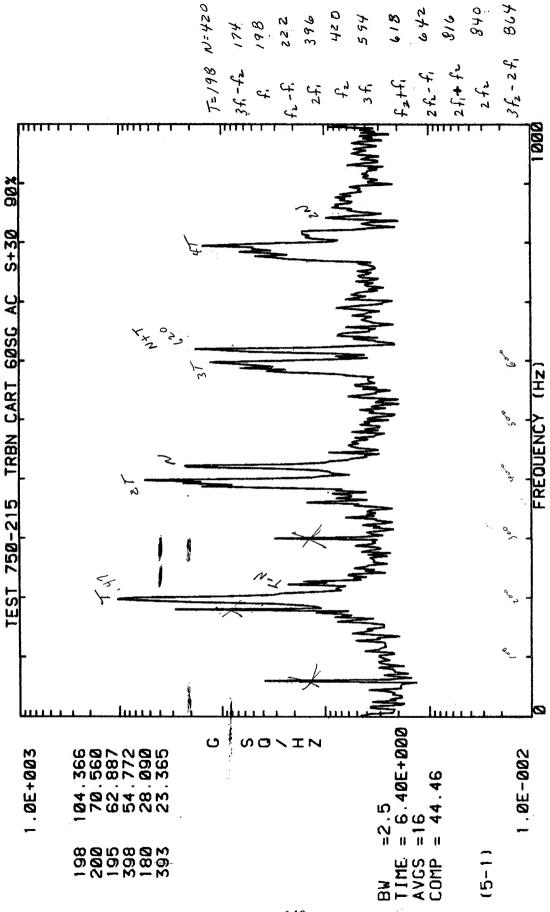
This section includes selected data in the form of working papers for two static firing tests, 750-215 and 750-234. The two major points of interest are the cage frequency on test 750-215 and the outer race frequency on test 750-234. Of special interest is the beating of the bearing frequencies with the synchronous frequency of the pump. The data in this section is only included to illustrate or demonstrate the applicability of the charts of the previous sections. A comparison of the measured frequency on test 750-234 and the applicable chart of the HPOTP outer race speed is also shown. Several points of possible contact angles for the measured speed ratio are shown on the chart. Also included is a plot of the outer race frequency for different power levels, including a slow ramp down. For this test, the contact angle does not appear to be a function of power level. When additional data from normal bearing operation, and especially from bearings that have experienced damage, becomes available, it is recommended that detailed analysis be performed and included in a report.



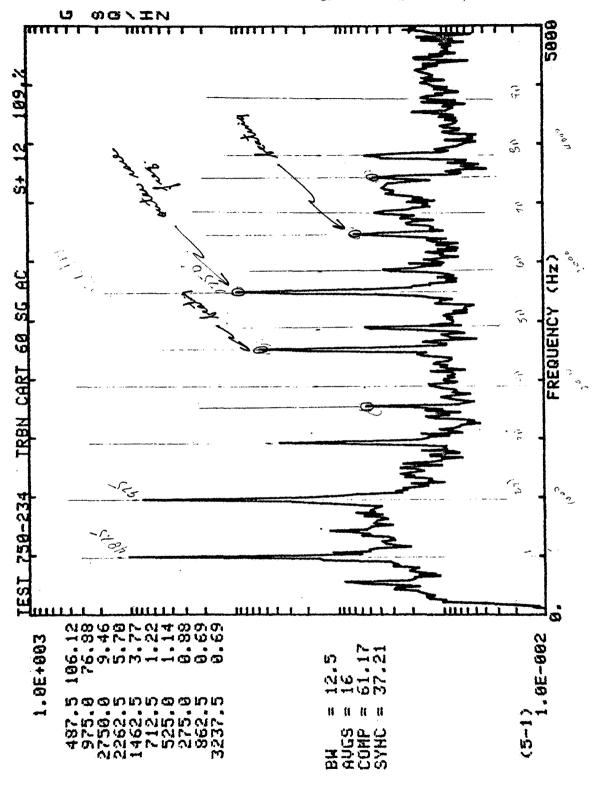


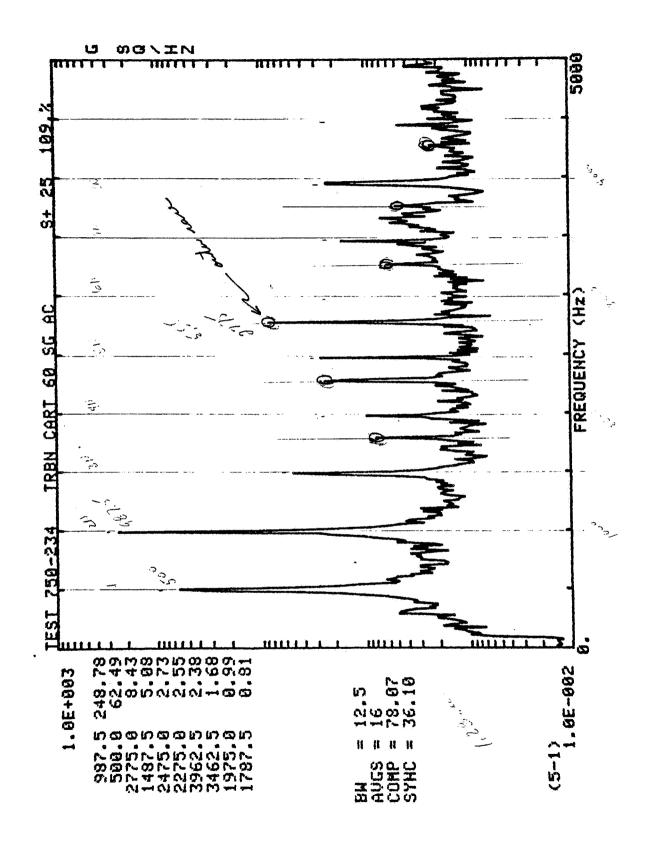


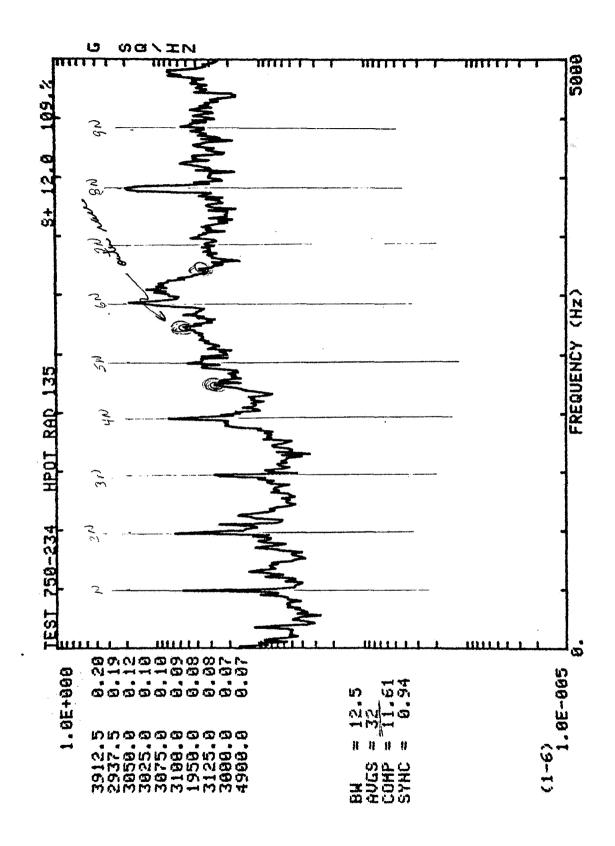


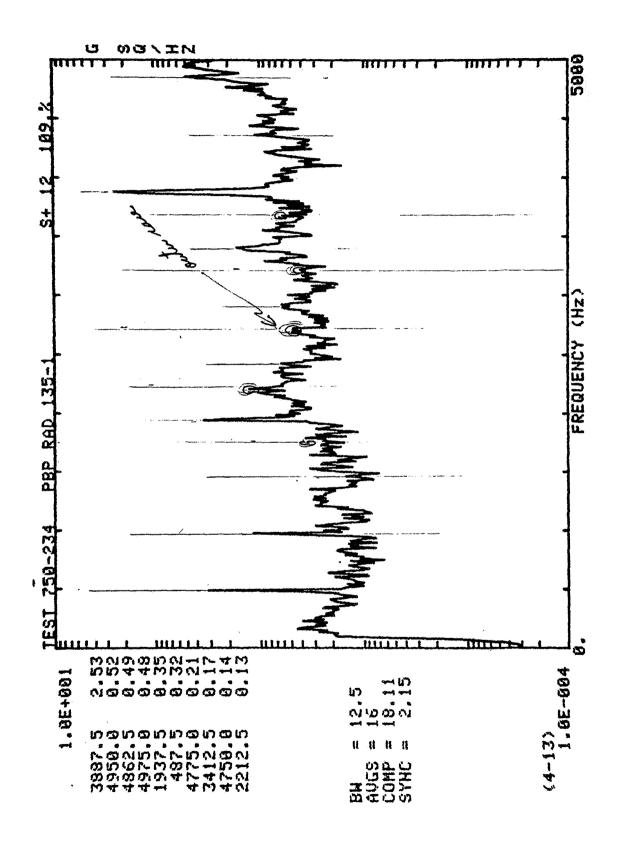


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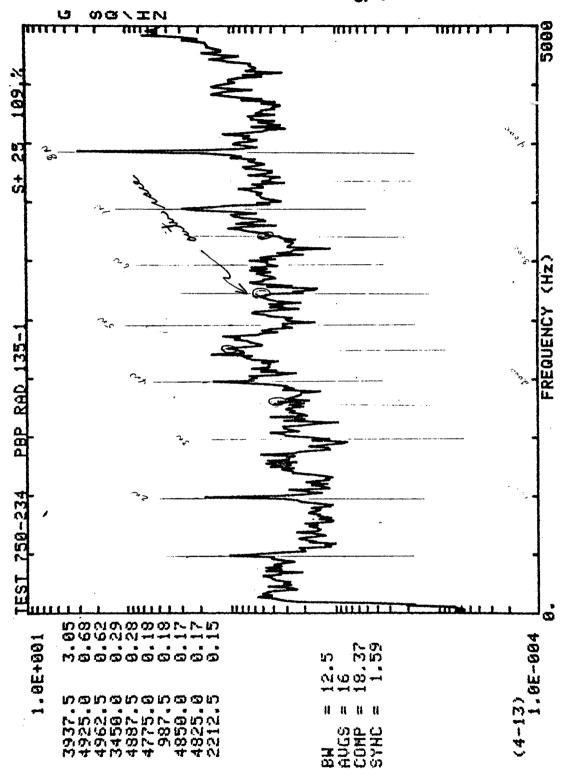


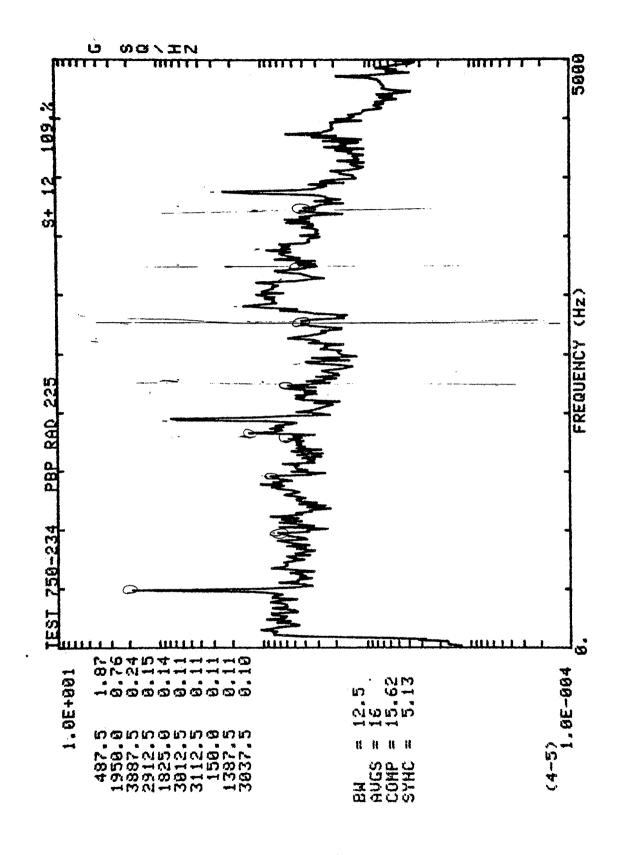


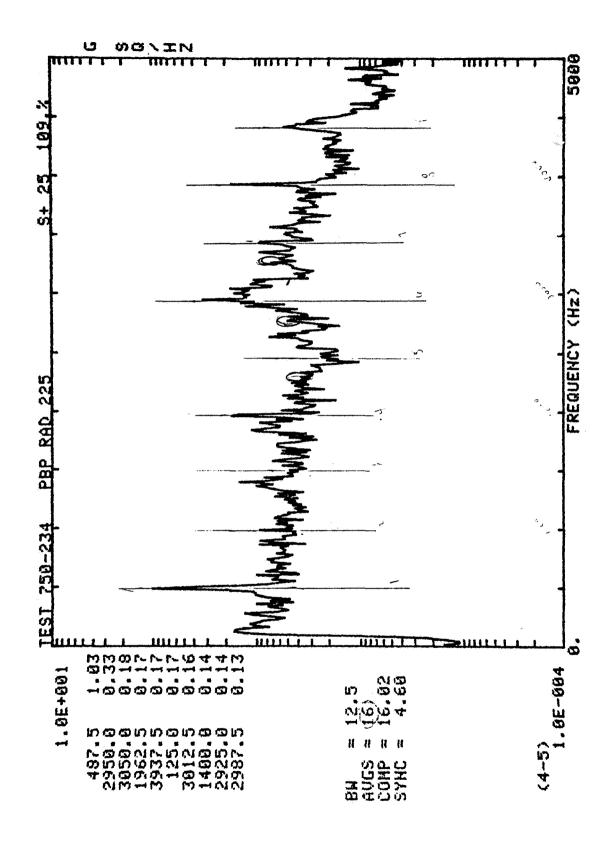


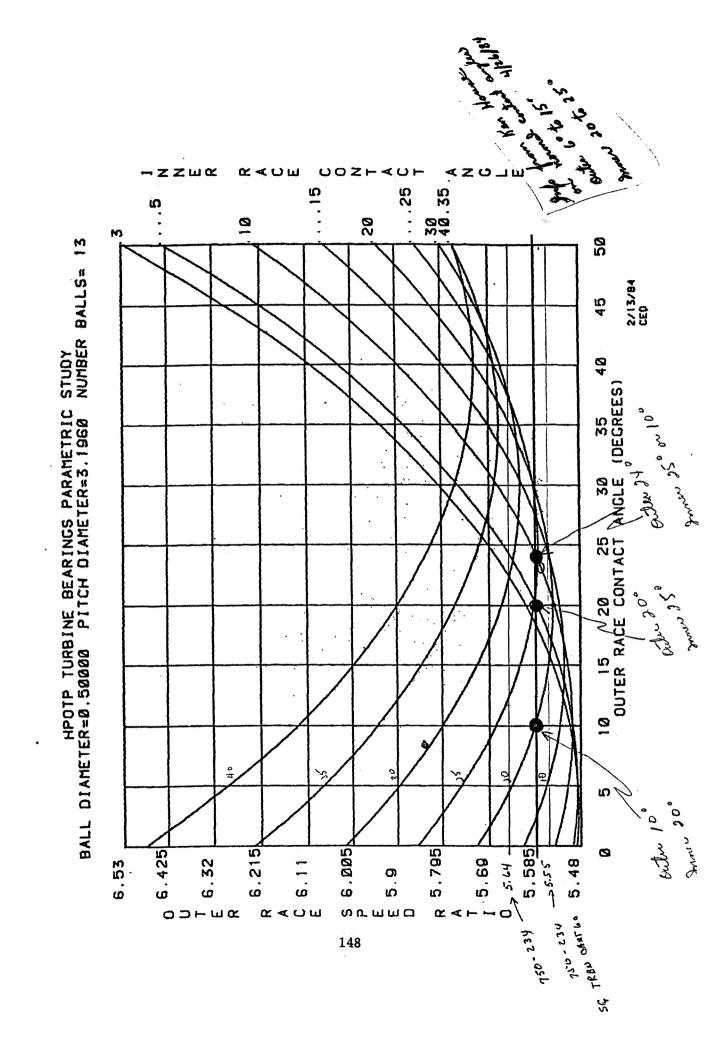


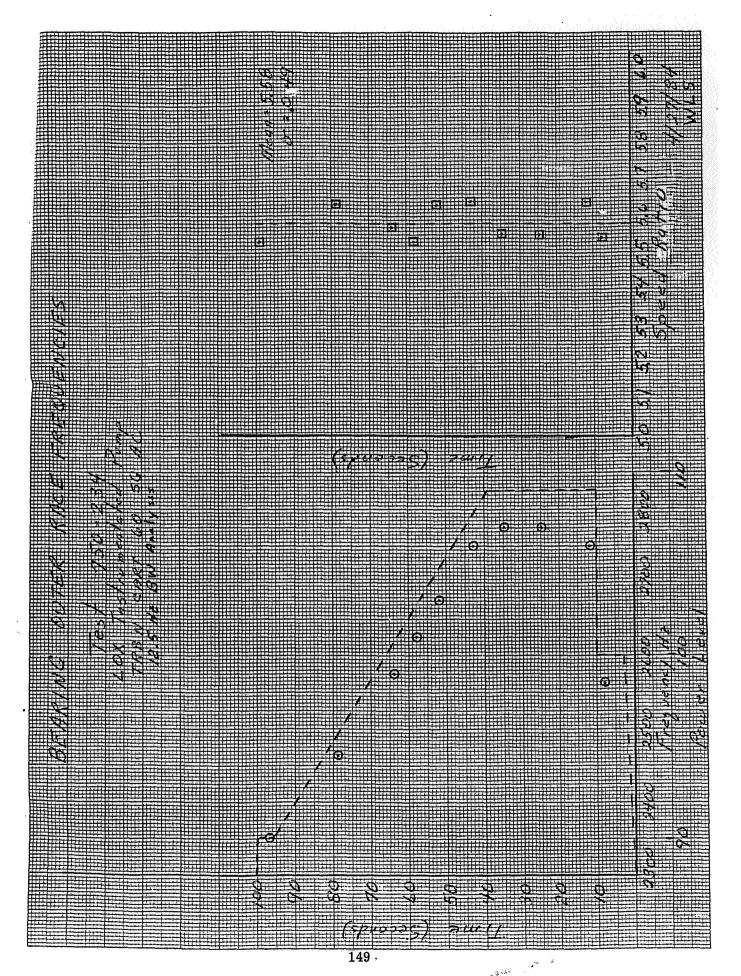
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APPENDIX C

WYLE LABORATORIES - RESEARCH STAFF TECHNICAL MEMORANDUM 64058-01-TM

STATISTICAL ANALYSIS OF THE VIBRATION DATA FOR THE SSME HIGH PRESSURE TURBOPUMPS DURING FLIGHT

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STATISTICAL ANALYSIS OF THE VIBRATION DATA FOR THE SSME HIGH PRESSURE TURBOPUMPS DURING FLIGHT

by

Wayne L. Swanson

An interim report of work performed under contract NAS8-33508

for

NATIONAL AERONAUTICS AND SPACE ADMINISTRATION GEORGE C. MARSHALL SPACE FLIGHT CENTER MARSHALL SPACE FLIGHT CENTER, ALABAMA 35812

FOREWORD

Wyle Laboratories' Scientific Services & Systems Group prepared this report for the George C. Marshall Space Flight Center, National Aeronautics and Space Administration. The work was performed under contract NAS8-33508, entitled "Dynamic Analysis of SSME Vibration and Pressure Data." Technical assistance and encouragement were provided by Mr. W. C. Smith, MSFC/ED24. The special assistance of Mr. P. Lewallen, MSFC/ED24, is acknowledged for performing numerous modifications of the MSFC Diagnostic Data Base Program required to adapt the routine for flight data analysis and documentation. The contribution of other members of ED24 and Wyle Laboratories Research Department is also acknowledged.

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1.0 INTRODUCTORY SUMMARY

This report documents the results of a statistical evaluation of RMS (root-mean-square) vibration levels measured during flight of the Space Shuttle. The data was recorded on-board the Orbiter, from accelerometers located on the Space Shuttle Main Engine (SSME) high pressure oxidizer turbopumps (HPOTP) and high pressure fuel turbopumps (HPFTP). It should be noted that the data recorded on-board the Shuttle vehicle has a 50-800 Hz bandpass filter and was analyzed using a 50-1000 Hz bandwidth. Ground test data are acquired over a wider frequency range. Therefore, any direct comparison of the composite vibration levels of the flight data to measurements recorded at the ground test stands without the bandpass filter will require the application of a small correction factor. However, the synchronous vibration levels will compare directly.

The evaluation included the composite and synchronous vibration levels at 65%, 100% and 104% power levels. Results are presented in the form of summary sheets listing the mean and standard deviation for each individual measurement; plots of the cumulative distribution with a Gamma distribution overlay, and a plot of the density function. Also presented is the ratio of the synchronous to composite vibration levels for the high pressure fuel and oxidizer turbopumps during 100% and 104% power levels.

Plots are presented of the Normal, Rayleigh, and Gamma Probability Distribution functions for comparison with over a thousand measured ground test data points. The data represents the oxidizer composite and synchronous vibration levels from ground static firings conducted on the A1, A2, and A3 test stands. An examination of the plots demonstrates the Gamma distribution function should provide reasonable approximations to the flight data. The application of a classical distribution is desirable for data characterization since this permits continuous statistical definition and manipulation from discrete flight measurement observations. Sketches are included of the accelerometer measurement locations and the power profile plots for each flight.

All of the plots contained in this report are the automatic output of the menu driven MSFC Diagnostic Data Base Program. Details of the program are documented in Reference 1.

2.0 TECHNICAL DISCUSSION

2.1 Space Shuttle Flights

Table I summarizes the 19 flights of the Space Shuttle as of August 1985.¹ The data analysis is based upon 18 flights, since only the mean square vibration levels sampled at 100 msec intervals were recorded on STS-9. This type of data is not compatible with the analysis methods used for this report. Included in Table I are the launch date, Space Shuttle Vehicle identification, maximum power level during flight, engine serial number, HPOTP serial number, and HPFTP serial numbers.

2.2 Measurement Location

The measurement locations on the HPOTP are shown in Figure 1 with the block arrangements for the 135°-1 and 135°-2 locations shown in Figure 2. A few of the early flights had measurements located at the 180° position, while the present flight measurement program is standardized to 3 measurements at the 45°, 135°-1 and 135°-2 positions. No measurements during flight are located on the High Pressure Oxidizer Turbine (HPOT) or the low pressure oxidizer turbopumps (LPOTP).

Figure 3 shows the measurement locations for the HPFTP. The measurement location of early flights was also somewhat different for the fuel turbopump than the present standardized plan of 3 measurements at the 0°, 174° and 186° positions. Data recorded at 180° position on the early flights is listed at the 186° location for the purpose of storage in the computer data bank. In addition, a few flights included data at the 90° position rather than the present 0° location. No measurements are located on the high pressure fuel turbine (HPFT) end or the low pressure fuel turbopump (LPFTP) during flight. All measurements are in the radial direction for both the HPOTP and HPFTP. The relationship of the accelerometer measurement location plane to the SSME powerhead components is shown in Figure 4.

Appendix A includes results from flights 27 (51-I) and 28 (51-J) which were not available at the time the statistical analysis was performed. The vibration levels of both flights were nominal and will not provide a significant change to the statistical values of this report. As additional flight data becomes available, this report will be periodically updated.

TABLE I. SHUTTLE FLIGHT

HPFP 1 + 2 + 3	R1 + 0306R2 + 0009R1 R1 + 0306R2 + 0009R1 R1 + 0306R2 + 0009R1 + 0306R2 + 0009R2 + 0306R2 + 9006R2 + 2315 + 2213R1 + 9211 + 2116R2 R1 + 2213R1 + 9210 R1 + 2213R1 + 9210 R1 + 2018 + 2116R2 R2 + 2017R2 + 4001R1 R2 + 2017R2 + 4003 + 4201R2 + 4003R1 R1 + 4201R2 + 4003R1 R1 + 4201R2 + 4003R1 R1 + 4201R2 + 4003R1
	9006R1 9006R1 9006R1 2009 2009 2315 2315 2315 2017R1 5101R1 5101R1 2020R2 2515R1 2020R2 2515R1 2121 2515R1 2121 2515R1
	+ 2105 + 2105 + 2105 + 2105 + 2105 + 2016 + 2016 + 2016 + 2016 + 2016 + 2016 + 4001 + 9110 + 9110 + 9110 + 9110 + 4001 + 4001 + 4001 + 4001 + 4001 + 4001 + 4001 + 4001
HPOP 1+2+3	1 + 2404 1 + 2404 1 + 2404 3 + 2404 3 + 2404 4 2015 + 2015 + 2015 + 2015 + 2011 1 + 2021 + 9211 1 + 2021 + 2018R1 + 2018R1 + 2018R1 + 2018R1 + 2018R1 + 2016R3 + 2016R3 + 2016R3 + 2016R3 + 2016R3
	0007R1 0007R1 0007R1 0007R1 9010 9010 2020 2020 2020 2020 2019R1 2020 2115 2019R1 2115 2019R1 2115 2019R1 2115
SSME 1 + 2 + 3	2007 + 2006 + 2005 2007 + 2006 + 2005 2007 + 2006 + 2005 2007 + 2006 + 2005 2007 + 2006 + 2005 2017 + 2015 + 2012 2017 + 2015 + 2012 2017 + 2015 + 2012 2017 + 2015 + 2012 2019 + 2015 + 2012 2109 + 2018 + 2012
POWER LEVEL	100 100 100 100 100 100 100 100 100 100
OV/FLT*	102-1 102-2 102-3 102-4 102-5 099-1 103-1 103-2 103-2 103-5 103-5 103-5 103-5
LAUNCH	04/12/81 11/12/81 03/22/82 06/27/82 11/11/82 06/18/83 06/18/83 02/03/84 04/06/84 08/30/84 11/08/84 01/24/85 04/12/85 04/12/85 04/29/85 06/17/85
STS LAUNCH	1 2 3 4 4 5 6 7 8 9(41-A) 11(41-B) 13(41-C) 14(41-D) 17(41-G) 19(51-A) 20(51-C) 23(51-C) 23(51-C) 26(51-C) 26(51-C) 26(51-C) 26(51-C) 26(51-C)

OV-099 Challenger; OV-102 Columbia; OV-103 Discovery; OV-104 Atlantis

The data of STS Launch 27 (51-I) and 28 (51-J) are included in Appendix A. Both flights were nominal and will not influence the statistical data contained in this report. *

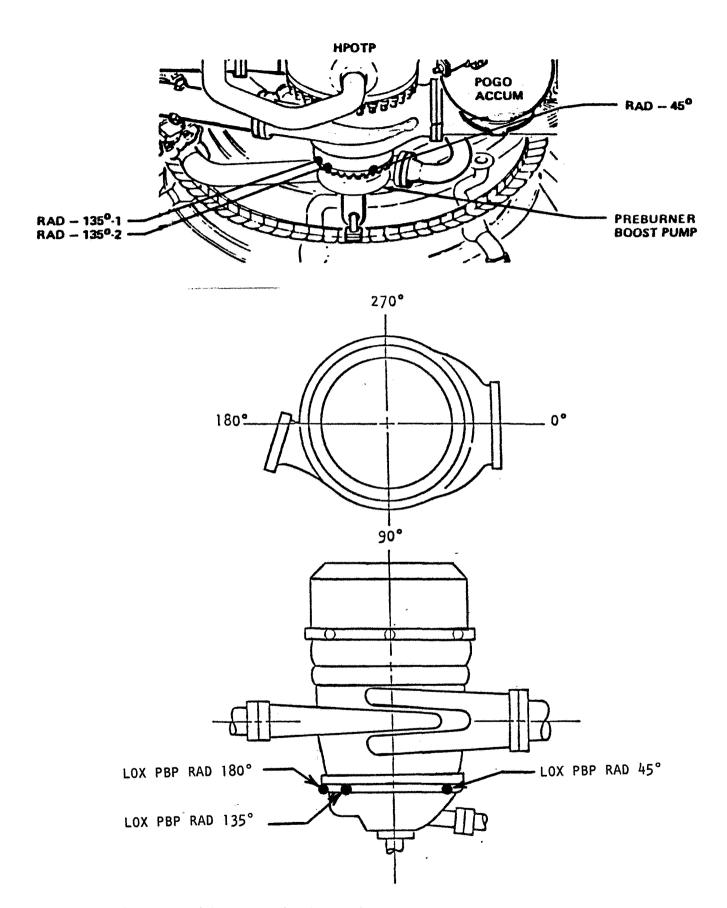


Figure 1. High Pressure Oxidizer Turbopump Accelerometer Locations, Flight

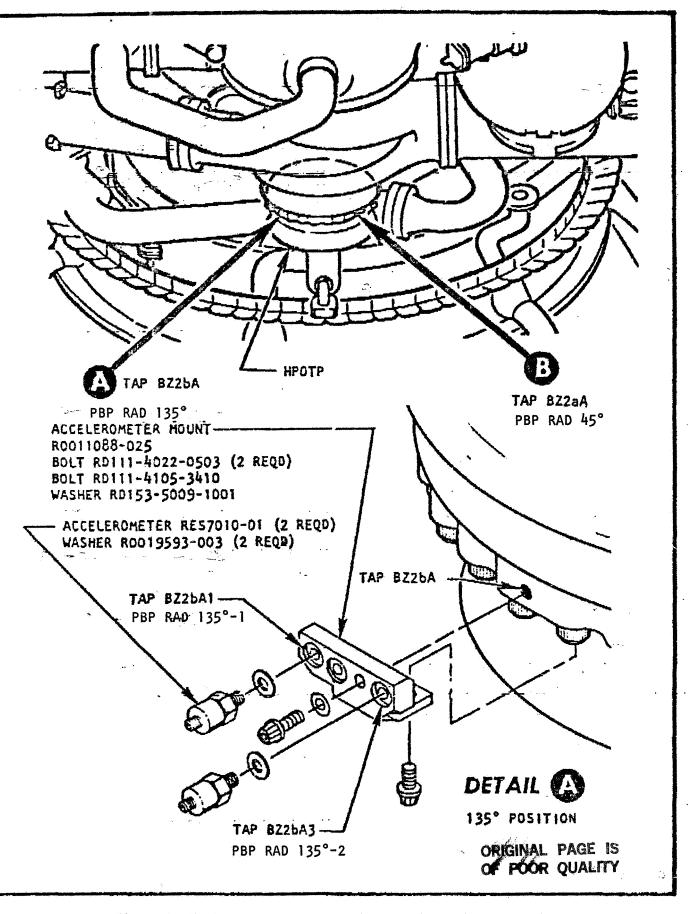
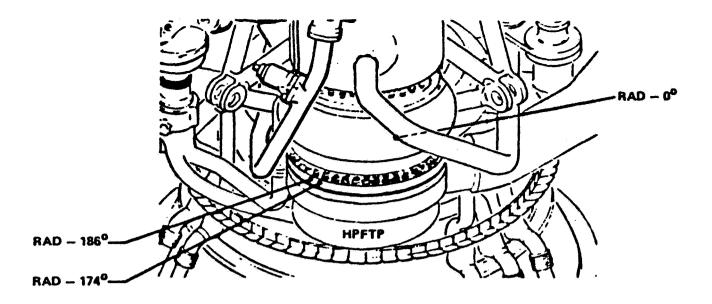


Figure 2. HPOTP Accelerometer Block 135°-1 and 135°-2, Flight



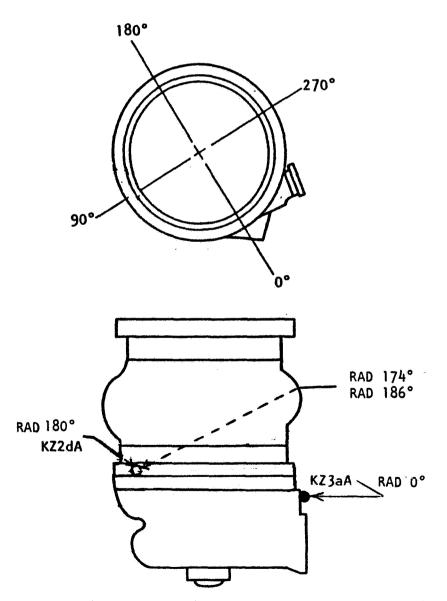


Figure 3. High Pressure Fuel Turbopump Accelerometer Locations, Flight

SSME POWERHEAD COMPONENT ARRANGEMENT

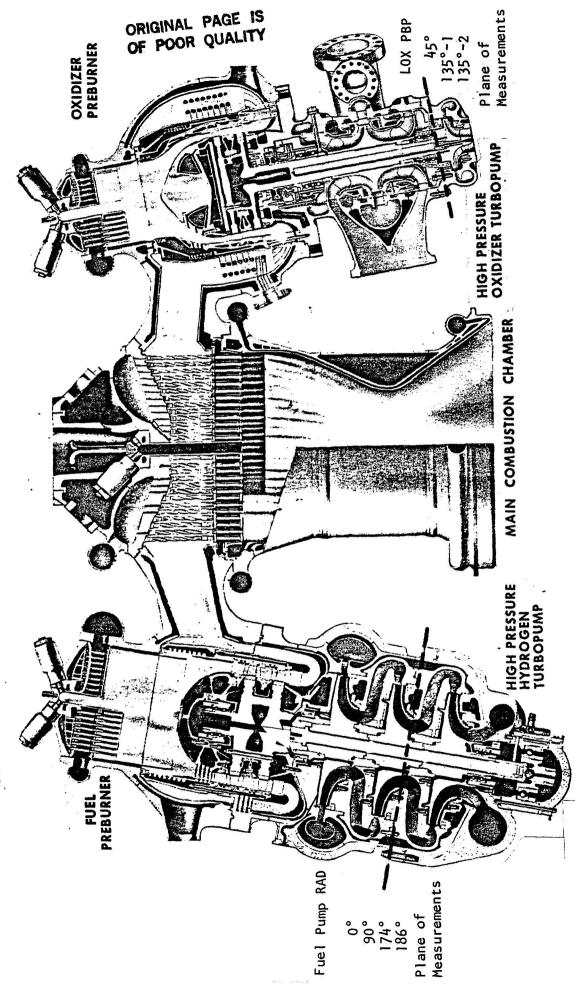


Figure 4. Accelerometer Location Plane, Flight

2.3 Power Profiles

The power profiles for each of the 18 flights are shown in Figures 5 through 8. The profiles for all ground tests and flights are stored in the MSFC Diagnostic Data Bank for retrieval and plotting. It should be noted that two profiles are shown for Mission STS 51-F indicating the early cutoff of engine number 1 during this flight.

2.4 Mean and Standard Deviation of Vibration Measurements

Given a data sample of size N the mean and variance are defined by

$$\bar{x} = 1/N \sum_{N} x_i$$
 (Sample Mean) (2.4-1)

$$\bar{\sigma}^2 = 1/(N-1) \sum_{N} (x_i - \bar{x})^2$$
 (Sample Variance) (2.4-2)

The standard deviation is the positive square root of the variance and defined by

SD =
$$\sqrt{\frac{1}{N-1}} \sum_{N} (x_i - \bar{x})^2$$
 (Sample Standard Deviation) (2.4-3)

2.4.1 Combined Data Groups

Each of the above statistics was first calculated for each measurement location and then combined as necessary for printout or plotting. The following is a discussion of procedures for combining data depending on whether the sums and the sum of squared terms or only the mean and standard deviation are stored.

Assume we wish to combine the vibration levels measured on the LOX PBP 135°-1 with the levels measured on LOX PBP 135°-2, where the mean and standard deviation were calculated for each measurement. If the sums and sum of squared terms are stored the combined mean and standard deviation are as follows.

$$\bar{x}_{12} = \frac{\sum_{N_1} (x_i)_1 + \sum_{N_2} (x_i)_2}{N_1 + N_2}$$
 (2.4-4)

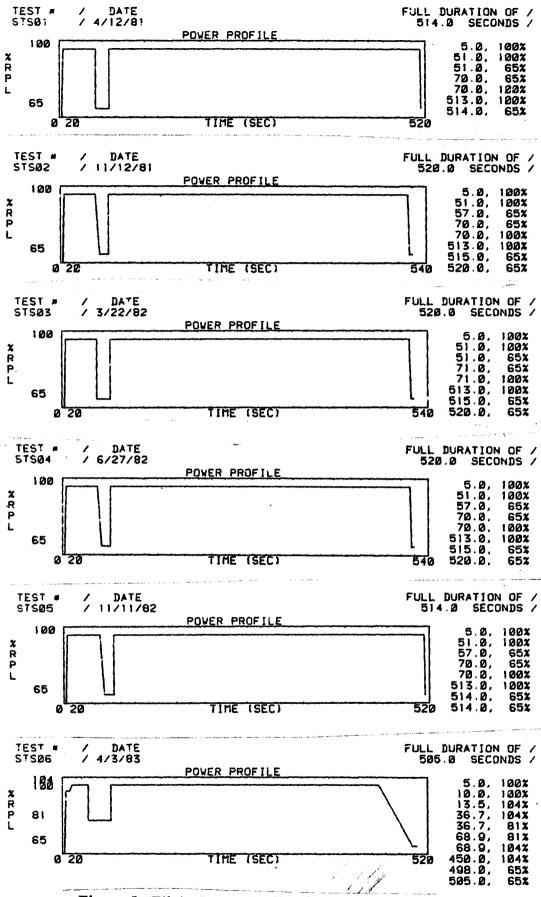


Figure 5. Flight Power Profile, STS-1 to STS-6

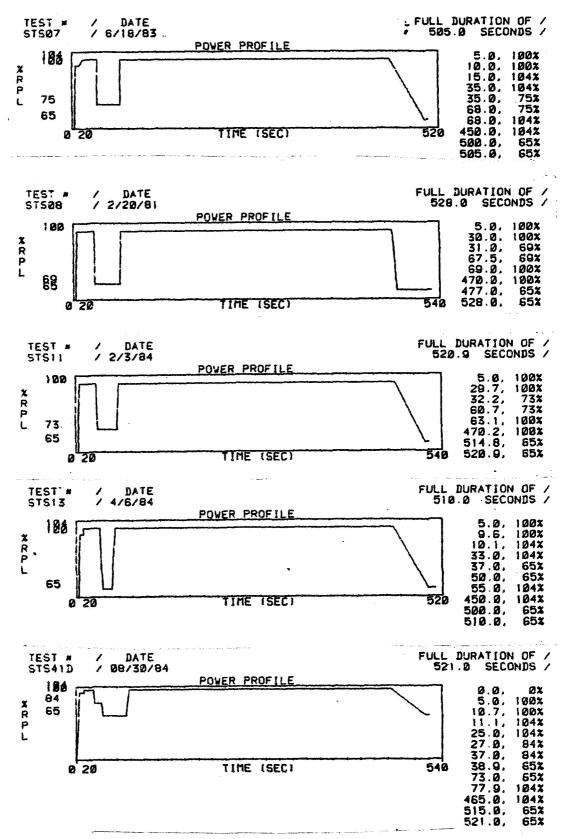


Figure 6. Flight Power Profile, STS-07 to STS-41D

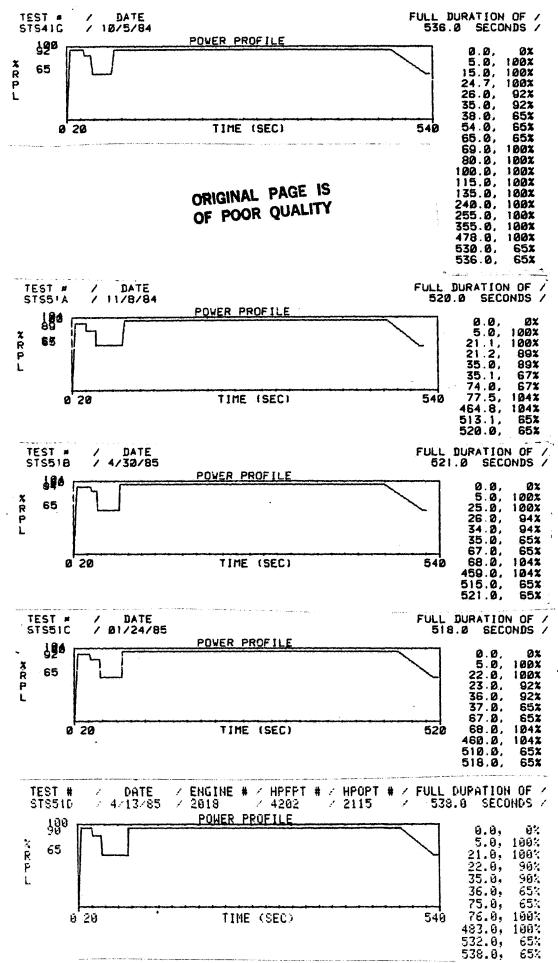


Figure 7. Flight Power Profile STS-41G to STS-51D

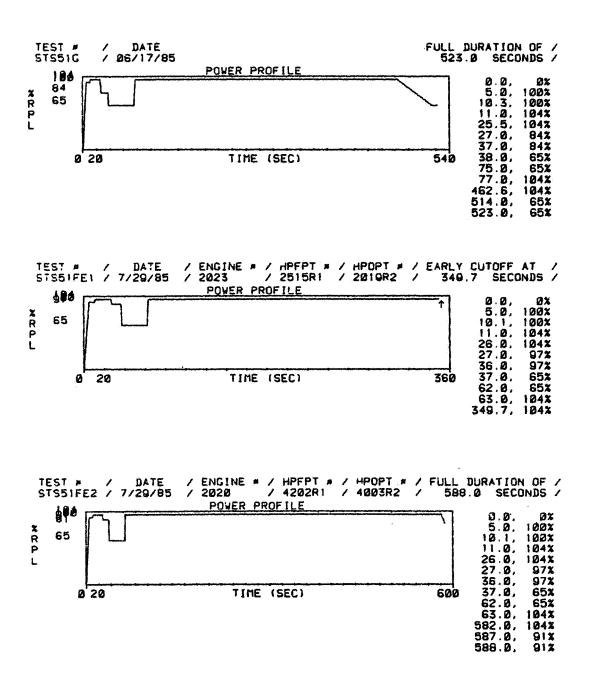


Figure 8. Flight Power Profile, STS-41G to STS-51F

where N_1 and $(x_i)_1$ are the number of measurements and vibration value respectively of the LOX PBP 135°-1 location, N_2 , $(x_i)_2$ the values of the LOX PBP 135°-2 location and \bar{x}_{12} is the combined mean vibration value.

Equation (2.4-3) for calculation of the standard deviation is modified to a format where the only requirement is storage of the sums. Using Equations (2.4-1) and (2.4-3)

SD
$$= \sqrt{\frac{1}{N-1}} \sum_{N} (x_{i} - \bar{x})^{2}$$

$$(SD)^{2} (N-1) = \sum_{N} (x_{i} - \bar{x})^{2}$$

$$= \sum_{N} (x_{i}^{2} - 2x_{i} \bar{x} + \bar{x}^{2})$$

$$= \sum_{N} (x_{i})^{2} - \sum_{N} 2 x_{i} \bar{x} + \sum_{N} (\bar{x})^{2}$$

Since

$$\sum_{\mathbf{N}} 2 \mathbf{x_i} = 2 \mathbf{N} \mathbf{\bar{x}}$$

and

$$\sum_{N} (\bar{x})^{2} = N(\bar{x})^{2}$$

$$(SD)^{2} (N-1) = \sum_{N} (x_{i})^{2} - 2N(\bar{x})^{2} + N(\bar{x})^{2}$$

$$= \sum_{N} (x_{i})^{2} - N(\bar{x})^{2}$$

and

SD =
$$\sqrt{\frac{\sum_{N} (x_i)^2 - N(\bar{x})^2}{N-1}}$$
 (2.4-6)

or

SD
$$= \sqrt{\frac{\sum_{N} (x_i)^2 - (\sum_{N} x_i)^2}{N-1}}$$
 (2.4-7)

As can be easily seen from examination of Equation (2.4-7), only the number of data points and the sum of x_i and $(x_i)^2$ values are required for calculation of the standard deviation. Most hand calculators and computer programs use this method rather than Equations (2.4-1) and (2.4-3). Equations (2.4-1) and (2.4-3) require the calculation of the mean for the complete data set before the sum of the difference squared can be calculated.

The standard deviation for the combined LOX PBP 135°-1 and LOX PBP 135°-2, assuming the sum of the x_i and $(x_i)^2$ terms are available is

$$SD_{12} = \sqrt{\frac{\sum_{N_1} (x_i)_1^2 + \sum_{N_2} (x_i)_2^2}{\sum_{N_1 + N_2} (x_i)_2^2} - \left[\frac{\left[\left(\sum_{N_1} x_i\right)_1 + \left(\sum_{N_2} x_i\right)_2\right]^2}{N_1 + N_2}\right]}$$

$$(2.4-8)$$

However, if the sums are not available the combined mean and standard deviation can be calculated from the individual number of data points, means and standard deviations as follows.

From Equation (2.4-1)

$$\sum_{\mathbf{N}} \mathbf{x_i} = \mathbf{N} \, \tilde{\mathbf{x}} \tag{2.4-9}$$

and with Equation (2.4-4) the combined mean of the LOX PBP 135°-1 and LOX PBP 135°-2 is

$$\bar{x}_{12} = \frac{N_1 \bar{x}_1 + N_2 \bar{x}_2}{N_1 + N_2} \tag{2.4-10}$$

where the subscripts 1 and 2 of N and \bar{x} indicate the number of data points and mean of the individual data sets, respectively.

For the calculation of the standard deviation using Equations (2.4-1), (-6), and (-8)

$$\sum_{\mathbf{N}} \mathbf{x_i} = \mathbf{N} \mathbf{\bar{x}}$$

$$\sum_{N} (x_i)^2 = (SD)^2 (N-1) + N(\bar{x})^2$$

and substitution into Equation (2.4-8)

$$(SD_{12})^{2} (N_{1} + N_{2} - 1) = (SD)_{1}^{2} (N_{1} - 1) + N_{1} (\bar{x})_{1}^{2} + (SD)_{2}^{2} (N_{2} - 1) + N_{2} (\bar{x})_{2}^{2}$$

$$- \left[\frac{(N_{1} \bar{x}_{1} + N_{2} \bar{x}_{2})^{2}}{N_{1} + N_{2}} \right]$$

and the combined standard deviation of the LOX PBP 135°-1 and LOX PBP 135°-2 is

$$SD_{12} = \sqrt{\frac{(SD)_{1}^{2} (N_{1}-1) + (SD)_{2}^{2} (N_{2}-1) + N_{1} (\bar{x}_{1})^{2} + N_{2} (\bar{x}_{2})^{2} - \left[\frac{(N_{1}\bar{x}_{1}+N_{2}\bar{x}_{2})^{2}}{N_{1}+N_{2}}\right]}{N_{1}+N_{2}-1}}$$
(2.4-11)

The procedure can be repeated if an additional data set, for example the LOX PBP RAD 45°, is to be combined with the LOX PBP RAD 135°-1 and LOX PBP RAD 135°-2 data set. A more elegant derivation of the equations for combining multiple data sets, augmenting a data set and deleting a data point from unpublished work of Tom Coffin is included in the next section. A procedure for combining data based on the small sample size theorem for the high order moments (skewness and kurtosis) will be forthcoming in future documentation.

2.5 Formulae for Estimating Basic Engine Parameter Statistics

2.5.1 Background

Given a sample of size N from a population of size P, the mean and variance are defined for N and P by

$$\overline{m} = (1/N) \sum_{N} x_i$$
 (Sample mean) (2.5-1)

$$m = (1/P) \sum_{p} x_{i}$$
 (Population mean) (2.5-2)

$$\bar{\sigma}^2 = (1/N-1) \sum_{N} (x_i - \bar{m})^2$$
 (Sample variance) (2.5-3)

$$\sigma^2 = (1/P) \sum_{p} (x_i-m)^2$$
 (Population variance) (2.5-4)

Note that for large N,

$$(N/N-1) \rightarrow 1$$
.

so formula 3 approaches

$$\bar{\sigma}^2 \simeq (1/N) \sum_{N} (x_i - \bar{m})^2$$
 (for large N) (2.5-3A)

The asymptotic convergence between formulae 2.5-3 and -3A is more strongly emphasized by observing that the standard deviation is the primary statistic of interest, so the practical deviation between formulae 2.5-3 and -3A is as

$$\left\{N(N-1)^{-1}\right\}^{\frac{1}{2}}$$

Since the population of possible engine parameter outcomes is infinite, our statistical estimates are based on formulae 2.5-1 and 2.5-3 or -3A.

2.5.2 Combined Multiple Data Groups

Next, assume a sample, S, consisting of three subgroups, $\{X\}$, $\{Y\}$, $\{Z\}$. Technically

$$S = XUYUZ (2.5-5)$$

A practical example would be to let X, Y, Z represent a parameter measured on test stands A_{I} , A_{II} , A_{III} , respectively. The set S then represents the parameter variation giving equal weight to each test from all test stands.

Assume also that we have computed \bar{m} and $\bar{\sigma}$ for each of these groups and wish to compute the same statistics for the complete set (2.5-5). It is desirable to use the group statistics already calculated to obtain these results, as opposed to applying formulae 2.5-1 and 2.5-3 on the complete data set. More specifically, given

$$\bar{m}_X$$
, \bar{m}_Y , \bar{m}_Z ; $\bar{\sigma}_X$, $\bar{\sigma}_Y$, $\bar{\sigma}_Z$

compute \bar{m}_S , $\bar{\sigma}_S$, where S is defined by formula 2.5-5.

First, consider the mean \overline{m}_{S} . By formula 2.5-1,

$$\bar{m}_{S} = (1/N_{S}) \left[\sum_{N_{X}} x_{i} + \sum_{N_{Y}} y_{i} + \sum_{N_{Z}} z_{i} \right]$$
 (2.5-6)

where $N_S = N_X + N_Y + N_Z$. (2.5-7)

But also by formula 2.5-1,

$$\sum_{N_X} x_i = N_X \overline{m}_X$$

$$\sum_{N_Y} y_i = N_Y \overline{m}_Y$$

$$\sum_{N_Z} z_i = N_Z \overline{m}_Z$$
(2.5-8)

so
$$\overline{m}_{S} = (1/N_{S}) \left[N_{X} \overline{m}_{X} + N_{y} \overline{m}_{Y} + N_{Z} \overline{m}_{Z} \right]$$
 (2.5-9)

Or, more compactly,

$$\overline{m}_{S} = (1/N_{S}) \sum_{j} N_{j} \overline{m}_{j}$$

$$N_{S} = \sum_{i} N_{j}.$$
(2.5-10)

where

Next consider the variance, $\bar{\sigma}_{\rm S}^2$. By formula 2.5-3.

$$\bar{\sigma}_{S}^{2} = (1/N_{S}^{-1}) \left\{ \sum_{N_{X}} (x_{i}\bar{m}_{S})^{2} + \sum_{N_{Y}} (y_{i}\bar{m}_{S})^{2} + \sum_{N_{Z}} (z_{i}\bar{m}_{S})^{2} \right\}$$
 (2.5-11)

Expanding the first sum in brackets,

$$\sum_{N_X} (x_i - \overline{m}_S)^2 = \sum_{N_X} x_i^2 - 2N_X \overline{m}_X \overline{m}_S + N_X \overline{m}_S^2, \qquad (2.5-12)$$

and noting that by formula 2.5-3,

$$\sum_{N_X} x_i^2 = (N_X - 1) \, \overline{\sigma}_X^2 + N_X \overline{m}_X^2 \qquad (2.5-13)$$

the first sum in formula 2.5-11 may be written

$$\sum_{N_X} (x_i - \overline{m}_S)^2 = (N_X - 1) \overline{\sigma}_X^2 + N_X (\overline{m}_X - \overline{m}_S)^2$$
 (2.5-14)

and an identical form follows for the remaining two sums.

The variance of the combined data set may therefore be conveniently computed by the formula

$$\overline{\sigma}_{S}^{2} = (1/N_{S}^{-1}) \left\{ \sum_{i} (N_{i}^{-1}) \overline{\sigma}_{i}^{2} + \sum_{i} N_{i} (\overline{m}_{i}^{-m}_{S})^{2} \right\}$$
 (2.5-15)

Again, if the data groups are large (say, N_i is greater than 30),

$$\bar{\sigma}_{S}^{2} \simeq (1/N_{S}) \left\{ \sum_{i} \bar{\sigma}_{i}^{2} + \sum_{i} N_{i} (\bar{m}_{i} - \bar{m}_{S})^{2} \right\}$$
 (2.5-16)

2.5.3 Augmenting a Data Set

Often, means and variances may be computed for a set of data and a new data point then obtained. It is desirable to compute these statistics for the newly augmented data set using those already obtained (as opposed to starting anew).

Consider a group $\{X\}$, of size N_X , for which we have already computed \overline{m}_X , $\overline{\sigma}_X$ by formulae 2.5-1 and 2.5-3, respectively, and let

$$S = \{x_1, x_2, ..., x_N, Z\}$$
 (2.5-17)

then, by formula 2.5-1,

$$\bar{m}_{S} = (1/N_{X}^{+1}) \left\{ \sum_{N_{X}} x_{i} + Z \right\}$$
 (2.5-18)

or simply

$$\overline{m}_{S} = (1/N_{X}+1) (N_{X}\overline{m}_{X}+Z)$$
 (2.5-19)

Finally, by formulae 2.5-3 or 2.5-11,

$$\vec{\sigma}_{S}^{2} = (1/N_{X}) \left\{ \sum_{N_{X}} (x_{i} - \vec{m}_{S})^{2} + (Z - \vec{m}_{S})^{2} \right\}$$
 (2.5-20)

and using 2.5-17,

$$\bar{\sigma}_{S}^{2} = (1/N_{X}) \left\{ (N_{X}^{-1}) \bar{\sigma}_{X}^{2} + N_{X} (\bar{m}_{X}^{-\bar{m}}_{S})^{2} + (Z - \bar{m}_{S})^{2} \right\}$$
 (2.5-21)

2.5-19 and 2.5-21 provide the desired formulae.

2.5.4 Deleting a Data Point

A third situation is encountered when the mean and variance for a data set have been computed, after which it is found that an included test result is invalid. It is then convenient to have formulae available to obtain the statistics for the reduced set, for example, neglecting the invalid data point.

Let S, S' represent the complete and reduced data set, respectively. By simply rearranging 2.5-19, the mean for the reduced set is

$$\overline{m}_{S'} = \frac{N_S \overline{m}_S - Z}{N_S - 1}$$
 (2.5-22)

where Z represents the invalid data point to be deleted. Similarly, the desired variance is obtained by manipulating formula 2.5-21:

$$\bar{\sigma}_{S'}^2 = (1/N_S^{-2}) \left\{ (N_S^{-1}) \left[\bar{\sigma}_S^2 - (\bar{m}_{S'}^{-1} - \bar{m}_S^{-1})^2 \right] - (Z - \bar{m}_S^{-1})^2 \right\}$$
 (2.5-23)

The above formulae are easily programmed on a small calculator for ready reference, and have been implemented in the diagnostic data base software for data base editing and update.

2.6 Classical Distribution Functions

Three classical continuous probability distributions were selected for comparison with the SSME vibration data. They were the Normal, Rayleigh and Gamma functions and are listed as programmed in the Diagnostic Data Bank in the next paragraph. Since the choice of a classical probability function for a data set is arbitrary, additional investigations are planned to evaluate other classical distributions and functions of higher order. Best-Fit (Chi-Square Goodness-of-Fit, Bonferroni-Type Inequalities, etc.) will also be investigated. However, a visual inspection of Figures 9 to 32 indicates the Gamma function is reasonable for the SSME high pressure turbopump vibration data from static firing tests and should be applicable to the flight data. Plots are shown for both the composite and synchronous vibration levels. Static firing tests were utilized for the comparison, since a larger data base was available consisting of over 1,000 data samples.

The application of a classical distribution is desirable for data characterization since this permits continuous statistical definition and manipulation from discrete flight measurement observations. The cumulative distribution plots provide a quick-look assessment of flight results with the historical distribution of measurements from previous flights. Density plots are useful for an assessment of the historical data scatter or dispersion around the mid-point or mean value. The density functions are shown in Figures 15 to 20 for the composite values and Figures 27 to 32 for the synchronous values from which the cumulative distribution was calculated from

$$F(N\Delta x) = \sum_{i=1}^{N} f(x_i)$$
 (2.6-1)

where N Δx is the Grms level used in plotting.

Normal Distribution

$$f(x) = 1/S\sqrt{2\pi} e \left[-\frac{(x-M)^2}{2S^2} \right]_{\Delta x}$$
 (2.6-2)

M = Mean Grms Level

S = Standard Deviation

 Δx = Step Size = 0.5 Grms

Rayleigh Distribution

$$f(x) = \frac{x}{\alpha^2} e^{-x^2/2 \alpha^2} \Delta x \qquad (2.6-3)$$

$$\Delta x$$
 = Step Size = 0.5 Grms

The parameter α of the Rayleigh density can be the mean, standard deviation, and the first moment or second moment of the Rayleigh function (Reference 2). A more detailed study and discussion of the Rayleigh density and other classical functions will be included in future documentation.

Rayleigh (M)

$$\alpha$$
 = Mean

Rayleigh (SD)

$$\alpha$$
 = Standard Deviation

Rayleigh (MR)

$$\alpha = \frac{M}{\sqrt{\pi/2}} \qquad M = Mean$$

Rayleigh (TC)

$$\alpha = \frac{S}{\sqrt{2 - \pi/2}}$$
 S = Standard Deviation

Gamma Distribution

The Gamma distribution will be presented in more detail, since it appears to provide the most reasonable fit to the vibration data. It should be noted that the Gamma distribution contains two parameters related to both the mean and standard deviation. The four Rayleigh functions are one parameter systems and utilize the mean or standard deviation, but not both. The Gamma probability distribution is defined as

$$f(x) = \frac{\lambda}{\Gamma(r)} (\lambda x)^{r-1} e^{-\lambda x} \qquad x > 0 \qquad (2.6-4)$$

where $\Gamma(r)$ is the Gamma, or generalized factorial function.

The parameter λ and r in terms of the mean and variance from Reference (3) are:

$$\bar{x} = \frac{r}{\lambda}, \sigma^2 = r/\lambda^2$$
 (2.6-5)

Solving each equation for r

$$r = \bar{x} \lambda , \quad r = \sigma^2 \lambda^2 \qquad (2.6-6)$$

or

$$\lambda^2 \sigma^2 = \lambda \bar{x} \tag{2.6-7}$$

$$\lambda = \bar{x}/\sigma^2 \tag{2.6-8}$$

From the first of Equation (2.6-5) and (2.6-8)

$$\bar{x} = \frac{r \sigma^2}{\bar{x}}$$
 (2.6-9)

SO

$$r = \bar{x}^2/\sigma^2 \tag{2.6-10}$$

Using Equations (2.6-4), (-8) and (-10)

$$f(x) = \frac{\bar{x}}{\sigma^2 \Gamma[\bar{x}^2/\sigma^2]} \left[\frac{\bar{x} x}{\sigma^2} \right]^{\left(\frac{\bar{x}^2}{\sigma^2} - 1\right)} e^{-\frac{\bar{x} x}{\sigma^2}}$$
(2.6-11)

Some important relationships of the Gamma function are:

$$\Gamma(n+1) = \int_{0}^{\infty} x^{n} e^{-x} dx, \text{ which leads to}$$

$$\Gamma(n) = (n-1) \Gamma(n-1)$$

$$\Gamma(n) = (n-1)!$$

$$\Gamma(n+1) = n!$$
(2.6-12)

Thus the definition as a generalized factorial function.

Therefore in terms of the mean Grms and standard deviation the Gamma density function is

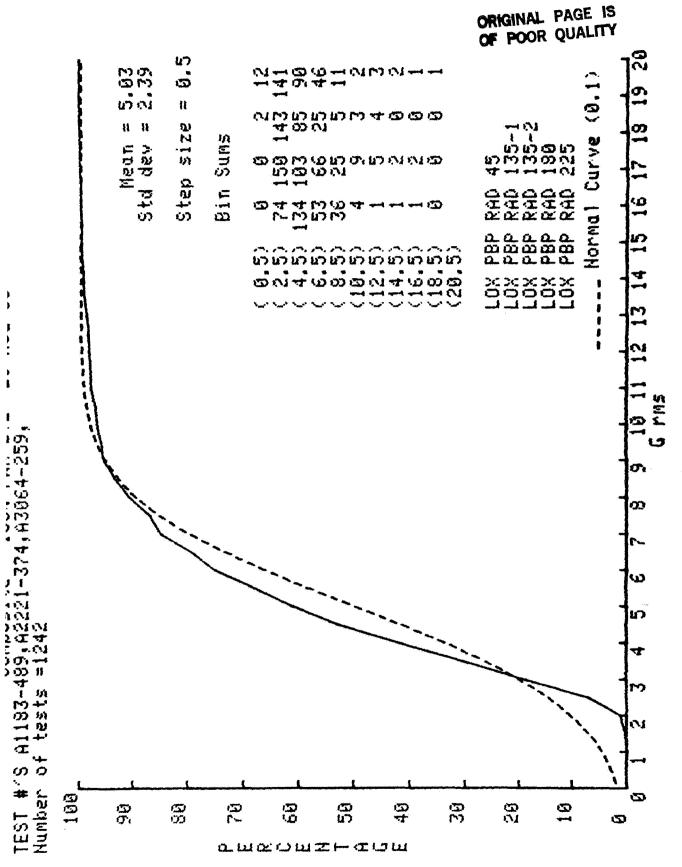
$$f(x) = \frac{\frac{m}{s^2[m^2/s^2-1]!} + \frac{mx}{s^2}}{s^2} + e^{-\frac{(mx)}{s^2}} \Delta x \qquad (2.6-13)$$

m = Mean Grms Level

s = Standard Deviation

 $\Delta x = \text{Step Size} = 0.5$

Although the Gamma distribution appears to provide a reasonable fit to the data, some additional improvements should be investigated. These include a change in the class interval width, unequal class intervals and maybe some type of truncated Gamma or other classical function to account for the low synchronous values approaching the noise floor of the instrumentation. It may be noted F(x) and f(x) are not the continuous form of the cumulative probability function and probability density function, but represent percentiles within discrete class intervals. This formulation permits direct comparison between classical function approximations and discrete frequency distributions representing empirical measurement characteristics.



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Cumulative Probability Distribution (LOX PBP RAD, Static Firing, Composite) Normal Overlay Figure 9.

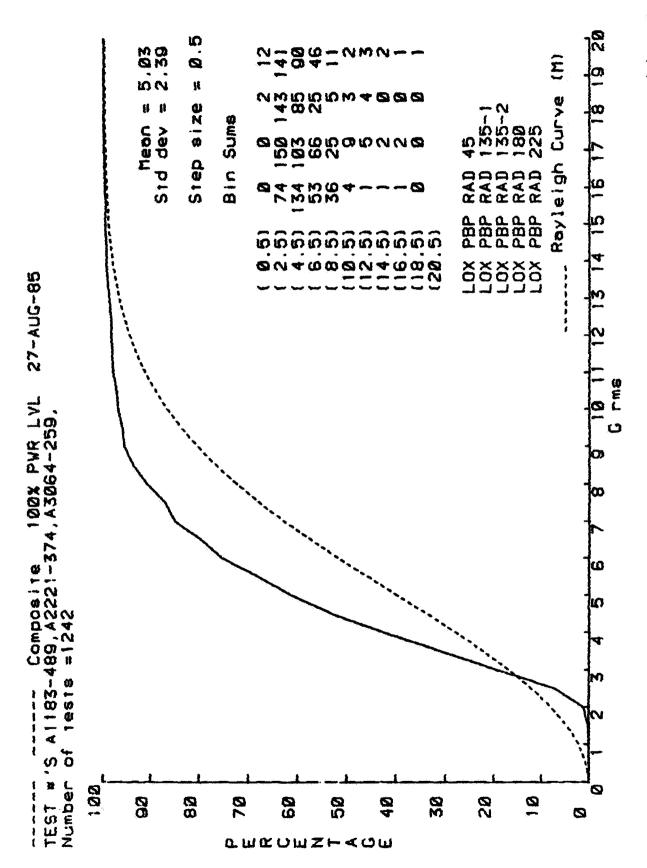
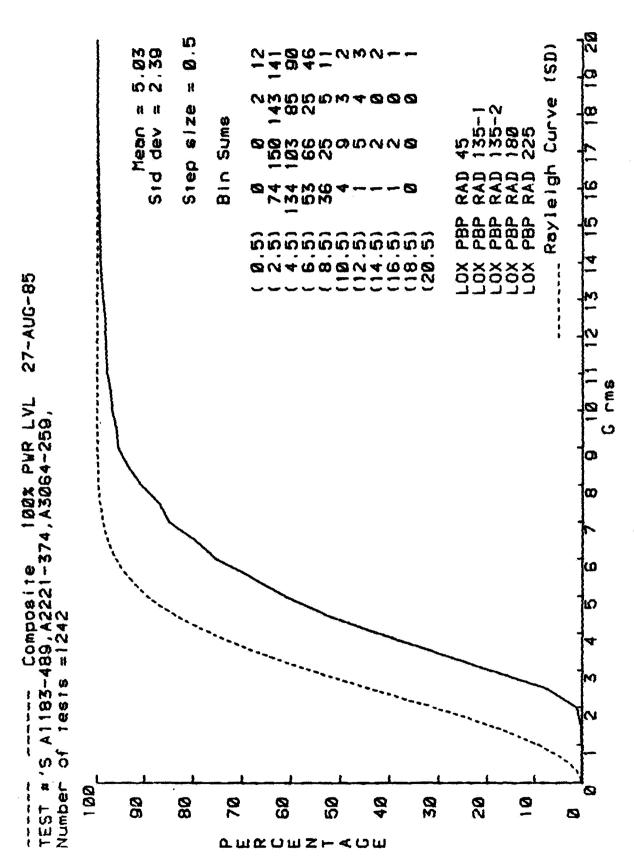


Figure 10. Cumulative Probability Distribution (LOX PBP RAD, Static Firing, Composite) Rayleigh (M) Overlay



Cumulative Probability Distribution (LOX PBP RAD, Static Firing, Composite) Rayleigh (SD) Overlay Figure 11.

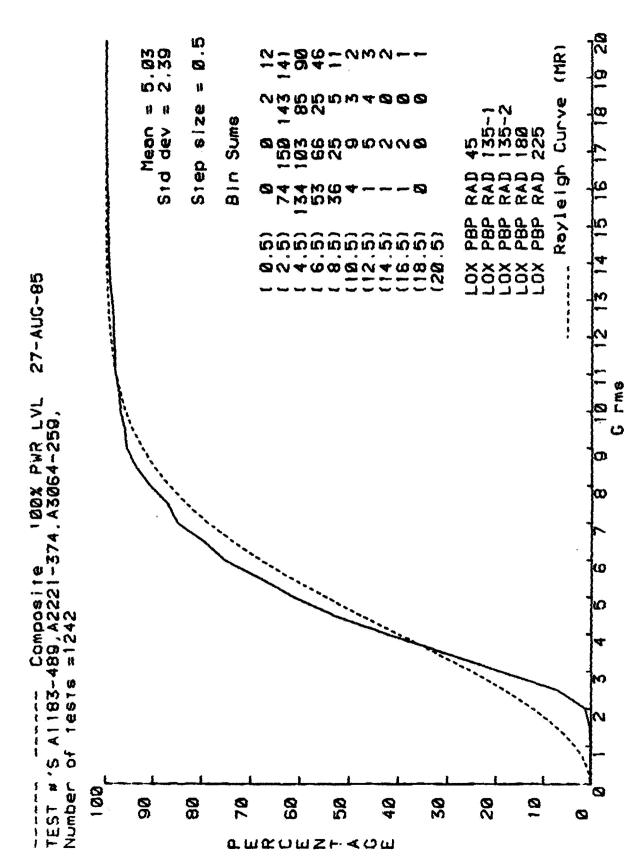


Figure 12. Cumulative Probability Distribution (LOX PBP RAD, Static Firing, Composite) Rayleigh (MR) Overlay

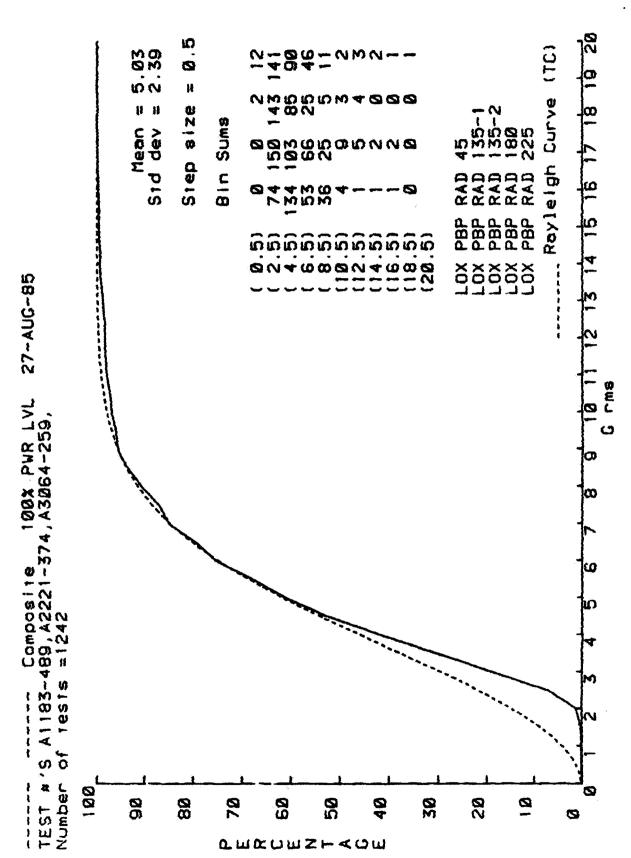


Figure 13. Cumulative Probability Distribution (LOX PBP RAD, Static Firing, Composite) Rayleigh (TC) Overlay

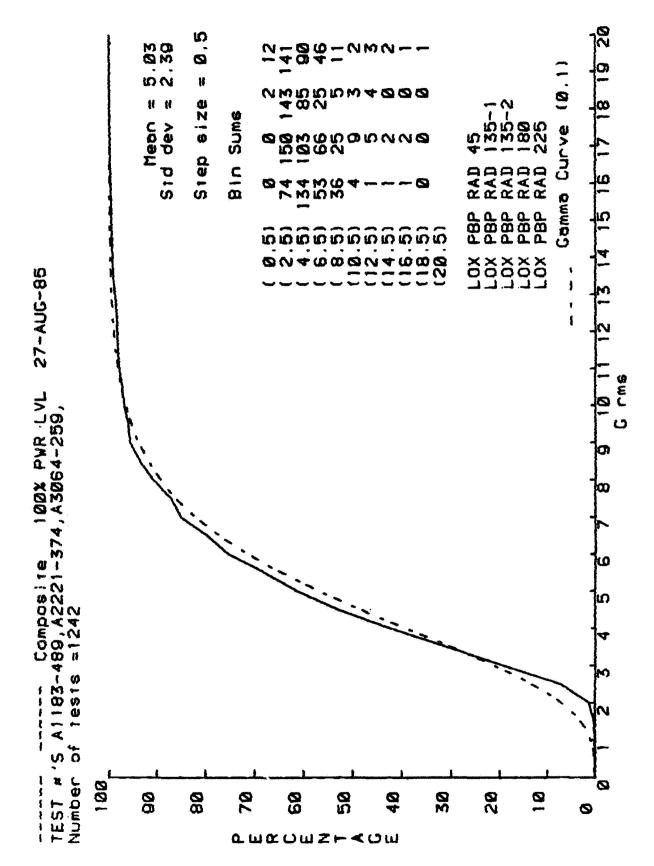


Figure 14. Cumulative Probability Distribution (LOX PBP RAD, Static Firing, Composite) Gamma Overlay

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Figure 15. Probability Density (LOX PBP RAD, Static Firing, Composite) Normal Overlay

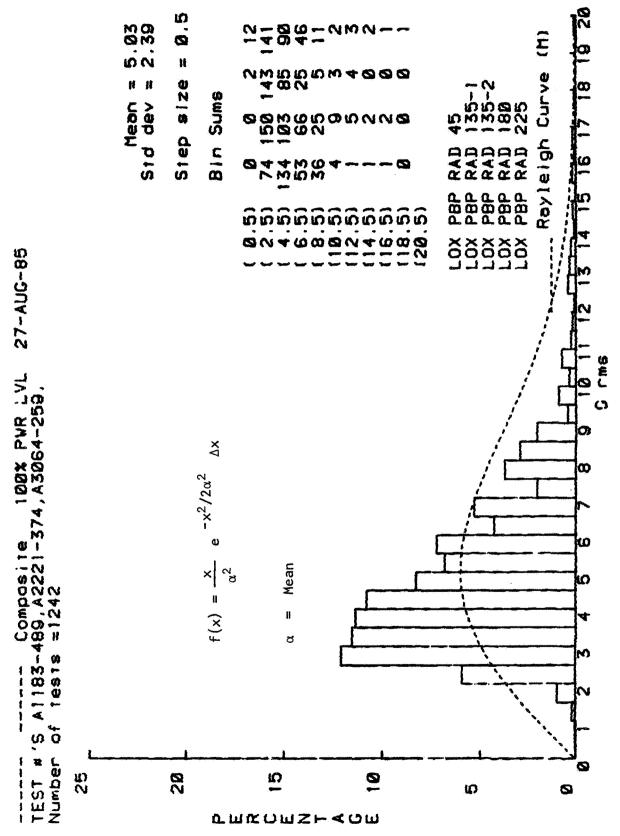


Figure 16. Probability Density (LOX PBP RAD, Static Firing, Composite) Rayleigh (M) Overlay

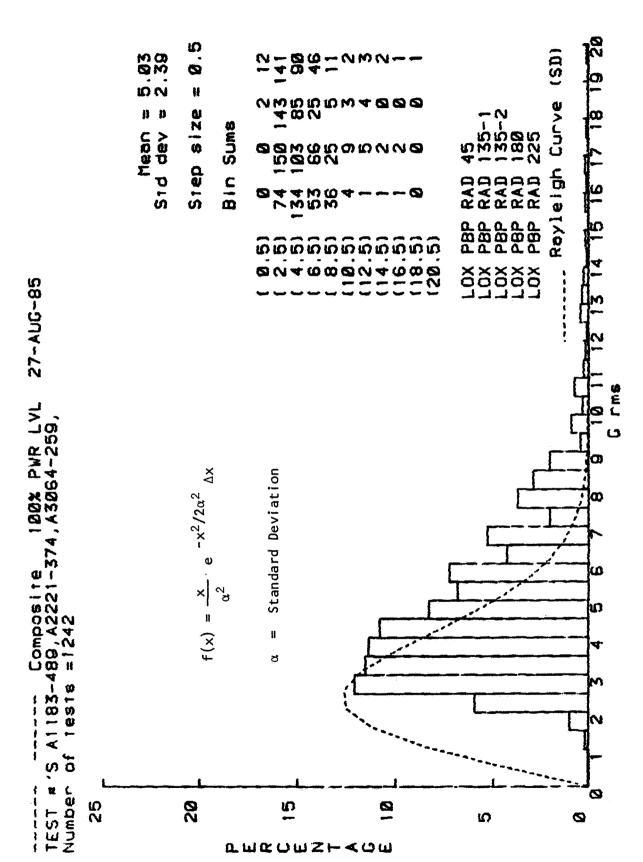


Figure 17. Probability Density (LOX PBP RAD, Static Firing, Composite) Rayleigh (SD) Overlay

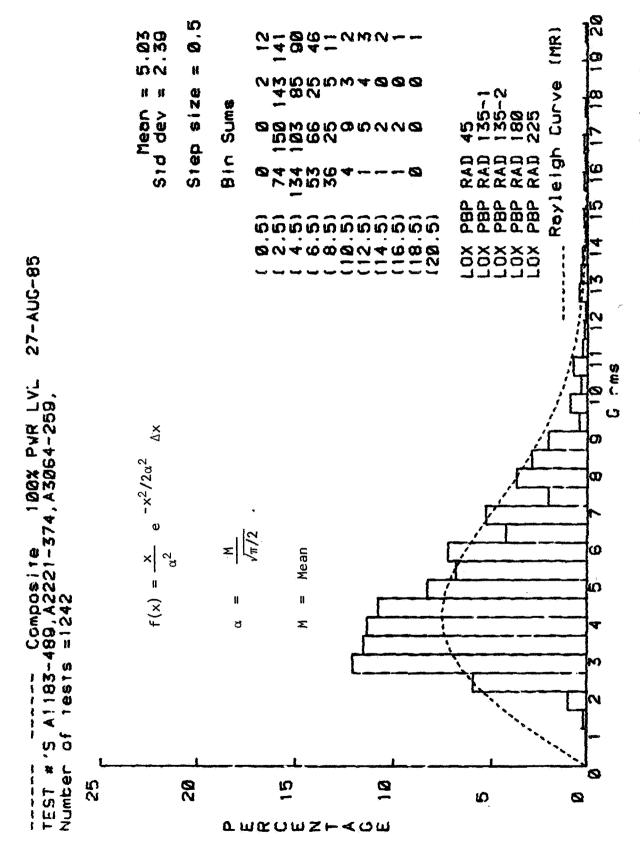


Figure 18. Probability Density (LOX PBP RAD, Static Firing, Composite) Rayleigh (MR) Overlay

40

C-5

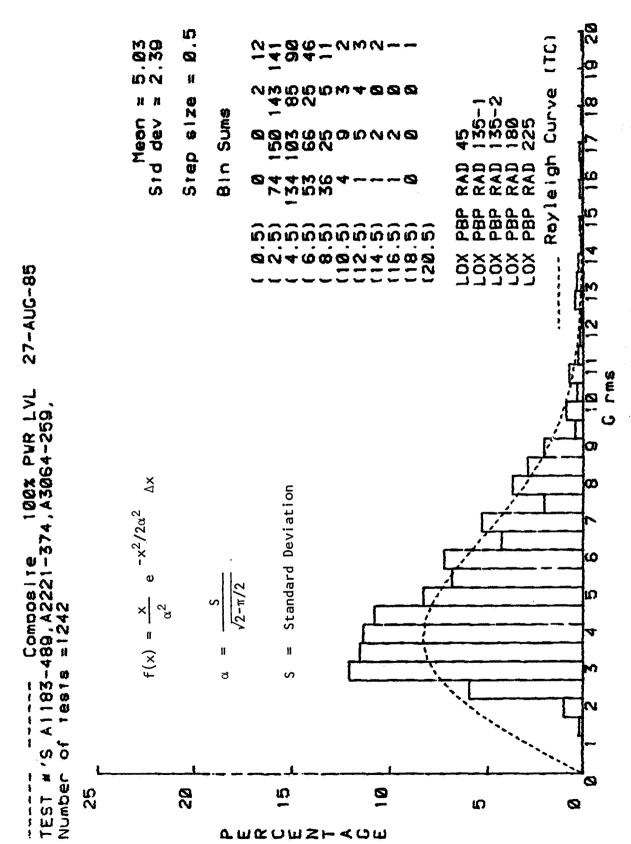


Figure 19. Probability Density (LOX PBP RAD, Static Firing, Composite) Rayleigh (TC) Overlay

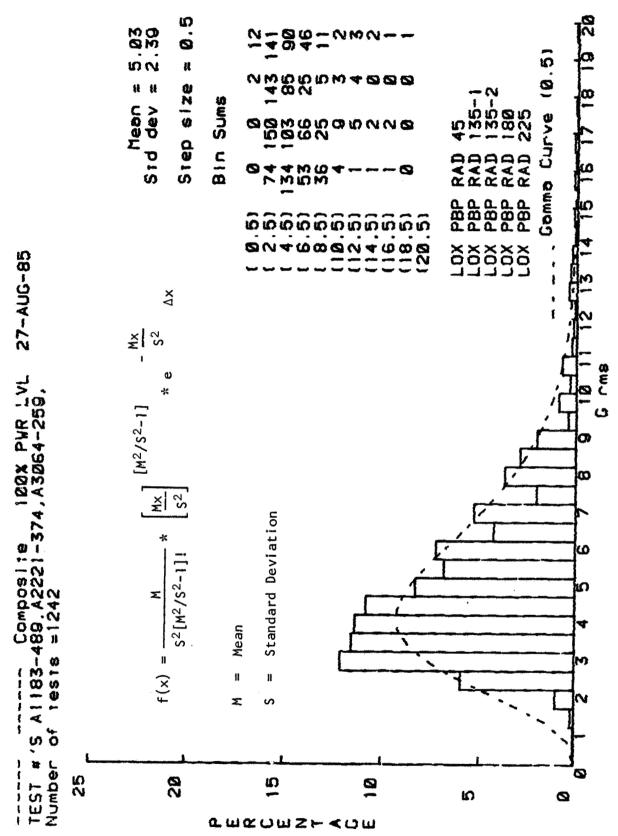
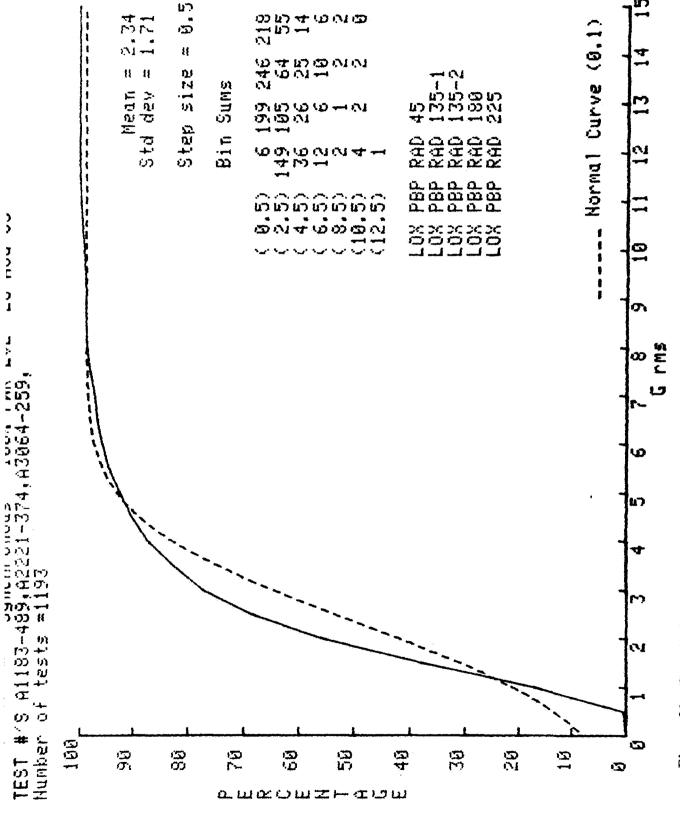


Figure 20. Probability Distribution (LOX PBP RAD, Static Firing, Composite) Gamma Overlay



) }

Figure 21. Cumulative Probability Distribution (LOX PBP RAD, Static Firing, Synchronous) Normal Overlay

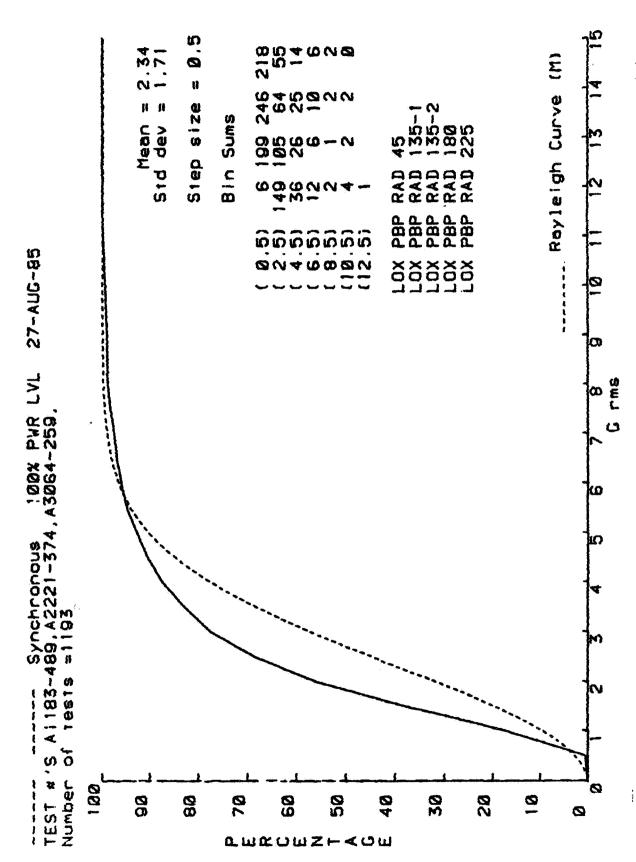


Figure 22. Cumulative Probability Distribution (LOX PBP RAD, Static Firing, Synchronous) Rayleigh (M) Overlay

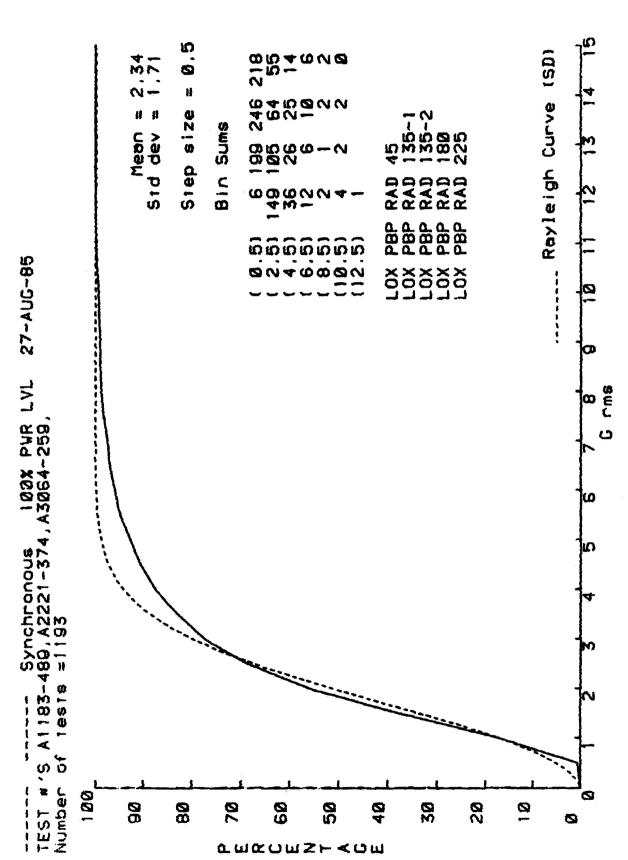


Figure 23. Cumulative Probability Distribution (LOX PBP RAD, Static Firing, Synchronous) Rayleigh (SD) Overlay

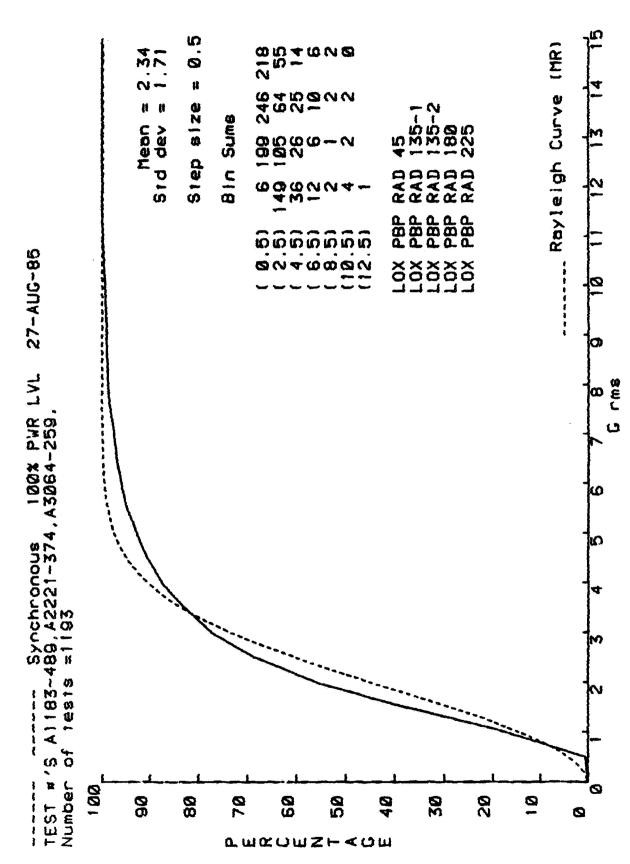


Figure 24. Cumulative Probability Distribution (LOX PBP RAD, Static Firing, Synchronous) Rayleigh (MR) Overlay

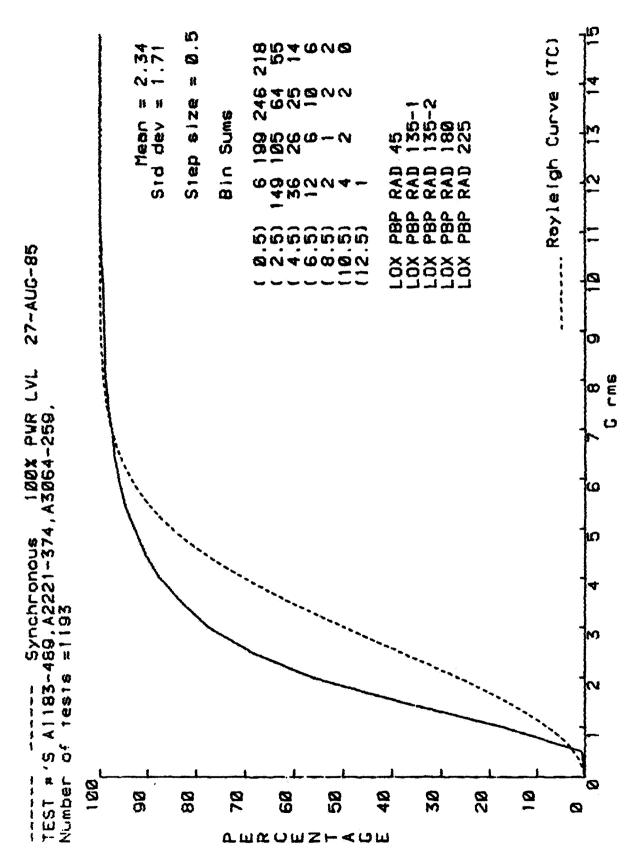


Figure 25. Cumulative Probability Distribution (LOX PBP RAD, Static Firing, Synchronous) Rayleigh (TC) Overlay

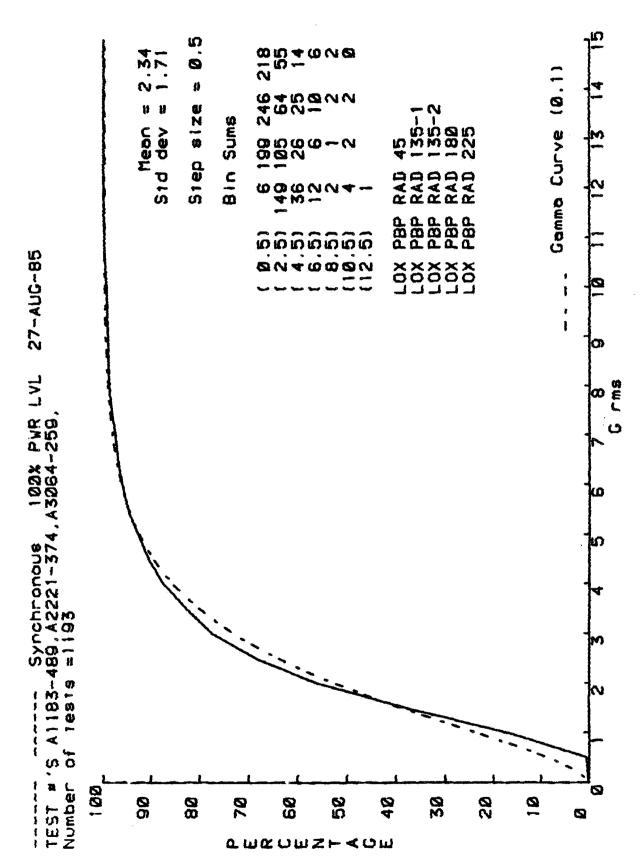
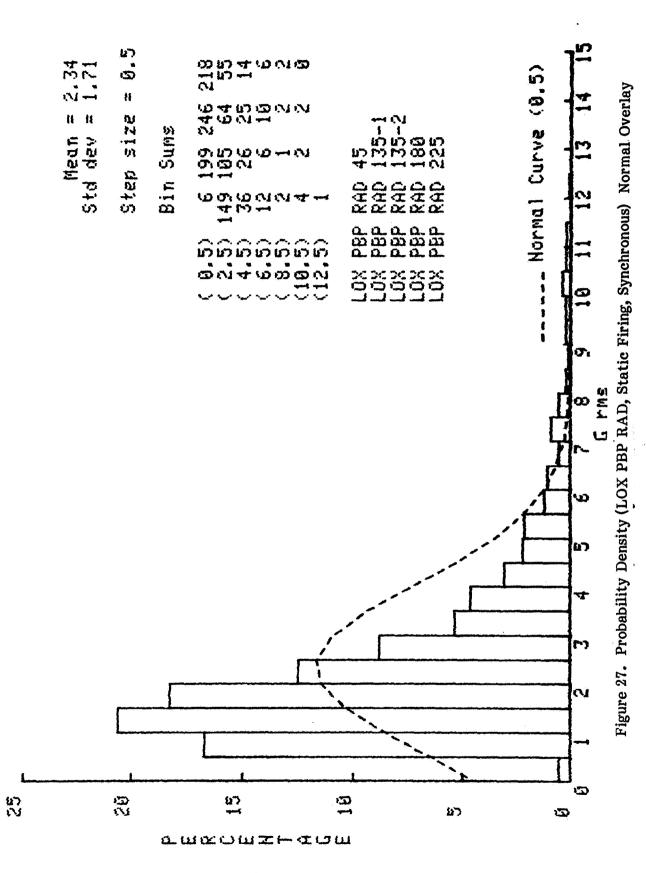


Figure 26. Cumulative Probability Distribution (LOX PBP RAD, Static Firing, Synchronous) Gamma Overlay



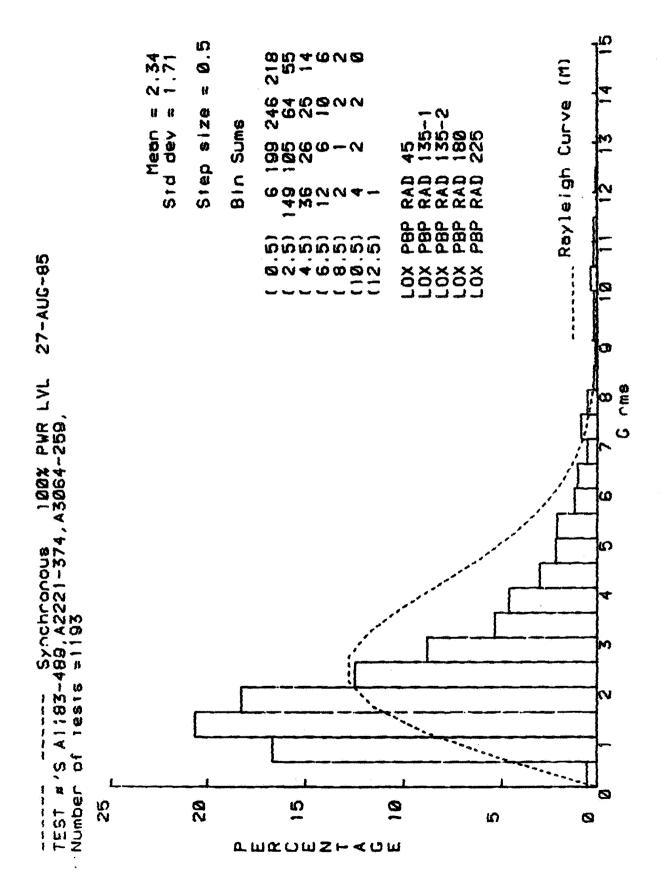


Figure 28. Probability Density (LOX PBP RAD, Static Firing, Synchronous) Rayleigh (M) Overlay

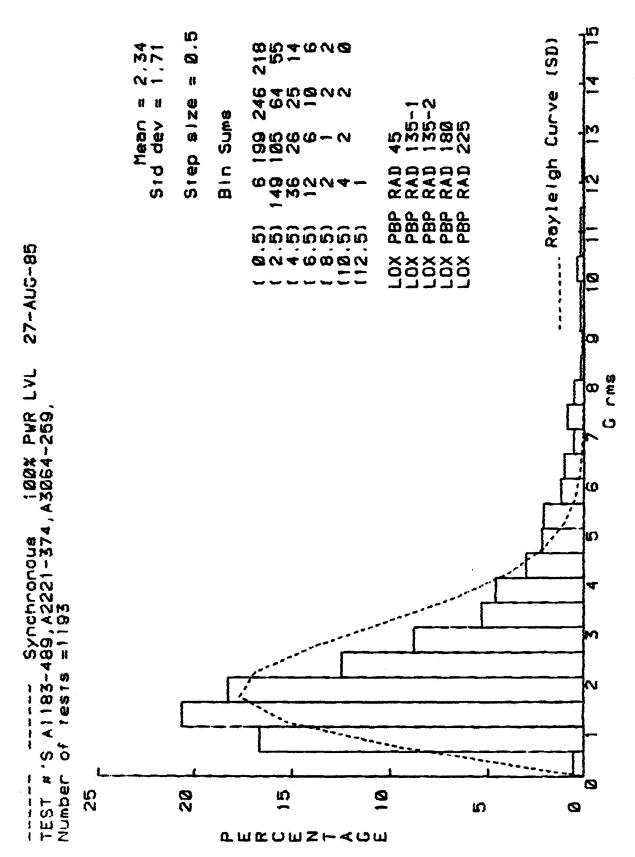


Figure 29. Probability Density (LOX PBP RAD, Static Firing, Synchronous) Rayleigh (SD) Overlay

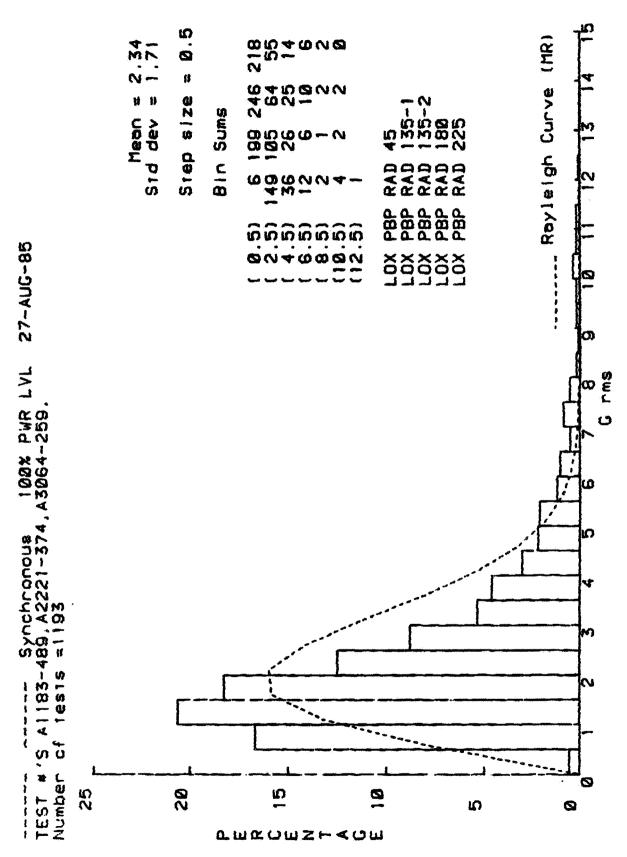


Figure 30. Probability Density (LOX PBP RAD, Static Firing, Synchronous) Rayleigh (MR) Overlay

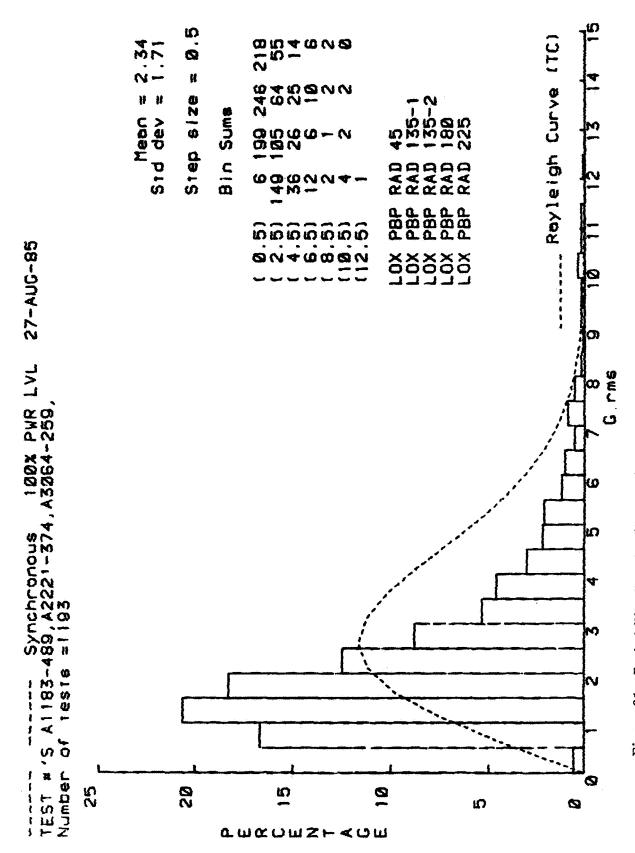


Figure 31. Probability Density (LOX PBP RAD, Static Firing, Synchronous) Rayleigh (TC) Overlay

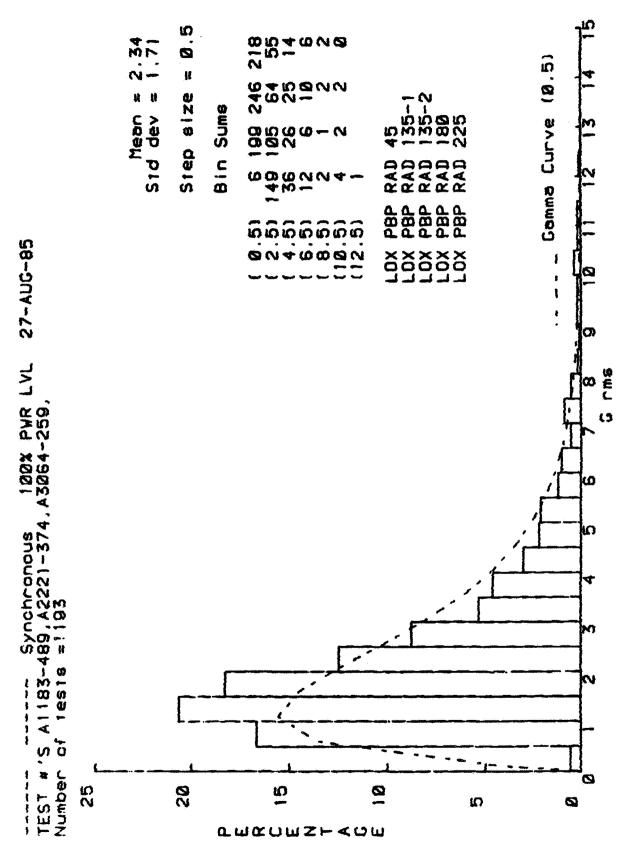


Figure 32. Probability Distribution (LOX PBP RAD, Static Firing, Synchronous) Gamma Overlay

2.7 Sort Routine for Probability Density Function

A variation of the following quick sort routine is used in the MSFC Diagnostic Data Base Program to calculate the density functions. The procedure follows Reference 4. This method requires only one data pass and therefore is basically the fastest most simple routine available.

Consider the N data values for the composite, synchronous etc. for each measurement. The probability density function can be estimated by

$$\hat{f}(x) = \frac{N_x}{NW}$$

where W is a narrow interval centered at x and N_x is the number of data values which fall within the range $x \pm W/2$. A general procedure to estimate $\hat{f}(x)$ can be obtained digitally by dividing the full range of x into an appropriate number of equal width class intervals. Tabulate the number of data values in each class interval, and divide by the product of the class interval width W and the sample size N. The estimate $\hat{f}(x)$ is not unique since it is dependent upon the number of class intervals and their width selected for the analysis. Equal class intervals of 0.5 Grms were used in the MSFC Diagnostic Data Bank Program. The number of class intervals is equal to twice the maximum value of the plot with the data plotted at x rather than $x \pm W/2$. This is not in strict accordance with the above definition, but for data interpretation the plots show the percentage of data values less than or equal to x, where x is the Grms value.

A general procedure for evaluation is as follows. Let K define the number of class intervals selected to cover the entire range of the data values from a_o to b_m . Then the width of each interval is given by

$$W = \frac{b_m - a_o}{K}$$

and the end point of the ith interval is

$$n_i = a_o + i W \qquad i = 0, 1, 2, ... K$$

where $n_o = a_o$ and $n_k = b_m$. The bin numbers will now be defined as a sequence of K+2 numbers $[N_i]$, i = 0, 1, 2, ..., K+1, by the conditions

= $[number of x such that x \le n_0]$

= $[number of x such that <math>n_o < x \le n_1]$

= $[number of x such that n_{i-1} < x \le n_i]$ N;

= [number of x such that $n_{k-1} < x \le n_k$] = [number of x such that $x > n_k$] N_k

 N_{k+1}

This procedure will sort out the N data values of x so that the bin number sequence [N_i] satisfies

$$N = \sum_{i=0}^{K+1} N_i$$

A quick one pass method of sorting on a digital computer is to evaluate each value x_n ; n=1, 2, ..., N in turn as follows.

if $x_n \le a_o$, add the integer one to N_o .

b. If
$$a_o < x_n \le b_m$$
, compute $I = \frac{x_n - a_o}{W}$

then select i as the largest integer less than or equal to I, and add the integer one to N_i.

If $x_n > b_m$, add the integer one to N_{k+1} . C.

The four output forms are histogram, percentage of data in each class interval, probability density estimate and probability distribution estimate.

The histogram is simply N_i without changes

$$H_i = N_i$$
 Histogram

where H_i is the number of data values in each class interval.

The second output is the sample percentage of data in each class interval defined for i = 0, 1, 2, ... K+1 by

$$\hat{F}_i \% = \frac{N_i}{N} \times 100$$
 Percentage of Data

The third output is the probability density estimate defined at the midpoints of the K class intervals in $[a_0, b_m]$ by

$$\hat{f}_i$$
 = $\frac{\hat{F}_i}{W}$ = $\frac{N_i}{N}$ $\frac{K}{b_m - a_o}$ i=1, 2, 3 ... K Probability Density

and the probability distribution estimate defined at the class interval end points where i = 0, 1, 2, ..., K+1.

$$\hat{F}(i) = \sum_{j=0}^{i} \hat{F}_{j} = W \sum_{j=0}^{i} \hat{p}_{j}$$

2.8 Ratio of Synchronous to Composite

The analysis of the ratio of synchronous to composite vibration levels measured in flight is documented for future reference. This data will be utilized in studies to relate flight to static firing data, the effect of vibration level amplitude on the ratio of synchronous to composite, evaluation of the FASCOS system and justification of vibration redlines.

The ratio of synchronous to composite vibration levels of Figures 33, 34, 35, and 36 for 100% and 104% power levels were calculated using the data stored in the MSFC Diagnostic Data Base. Both the composite (50-1000 Hz) and synchronous vibration levels in the data base are derived from a sliding 11 point average (0.4 second PSDs) which is equal to 4.4 seconds of data during each power level. The highest* or maximum value of this average is then stored in the data base** to represent the characteristic Grms vibration level at that power level. Since the Diagnostic Data Base Program does not record or track the time of occurrence during the flight the ratio may or may not represent the same time period of the flight. However, past history has shown the composite and synchronous track in a reasonable manner during most static firing tests and flights. This pseudo ratio shown in the figures should therefore be fairly representative of a ratio calculated from data recorded at the same time period. Additional investigations are planned to evaluate the skewed distribution on the high pressure fuel turbopump and the appearance of a bi-modal type of distribution on the high pressure oxidizer turbopump. One possibility is the ratio of synchronous to composite is a function of the vibration level. the investigation will include a comparison with the measured static ground test data.

^{*}The vibration level stored in the Diagnostic Data Base and reported at data review meeting could be called the "highness" vibration level. Highness as defined in the Webster Dictionary "the highest of the nobility" with noble defined as "having excellent qualities; superior." The MSFC Technical Monitor for this report has suggested contiguous average maximum vibration level as a descriptive term, while the Wyle Technical Reviewer has suggested noble vibration level. Only historical usage will finally define the terminology.

^{**}The computer also skips random clipped signals and the output data is analyzed to purge the data base of invalid and extreme noisy data.

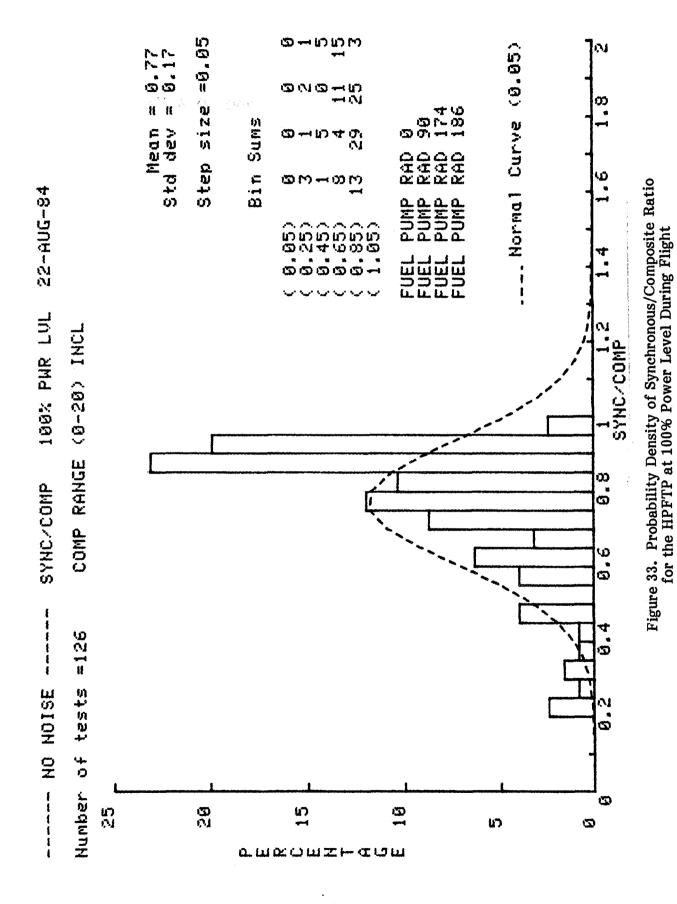
ORIGINAL PAGE IS OF POOR QUALITY

ANALYS1S USED IN THIS ESTS

TEST #/S STS01,STS02,STS03,STS04,STS05,STS06,STS07,STS08,STS11,STS13,STS

• ENTER.

LIST STANDARD TABLE
PLOT PROBABILITY DISTRIBUTION
PLOT PROBABILITY DENSITY
SELECT A NEW SET OF TESTS
SELECT NEW DATA TYPE AND PWRLUL
RETURN TO MAIN 200400



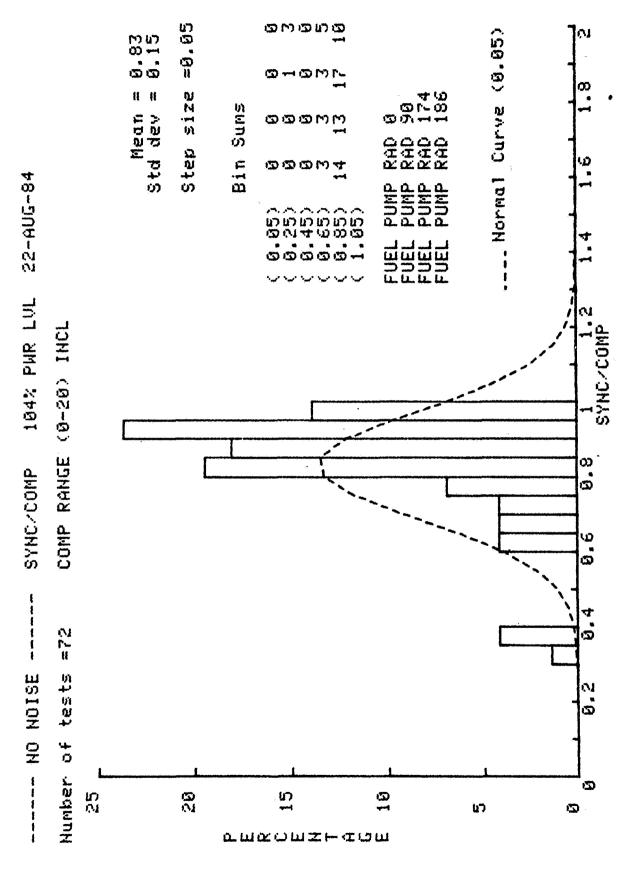
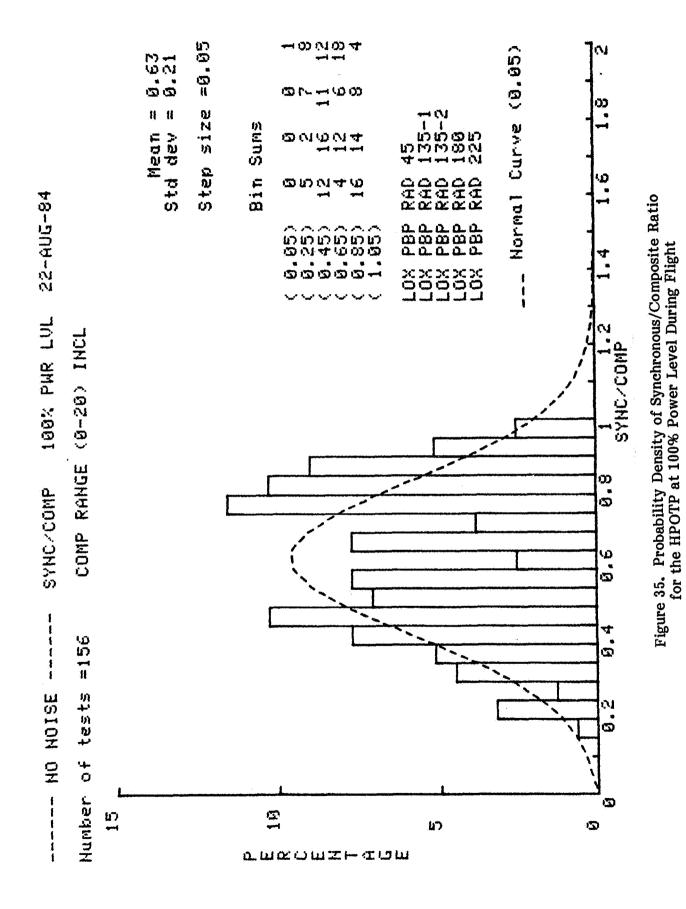


Figure 34. Probability Density of Synchronous/Composite Ratio for the HPFTP at 104% Power Level During Flight



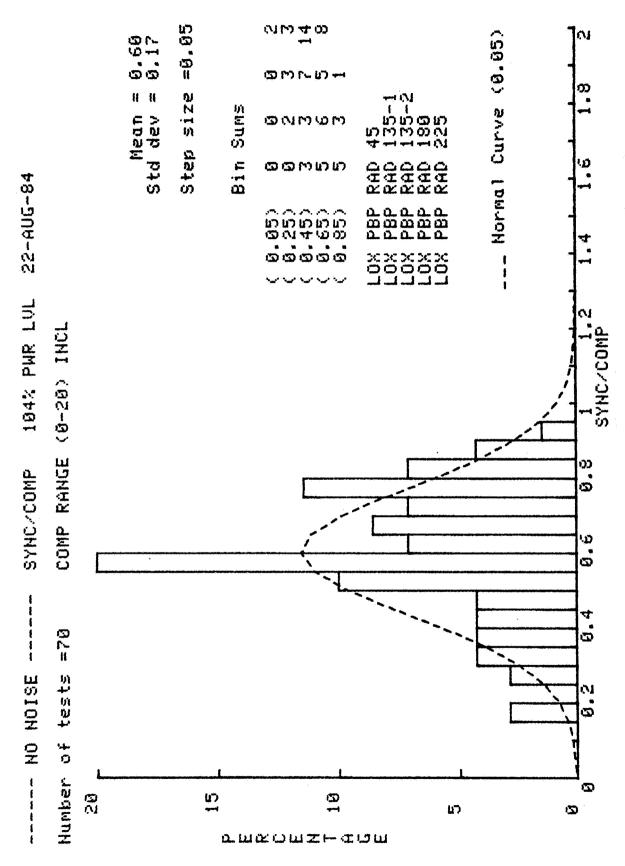


Figure 36. Probability Density of Synchronous/Composite Ratio for the HPOTP at 104% Power Level During Flight

2.9 Turbopump Rotational Speed History

The rotational speed of the high pressure oxidizer turbopump (HPOTP) and high pressure fuel turbopump (HPFTP) are shown in Figures 37 and 38. The speed is calculated from the synchronous frequency of the measured vibration data and represents the maximum speed of the pump during the flight at 100% and 104% power levels. The notation on the plot lists the flight number STS xx, engine position Ex and turbopump serial number.

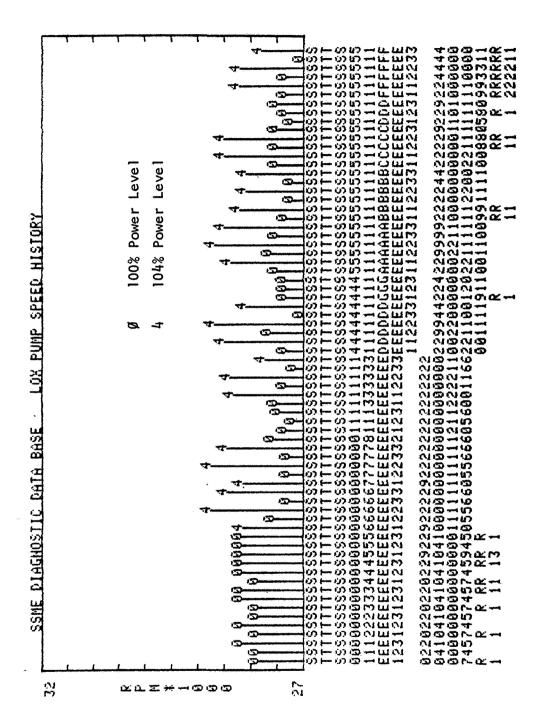


Figure 37. HPOTP Maximum Rotational Speed During Flight

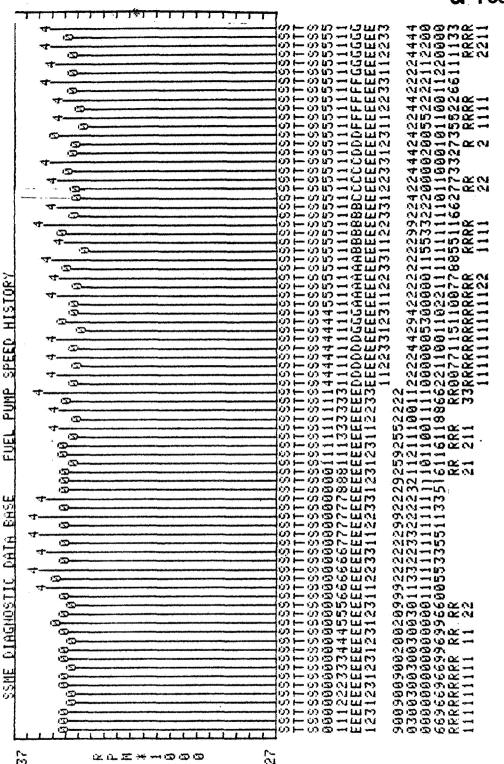


Figure 38. HPFTP Maximum Rotational Speed During Flight

3.0 REFERENCES

- 1. Lewallen, P., "SSME Vibration Data Base," (In publication MSFC/NASA TN), 1985.
- 2. Papoulis, A., "Probability Random Variables and Stochastic Processes," McGraw-Hill Book Company, NY, 1965, p. 148.
- 3. Hines, W. W. and D. C. Montgomery, "Probability and Statistics," Ronald Press Co., NY, 1972, p. 157.
- 4. Bendet, J. S. and A. G. Pierson, "Random Data: Analysis and Measurement Procedures," Wiley-Interscience, NY, 1971, p. 309.

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4.0 RESULTS

A summary of the mean vibration levels, the standard deviation, and maximum level measured on the SSME high pressure oxidizer and fuel turbopump during flight is shown in Figures 39 through 50.* The results are for the SSME operating at 104%, 100% and 65% power levels. Statistics are for each measurement location and the average of all locations which represents a spatial average around the turbopump. Both the composite (50-1000 Hz) and synchronous vibration levels were considered in this investigation.

Cumulative probability distribution plots are shown in Figures 51 through 62 with the classical Gamma distribution plotted as an overlay dashed line. These plots as discussed in Section 2.6 can provide a quick-look assessment of flight results as compared to this historical distribution of the previous flight data. The probability density for each power level for the oxidizer and fuel turbopumps is shown in Figures 63 through 74. These plots provide a quick assessment of the historical flight data scatter or dispersion from the mid-point or mean value whichever may be of interest. The tabulated data on each plot is the number of data points in each 0.5 Grms interval. Also the number of tests is equal to the number of test samples rather than the number of flights.

For future reference, flight numbers keyed into the computer are listed for the flights used in this analysis. The data sheets for each measurement are also included for reference.

* The data of STS Launch 27 (51-I) and 28 (51-J) are included in Appendix A. Both flights were nominal and will not have a significant effect on the statistical data of Figures 39 through 74.



USED IN THIS ANALYSIS: TESTS

TEST #'S STSØ1, STSØ2, STSØ3, STSØ4, STSØ6, STSØ7, STSØ8, STS11, STS13, STS 410, STS41G, STS51A, STS51C, STS51D, STS51F, STS51G,

> LIST STANDARD TABLE
> PLOT PROBABILITY DISTRIBUTION
> PLOT PROBABILITY DENSITY
> SELECT A NEW SET OF TESTS
> SELECT HEW DATA TYPE AND PWRLUL
> RETURN TO MAIN **200400** ENTER.,

FLIGHT SUMMARY SHEETS

HPOTP AND HPFTP

104%, 100% AND 65% POWER LEVEL

				Compos		@104X	Power					
	FUEL PUMP R	PUMP	RAD @	FUEL		PUMP	RAD 9	PUMP RAD 90	FUEL	PUMP	RAD 1	74
. 9	1	K		Σ	1	1C		x	X OC	K		Ž X
- 000 -	R	.		.	2			د	R	د		၁
Stand	Tests	SWL S	Sig	BEL	Tests	350	Sig		Tests	300	Sig	SEL
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				Composite		@104X	Power	@104% Power Level	!		!	
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				Nox		1		χøΣ		1		
Tes T	*	ات		O	R	ĸ		ပ	æ	C		ပ
Stand	Tests	Ļ	SIG	rm8	Tests	SEL	Sig	250	Tests	SEL	Sig	SEL
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INT D LOWEL TRACE	3.04 1.14 72
Composite	ion i
Spatial Average	Grms Standard Deviation # Data Points

Figure 39. Summary of Composite Vibration Levels on the High Pressure Fuel Turbopump at 104% Power Level During Flight

74	ž O U	0 ! E ! L !	3.8	മ		Σί	0.0
RAD 1		SIG	8.0	23-AUG-85	TURB AXIAL	Sig	0.00.00
JUMP	iC)	S I	18 2.6	23-	rurb	ち で 8	0.0
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wer Lev	X D D	の ! を ! し !	, s	Y OF SSME VIBRATION	wer Ley D	ک ان ک ان ک	0.0
4% PO		2 i	3 1.3 1.0 2.3	E VIBI	AX PO	Sig	0.0 0.0 0.0
@ 1 Ø ⊃UMP	Ю	0 1 E 1	W.	SSM	@1Ø TURB	ιΩ É	9.0
Synchronous @104% Power Level FUEL PUMP RAD 90 FUEL PUMP RAD 174	32 .	Tests	м	STICAL SUMMARY OF SSME VIBRATION DATA	Synchronous @104% Power Level AD 186 FUEL TURB RAD 90 FUEL	r Tests	0
		0 E	1.0 4.7	STICAL SUMMAR	Synch 186	Σ S S S S S S S S S S S S S S S S S S S	1.0 5.0
RAD		Sign	6		RAD 1	Sig	1.0
PUMP	K)	SI	2.7	STATI	JUMP PUMP	10 E	1 0
FUEL PUMP RAD 0	*	0 1	24		FUEL PUMP R	Tests ests	27
	T O O	Stand	STS			Stand	518

104% Power Level	= 2.53	= 0.99	= 72
Synchronous		Standard Deviation	# Data Points
Spatial Average	Grms	Stanc	# Da

Figure 40. Summary of Synchronous Vibration Levels on the High Pressure Fuel Turbopump at 104% Power Level During Flight

104% Power Level	= 2.76 = 0.75 = 70
Composite	Grms Standard Deviation # Data Points
Spatial Average	Grms Stande

Figure 41. Summary of Composite Vibration Levels on the High Pressure Oxidizer Turbopump at 104% Power Level During Flight

104% Power Level	= 1.69	= 0.76	= 71
Synchronous		Standard Deviation	# Data Points
Spatial Average	Grms	Stand	# Da

Figure 42. Summary of Synchronous Vibration Levels on the High Pressure Oxidizer Turbopump at 104% Power Level During Flight

4	X U E L	7.2			X 3 E	0.0
FUEL PUMP RAD 174	Sign		23-AUG-85		Sig	8
JUMP	IO E	1 0	23-	rure	10 E	0.0
	Tests	23	DATA	FUEL TURB AXIAL	# 8 1	8
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Powe RAD G	Sig	13 3.6 1.2	E VIBR	Powe RAD G	Sig	8
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Compas: 1e (Tes 18	<u> </u>	SUMMARY OF		# 0 : 1 : 2 : 2 : 2 : 3 : 3 : 3 : 3 : 3 : 3 : 3	0
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RAD 0	<u>ග</u>	- 6	ISTICA	RAD	Bis	.5 .5
PUMP	IC) E	2	STATIS	PUMP	10 E	2.7
FUEL PUMP RA	Tests	38		FUEL PUMP RA	T S T S	ሺ 4
	Stand	STS			Stand	STS

100% Power Level	= 2.66 = 1.36 = 126
Composite	Grms Standard Deviation # Data Points
Spatial Average	Grms Stande # Date

Figure 43. Summary of Composite Vibration Levels on the High Pressure Fuel Turbopump at 100% Power Level During Flight

Synchronous & 100x Power Level FUEL PUMP RAD 174 Max Max Max G	0.7 3.4	23-AUG-85	TURB AXIAL	Sig ras	0.0 0.0 0.0
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\ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \	4. TÜ	VIBRATION	Swer Li	S E I	9
RAD S	13 2.6 1.2 4.5	SSME VI	BOX POR	Sig	0.0 0.0
80 Z Z Z Z Z Z Z Z Z Z Z Z Z Z Z Z Z Z Z	2.6	OF SS	S @1	(C)	0
Chronous FUEL Tesis		STATISTICAL SUMMARY OF SSME VIBRATION	Synchronous @100% Power Level FUEL PUMP RAD 186 FUEL TURB RAD 90 FUEL	F 8 5 5 5 5 5 5 5 5 5 5 5 5 5 5 5 5 5 5	
	5.2	ICAL S	88 86	X S E I	6.4
FUEL PUMP RAD 0	6	ATISTI	RAD	Sig	*
4 10 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	2.0	STA	PUMP	SEL	54 2.2
	36		FUEL	100 m	10
STOOTS	STS			Srand	STS

100% Power Level	= 2.08	= 1.20	126
	•••		••
Synchronous	70	Standard Deviation	# Data Points
Spatial Average	Grms	Stand	# Da

Figure 44. Summary of Synchronous Vibration Levels on the High Pressure Fuel Turbopump at 100% Power Level During Flight

				Compo		BIDDX	Power	Power Level				
	LOX PBP RAD	BP RA	AD 455	rax		BAI BAI	135-	· ·	LOX PBP RAD 135-2	SP RA	135	2.
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1681	R	و		ی	ų	و		و	*	ဗ		ני
Stand	Tests	() E L	Sig	8EL	Tesis	SWL	S	SEL	Tesis	3	Sig	いだし
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515	50	2.7	•	7.0	50	2.8 1.2	1.2	ຄ ໝ່	38	3	7	B,
) ·	• •		•					1	!			
		STATI		AL SUM	STICAL SUMMARY OF SSME VIBRATION	SSME	VIBE	RATION		23-1	23-AUG-85	5
		! { !	1 1 1 1	1 1 1		1	<	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1				
				Composite		100%	Power	8100% Power Level	: :			
	LOX PBP RAD	BP RA	4D 18B			RAI	222		LOX TURB RAD	JRB R.	AD 45	
		ļ		XOT X		(ZOX X		1		XOL
Test	*	ئ		ပ	R	ب		ပ	82 .	ပ		ပ
Stand	Tests	38	Sig	380	Tests	SEL	Sig	LWS	Tesis	SEL.	Sig	SEJ
		; ; !	\$ 6 8	1 1 1		1 1	ŧ }	1 1	1 1 1	1	1	† ()
STS	2	3.4	89.	ອ.ຜ	8	0.0	8	0.0	8	0.0	0.0	0.0

Spatial Average Composite 100% Power Level

6	2.33	1.17	157
ı	1	H	II
2	Criiis	Standard Deviation	# Data Points

Figure 45. Summary of Composite Vibration Levels on the High Pressure Oxidizer Turbopump at 100% Power Level During Flight

35-2	700 C C C C C C C C C C C C C C C C C C	2 5.3	-82		0 E	6
AD 1	S	2.2 1.2	23-AUG-85	RAD	S	6
PBP RAD 135-2	10 E 1		23	TURB	IO E I	9
×	# 0 ! 0 !	39	N DATA	evel LOX TURB RAD 45	# S 1 S 1	•
6130% Power Level RAD 135-1 LO	X O E I	හ ග	BRATIO	@100% Power Level	X O E I	
30% P Ad 13	5	2.1 1.3	SSME VIB	80% P AD 22	Sig	(
20 GB C	(O	2.1	OF SS	BP R	(C) (E)	(
Synchronous LOX PBP	F 00 1	50	UMMARY	Synchronous LOX PBP	# 8 H	(
いとい	E CI SOEI	8	TICAL S		X O E I	•
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LOX PBP RAD	2	54		LOX PBP RAD	# # # # # # # # # # # # # # # # # # #	.,
	Stand	STS			Stand	

Spatial Average Synchronous 100% Power Level

Grms = 1.93
Standard Deviation = 1.21
Data Points = 157

Figure 46. Summary of Synchronous Vibration Levels on the High Pressure Oxidizer Turbopump at 100% Power Level During Flight

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7				82			
RAD	V	3 1	8.5	23~AUG-85	TURB AXIAL	Sig	8
PUMP	ان د		-	23-	TURB	10 E	6
FUEL PUMP RAD 174	# W		24	DATA	FUEL	# 0 1	0
	X 00 8			ATION	Level	X 00 E E L 1	9
@ 65% Power Leve	<u></u>	D (8.5	SSME VIBR	Power Leve RAD 90	Sig	6
B 653	ال ال ال		2 - 2	F SSF	e 65% Turb F	(C) (E)	8
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	χ φυ έ Σ) t	G 3	AL SUM	Composite AD 186 FUEL	X 0 1 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	W 0
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FUEL PUMP R	12. U	7 I	24		FUEL PUMP R	# B B B B B B B B B B	2
		5 1	STS			Stand	STS

100% Power Level	= 1.17	= 0.38	92 =
Composite		Standard Deviation	# Data Points
Spatial Average	Grms	Stands	# Date

Figure 47. Summary of Composite Vibration Levels on the High Pressure Fuel Turbopump at 65% Power Level During Flight

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wer Lev	X O E I	8	RATION	Wer Lev	KO E I	0.0
SA PO	S	2 .0.5 0.1 0.5	E VIB	SX Po RAD 9	Sig	0.0 0.0 0.0
e Pump	ا ا ا ا	6	F SSM	e 6 TURB	SEI	0
Synchronous @ 85% Power Level FUEL PUMP RAD 90 FUEL PUMP RAD 174	# 00 1	~	STATISTICAL SUMMARY OF SSME VIBRATION DATA	Synchronous 8 65% Power Level RAD 186 FUEL TURB RAD 90 FUEL	# 00 t	Ø
		•	AL SUP	Synch	X O E I	0.3
RAD 0	5	Ø M	ISTIC	RAD 1	Sign	8
		7.0	STATI		() E	8
FUEL PUMP	1 65 H	24		FUEL PUMP	Tes:	26
	Stand	STS			Stand	STS

Spatial Average Synchronous 65% Power Level

Grms = 0.71 Standard Deviation = 0.30 # Data Points = 76

Figure 48. Summary of Synchronous Vibration Levels on the High Pressure Fuel Turbopump at 65% Power Level During Flight

ve] LOX PBP RAD 135-	Tests rms Sig rms Tests rms Sig rms	24 0.9 0.1 1.1 24 0.9 0.1 1.1	Y OF SSME VIBRATION DATA 23-AUG-85	ve] LOX TURB RAD 45	Tests rms Sig rms Tests rms Sig rms	
Composite	X 00 1 00 E 1 E ()	4.	AL SUMMARY OF	Composite LOX	X & !	0
4D 45	<u>0</u> 1	8.2	TIC	4D 180	Sign	6
8P R/	10 E	. 6 . 6	STATIS	BP R	10 E	6
LOX PBP RAD	00 1 00 1 1 1	27		LOX PBP RAD	# Q !	•
	Stand	STS			Stond	() }

65% Power Level	= 0.92	= 0.18	= 75
Composite		Standard Deviation	# Data Points
Spatial Average	Grms	Stande	# Date

Figure 49. Summary of Composite Vibration Levels on the High Pressure Oxidizer Turbopump at 65% Power Level During Flight

LOX PB LOX PB LOX PB	chronous & 65% Pow Lox PBP RAD 135~	Tests The Sig The	3.9 24 0.4 0.2 0.8 25 0.3 0.2 0.8	STATISTICAL SUMMARY OF SSME VIBRATION DATA 23-AUG-85	chronous @ 65% Power Level LOX PBP RAD 225	C R C C C R C C C C C C C C C C C C C C	
LOX PB LOX PB LOX PB LOX PB	Bower L			/IBRATIO	Power L		
LOX PB LOX PB LOX PB LOX PB	: 8 65% BP RAD 1	10 E 1		F SSME V	G 65X	(U E)	5
LOX PB LOX PB LOX PB LOX PB	chronous Lox P	# 0 ;	24	JMMARY 0	shronous LOX P	Tes # 6	
LOX PB LOX PB LOX PB LOX PB	χ Σ Σ	E CI	0	SAL SI			2
LOX PB LOX PB LOX PB LOX PB		9	8	11ST10		Sig	G
# TO ! # TO !	BP R		4.	STAT	8P R/		6
STS Test	LOXP	# C C C C C C C C C C C C C C C C C C C	27		LOX P	Tests	6
		Stand	STS			Stand	STS

65% Power Level	= 0.38	= 0.22	92 =
Spatial Average Synchronous	Grms	Standard Deviation	# Data Points

Figure 50. Summary of Synchronous Vibration Levels on the High Pressure Oxidizer Turbopump at 65% Power Level During Flight

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FLIGHT CUMULATIVE PROBABILITY DISTRIBUTIONS

HPOTP AND HPFTP

104%, 100% AND 65% POWER LEVEL

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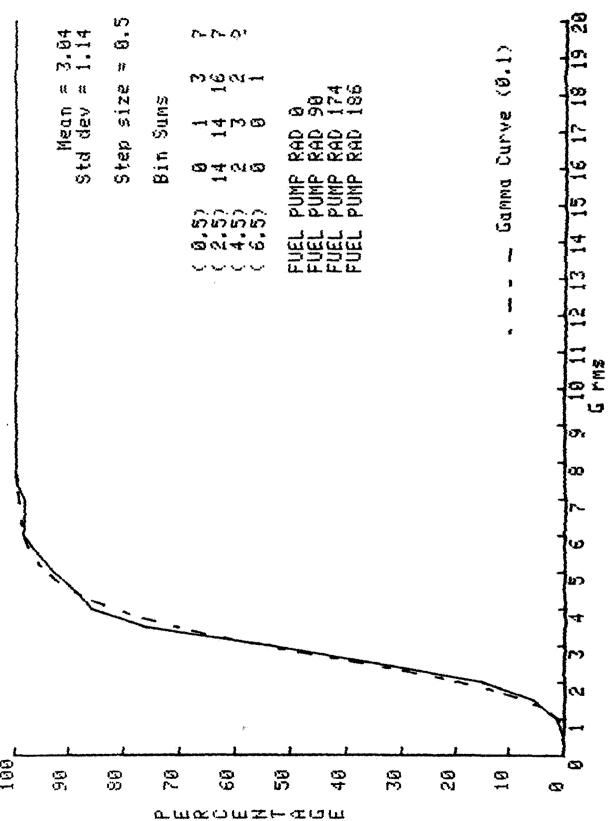


Figure 51. Cumulative Distribution of Composite Vibration Levels on the High Pressure Fuel Turbopump at 104% Power Level During Flight

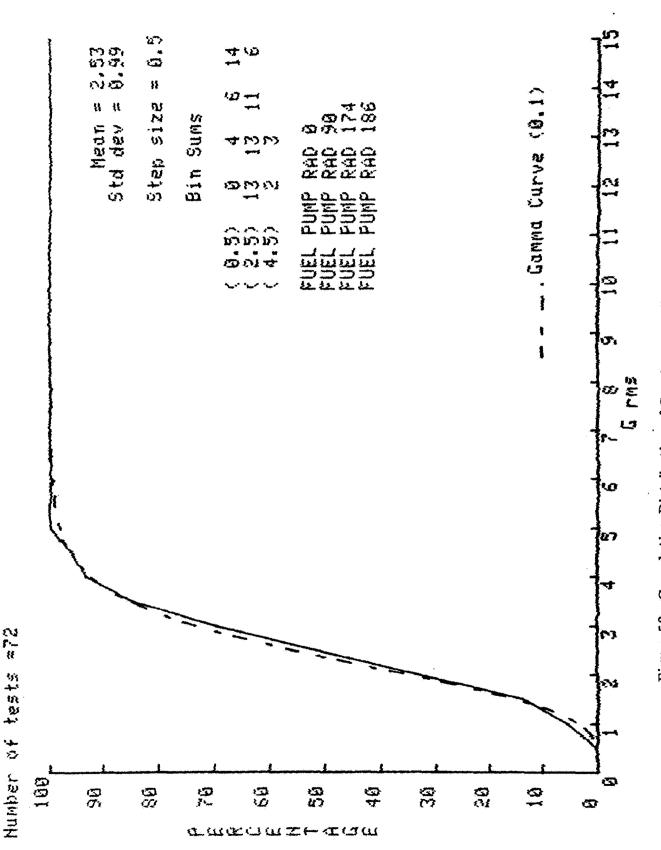


Figure 52. Cumulative Distribution of Synchronous Vibration Levels on the High Pressure Fuel Turbopump at 104% Power Level During Flight

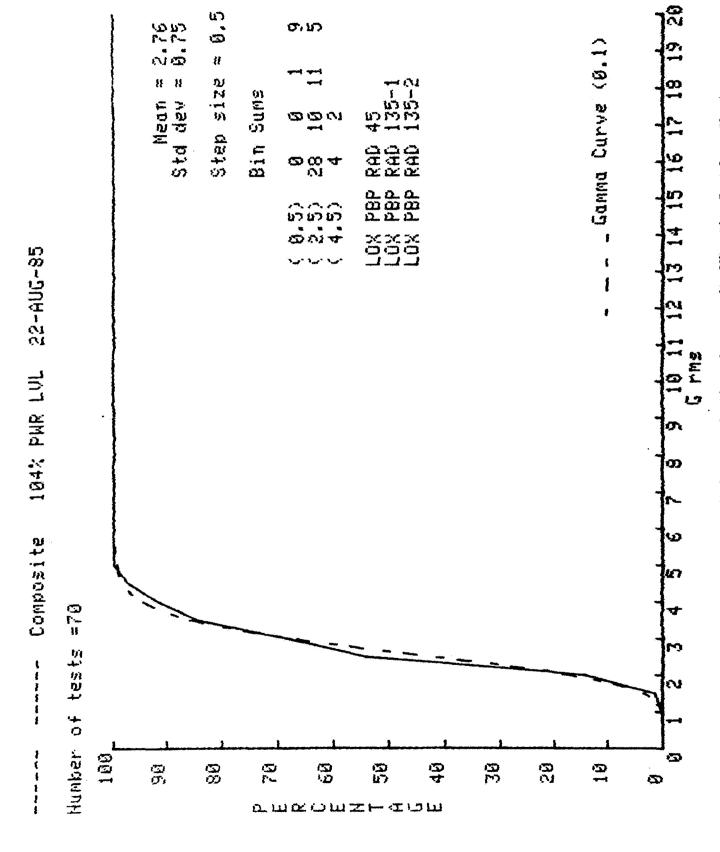


Figure 53. Cumulative Distribution of Composite Vibration Levels on the High Pressure Oxidizer Turbopump at 104% Power Level During Flight

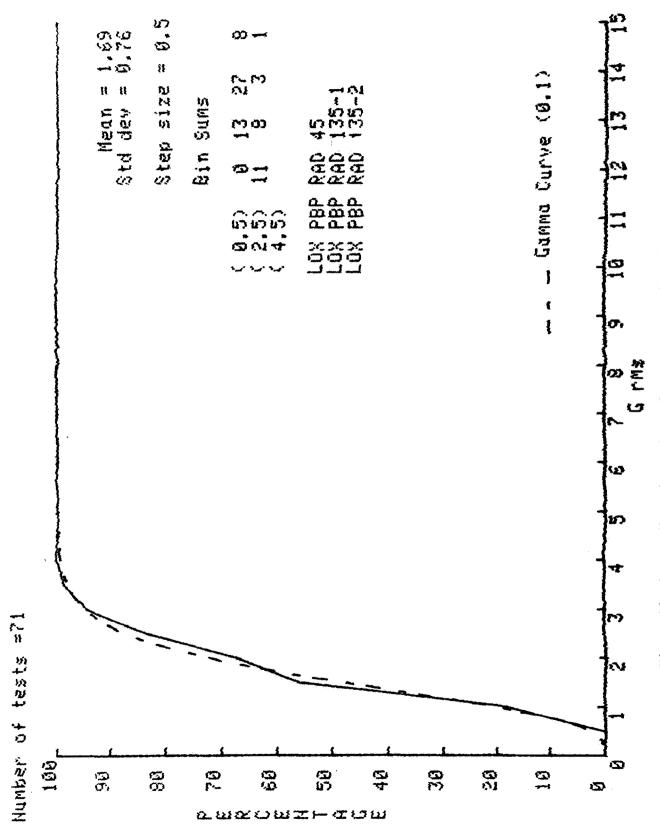


Figure 54. Cumulative Distribution of Synchronous Vibration Levels on the High Pressure Oxidizer Turbopump at 104% Power Level During Flight

Figure 55. Cumulative Distribution of Composite Vibration Levels on the High Pressure Fuel Turbopump at 100% Power Level During Flight

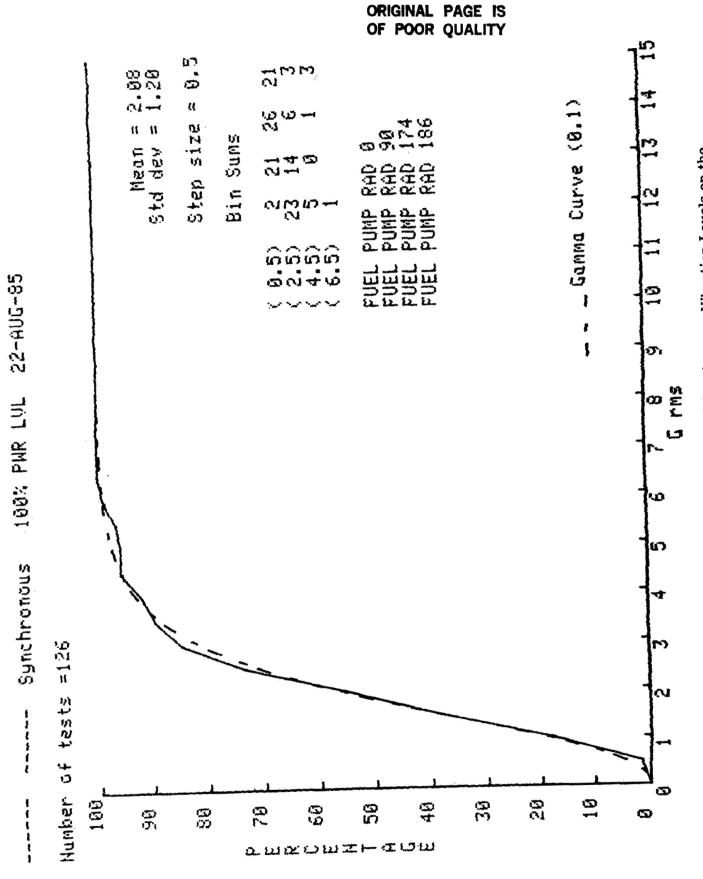


Figure 56. Cumulative Distribution of Synchronous Vibration Levels on the High Pressure Fuel Turbopump at 100% Power Level During Flight

Figure 57. Cumulative Distribution of Composite Vibration Levels on the High Pressure Oxidizer Turbopump at 100% Power Level During Flight

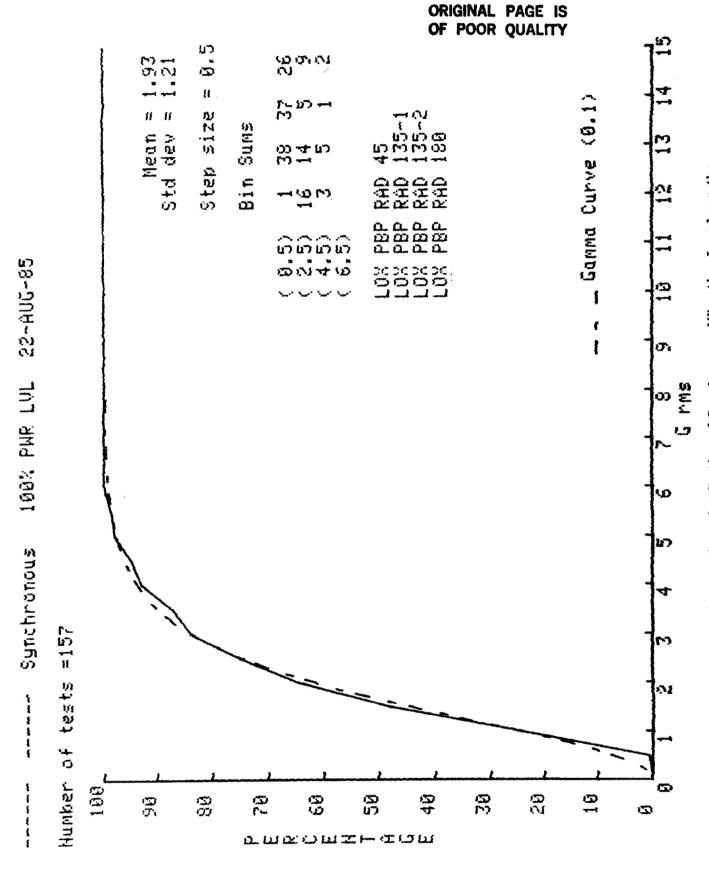


Figure 58. Cumulative Distribution of Synchronous Vibration Levels on the High Pressure Oxidizer Turbopump at 100% Power Level During Flight

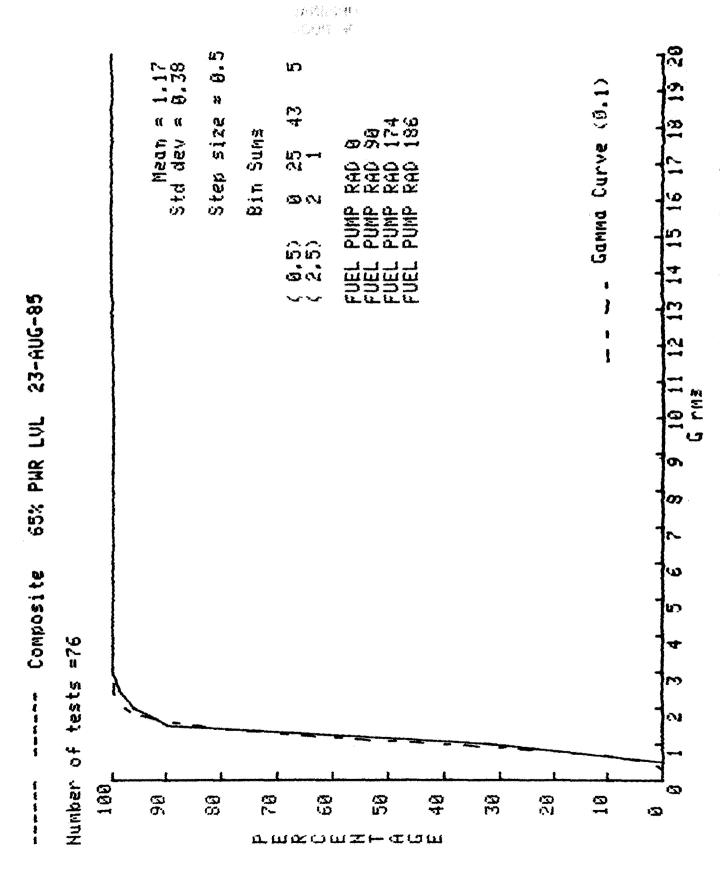


Figure 59. Cumulative Distribution of Composite Vibration Levels on the High Pressure Fuel Turbopump at 65% Power Level During Flight

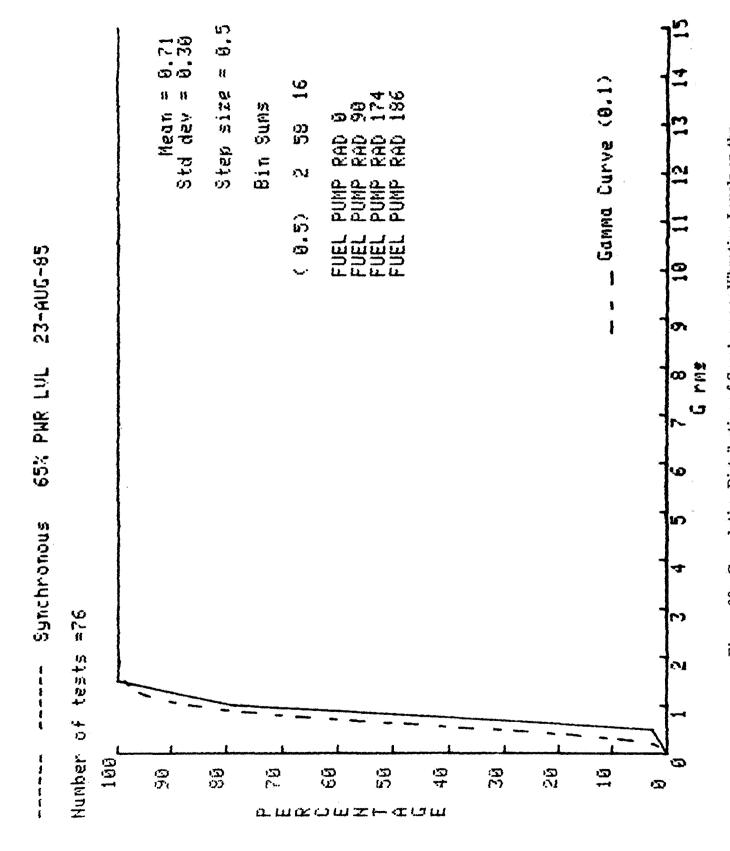


Figure 60. Cumulative Distribution of Synchronous Vibration Levels on the High Pressure Fuel Turbopump at 65% Power Level During Flight

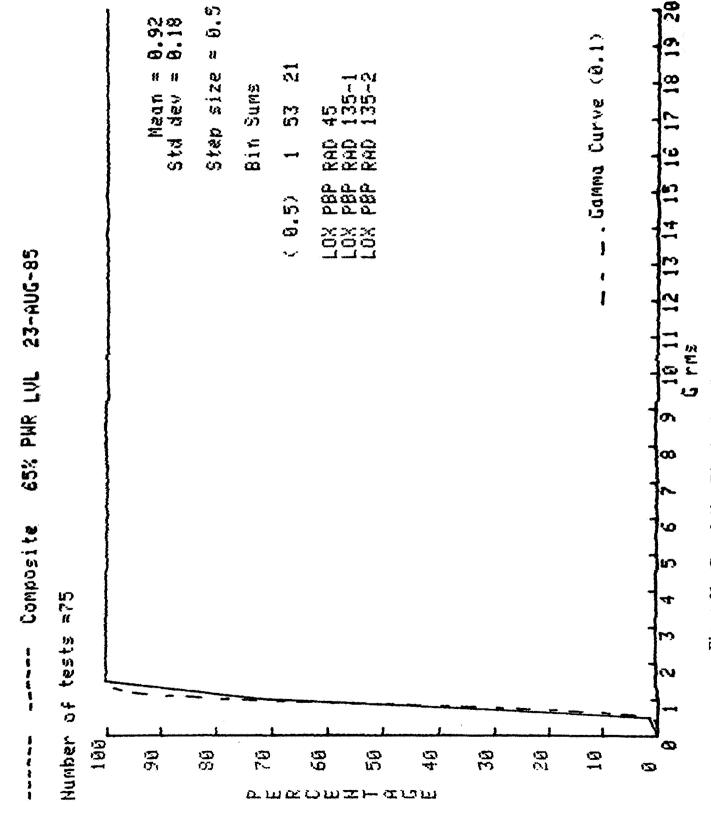


Figure 61. Cumulative Distribution of Composite Vibration Levels on the High Pressure Oxidizer Turbopump at 65% Power Level During Flight

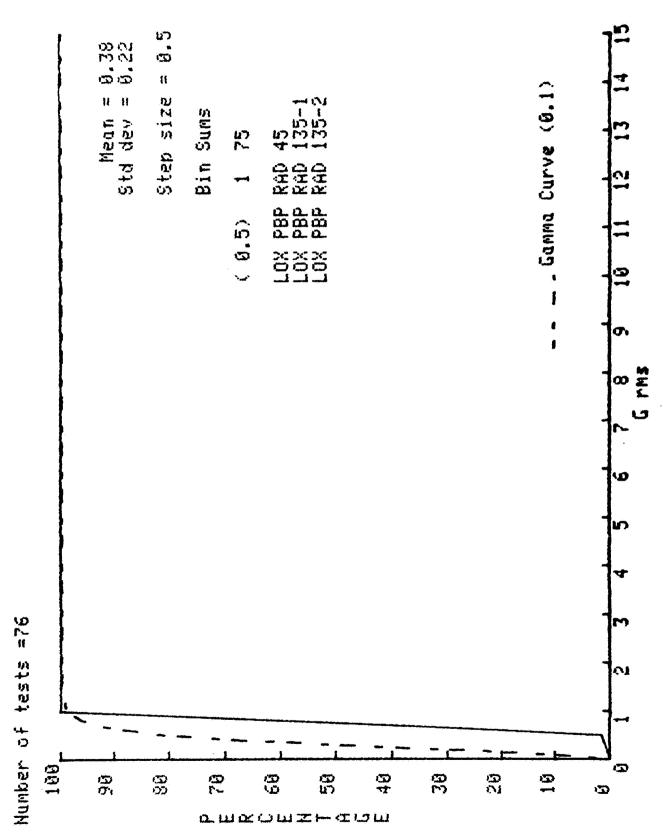


Figure 62. Cumulative Distribution of Synchronous Vibration Levels on the High Pressure Oxidizer Turbopump at 65% Power Level During Flight

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FLIGHT PROBABILITY DENSITY FUNCTION

HPOTP AND HPFTP

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Figure 63. Probability Density of Composite Vibration Levels on the High Pressure Fuel Turbopump at 104% Power Level During Flight

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Figure 64. Probability Density of Synchronous Vibration Levels on the High Pressure Fuel Turbopump at 104% Power Level During Flight

Figure 65. Probability Density of Composite Vibration Levels on the High Pressure Oxidizer Turbopump at 104% Power Level During Flight

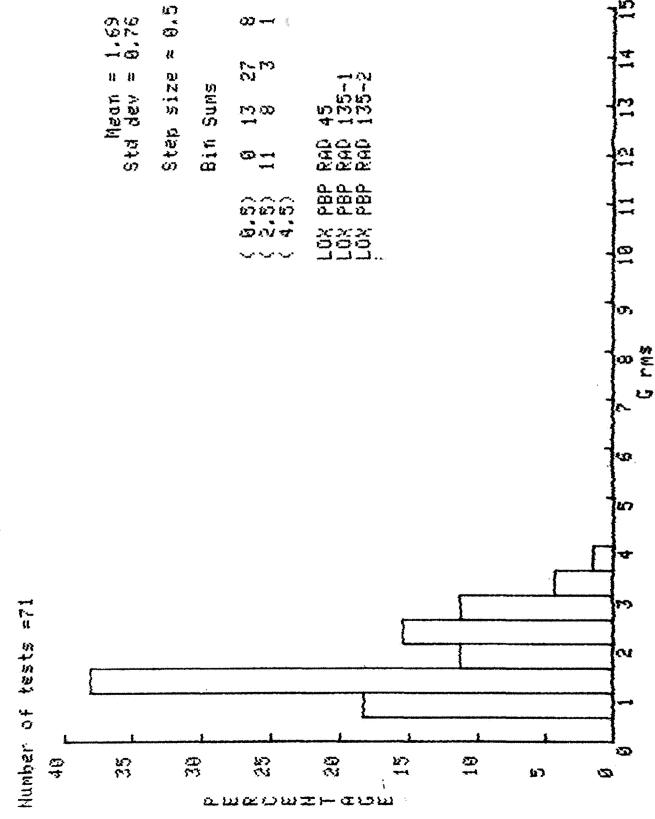


Figure 66. Probability Density of Synchronous Vibration Levels on the High Pressure Oxidizer Turbopump at 104% Power Level During Flight

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Figure 67. Probability Density of Composite Vibration Levels on the High Pressure Fuel Turbopump at 100% Power Level During Flight

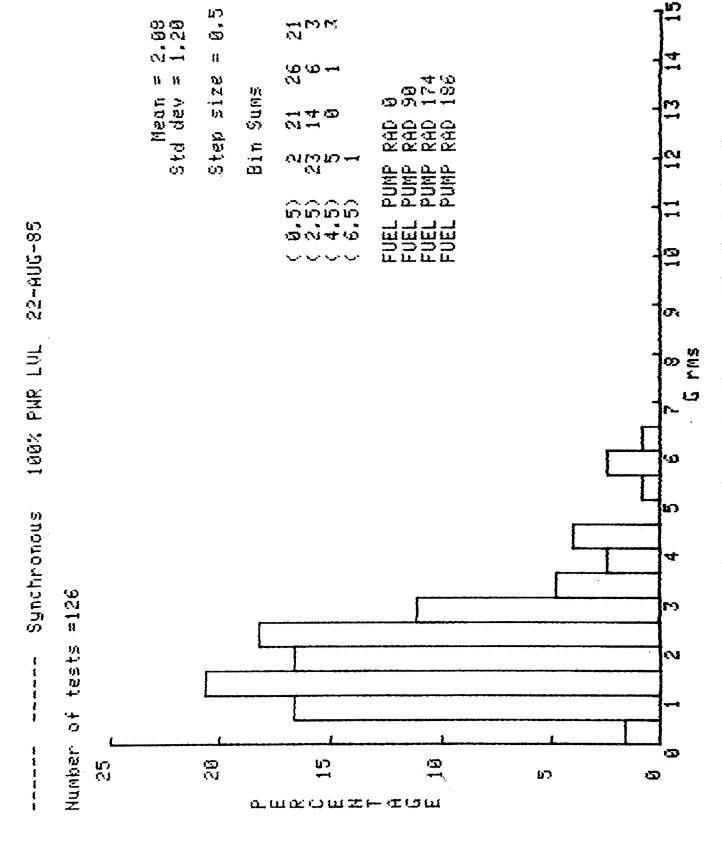
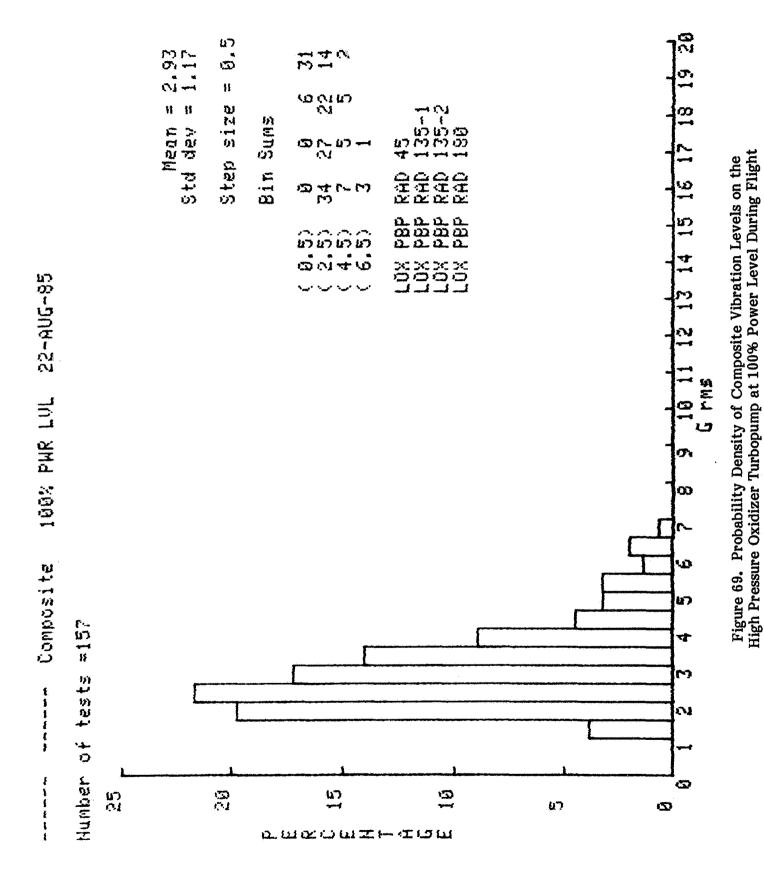
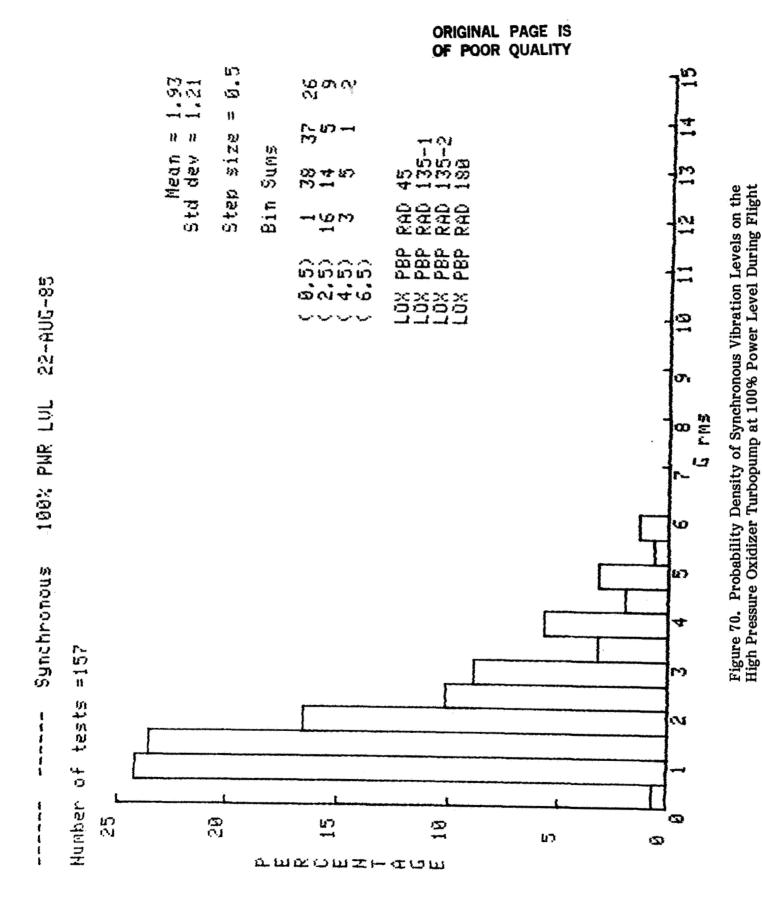


Figure 68. Probability Density of Synchronous Vibration Levels on the High Pressure Fuel Turbopump at 100% Power Level During Flight





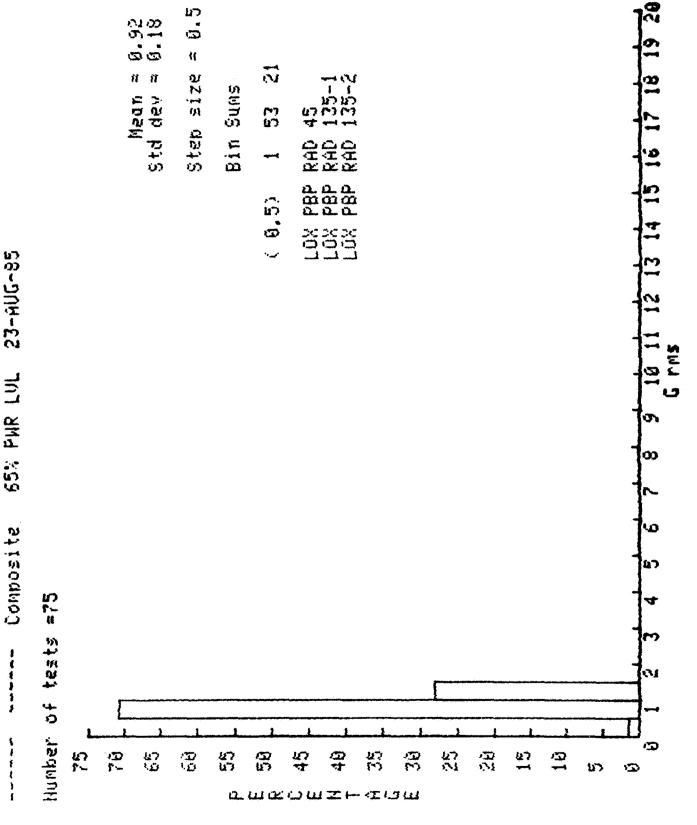


Figure 71. Probability Density of Composite Vibration Levels on the High Pressure Oxidizer Turbopump at 65% Power Level During Flight

Figure 72. Probability Density of Synchronous Vibration Levels on the High Pressure Oxidizer Turbopump at 65% Power Level During Flight

Figure 73. Probability Density of Composite Vibration Levels on the High Pressure Fuel Turbopump at 65% Power Level During Flight

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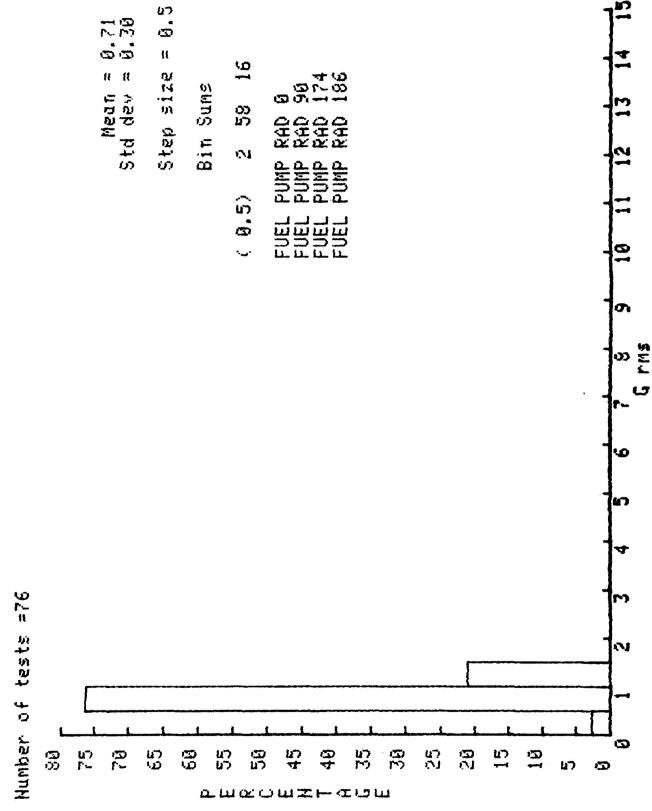


Figure 74. Probability Density of Synchronous Vibration Levels on the High Pressure Fuel Turbopump at 65% Power Level During Flight

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FLIGHT DATA SHEETS

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104% POWER LEVEL

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FLIGHT DATA SHEETS

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104% POWER LEVEL

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FLIGHT DATA SHEETS

HPFTP

100% POWER LEVEL

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FLIGHT DATA SHEETS

HPOTP

100% POWER LEVEL

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APPENDIX A

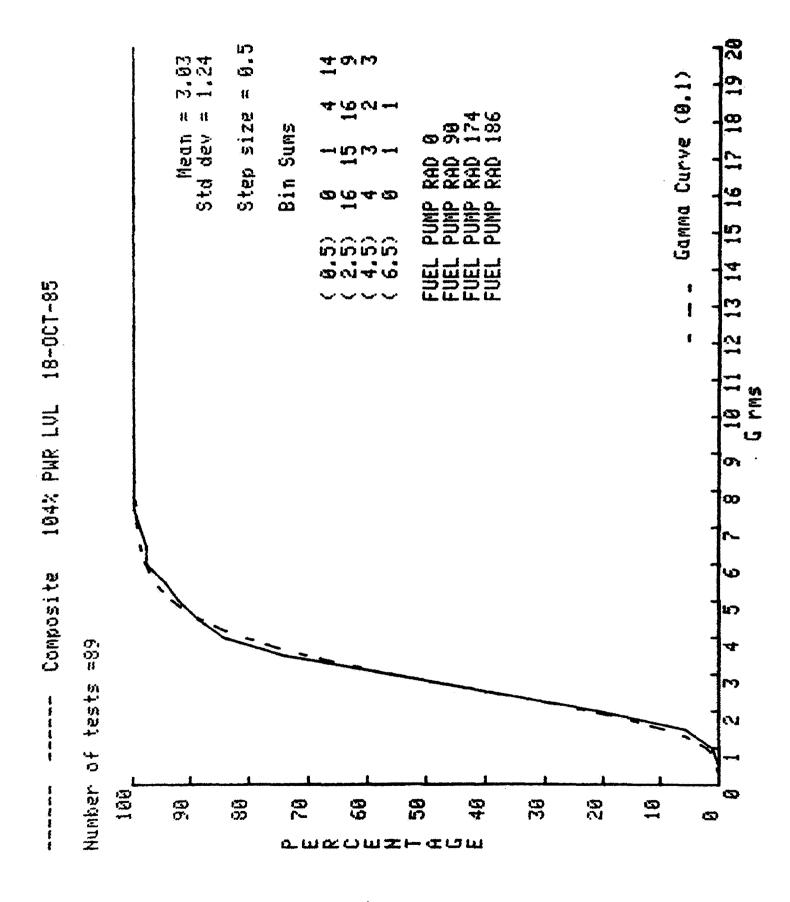
VIBRATION DATA FROM STS LAUNCH 27 (51-I) AND 28 (51-J)

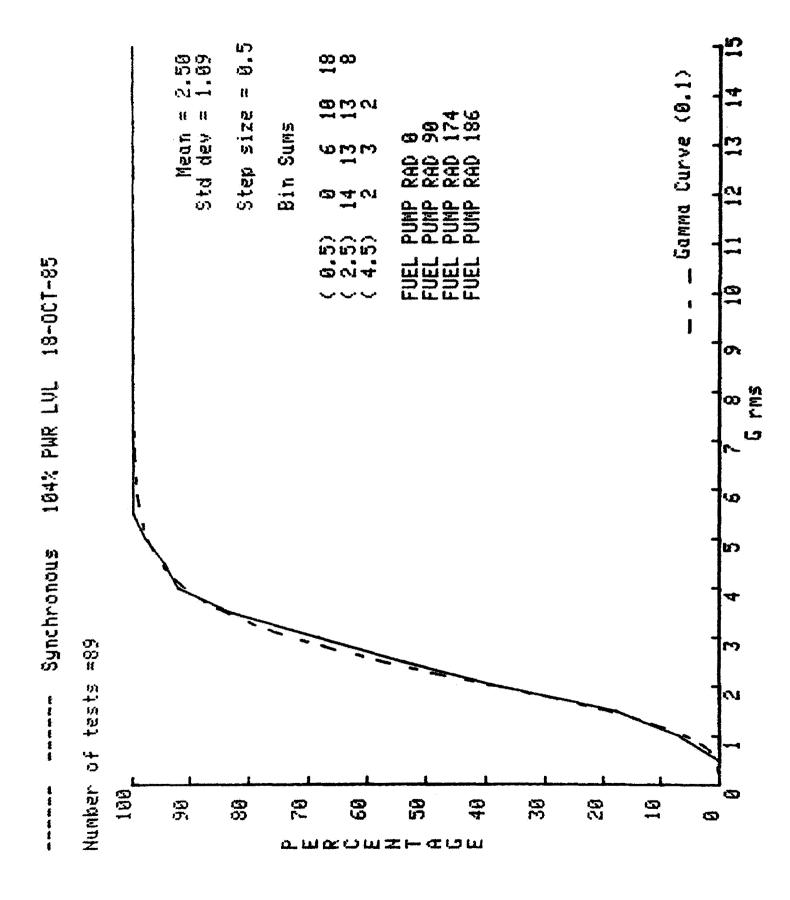
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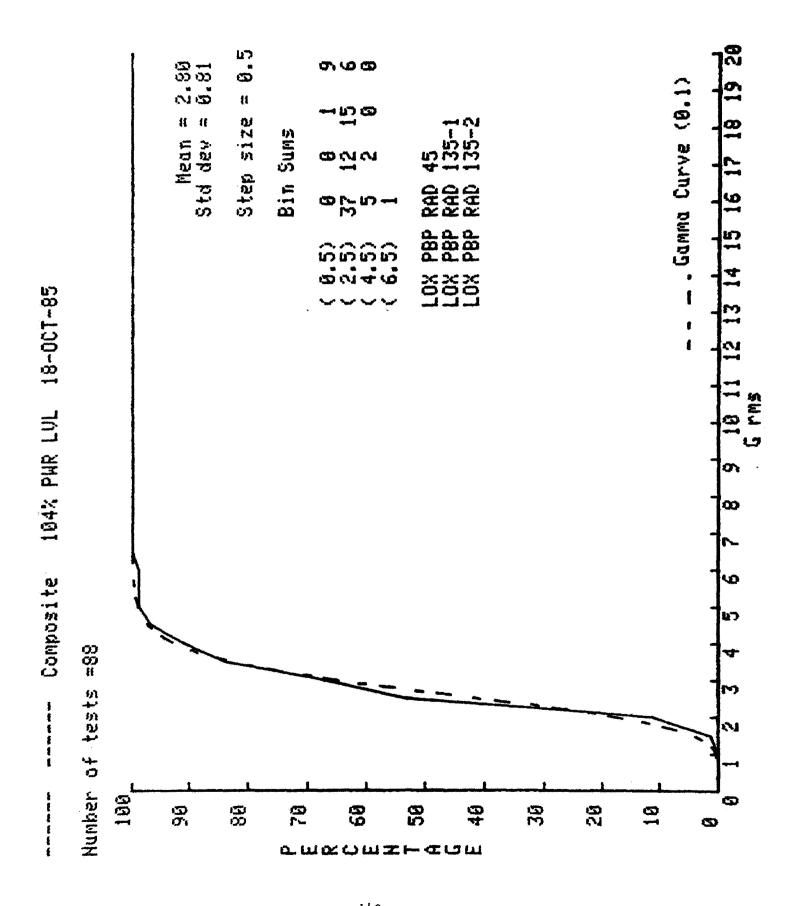
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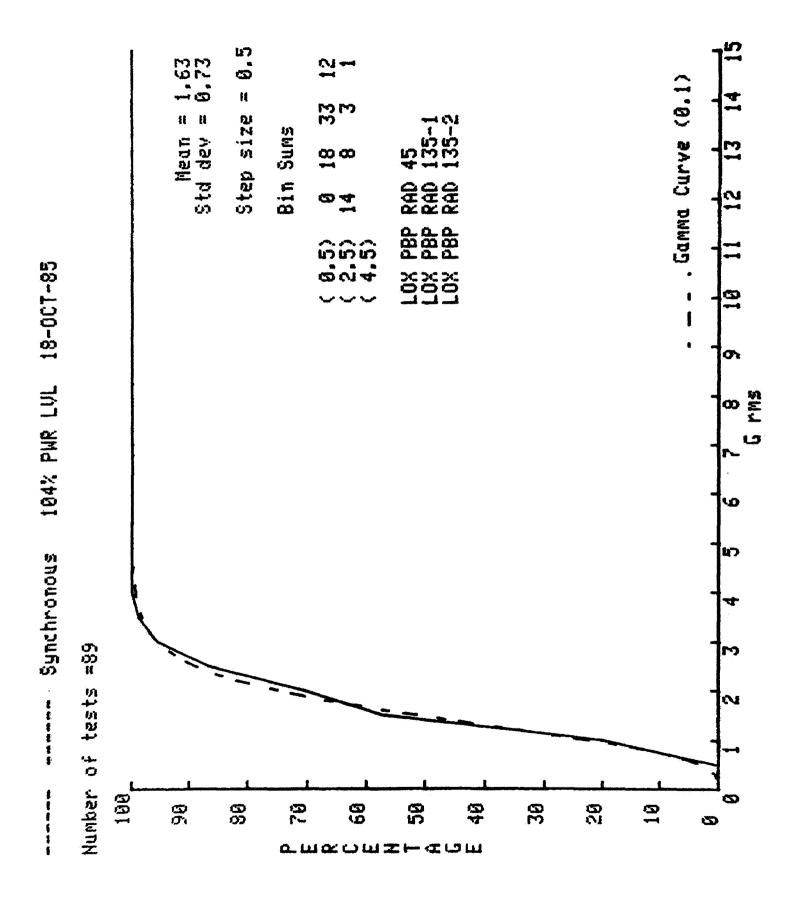
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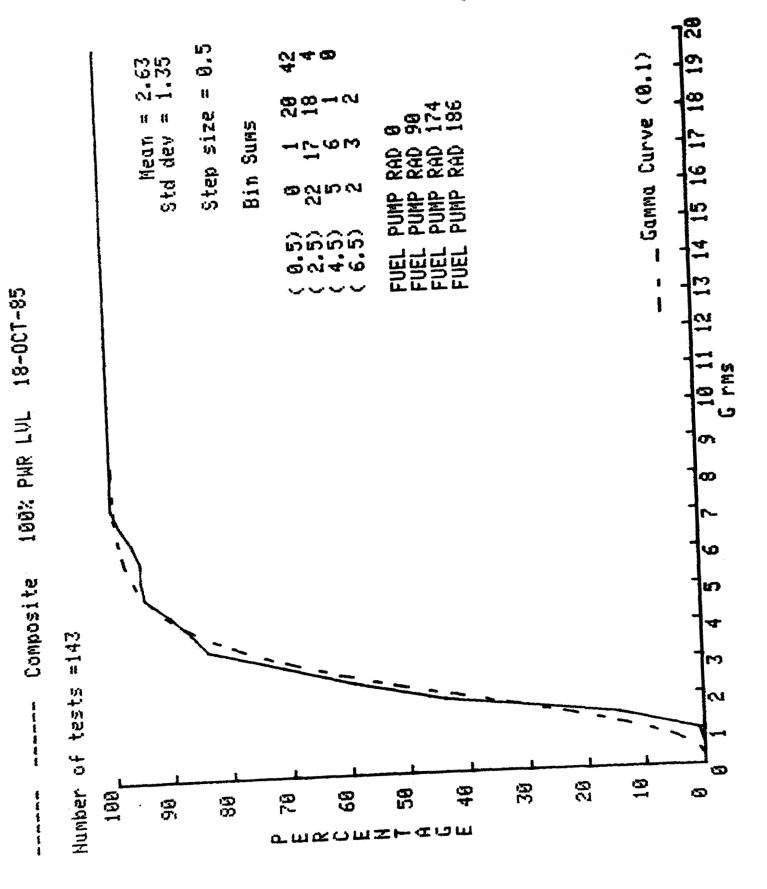


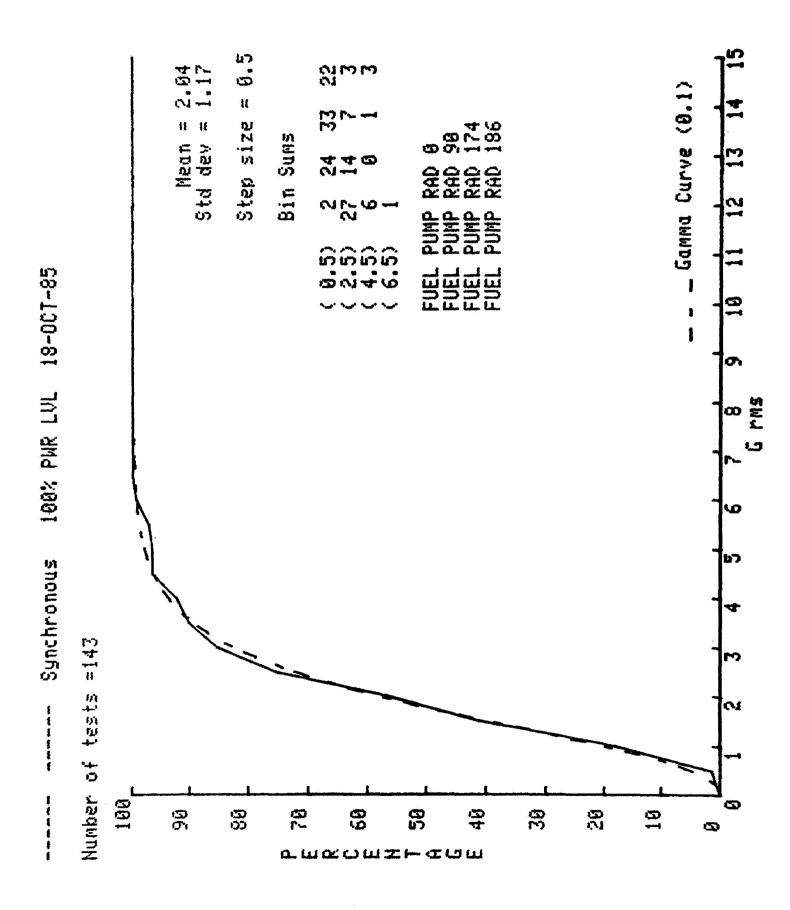


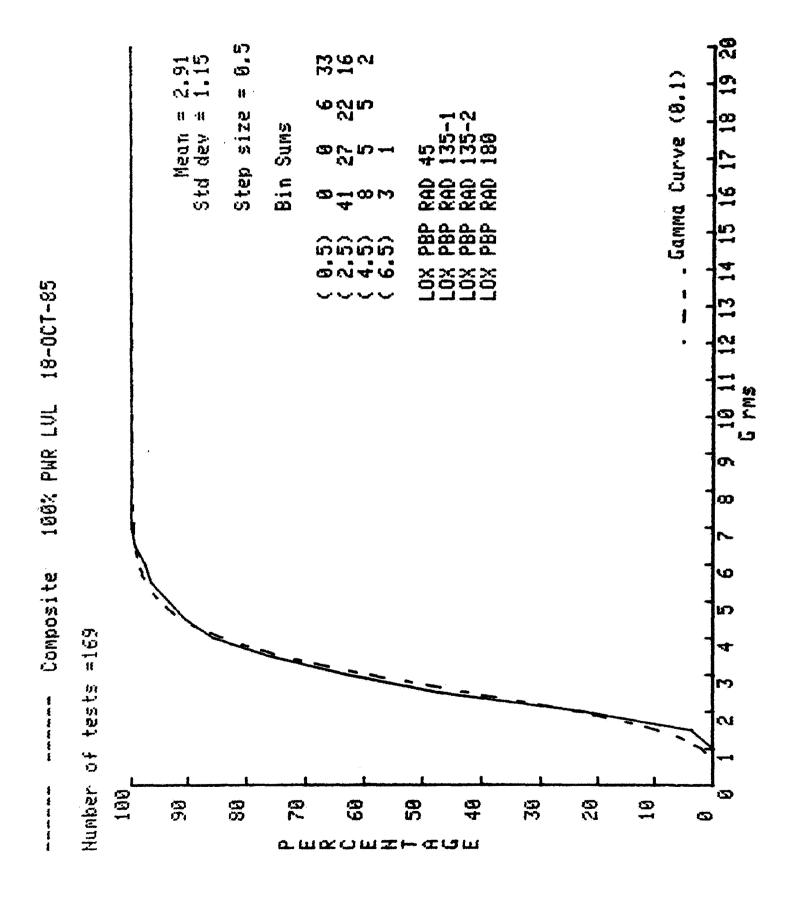


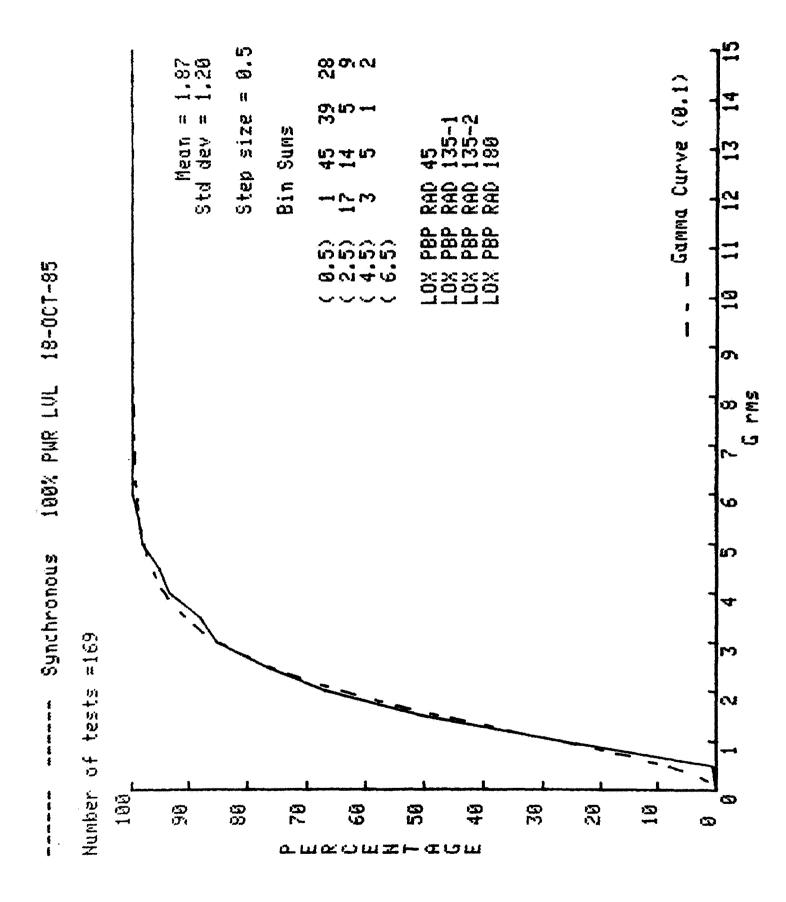


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APPENDIX D

WYLE LABORATORIES - RESEARCH STAFF TECHNICAL MEMORANDUM 65058-02-TM

ANALYSIS OF THE SYNCHRONOUS VIBRATION LEVELS FROM "HIGH RUNNING MAIN IMPELLERS" ON THE SSME HIGH PRESSURE OXIDIZER TURBOPUMP

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by

Wayne L. Swanson

An interim report of work performed under contract NAS8-33508

for

NATIONAL AERONAUTICS AND SPACE ADMINISTRATION GEORGE C. MARSHALL SPACE FLIGHT CENTER MARSHALL SPACE FLIGHT CENTER, ALABAMA 35812

FOREWORD

Wyle Laboratories' Scientific Services & Systems Group prepared this report for the George C. Marshall Space Flight Center, National Aeronautics and Space Administration. The work was performed under contract NAS8-33508, entitled "Dynamic Analysis of SSME Vibration and Pressure Data." Technical assistance and encouragement were provided by Mr. W. C. Smith, MSFC/ED24. The special assistance of Mr. P. Lewallen, MSFC/ED24, is acknowledged for modifying the MSFC Diagnostic Data Base Program software to calculate a unique spatial average. The contribution of other members of ED24 and Wyle Laboratories Research Department is also acknowledged.

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1.0 INTRODUCTION AND CONCLUSIONS

The purpose of this report is threefold: 1) to document an investigation of higher than expected (number of occurrences and amplitude) synchronous vibration levels on the high pressure oxidizer turbopump (HPOTP), 2) to illustrate the value of basic fundamental statistical methods of data analysis, incorporated in the MSFC Diagnostic Data Base Program, and 3) to document a data list of tests where the HPOTP vibration data are not contaminated by high running main impellers, whirl, instrumentation malfunctions, etc. Both the HPOTP Preburner Pump (PBP) and Turbine (TURB) measurements were considered in the analysis, operating at 100%, 104% and 109% power levels.

The terminology "High Running Main Impellers" was applied, after the study was completed, to an investigation in the last quarter of 1982 and early 1983 of higher than expected (number and amplitude) synchronous vibration levels on the HPOTP. When the original study was performed the vibration data was hand plotted in a format similar to the plotting routines now available using the MSFC Diagnostic Data Base Program. Data in this reports documents a re-evaluation and update of the original effort with maximum utilization of the MSFC computer program for data sorting, analysis and plotting. Analysis included calculation of the mean, standard deviation, spatial average, cumulative distribution and probability density with the classical Gamma distribution plotted as an overlay. Elegant and/or sophisticated statistical techniques were not used or required in the analysis, since visual methods were adequate to show a distinct difference between data groups.

This report does not change the conclusions and results of the original study which indicated a strong correlation between six main impellers and the high synchronous vibration levels. The analysis does, however, illustrate the application of probability density estimates for detecting embedded measurement groups representing differing statistical (and likely physical) behavior. In addition, the statistical characterization of the vibration data provided herein represents nominal HPOTP operation for future reference.

2.0 TECHNICAL DISCUSSION

2.1 Diagnostic Data Base

Table I is a listing of the relevant vibration measurements stored in the MSFC Diagnostic Data Base Program. The listing includes the test number, date of test, engine serial number, HPFTP serial number, HPOTP serial number and the power level of which the vibration data was acquired. For this analysis the number of tests at each power level was:

407 tests @ 100%

155 tests @ 104%

234 tests @ 109%.

These tests resulted in the following synchronous vibration data sample for analysis at the HPOTP preburner pump and turbine measurement locations. Each measurement was treated as an individual data point and therefore the results represent the spatial average over the transducer locations.

Number of Data Samples	Power <u>Level</u>	Measurement Location
1299	100%	LOX PBP RAD 45, 135-1, 135-2,
542	104%	180, 225
712	109%	•
∜		
971	100%	
348	104%	LOX TURB RAD 45, 90, 135
546	109%	

Serial numbers of HPOTP's with the suspect main impellers discussed in Section 2.4 are highlighted and the tests marked with an "H". Also the tests that experienced whirl are marked with an "SS" and the power level noted in the remarks column. These tests were also deleted before calculation of the statistics for normal turbopump operation.

2.2 Vibration Measurement Location

The plane in which the preburner pump and turbine accelerometers are located is shown in Figure 1. All accelerometers were oriented to measure the vibration in the radial direction. In Figure 2 the major components of the HPOTP pump section are identified including the main impeller.

TABLE 1. SSME HIGH PRESSURE OXIDIZER AND FUEL TURBOPUMP VIBRATION DATA IN MSFC DIAGNOSTIC DATA BASE

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HIGH PRESSURE OXYGEN TURBOPUMP

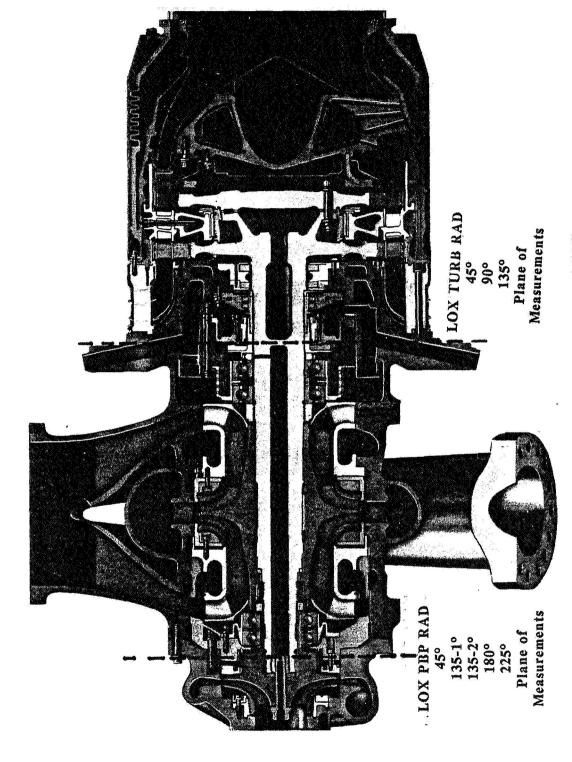


Figure 1. Accelerometer Location Plane HPOTP

Figure 2. Major Components of HPOTP Pump

2.3 Total Data Base HPOTP Synchronous Vibration

All tests listed in Table I were used to generate the plots shown in Figures 3 to 14. Separate plots are shown for 100%, 104%, and 109% power levels. These plots are the cumulative and density histograms of all the relevant synchronous Grms vibration data presently in the MSFC Diagnostic Data Base. Immediately obvious, especially at the 104% power level, is the bi-modal type of distribution which indicates the possibility of two different data groups. Also of note is the fact that a bi-modal type of distribution does not appear on the turbine end vibration measurements.

In the last quarter of 1982 a major effort was instigated to evaluate the second group of tests i.e. tests with synchronous levels greater than approximately 4 Grms. Numerous MSFC and contractor personnel were involved in the effort and investigated different facets of the problem such as imbalance, tear down inspection records, common components, etc. for each vibration data group. The conclusion from the original study was that the increased synchronous vibration levels were associated with the HPOP Main Impeller.

2.4 Listing of Suspect Main Impeller

The results of the MSFC/NASA investigation specifically identified six main impellers common to the second data group of tests, i.e. tests with synchronous vibration levels greater than 4 Grms. A total of 33 main impellers were investigated. The serial numbers, tests, power levels and the serial number of the HPOTP where the main impeller was installed are shown in Tables II through VII. These tables are a modified version of output of a computer routine available within NASA/MSFC for tracking components of the SSME.

----- Synchronous 104% PWR LVL 12-NOV-85 TEST #7S A1291-495.A2201,A2202-384,A3125-261, Number of tests =542

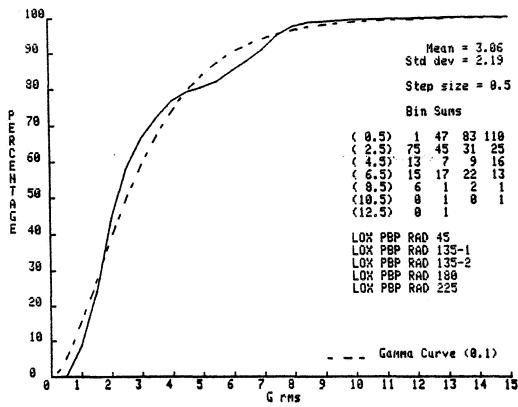


Figure 3. Cumulative Distribution HPOTP-PBP Total Data Base 104%

TEST #/S A1291-495, A2201, A2202-384, A3125-261, Humber of tests =542 25 Mean = 3.06 Std dev = 2.19 29 Step size = 0.5 Bin Suns PERCETTAGE (8.5) (2.5) (4.5) (6.5) (8.5) (19.5) (12.5) 118 25 16 13 83 31 9 45 7 75 13 15 6 15 22 2 17 10 LOX PBP RAD 45 LOX PBP RAD 135-LOX PBP RAD 135-LOX PBP RAD 180 LOX PBP RAD 225 135-1 135-2 5 Gamma Curve (0.5) Û 8 10 11 12 G rms

Figure 4. Probability Density HPOTP-PBP Total Data Base 104%

----- Synchronous 104% PWR LVL 12-NOV-85 TEST #'S A1291-495,A2201,A2202-384,A3125-261, Number of tests =348

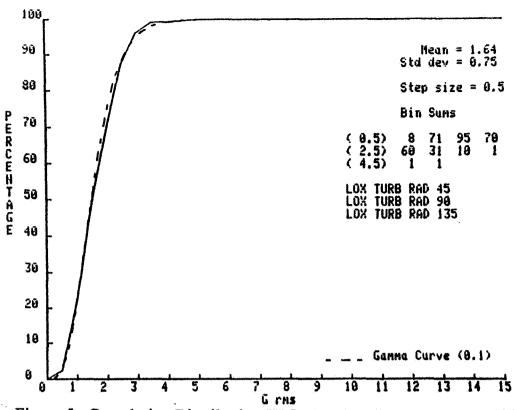
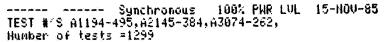


Figure 5. Cumulative Distribution HPOTP-TURB Total Data Base 104%

TEST #'S A1291-495, A2201, A2202-384, A3125-261, Humber of tests = 348 194% PHR LUL 12-HOU-85 30 Mean = 1.64 Std dev = 0.75 25 Step size = 0.5 Bin Suns PERCENTAGE 20 (0.5) (2.5) (4.5) 8 71 70 31 68 LOX TURB RAD 45 LOX TURB RAD 90 15 LOX TURB RAD 135 10 5 Gamma Curve (0.5) 12 13 14 11

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Figure 6. Probability Density HPOTP-TURB Total Data Base 104%



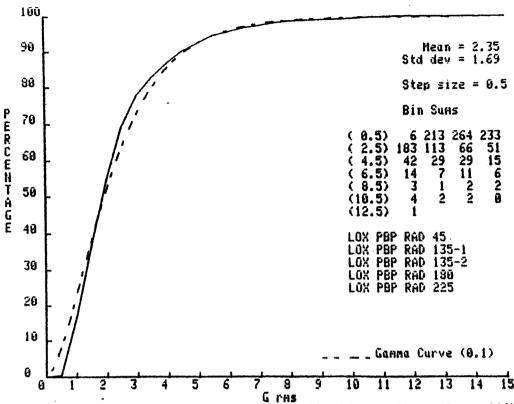


Figure 7. Cumulative Distribution HPOTP-PBP Total Data Base 100%

----- Synchronous 100% PWR LVL 15-NOV-85 TEST #15 A1194-495,A2145-384,A3074-262, Number of tests =1299

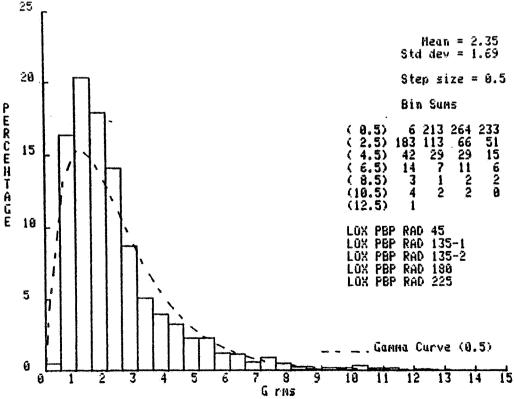


Figure 8. Probability Density HPOTP-PBP Total Data Base 100%

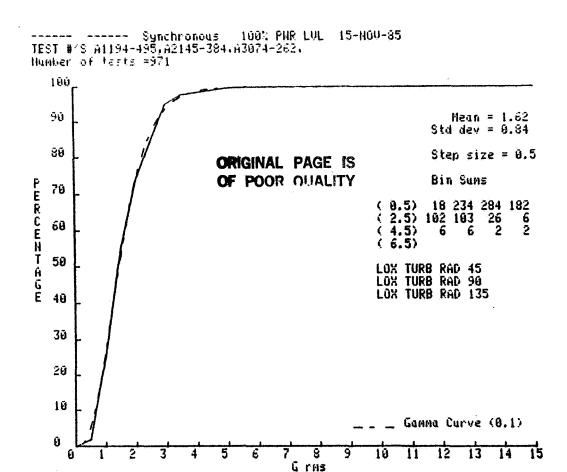


Figure 9. Cumulative Distribution HPOTP-TURB Total Data Base 100%

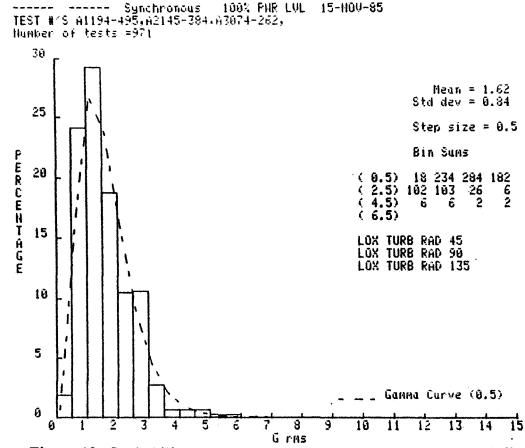


Figure 10. Probability Density HPOTP-TURB Total Data Base 100%

----- Synchronous 109% PWR LUL 14-NOV-85 TEST #'S A1322-493, A2193-381, A3125-262, Number of tests =712

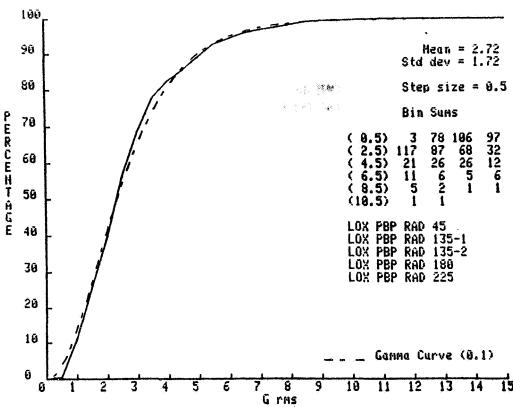


Figure 11. Cumulative Distribution HPOTP-PBP Total Data Base 109%

----- Synchronous 109% PMR LUL 14-H0U-85 TEST #'S A1322-493,A2193-381,A3125-262, Humber of tests =712

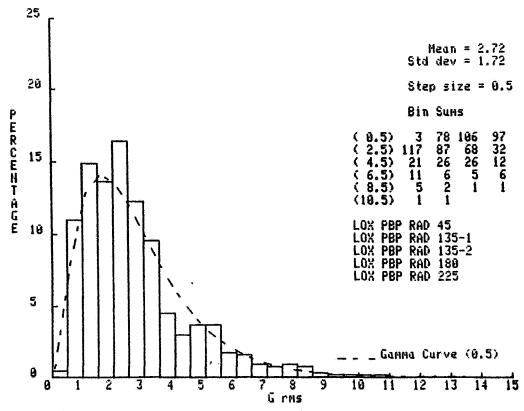


Figure 12. Probability Density HPOTP-PBP Total Data Base 109%

----- Synchronous 109% PWR LUL 14-NOV-85 TEST #/S A1322-493, A2193-381, A3125-262, Humber of tests =546

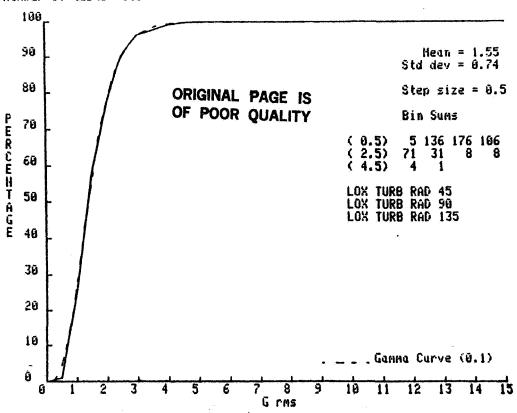


Figure 13. Cumulative Distribution HPOTP-TURB Total Data Base 109%

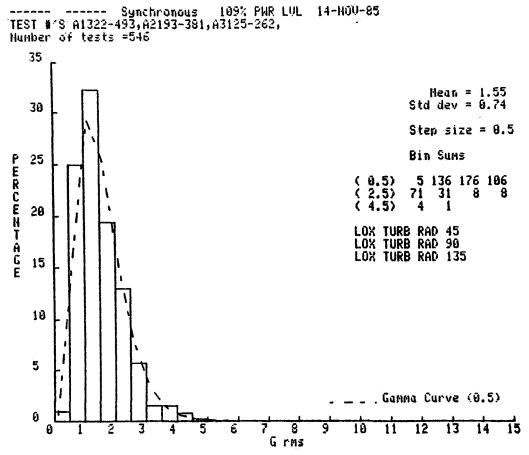


Figure 14. Probability Density HPOTP-TURB Total Data Base 109%

TABLE II, HPOP MAIN IMPELLER HISTORY - S/N 2427800

HPOP Main Impeller Histories Data as of November 4, 1985 - P/N RS007718-043

HPOTP	Test Date	Tests	NOMDUR	100% PWR	104% PWR	109% PWR	111% PWR
2108	82/02/01	901357	500.00	25.74	0.10	449.20	19.80
2108	82/02/08	901358	500.00	25.68	0.10	469.20	0.00
2108R1	82/02/19	902265	100.00	95.86	0.00	00.0	0.00
2108R1	82/02/22	902266	500.00	6.56	1.94	380.10	0.00
2108R2	82/06/18	902278	1.50	0.00	0.00	0.00	00.0
2108R2	82/06/20	902279	50.00	4.90	0.20	30.10	0.00
2108R2	82/06/28	902280	1.50	0.00	0.00	0.00	0.00
2108R2	82/06/29	902281	1.50	00.0	0.00	00.00	0.00
2108R2	82/07/01	902282	1.50	00.00	0.00	0.00	0.00
08R2	82/07/03	902283	50.00	4.90	0.20	30.10	0.00
2108R2	82/01/09	902284	500.00	6.43	1.94	380.20	0.00
2108R2	82/07/13	902285	10.00	5.75	0.00	0.00	0.00
2108R2	82/07/27	750169	1.49	00.00	0.00	0.00	0.00
2108R2	82/01/29	750170	50.00	35.78	0.00	0.00	0.00
2108R2	82/08/04	750171	299.89	14.92	0.20	270.10	0.00
2108R2	82/08/07	750172	300.00	14.87	0.20	270.10	0.00
12	82/10/18	901392	1.50	00.0	0.00	0.00	0.00
2312	82/10/21	901393	51.00	46.76	0.00	0.00	0.00
12	83/01/28	750189	3.65	0.00	0.00	00.0	0.00
2412	83/02/04	750190	250.00	64.89	139.80	9.60	0.00
2412	83/03/23	750193	, 70.00	5.50	50.10	0.00	0.00
12	83/04/14	750194	16.84	5.36	6.94	00.0	0.00
2412	83/04/22	750195	300.00	7.15	240.20	0.00	0.00
12	83/05/02	750196	150.00	64.89	59.70	0.00	0.00
12	83/05/16	750197	320.00	7.23	240.20	00.0	0.00
2412	83/05/23	750198	320.00	8.74	240.20	00.00	0.00
2412	83/05/28	750199	190.00	35.30	140.10	00.0	0.00
2412	83/06/04	750200	190.00	25.23	150.10	0.00	0.00
412	83/06/09	750201	100.00	5.47	80.10	0.00	0.00
2412	83/06/21	750202	2.20	0.00	0.00	00.0	0.00
412	83/06/25	750203	100.00	5.46	80.10	0.00	0.00
412	83/06/30	750204	320.02	7.17	240.20	00.00	0.00
412	83/01/06	750205	320.00	7.16	240.20	00.0	0.00
2412	83/07/11	750206	320.00	22.84	224.80	00.0	0.00
412	83/07/21	750207	100.00	20.60	74.70	00.0	0.00
Total S/N 2427800	127800		5992.68	581.14	2212.32	2288.70	19.80
•							

TABLE III. HPOP MAIN IMPELLER HISTORY - S/N 3134124

HPOP Main Impeller Histories Data as of November 4, 1985 - P/N RS007718-043

109% PWR 111% PWR	429.20 0.00	249.20 0.00	479.20 0.00		509.20 0.00	452.78 0.00	380.20 0.00		1.94 380.20	1.94 380.20 240.10 0.00	8	2	,		2	2	,	2	2	2
104% PWR	0.20	0.20	0.20	0.00	0.20	0.10	1.94	70	1.94	1.94	1.94 0.10 0.00	1.94 0.10 0.00 0.00	1.94 0.10 0.00 0.00	1.94 0.10 0.00 0.00 0.00	1.94 0.10 0.00 0.00 1.94	1.94 0.10 0.00 0.00 1.94	1.94 0.00 0.00 0.00 1.94 1.94	1.94 0.00 0.00 0.00 1.94 0.00	1.94 0.00 0.00 0.00 1.94 0.00	1.34 0.10 0.00 0.00 1.94 1.94 1.94
100% PWR	5.44	5.36	5.35	90.70	199.53	5.15	6.32		6.14	6.14 4.69	6.14 4.69 0.00	6.14 4.69 0.00 95.83	6.14 4.69 0.00 95.83 0.00	6.14 4.69 0.00 95.83 0.00 85.80	6.14 4.69 0.00 95.83 0.00 85.80 6.57	6.14 4.69 0.00 0.00 85.80 6.57	6.14 4.69 0.00 0.00 85.80 6.57 6.58	6.14 4.69 0.00 0.00 85.80 6.57 6.58 35.88	6.14 4.69 0.00 0.00 85.83 6.57 6.58 4.92	6.14 0.00 0.00 0.00 85.83 6.57 6.58 6.58 6.76 6.58
NOMDUR	500.00	270.00	500.00	95.40	750.00	463.58	500.00		500.00	500.00 250.00	500.00 250.00 1.50	500.00 250.00 1.50 100.00	500.00 250.00 1.50 100.00 1.50	500.00 250.00 1.50 100.00 1.50	500.00 250.00 1.50 100.00 100.00 500.00	500.00 250.00 1.50 100.00 1.50 500.00 500.00	500.00 250.00 1.50 100.00 1.50 500.00 500.00	500.00 250.00 1.50 100.00 100.00 500.00 500.00	500.00 250.00 1.50 100.00 100.00 500.00 500.00 500.00	500.00 250.00 1.50 100.00 100.00 500.00 500.00 250.00
Tests	901344	901345	901346	901347	901348	901349	902268		902269	902269 902270	902269 902270 901365	902269 902270 901365 901366	902269 902270 901365 901366 901396	902269 902270 901365 901366 901396	902269 902270 901365 901366 901396 901397	902269 902270 901365 901366 901396 901398	902269 902270 901365 901366 901397 901399 901399	902269 902270 901365 901366 901397 901398 901399 901400	902269 902270 901365 901366 901397 901398 901400 901400	902269 902270 901365 901366 901397 901399 901400 901403
Test Date	81/11/14	81/11/18	81/11/19	81/11/30	81/12/02	81/12/04	82/03/15		82/03/23	82/03/23 $82/03/29$	82/03/23 82/03/29 82/05/15	82/03/23 82/03/29 82/05/15 82/05/19	82/03/23 82/03/29 82/05/15 82/05/19 82/12/05	82/03/23 82/03/29 82/05/15 82/05/19 82/12/05	82/03/23 82/03/29 82/05/15 82/05/19 82/12/05 82/12/07	82/03/23 82/03/29 82/05/15 82/05/19 82/12/05 82/12/07 82/12/14	82/03/23 82/03/29 82/05/15 82/05/19 82/12/05 82/12/07 82/12/14 82/12/18	82/03/23 82/03/29 82/05/15 82/05/19 82/12/05 82/12/14 82/12/14 82/12/18 82/12/23	82/03/23 82/03/29 82/05/15 82/05/19 82/12/07 82/12/14 82/12/14 82/12/18 82/12/23 83/01/22	82/03/23 82/03/29 82/05/15 82/05/19 82/12/07 82/12/14 82/12/14 82/12/18 83/01/22 83/01/28
HPOTP	2109	2109	2109	2109	2109	2109	2111		2111	$2111 \\ 2111$	2111 2111 2211	2111 2111 2211 2211	2111 2111 2211 2211 2311	2111 2111 2211 2211 2311 2311	2111 2111 2211 2211 2311 2311	2111 2111 2211 2211 2311 2311 2311	2111 2111 2211 2211 2311 2311 2311 2311	2111 2111 2211 2211 2311 2311 2311 2311	2111 2111 2211 2211 2311 2311 2311 2311	2111 2111 2211 2211 2311 2311 2311 2311

TABLE IV. HPOP MAIN IMPELLER HISTORY - S/N 3134446

HPOP Main Impeller Histories Data as of November 4, 1985 - P/N RS007718-043

111% PWR	0.00	00.00	0.00	0.00	0.00	0.00	0.00	380.20	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	380.20
109% PWR	380.20	0.00	00.00	0.00	30.10	380.20	380.20	1.94	31.86	00.00	00.00	0.00	0.00	00.0	00.0	0.00	0.00	00.00	0.00	0.00	1204.50
104% PWR	1.94	0.00	0.00	0.00	0.20	1.94	1.94	1.94	0.10	0.00	0.00	79.70	240.20	240.00	40.10	0.00	270.10	270.10	0.00	79.70	1227.96
100% PWR	6.64	0.00	295.89	0.00	4.88	09.9	6.58	6.33	4.86	0.00	0.39	95.93	6.97	7.54	15.20	285.45	15.00	15.07	0.00	95.95	905.11
NOMDUR	500.00	5.12	300.00	1.50	50.00	500.00	500.00	500.00	41.76	1.50	4.95	190.00	320.00	320.00	70.00	300.00	300.00	300.00	1.50	190.00	4446.33
Tests	901374	901376	901377	901378	901379	901380	901381	901382	750173	902308	902309	902310	750208	750209	750216	750217	750218	750219	901431	901432	
Test Date	82/06/30	82/07/10	82/07/14	82/07/23	82/07/25	82/07/27	82/07/30	82/08/02	82/08/18	83/04/08	83/04/14	83/04/18	83/08/02	83/08/08	83/10/05	83/10/11	83/10/18	83/10/24	83/12/29	84/01/04	134446
HPOTP	2212 2212	2212	2212	2212	2212	2212	2212	2212	2212R1	2208	2208	2208	2208	2208		2208	2208	2208	2208R1	2208R1	Total S/N 3134446

TABLE V. HPOP MAIN IMPELLER HISTORY - S/N 3135444

HPOP Main Impeller Histories Data as of November 4, 1985 - P/N RS007718-043

HPOTP	Test Date	Tests	NOMDUR	100% PWR	104% PWR	109% PWR	111% PWR
0110	82/06/06	902277	250.00	4.94	0.20	225.10	0.00
0110R1	82/09/13	901386	1.54	0.00	0.00	00.0	0.00
0110R1	82/09/19	901387	1.50	0.00	0.00	0.00	0.00
0110R1	82/09/21	901388	5.40	0.92	0.00	0.00	0.00
0110R1	82/09/25	901389	120.00	95.82	9.70	00.0	00.0
0210	82/12/08	750183	299.95	85.78	124.20	85.05	0.00
0210R1	83/01/11	902305	1.50	0.00	0.00	0.00	0.00
0210R1	83/01/13	902306	86.44	82.28	0.00	00.0	0.00
0210R2	83/03/02	750192	39.89	5.21	29.99	00.00	00.0
Total S/N 3135444	3135444		806.22	274.95	164.09	310.15	0.00

TABLE VI. HPOP MAIN IMPELLER HISTORY - S/N 7326708

HPOP Main Impeller Histories Data as of November 4, 1985 - P/N RS007718-049

	HPOTP	Test Date	Tests	NOMDUR	100% PWR	104% PWR	109% PWR	111% PWR
	2000	80/01/22	901263	1.50	0.00	0.00	0.00	0.00
	0007	80/01/24	901264	1.50	0.00	00.0	00.0	0.00
	0007	80/01/25	901265	1.50	0.00	0.00	00.00	00.0
	0007R1	80/02/11	750065	1.50	0.00	0.00	00.0	0.00
	0007R1	80/02/12	750066	300.00	248.38	0.00	0.00	0.00
	0007R1	80/02/22	750067	300.00	254.34	0.00	0.00	0.00
	0007R1	80/06/16	901282	520.00	424.34	0.00	0.00	0.00
	0007R1	81/02/20	FRF001-A	21.86	15.26	0.00	0.00	0.00
	0007R1	81/04/12	STS001-A	519.42	432.45	0.00	0.00	00.0
	0007R1	81/11/12	STS002-A	520.13	435.78	0.00	0.00	0.00
-	0007R1	82/03/22	STS003-A	519.67	435.66	00.0	0.00	0.00
	0007R1	82/06/27	STS004-A	519.03	443.06	0.00	0.00	0.00
	0007R2	82/08/15	901383	300.00	295.85	0.00	0.00	0.00
-	0107	83/11/04	902320	1.50	0.00	0.00	0.00	0.00
	0107	83/11/09	902321	1.50	00.0	0.00	0.00	0.00
-	0107	83/11/11	902322	190.00	95.77	79.70	0.00	0.00
l. o								
	Total S/N 7326708	326708		5022.71	3353.93	352.08	59.44	0.00

TABLE VII. HPOP MAIN IMPELLER HISTORY - S/N 7363066

HPOP Main Impeller Histories Data as of November 4, 1985 - P/N RS007718-043

111% PWR	0.00	0.00	0.00	0.00	0.00
109% PWR	0.00	380.20	230.10	208.30	818.60
104% PWR	0.00	1.94	0.20	0.40	2.54
100% PWR	0.00	6.49	4.95	4.88	16.52
NOMDUR	1.50	200.00	250.00	250.00	1006.10
Tests	902300 902301	901401	901402	750191	
Test Date	82/10/23 $82/10/25$	83/01/04	83/01/08	83/02/12	7363066
HPOTP	9011 9011	9111	9111	9111R1	Total S/N 7363066

2.5 Synchronous Vibration Data of Six Main Impellers

The next step in the investigation was to repeat the analysis with the six main impeller vibration test data separated from the data sample. The results are shown in Figures 15 to 22 at the 104% power level. These plots present a very strong implication of two distinct data groups and indicate the listed six main impellers This conclusion is based upon the obvious visual difference as very suspect. between the density histograms of Figures 4, 15 and 16. No elegant statistical mathematical methods are required. Also it should be noted that the cumulative distribution after removal of the suspect main impeller data provides a much better fit to the classical Gamma distribution discussed in Reference 1.1 Figures 23 to 38 are the plots at 100% and 109% power level and also indicate a difference between groups, while not as dramatic as the 104% power level. Very little change appears in the LOX TURB RAD vibration cumulative distribution and probability density plots which is further evidence to suspect components on the preburner end of the turbo-Since the purpose of this document is to record the results of the study, rather than a detailed discussion of statistical techniques and physical effects, a detailed analysis of each plot will not be addressed. The difference in the calculated mean Grms and standard deviation for the three data groups are listed in Table VIII.

¹ Reference 1. Swanson, W. "Statistical Analysis of the Vibration Data for the SSME High Pressure Turbopump During Flight," Wyle TM 64058-01 October 1985.

TABLE VIII. LOX PBP RAD SYNCHRONOUS VIBRATION LEVELS

Total Da	ita Base	100% Power Level Six Main Impellers	Normal Operation
Mean	2.35 Grms	4.61 Grms	1.89 Grms
Std Dev	1.69	2.16	1.12
Data Sample	1299	219	1080
		104% Power Level	
Mean	3.06 Grms	6.57 Grms	2.09 Grms
Std Dev	2.09	1.86	1.05
Data Sample	542	111	412
		109% Power Level	
Mean	2.72 Grms	5.42 Grms	2.15 Grms
Std Dev	1.72	2.14	1.03
Data Sample	712	114	576

Spatial Average LOX TURB RAD Synchronous

100% Power Level

Total Da	ta Base	Six Main Impellers	Normal Operation
Mean	1.62 Grms	2.07 Grms	1.55 Grms
Std Dev	0.84	1.08	0.76
Data Sample	971	138	833
		104% Power Level	
Mean	1.64 Grms	1.80 Grms	1.59 Grms
Std Dev	0.75	0.76	0.73
Data Sample	348	61	276
		109% Power Level	
Mean	1.55 Grms	1.70 Grms	1.52 Grms
Std Dev	0.74	0.82	0.73
Data Sample	546	82	449

Normal HPOTP Operation 104%

TESTS USED IN THIS ANALYSIS:

TEST #'S A1291-323, A1390-430, A1433-440, A1446-495, A2201-307, A2311 -319, A2323-326, A2329-343, A2345-354, A2357-374, A2383-384, A3125-181, A3211-215, A3 221-261,

- ENTER...1) LIST STANDARD TABLE
 2) PLOT PROBABILITY DISTRIBUTION
 3) PLOT PROBABILITY DENSITY
 4) SELECT A NEW SET OF TESTS
 5) SELECT HEN DATA TYPE AND PWRLVL
 - 6) RETURN TO MAIN

Six Main Impellers 104%

TESTS USED IN THIS ANALYSIS:

TEST #/S A1389, A1432, A1442-443, A2310, A2375-376, A3183-209, A3216-219

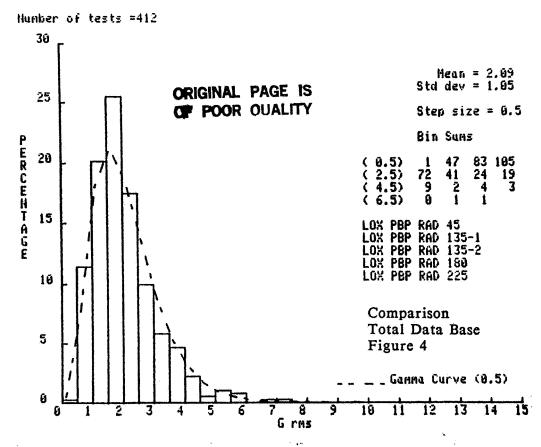


Figure 15. Probability Density for HPOTP-PBP Normal Operation 104%

----- Synchronous 104% PWR LVL 14-HOV-85
TEST #'S A1389,A1432,A1442-443,A2310,A2375-376,A3183-209,A3216-219,
Humber of tests =111.

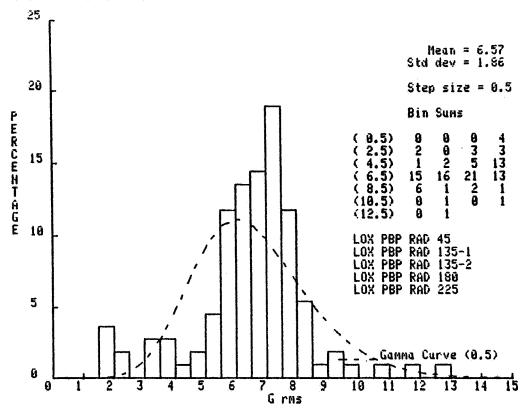


Figure 16. Probability Density for HPOTP-PBP Six Main Impellers 104%

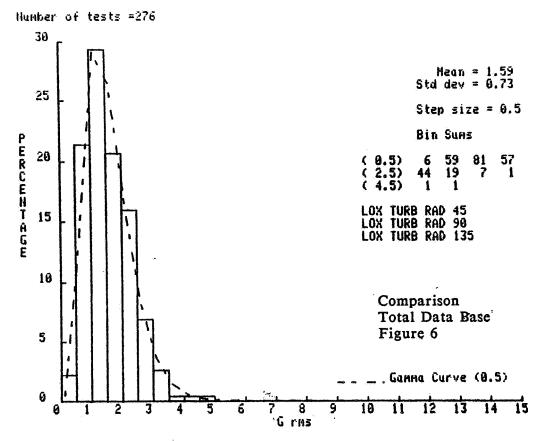


Figure 17. Probability Density HPOTP-TURB Normal Operation 104%

----- Synchronous 104% PWR LVL 14-HOV-85 TEST #/S A1389,A1432,A1442-443,A2310,A2375-376,A3183-209,A3216-219, Humber of tests =61 25 Mean = 1.80 Std dev = 0.76 20 Step size = 0.5 Bin Sums PERCENTAGE (0.5) 13 10 15 LOX TURB RAD 45 LOX TURB RAD 90 LOX TURB RAD 135 10 5 Gamma Curve (0.5)

Figure 18. Probability Density HPOTP-TURB Six Main Impellers 104%

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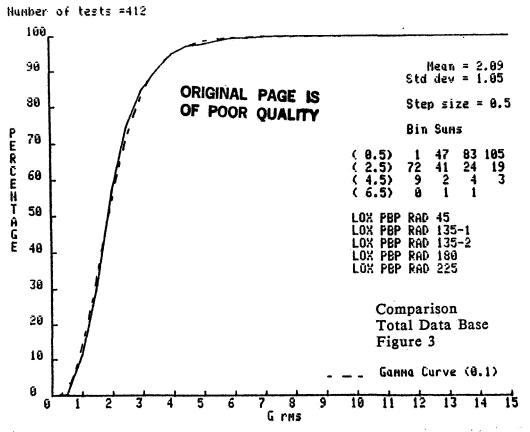


Figure 19. Cumulative Distribution HPOTP-PBP Normal Operation 104%

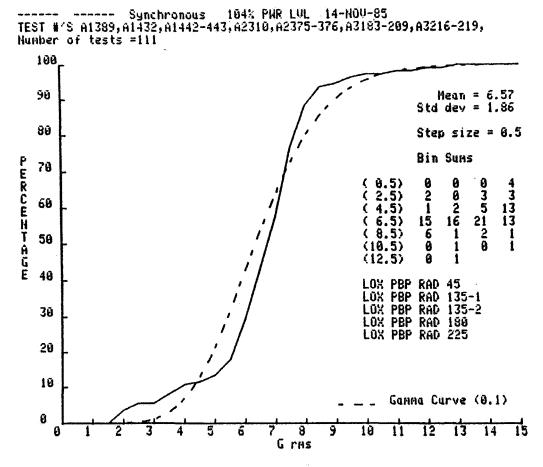


Figure 20. Cumulative Distribution HPOTP-PBP Six Main Impellers 104%

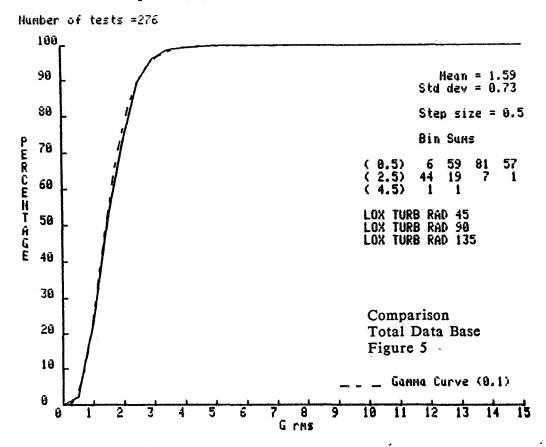


Figure 21. Cumulative Distribution HPOTP-TURB Normal Operation 104%

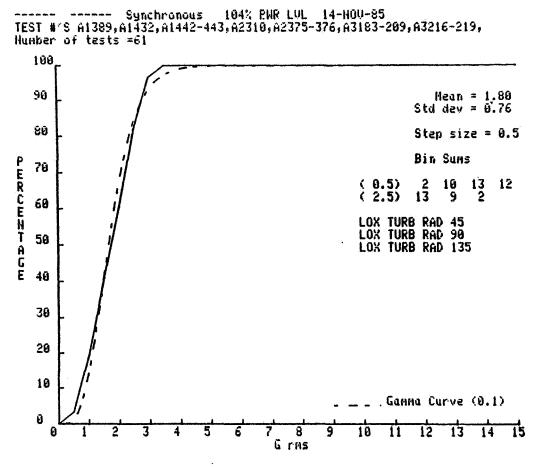


Figure 22. Cumulative Distribution HPOTP-TURB Six Main Impellers 104%

Normal HPOTP Operation 100%

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TESTS USED IN THIS ANALYSIS:

TEST #'S A1194-280,A1284-341,A1350-363,A1373,A1384,A1390-391,A1394-395,A
1406-430,A1433-440,A1445-495,A2145-264,A2271-274,A2289-303,A2307,A2311-3
19,A2323-374,A2377-384,A3074-162,A3177-182,A3184-188,A3210-215,A3220-262

- ENTER...1) LIST STANDARD TABLE
 2) PLOT PROBABILITY DISTRIBUTION
 3) PLOT PROBABILITY DENSITY
 4) SELECT A NEW SET OF TESTS
 5) SELECT NEW DATA TYPE AND PWRLUL

 - 6) RETURN TO MAIN

Six Main Impellers 100%

TESTS USED IN THIS ANALYSIS:

TEST *'S A1282,A1347,A1366,A1375-383,A1389,A1393,A1397-405,A1432,A1442-444,A2265-268,A2285,A2306,A2309-310,A2322,A2375-376,A3170-173,A3183,A3190-209,A3216-219,

- ENTER...1) LIST STANDARD TABLE

 2) PLOT PROBABILITY DISTRIBUTION

 3) PLOT PROBABILITY DENSITY

 4) SELECT A NEW SET OF TESTS

 5) SELECT NEW DATA TYPE AND PWRLUL

 6) RETURN TO MAIN

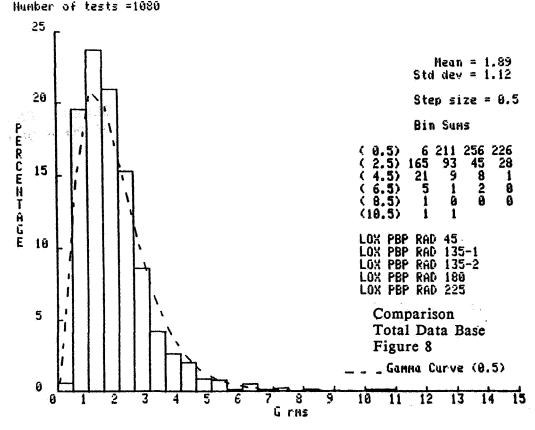


Figure 23. Probability Density HPOTP-PBP Normal Operation 100%

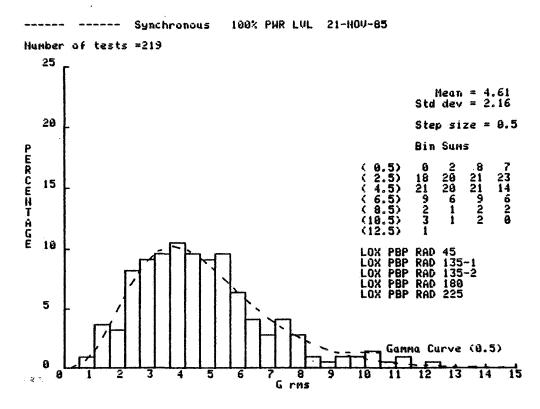


Figure 24. Probability Density HPOTP-PBP Six Main Impellers 100%

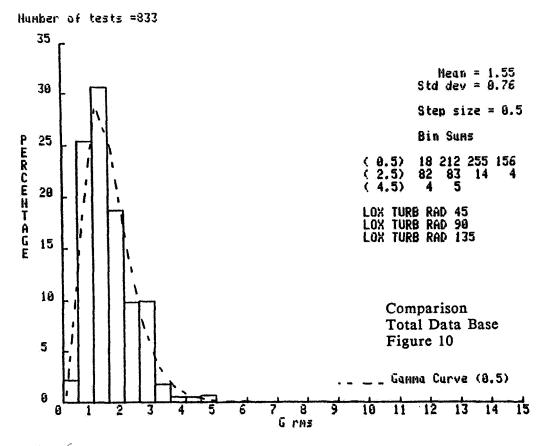


Figure 25. Probability Density HPOTP-TURB Normal Operation 100%

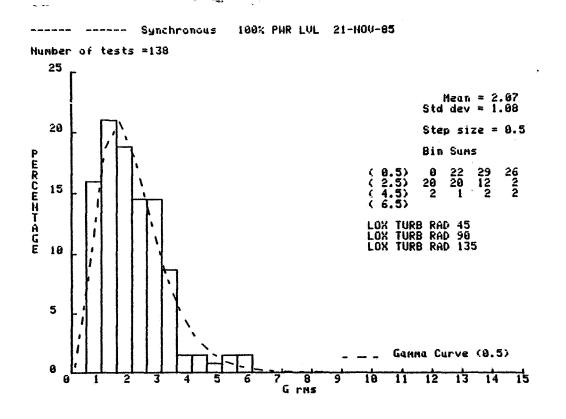
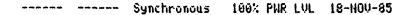


Figure 26. Probability Density HPOTP-TURB Six Main Impellers 100%



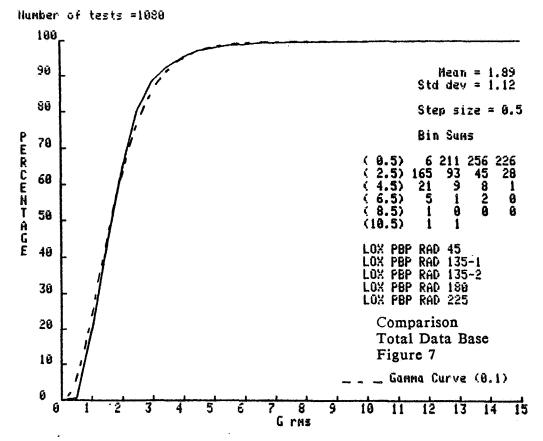


Figure 27. Cumulative Distribution HPOTP-PBP Normal Operation 100%

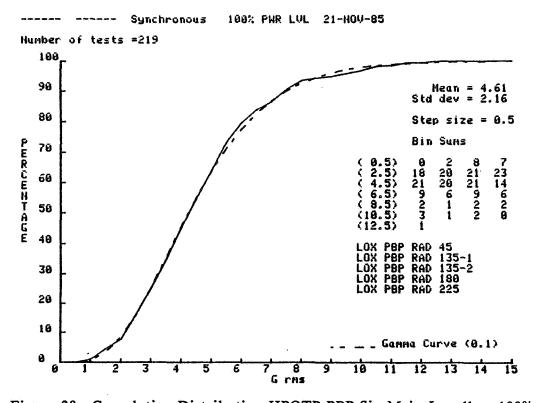


Figure 28. Cumulative Distribution HPOTP-PBP Six Main Impellers 100%

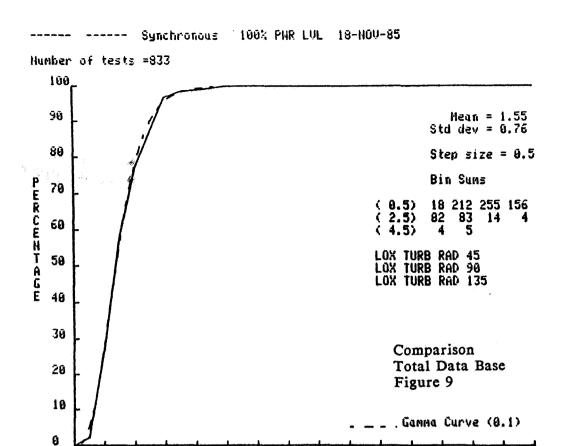


Figure 29. Cumulative Distribution HPOTP-TURB Normal Operation 100%

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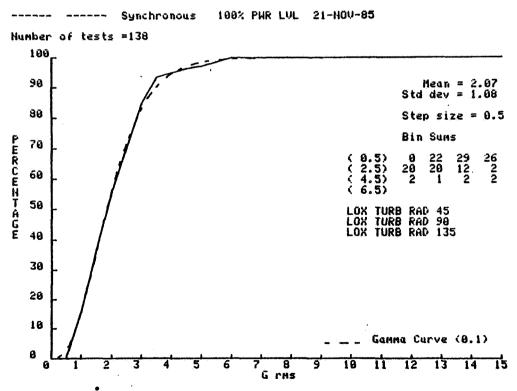


Figure 30. Cumulative Distribution HPOTP-TURB Six Main Impellers 100%

Normal HPOTP Operation 109%

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TESTS USED IN THIS ANALYSIS:

TEST #'8'A1322-343,A1351-355,A1361-362,A1364-372,A1384-395,A1433-436,A1445-493,A2193-261,A2267,A2272-276,A2286-372,A2377-381,A3125-152,A3154-168,A3174-181,A3184-188,A3211-262,

- ENTER...1) LIST STANDARD TABLE
 2) PLOT PROBABILITY DISTRIBUTION
 3) PLOT PROBABILITY DENSITY
 4) SELECT A NEW SET OF TESTS
 5) SELECT HEW DATA TYPE AND PWRLUL
 6) RETURN TO MAIN

Six Main Impellers 109%

TESTS USED IN THIS ANALYSIS:

TEST #78 A1344-349,A1358,A1374-381,A1398-399,A1401-405,A1443,A2268,A2277 -284,A2375-376,A3171,A3172,A3183,,A3190-191,

- ENTER...1) LIST STANDARD TABLE

 2) PLOT PROBABILITY DISTRIBUTION

 3) PLOT PROBABILITY DENSITY

 4) SELECT A NEW SET OF TESTS

 5) SELECT NEW DATA TYPE AND PWRLUL

 6) RETURN TO MAIN

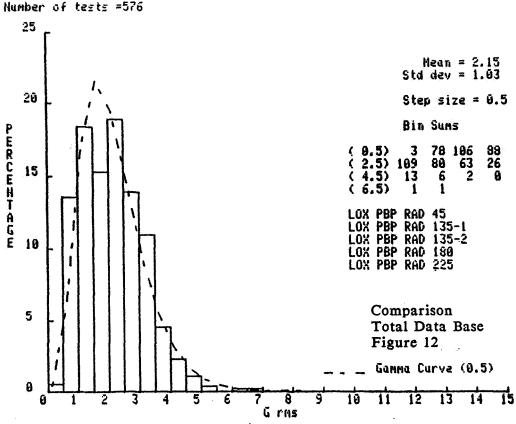


Figure 31. Probability Density HPOTP-PBP Normal Operation 109%

Synchronous 109% PWR LUL 15-HOV-85 Number of tests =114 25 Hean = 5.42 Std dev = 2.14 20 Step size = 0.5 Bin Sums PERCENTAGE (0.5) (2.5) (4.5) (6.5) (8.5) 58962 6 16 5 2 2 497 15 18 LOX PBP RAD 45 LOX PBP RAD 135-1 LOX PBP RAD 135-2 LOX PBP RAD 180 10 LOX PBP RAD 225 5 Genna Curve (8.5) Ū 8 Gras

Figure 32. Probability Density HPOTP-PBP Six Main Impellers 109%

----- ----- Synchronous 109% PNR LUL 14-NOV-85

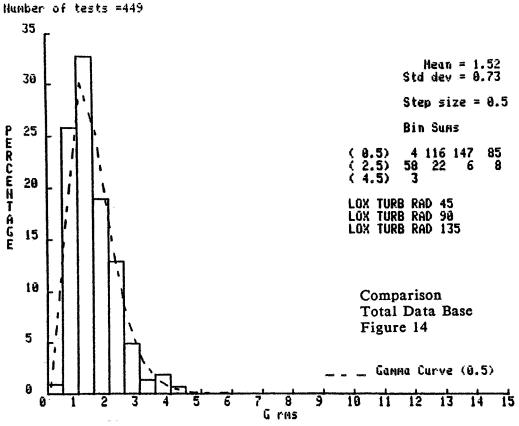


Figure 33. Probability Density HPOTP-TURB Normal Operation 109%

----- Synchronous 109% PWR LVL 15-NOV-85
Number of tests =82

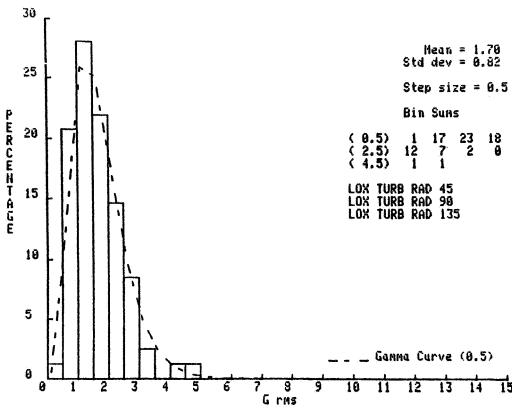
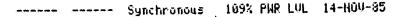


Figure 34. Probability Density HPOTP-PBP Six Main Impellers 109%



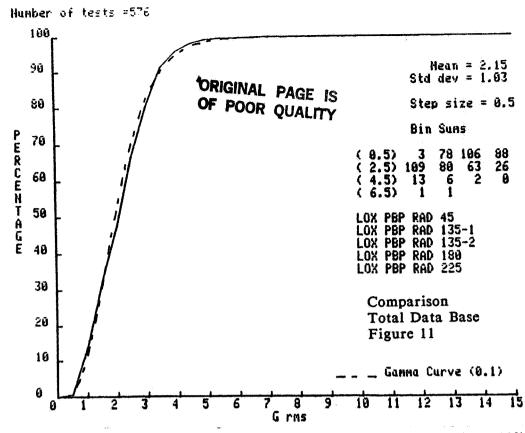


Figure 35. Cumulative Distribution HPOTP-PBP Normal Operation 109%

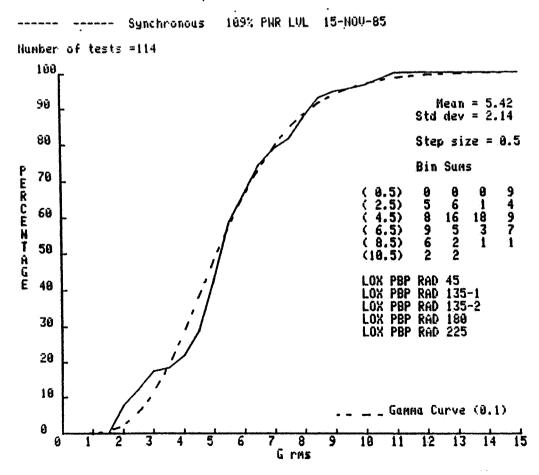


Figure 36. Cumulative Distribution HPOTP-PBP Six Main Impellers 109%

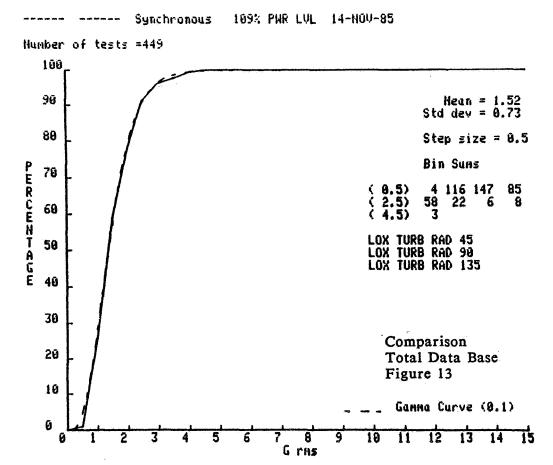


Figure 37. Cumulative Distribution HPOTP-TURB Normal Operation 109%

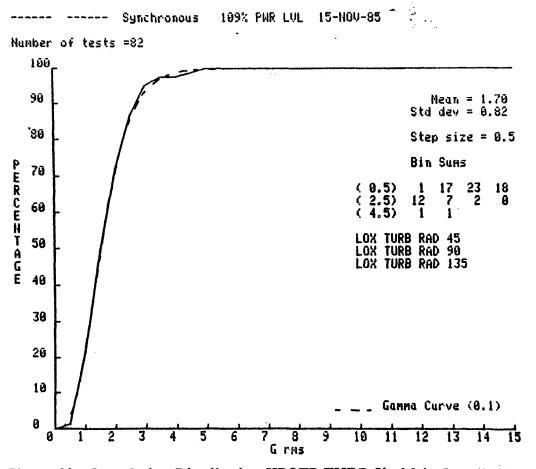


Figure 38. Cumulative Distribution HPOTP-TURB Six Main Impellers 109%

2.6 Random Selection of Tests

A random sample of 29 tests was selected, which is the number of tests in the six main impeller data sample, to evaluate the effect of sample size. The same analysis was used for this new data group and the results are shown in Figures 39 and 40. While it is recognized this method of analysis is not rigorous, it seems reasonable to assume a random selection should have followed a relative smooth continuous type of distribution unless the data is from two different data groups. The distribution is again bi-modal and presents additional evidence that the total data sample consists of two different data groups.

Random Selection of 29 Tests

TESTS USED IN THIS ANALYSIS:

TEST #'S A1389-390,A1407,A1420,A1433,A1438,A1453,A1475,A1483,A1487,A2212,A2296,A2311,A2314,A2326,A2331,A2340,A2363-365,A3181,A3193,A3199,A3201,A3218,A3221-222,A3227,A3257,

- ENTER...1) LIST STANDARD TABLE
 2) PLOT PROBABILITY DISTRIBUTION
 3) PLOT PROBABILITY DENSITY
 4) SELECT A NEW SET OF TESTS
 5) SELECT NEW DATA TYPE AND PWRLUL
 6) RETURN TO MAIN

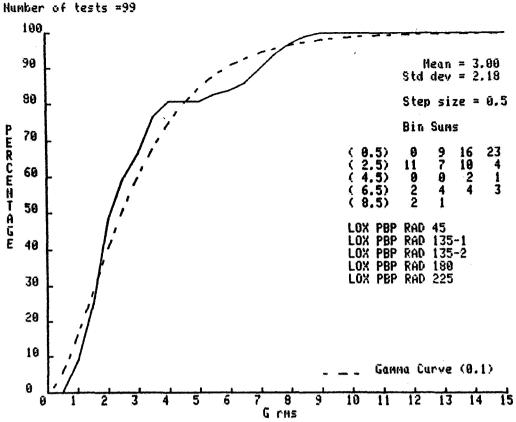


Figure 39. Cumulative Distribution HPOTP-PBP Random Selection of 29 Tests 104%

104% PWR LVL 15-NOV-85 Synchronous Humber of tests =99 -25 Mean = 3.00 Std dev = 2.18 20 Step size = 0.5 Bin Suns PERCENTAGE 16 970 23 2.5) 4.5) 6.5) 8.5) 15 822 13 LOX PBP **RAD 45** LOX PBP RAD 135-LOX PBP RAD 135-LOX PBP RAD 180 RAD 135-1 10 135-2 LOX PBP RAD 225 5 Gamma Curve (0.5) Ð 12 Gres

Figure 40. Probability Density HPOTP-PBP Random Selection of 29 Tests 104%

2.7 Vibration Test History of the Six Main Impellers

To complete this analysis, the synchronous spatial average vibration test history of the six main impellers is plotted. In the original study the data was hand plotted, and later incorporated as a routine in the MSFC Diagnostic Data Base Program. The output is shown in Figures 41 to 46. Listed below are the main impeller serial numbers, HPOTP serial number, last test and date of test.

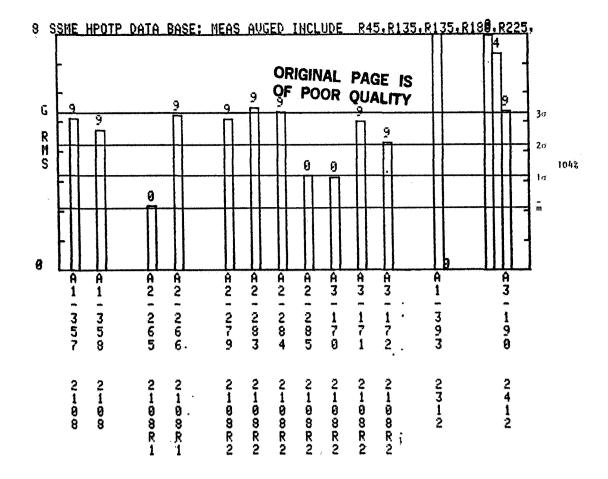
Main Impeller S/N	HPOTP #	Last Test	<u>Date</u>
2427800	2412	A3-207	7-21-83
3134124	2311R1	A1-405	2-4-83
3334446	2208R1	A1-432	1-4-84
3135444	0210R2	A3-192	3-2-83
7326066	0307	A2-376	11-11-83
7363708	9111R1	A3-191	2-12-83

It is beyond the scope of this study to fully investigate the variation in synchronous vibration levels from test to test, pump build to pump build or verify the six main impellers were the sole contributor to the bi-modal distribution of the HPOTP synchronous vibration data. However, since the original study only main impeller S/N 7326708, HPOTP #0307, Test A2-375 and A2-376 (Figure 46) has deviated from the pattern of all the identified main impellers being associated with abnormal synchronous vibration levels. For reference, the mean, $1\sigma_{c}$, $2\sigma_{c}$, and $3\sigma_{c}$ vibration levels for normal turbopump operation are as follows.

HPOTP PBP RAD Spatial Average Synchronous

	<u>100%</u>	<u>104%</u>	109%
Mean	1.89 Grms	2.09 Grms	2.15 Grms
Std Dev	1.12 Grms	1.05 Grms	1.03 Grms
Mean + 1σ	3.01 Grms	3.14 Grms	3.18 Grms
Mean + 2 σ	4.13 Grms	4.19 Grms	4.21 Grms
Mean + 3 o	5.25 Grms	5.24 Grms	5.24 Grms

The vibration levels for 104% power level are shown on each plot to illustrate the deviation from the expected normal operation value and relationship to the sigma levels.



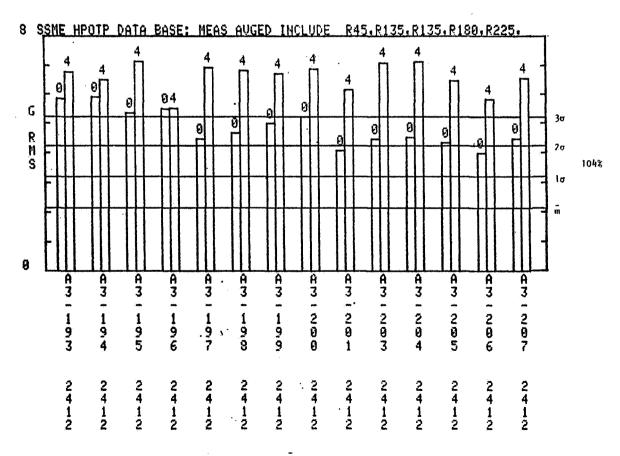
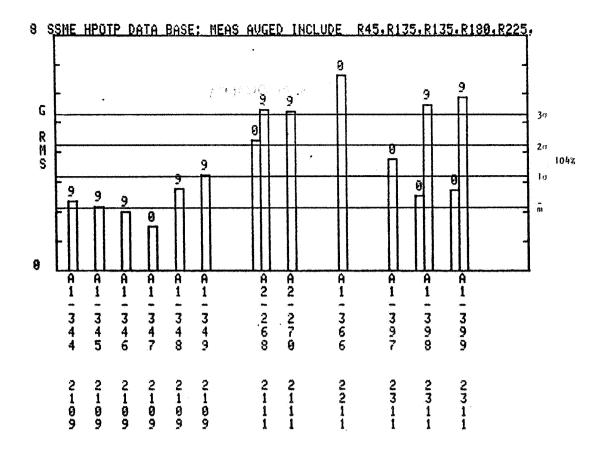


Figure 41. Synchronous Vibration Test History, Spatial Average PBP, Impeller S/N 2427800



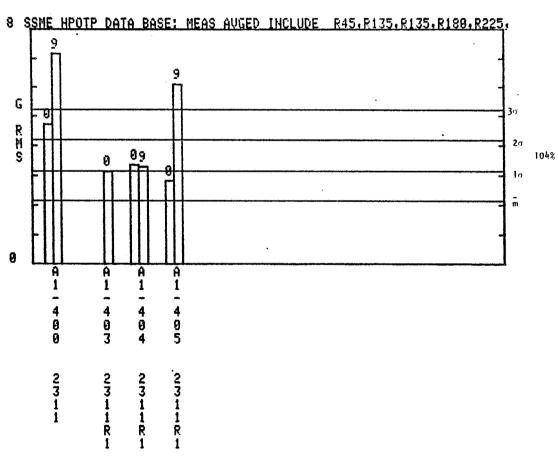
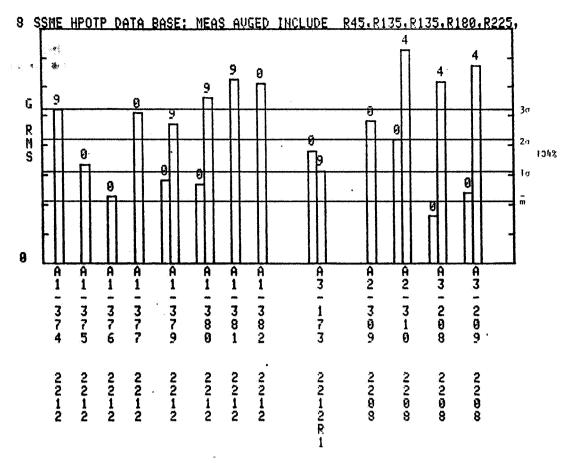


Figure 42. Synchronous Vibration Test History, Spatial Average PBP, Impeller S/N 3134124



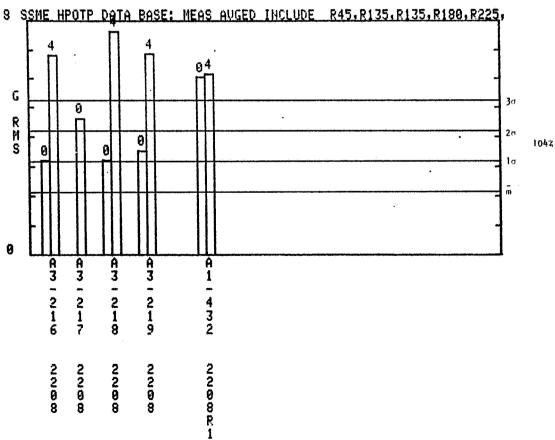


Figure 43. Synchronous Vibration Test History, Spatial Average PBP, Impeller S/N 3134446

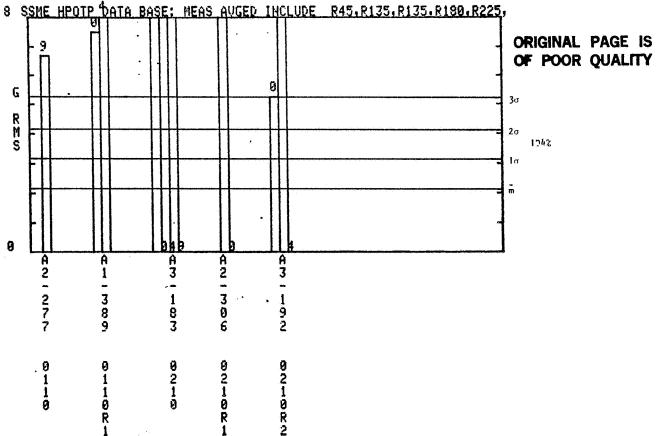


Figure 44. Synchronous Vibration Test History, Spatial Average PBP, Impeller S/N 3135444

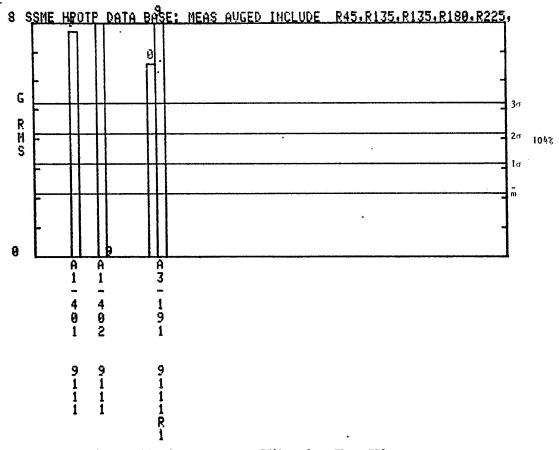
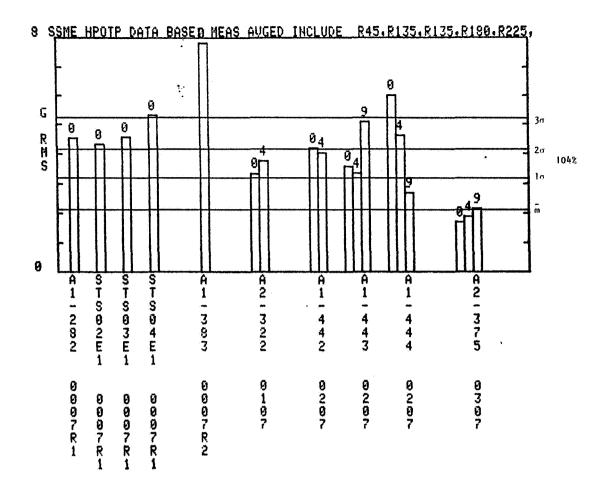


Figure 45. Synchronous Vibration Test History, Spatial Average PBP, Impeller S/N 7363066



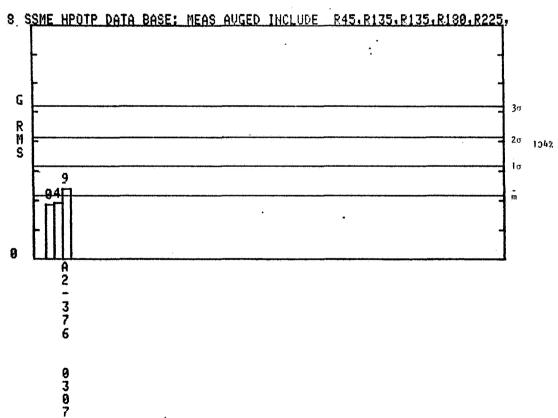


Figure 46. Synchronous Vibration Test History, Spatial Average PBP, Impeller S/N 7326708